
ABB GENERAL PURPOSE DRIVES

ACS580-01 drives

Hardware manual



ACS580-01 drives

Hardware manual

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1. Safety instructions



4. Mechanical installation



6. Electrical installation – IEC



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Update notice

Code	3AXD50000983780
Valid	2022-10-24
Contents	Declarations of conformity and safety data updated.

The notice concerns ACS580-01 drives (0.75 to 250 kW, 1.0 to 350 hp) hardware manual:

Manual code	Revision	Language	
3AXD50000044794	D	English	EN
3AXD50000044795	B	Dansk	DA
3AXD50000044796	B	Deutsch	DE
3AXD50000044797	B	Español	ES
3AXD50000044798	B	Suomi	FI
3AXD50000044799	B	Français	FR
3AXD50000044800	B	Italiano	IT
3AXD50000044831	B	Nederlands	NL
3AXD50000044832	B	Polski	PL
3AXD50000044833	B	Português	PT
3AXD50000044834	B	Русский	RU
3AXD50000044835	B	Svenska	SV
3AXD50000044836	B	Türkçe	TR
3AXD50000044837	B	中文	ZH

The safety data is calculated for redundant use, and applies only if both STO channels are used.

CHANGED: Safety data

The safety data for the Safe torque off function is given below.

Note: The safety data is calculated for redundant use, and applies only if both STO channels are used.

2 Update notice

Frame size	SIL	SC	PL	PFH ($T_1 = 20$ a) (1/h)	PFH _{avg} ($T_1 = 2$ a)	PFH _{avg} ($T_1 = 5$ a)	PFH _{avg} ($T_1 = 10$ a)	MTTF _D (a)	DC SFF (%)	SFF (%)	Cat.	HFT	CCF	T_M (a)	PFH ^{diag} (1/h)	λ_{Diag_s} (1/h)	λ_{Diag_d} (1/h)
$U_n = 230$ V																	
R1	3	3	e	2.79E-09	2.34E-05	5.83E-05	1.17E-04	2755	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R2	3	3	e	2.79E-09	2.34E-05	5.83E-05	1.17E-04	2756	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R3	3	3	e	2.59E-09	2.28E-05	5.72E-05	1.14E-04	2856	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R4	3	3	e	2.59E-09	2.28E-05	5.67E-05	1.14E-04	2870	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R5	3	3	e	3.94E-09	2.28E-05	5.69E-05	1.14E-04	2856	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R6, R7, R8, R9	3	3	e	3.92E-09	3.44E-05	8.59E-05	1.72E-04	9380	≥90	>99	3	1	80	20	1.40E-12	6.43E-08	1.40E-10
$U_n = 400$ V																	
R1, R2	3	3	e	2.55E-09	2.24E-05	5.59E-05	1.12E-04	2918	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R3	3	3	e	2.62E-09	2.31E-05	5.75E-05	1.15E-04	2823	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R4, R4 v2	3	3	e	2.59E-09	2.28E-05	5.67E-05	1.14E-04	2870	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R5	3	3	e	2.59E-09	2.28E-05	5.68E-05	1.14E-04	2868	≥90	>99	3	1	80	20	1.40E-12	6.43E-08	1.40E-10
R6, R7	3	3	e	3.92E-09	3.44E-05	8.59E-05	1.72E-04	9380	≥90	>99	3	1	80	20	1.40E-12	6.43E-08	1.40E-10
R8, R9	3	3	e	4.22E-09	3.69E-05	9.24E-05	1.85E-04	8792	≥90	>99	3	1	80	20	1.40E-12	1.96E-07	1.40E-10
$U_n = 600$ V																	
R2	3	3	e	2.67E-09	2.24E-05	5.57E-05	1.12E-04	2920	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R3	3	3	e	2.61E-09	2.30E-05	5.72E-05	1.15E-04	2840	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	2.89E-08
R5	3	3	e	2.59E-09	2.28E-05	5.69E-05	1.14E-04	2856	≥90	>99	3	1	80	20	1.53E-08	6.06E-08	1.36E-08
R7, R8, R9	3	3	e	4.25E-09	3.72E-05	9.29E-05	1.86E-04	6443	≥90	>99	3	1	80	20	1.40E-12	1.96E-07	1.40E-10
3AXD10001613533 B																	

CHANGED: Declarations of Conformity



EU Declaration of Conformity

Machinery Directive 2006/42/EC

We

Manufacturer: ABB Oy
 Address: Hiomotie 13, 00380 Helsinki, Finland.
 Phone: +358 10 22 11

declare under our sole responsibility that the following product:

Frequency converter

ACS580-01

with regard to the safety functions

- Safe Torque Off
- Safe stop 1 (SS1-t, with FSPS-21 PROFIsafe module, +Q986)

is in conformity with all the relevant safety component requirements of EU Machinery Directive 2006/42/EC, when the listed safety function is used for safety component functionality.

The following harmonized standards have been applied:

EN 61800-5-2:2007	Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional
EN IEC 62061:2021	Safety of machinery – Functional safety of safety-related control systems
EN ISO 13849-1:2015	Safety of machinery – Safety-related parts of control systems. Part 1: General requirements
EN ISO 13849-2:2012	Safety of machinery – Safety-related parts of the control systems. Part 2: Validation
EN 60204-1:2018	Safety of machinery – Electrical equipment of machines – Part 1: General requirements

The following other standards have been applied:


IEC 61508:2010, parts 1-2	Functional safety of electrical / electronic / programmable electronic safety-related systems
IEC 61800-5-2:2016	Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional

The product(s) referred in this Declaration of conformity fulfil(s) the relevant provisions of other European Union Directives which are notified in Single EU Declaration of conformity 3AXD10000497690.

Authorized to compile the technical file: ABB Oy, Hiomotie 13, 00380 Helsinki, Finland.

Helsinki, August 31, 2022
 Signed for and on behalf of:


 Mika Vartiainen
 Local Division Manager
 ABB Oy


 Harri Mustonen
 Product Unit Manager
 ABB Oy

Document number 3AXD10000302783



Declaration of Conformity

Supply of Machinery (Safety) Regulations 2008

We

Manufacturer: ABB Oy
Address: Hiomotie 13, 00380 Helsinki, Finland.
Phone: +358 10 22 11

declare under our sole responsibility that the following product:

Frequency converter

ACS580-01

with regard to the safety functions

- Safe Torque Off
- Safe stop 1 (SS1-t, with FSPS-21 PROFIsafe module, +Q986)

is in conformity with all the relevant safety component requirements of the Supply of Machinery (Safety) Regulations 2008, when the listed safety function is used for safety component functionality.

The following designated standards have been applied:

EN 61800-5-2:2007	Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional
EN IEC 62061:2021	Safety of machinery – Functional safety of safety-related control systems
EN ISO 13849-1:2015	Safety of machinery – Safety-related parts of control systems. Part 1: General requirements
EN ISO 13849-2:2012	Safety of machinery – Safety-related parts of the control systems. Part 2: Validation
EN 60204-1:2018	Safety of machinery – Electrical equipment of machines – Part 1: General requirements

The following other standards have been applied:

EN 61508:2010, parts 1-2	Functional safety of electrical / electronic / programmable electronic safety-related systems
EN 61800-5-2:2017	Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional

The product(s) referred in this declaration of conformity fulfil(s) the relevant provisions of other UK statutory requirements, which are notified in a single declaration of conformity 3AXD10001325742.

Authorized to compile the technical file: ABB Limited, Daresbury Park, Cheshire, United Kingdom, WA4 4BT.

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Further information



1

Safety instructions

Contents of this chapter

This chapter contains the safety instructions which you must obey when you install, start-up, operate and do maintenance work on the drive. If you ignore the safety instructions, injury, death or damage can occur.



Use of warnings and notes

Warnings tell you about conditions which can cause injury or death, or damage to the equipment. They also tell you how to prevent the danger. Notes draw attention to a particular condition or fact, or give information on a subject.

The manual uses these warning symbols:

**WARNING!**

Electricity warning tells about hazards from electricity which can cause injury or death, or damage to the equipment.

**WARNING!**

General warning tells about conditions other than those caused by electricity, which can cause injury or death, or damage to the equipment.

**WARNING!**

Electrostatic sensitive devices warning tells you about the risk of electrostatic discharge which can cause damage to the equipment.

General safety in installation, start-up and maintenance

These instructions are for all personnel who do work on the drive.



WARNING!

Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur.

- Keep the drive in its package until you install it. After unpacking, protect the drive from dust, debris and moisture.
- Use the required personal protective equipment: safety shoes with metal toe cap, safety glasses, protective gloves and long sleeves, etc. Some parts have sharp edges.
- Lift a heavy drive with a lifting device. Use the designated lifting points. See the dimension drawings.
- Be careful when handling a tall module. The module overturns easily because it is heavy and has a high center of gravity. Whenever possible, secure the module with chains. Do not leave an unsupported module unattended especially on a sloping floor.



- Beware of hot surfaces. Some parts, such as heatsinks of power semiconductors, and brake resistors, remain hot for a while after disconnection of the electrical supply.
 - Vacuum clean the area around the drive before the start-up to prevent the drive cooling fan from drawing the dust inside the drive.
 - Make sure that debris from drilling, cutting and grinding does not enter the drive during the installation. Electrically conductive debris inside the drive may cause damage or malfunction.
 - Make sure that there is sufficient cooling. See the technical data.
 - Before you connect voltage to the drive, make sure that all covers are in place. Do not remove the covers when voltage is connected.
-

- Before you adjust the drive operation limits, make sure that the motor and all driven equipment can operate throughout the set operation limits.
- Before you activate the automatic fault reset or automatic restart functions of the drive control program, make sure that no dangerous situations can occur. These functions reset the drive automatically and continue operation after a fault or supply break. If these functions are activated, the installation must be clearly marked as defined in IEC/EN/UL 61800-5-1, subclause 6.5.3, for example, "THIS MACHINE STARTS AUTOMATICALLY".
- The maximum drive power cycles is five times in ten minutes. Power cycling the drive too often can damage the charging circuit of the DC capacitors.
- If you have connected safety circuits to the drive (for example, Safe torque off or emergency stop), validate them at start-up. See separate instructions for the safety circuits.
- Beware of hot air exiting from the air outlets.
- Do not cover the air inlet or outlet when the drive is running.

Note:

- If you select an external source for the start command and it is on, the drive will start immediately after fault reset unless you configure the drive for pulse start. See the firmware manual.
- If the drive is in remote control mode, you cannot stop or start the drive with the control panel.
- Only authorized persons are allowed to repair a malfunctioning drive.



Electrical safety in installation, start-up and maintenance

■ Electrical safety precautions

These electrical safety precautions are for all personnel who do work on the drive, motor cable or motor.



WARNING!

Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur.

If you are not a qualified electrical professional, do not do installation or maintenance work.

Go through these steps before you begin any installation or maintenance work.

1. Clearly identify the work location and equipment.
2. Disconnect all possible voltage sources. Make sure that re-connection is not possible. Lock out and tag out.
 - Open the main disconnecting device of the drive.
 - If you have a permanent magnet motor connected to the drive, disconnect the motor from the drive with a safety switch or by other means.
 - Disconnect all dangerous external voltages from the control circuits.
 - After you disconnect power from the drive, always wait 5 minutes to let the intermediate circuit capacitors discharge before you continue.
3. Protect any other energized parts in the work location against contact.
4. Take special precautions when close to bare conductors.
5. Measure that the installation is de-energized. Use a quality voltage tester.
 - Before and after measuring the installation, verify the operation of the voltage tester on a known voltage source.
 - Make sure that the voltage between the drive input power terminals (L1, L2, L3) and the grounding (PE) busbar is zero.
 - Make sure that the voltage between the drive output terminals (T1/U, T2/V, T3/W) and the grounding (PE) busbar is zero.
 - Make sure that the voltage between the drive DC terminals (UDC+ and UDC-) and the grounding (PE) terminal is zero.

Note: If cables are not connected to the drive DC terminals, measuring the voltage from the DC terminal screws can give incorrect results.



6. Install temporary grounding as required by the local regulations.
7. Ask for a permit to work from the person in control of the electrical installation work.

■ Additional instructions and notes



WARNING!

Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur.

If you are not a qualified electrical professional, do not do installation or maintenance work.

- Make sure that the electrical power network, motor/generator, and environmental conditions agree with the drive data.
- Do not do insulation or voltage withstand tests on the drive.
- If you have a cardiac pacemaker or other electronic medical device, keep away from the area near motor, drive, and the drive power cabling when the drive is in operation. There are electromagnetic fields present which can interfere with the function of such devices. This can cause a health hazard.

Note:

- When the drive is connected to the input power, the motor cable terminals and the DC bus are at a dangerous voltage.
The brake circuit, including the brake chopper and brake resistor (if installed) are also at a dangerous voltage.
After disconnecting the drive from the input power, these remain at a dangerous voltage until the intermediate circuit capacitors have discharged.
- External wiring can supply dangerous voltages to the relay outputs of the control units of the drive.
- The Safe torque off function does not remove the voltage from the main and auxiliary circuits. The function is not effective against deliberate sabotage or misuse.

Printed circuit boards



WARNING!

Use a grounding wristband when you handle printed circuit boards. Do not touch the boards unnecessarily. The boards contain components sensitive to electrostatic discharge.

■ Grounding

These instructions are for all personnel who are responsible for the grounding of the drive.



WARNING!

Obey these instructions. If you ignore them, injury or death, or equipment malfunction can occur, and electromagnetic interference can increase.

If you are not a qualified electrical professional, do not do grounding work.

- Always ground the drive, the motor and adjoining equipment. This is necessary for the personnel safety.
- Make sure that the conductivity of the protective earth (PE) conductors is sufficient and that other requirements are met. See the electrical planning instructions of the drive. Obey the applicable national and local regulations.
- When using shielded cables, make a 360° grounding of the cable shields at the cable entries to reduce electromagnetic emission and interference.
- In a multiple-drive installation, connect each drive separately to the protective earth (PE) busbar of the power supply.



General safety in operation

These instructions are for all personnel that operate the drive.



WARNING!

Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur.

- If you have a cardiac pacemaker or other electronic medical device, keep away from the area near motor, drive, and the drive power cabling when the drive is in operation. There are electromagnetic fields present which can interfere with the function of such devices. This can cause a health hazard.
- Give a stop command to the drive before you reset a fault. If you have an external source for the start command and the start is on, the drive will start immediately after the fault reset, unless you configure the drive for pulse start. See the firmware manual.
- Before you activate the automatic fault reset or automatic restart functions of the drive control program, make sure that no dangerous situations can occur. These functions reset the drive automatically and continue operation after a fault or supply break. If these functions are activated, the installation must be clearly marked as defined in IEC/EN/UL 61800-5-1, subclause 6.5.3, for example, "THIS MACHINE STARTS AUTOMATICALLY".

Note:

- The maximum drive power cycles is five times in ten minutes. Power cycling the drive too often can damage the charging circuit of the DC capacitors. If you need to start or stop the drive, use the control panel keys or commands through the I/O terminals of the drive.
- If the drive is in remote control mode, you cannot stop or start the drive with the control panel.

Additional instructions for permanent magnet motor drives

■ Safety in installation, start-up, maintenance

These are additional warnings concerning permanent magnet motor drives. The other safety instructions in this chapter are also valid.



WARNING!

Obey these instructions. If you ignore them, injury or death, or damage to the equipment can occur.

If you are not a qualified electrical professional, do not do installation or maintenance work.

- Do not do work on the drive when a rotating permanent magnet motor is connected to it. A rotating permanent magnet motor energizes the drive including its input and output power terminals.

Before installation, start-up and maintenance work on the drive:

- Stop the drive.
- Disconnect the motor from the drive with a safety switch or by other means.
- If you cannot disconnect the motor, make sure that the motor cannot rotate during work. Make sure that no other system, like hydraulic crawling drives, can rotate the motor directly or through any mechanical connection like belt, nip, rope, etc.
- Do the steps in section *Electrical safety precautions (page 22)*.
- Install temporary grounding to the drive output terminals (T1/U, T2/V, T3/W). Connect the output terminals together as well as to the PE.

During the start-up:

- Make sure that the motor cannot run overspeed, for example, driven by the load. Motor overspeed causes overvoltage that can damage or destroy the capacitors in the intermediate circuit of the drive.



■ **Safety in operation**



WARNING!

Make sure that the motor cannot run overspeed, for example, driven by the load. Motor overspeed causes overvoltage that can damage or destroy the capacitors in the intermediate circuit of the drive.

2

Introduction to the manual

Contents of this chapter

This chapter describes the intended audience and contents of the manual. It contains a flowchart of steps in examining the delivery, installing and commissioning the drive. The flowchart refers to chapters/sections in this manual and other manuals.

Applicability

This manual applies to the ACS580-01 drives.

Target audience

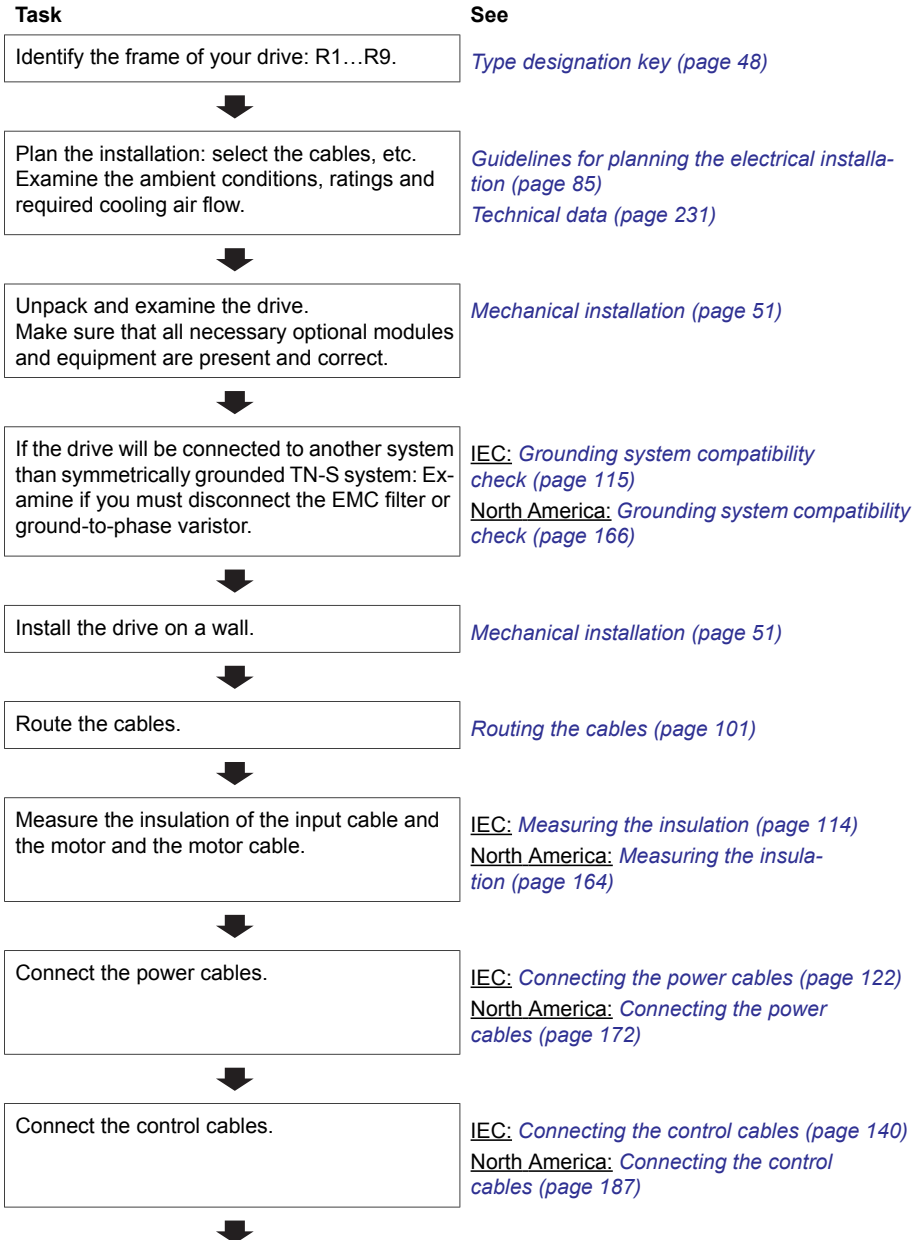
This manual is intended for people who plan the installation, install, commission and do maintenance work on the drive, or create instructions for the end user of the drive concerning the installation and maintenance of the drive.

Read the manual before working on the drive. You are expected to know the fundamentals of electricity, wiring, electrical components and electrical schematic symbols.

Categorization by frame size

The ACS580-01 is manufactured in frames (frame sizes) R1...R9. Some instructions and other information that concern only certain frames are marked with the symbol of the frame (R1...R9). The frame is marked on the type designation label of the drive, see *Type designation label (page 46)*.

Quick installation and commissioning flowchart



Task

Check the installation.

See*Installation checklist (page 209)*

Commission the drive.

ACS580 standard control program firmware manual (3AXD50000016097 [English])

Terms and abbreviations

Term	Description
ACS-BP-S	Basic control panel
Brake chopper	Conducts the surplus energy from the intermediate circuit of the drive to the brake resistor when necessary. The chopper operates when the DC link voltage exceeds a certain maximum limit. The voltage rise is typically caused by deceleration (braking) of a high inertia motor.
Brake resistor	Dissipates the drive surplus braking energy conducted by the brake chopper to heat
Capacitor bank	The capacitors connected to the DC link
CBAI-01	Bipolar analog IO extension module
CCA-01	Configuration adapter
CDPI-01	Communication adapter module
CHDI-01	115/230 V digital input extension module
CMOD-01	Multifunction extension module (external 24 V AC/DC and digital I/O extension)
CMOD-02	Multifunction extension module (external 24 V AC/DC and isolated PTC interface)
Control unit	The part in which the control program runs.
CPTC-02	Multifunction extension module (external 24 V and ATEX/UKEX-certified PTC interface)
DC link	DC circuit between rectifier and inverter
DC link capacitors	Energy storage which stabilizes the intermediate circuit DC voltage
DPMP-01	Mounting platform for control panel (flush mounting)
DPMP-02, DPMP-03	Mounting platform for control panel (surface mounting)
DPMP-EXT	Optional mounting platform for door mounting of control panel
Drive	Frequency converter for controlling AC motors
EFB	Embedded fieldbus
EMC	Electromagnetic compatibility
FBA	Fieldbus adapter
FCAN	Optional CANopen® adapter module
FCNA-01	Optional ControlNet™ adapter module
FDNA-01	Optional DeviceNet™ adapter module
FECA-01	Optional EtherCAT® adapter module

Term	Description
FEIP-21	Optional Ethernet adapter module for EtherNet/IP™
FENA-21	Optional Ethernet adapter module for EtherNet/IP™, Modbus TCP® and PROFINET IO® protocols, 2-port
FEPL-02	Optional Ethernet POWERLINK adapter module
FMBT-21	Optional Ethernet adapter module for Modbus TCP protocol
FPBA-01	Optional PROFIBUS DP® adapter module
FPNO-21	Optional PROFINET IO adapter module
Frame, frame size	Physical size of the drive or power module
FSCA-01	Optional RS-485 (Modbus/RTU) adapter
FSPS-21	Optional functional safety module
IGBT	Insulated gate bipolar transistor
Intermediate circuit	DC circuit between rectifier and inverter
Inverter	Converts direct current and voltage to alternating current and voltage.
Macro	A pre-defined set of default values of parameters in a drive control program.
NETA-21	Remote monitoring tool
Network control	With fieldbus protocols based on the Common Industrial Protocol (CIPTM), such as DeviceNet and Ethernet/IP, denotes the control of the drive using the Net Ctrl and Net Ref objects of the ODVA AC/DC Drive Profile. For more information, see www.odva.org .
Parameter	In the drive control program, user-adjustable operation instruction to the drive, or signal measured or calculated by the drive. In some (for example fieldbus) contexts, a value that can be accessed as an object. For example, variable, constant, or signal.
PLC	Programmable logic controller
PTC	Positive temperature coefficient
Rectifier	Converts alternating current and voltage to direct current and voltage
STO	Safe torque off (IEC/EN 61800-5-2)

Related documents

Name	Code (English/ Multilingual)	Code (Translation)
Drive manuals and guides		
ACS580 standard control program firmware manual	3AXD50000016097	
ACS580-01 hardware manual	3AXD50000044794	
ACS580-01 quick installation and startup guide for global (IEC) product types	3AXD50000527052	
ACS580-01 quick installation and startup guide for North American (NEC) product types	3AXD50000745524	
	3AXD50000788286	
ACS-AP-I, -S, -W and ACH-AP-H, -W Assistant control panels user's manual	3AUA0000085685	

Name	Code (English/ Multilingual)	Code (Translation)
Drive modules cabinet design and construction instructions	3AUA0000107668	
Installation of drive module frames R6 to R9 in Rittal VX25 enclosure supplement	3AXD50000523191	
Alternate Fuses, MMPs and Circuit Breakers for ABB Drives	3AXD50000645015	
Option manuals and guides		
ACS580, ACH580 and ACQ580 drive module frames R3 and R5 to R9 for cabinet installation (options +P940 and +P944) supplement	3AXD50000210305	
ACS580-01, ACH580-01 and ACQ580-01 installation guide for UK gland plate (option +H358)	3AXD50000034735	
CPTC-02 ATEX-certified thermistor protection module, Ex II (2) GD (+L537+Q971) user's manual	3AXD50000030058	
CDPI-01 communication adapter module user's manual	3AXD50000009929	
DPMP-01 mounting platform for control panels	3AUA0000100140	
DPMP-02/03 mounting platform for control panels	3AUA0000136205	
DPMP-04/05 mounting platform for control panels	3AXD50000308484	
FCAN-01 CANopen adapter module user's manual	3AFE68615500	
FCNA-01 ControlNet adapter module user's manual	3AUA0000141650	
FDNA-01 DeviceNet™ adapter module user's manual	3AFE68573360	
FECA-01 EtherCAT adapter module user's manual	3AUA0000068940	
FEIP-21 Ethernet/IP adapter module user's manual	3AXD50000158621	
FENA-01/-11/-21 Ethernet adapter module user's manual	3AUA0000093568	
FEPL-02 Ethernet POWERLINK adapter module user's manual	3AUA0000123527	
FMBT-21 Modbus/TCP adapter module user's manual	3AXD50000158607	
FPBA-01 PROFIBUS DP adapter module user's manual	3AFE68573271	
FPNO-21 PROFINET adapter module user's manual	3AXD50000158614	
FSCA-01 RS-485 adapter module user's manual	3AUA0000109533	
FSPS-21 Safety functions fieldbus module user's manual	3AUA0000158638	
ACS580-01..., ACH580-01... and ACQ580-01...+C135 drives with flange mounting kit supplement	3AXD50000349821	
ACS580-01..., ACH580-01... and ACQ580-01...+C135 frames R1 to R3 flange mounting kit quick installation guide	3AXD50000119172	
ACS580-01..., ACH580-01... and ACQ580-01...+C135 frames R4 to R5 flange mounting kit quick installation guide	3AXD50000287093	
ACS880-01..., ACS580-01..., ACH580-01... and ACQ580-01...+C135 frames R6 to R9 flange mounting kit quick installation guide	3AXD50000019099	

Name	Code (English/ Multilingual)	Code (Translation)
Main switch and EMC C1 filter options (+F278, +F316, +E223) installation supplement for ACS580-01, ACH580-01 and ACH580-01 frames R1 to R5	3AXD50000155132	
UL Type 12 hood quick installation guide for ACS580-01, ACH580-01, ACQ580-01, ACH580-31, ACQ580-31, ACS880-11 and ACS880-31	3AXD50000225972	
Tool and maintenance manuals and guides		
Drive composer PC tool user's manual	3AUA0000094606	
Converter module capacitor reforming instructions	3BFE64059629	
NETA-21 remote monitoring tool user's manual	3AUA0000096939	
NETA-21 remote monitoring tool installation and start-up guide	3AUA0000096881	
Animation		
ACH580-01, ACQ580-01, ACS580-01 and ACS880-01 frames R6...R7 installation in Rittal VX25 400 mm enclosure animation	9AKK107991A9541	

You can find manuals and other product documents in PDF format on the Internet at www.abb.com/drives/documents.

The code below opens an online listing of the manuals applicable to this product.



[ACS580-01 manuals](#)



3

Operation principle and hardware description

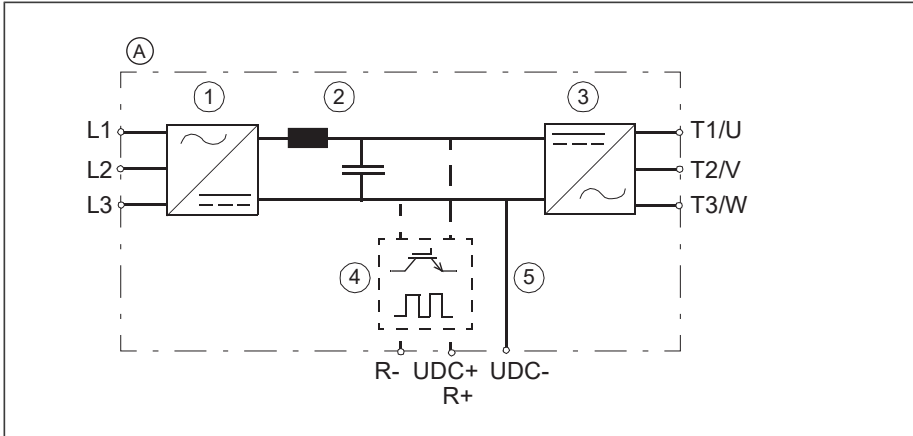
Contents of this chapter

This chapter briefly describes the operation principle and construction of the drive.

Operation principle

The ACS580-01 is a drive for controlling asynchronous AC induction motors, permanent magnet motors and synchronous reluctance motors (SynRM).

The figure below shows the simplified main circuit diagram of the drive.



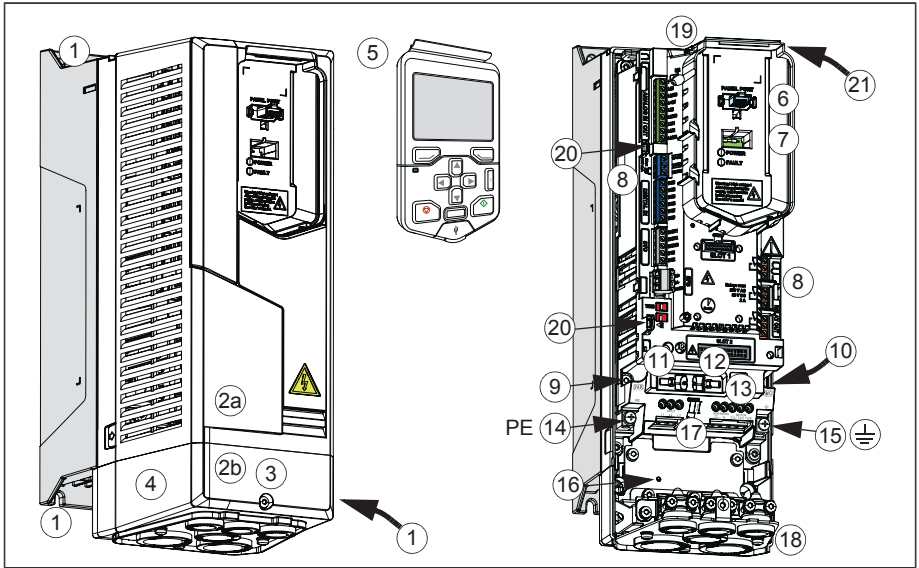
A	Drive
1	Rectifier. Converts alternating current and voltage to direct current and voltage.
2	DC link. DC circuit between rectifier and inverter.
3	Inverter. Converts direct current and voltage to alternating current and voltage.
4	Built-in brake chopper (R-, R+) in frames R1...R3. Conducts the surplus energy from the intermediate DC circuit of the drive to the brake resistor when necessary. The chopper operates when the DC link voltage exceeds a certain maximum limit. The voltage rise is typically caused by deceleration (braking) of a high inertia motor. The user obtains and installs the brake resistor when needed.
5	DC connection (UDC+, UDC-), for an external brake chopper in frames R4...R9.

Layout

Frames R1...R2

The layout of a frame R1 drive is presented below. The main structure of frame R2 is similar to R1. IP55 / UL Type 12 frames are also slightly different from IP21 / UL Type 1 frames, for example, IP21 / UL Type 1 front cover has two parts while IP55 / UL Type 12 front cover only has one part.

R1 IP21 / UL Type 1



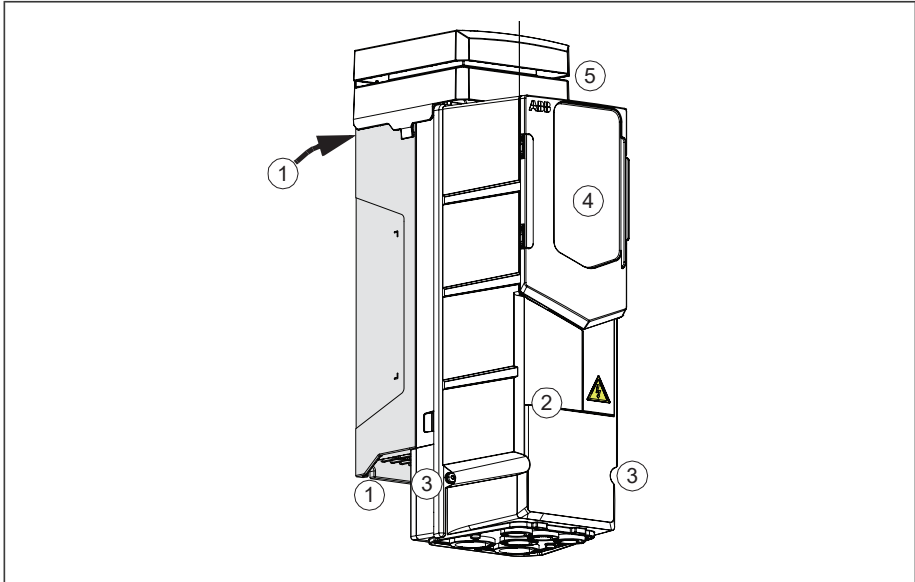
1	Mounting points (4 pieces)
2	Cover: upper part (2a), lower part (2b)
3	Cover screw
4	Cable/conduit box
5	Control panel
6	Control panel connection
7	Cold configuration connection for CCA-01
7	Power OK and Fault LEDs. See section LEDs (page 227) .
8	I/O connections. See External control connection terminals, frames R1...R5 (page 43) .
9	Varistor grounding screw (VAR). For disconnecting, see page 119 (IEC) or page 169 (North America) .

10	EMC filter grounding screw (EMC (DC)). For disconnecting, see page 119 (IEC) or page 169 (North America) .
11	Place for storing the removed VAR screw
12	Place for storing the removed EMC screw
13	Input power connection (L1, L2, L3), motor connection (T1/U, T2/V, T3/W) and brake resistor connection (R-, R+)
14	PE connection (power line)
15	Grounding connection (motor)
16	Additional grounding connection
17	Stripping length (8 mm) checker
18	Cable entry
19	Main cooling fan
20	Cable tie mounts for I/O cables
21	Auxiliary cooling fan connector

36 Operation principle and hardware description

This is an example of IP55 / UL Type 12 frames. They have one-piece front cover, which has a transparent window to leave the control panel visible. UL Type 12 frames have a hood, whose construction depends on the frame size.

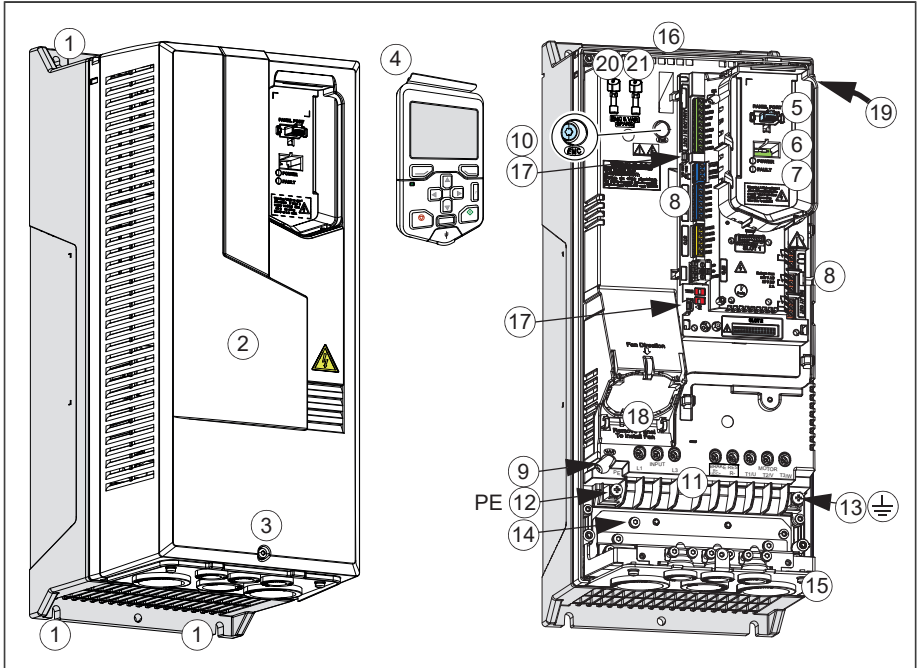
R1 IP55 / UL Type 12



1	Mounting points (4 pieces), top points are under the hood, which is installed last.
2	Front cover
3	Cover screws (2 pieces)
4	Control panel behind the transparent window
5	Hood, UL Type 12 only. Hood types vary by the frame size, see page 268.

Frame R3

R3 IP21 / UL Type 1

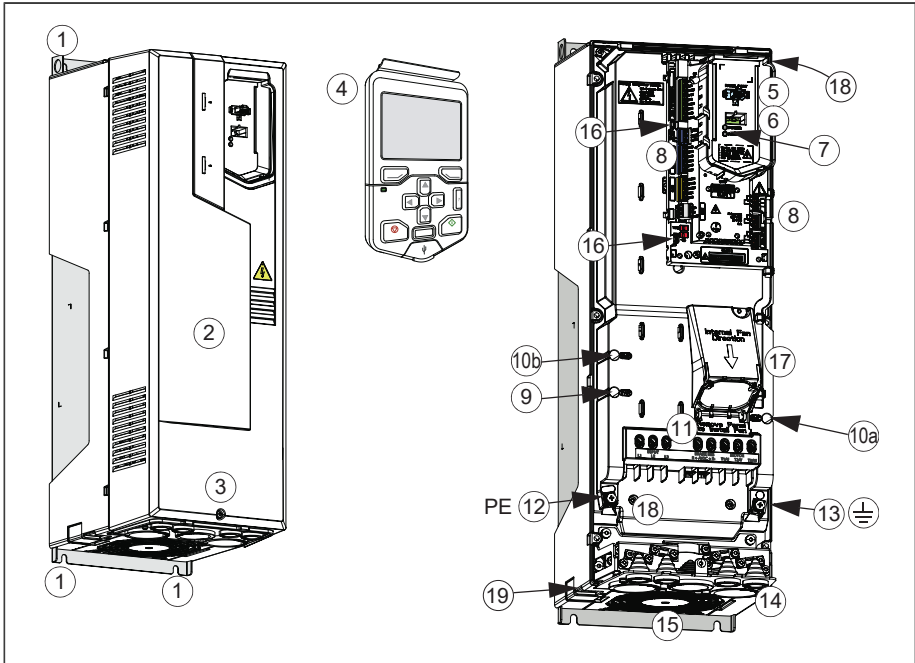


1	Mounting points (4 pieces)
2	Cover
3	Cover screw
4	Control panel
5	Control panel connection
6	Cold configuration connection for CCA-01
7	Power OK and Fault LEDs. See section LEDs (page 227) .
8	I/O connections. See External control connection terminals, frames R1...R5 (page 43) .
9	Varistor grounding screw (VAR). For disconnecting, see page 119 (IEC) or page 169 (North America) .
10	EMC filter grounding screw (EMC (DC)). For disconnecting, see page 119 (IEC) or page 169 (North America) .

11	Input power connection (L1, L2, L3), motor connection (T1/U, T2/V, T3/W) and brake connection (R-, R+)
12	PE connection (power line)
13	Grounding connection (motor)
14	Additional grounding connection
15	Cable entry
16	Main cooling fan
17	Cable tie mounts for I/O cables
18	Auxiliary cooling fan. For IP55/UL Type 12 drives only.
19	Auxiliary cooling fan connector
20	Place for storing the removed EMC screw
21	Place for storing the removed VAR screw

Frame R4

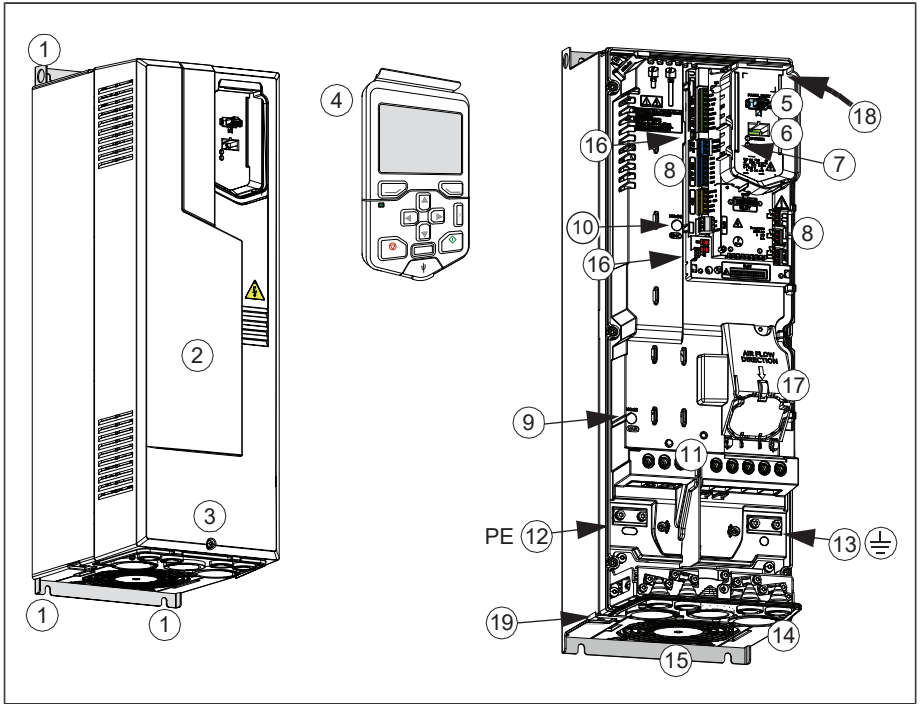
R4 IP21 / UL Type 1



1	Mounting points (4 pieces)
2	Cover
3	Cover screw
4	Control panel
5	Control panel connection
6	Cold configuration connection for CCA-01
7	Power OK and Fault LEDs. See section LEDs (page 227) .
8	I/O connections. See External control connection terminals, frames R1...R5 (page 43) .
9	Varistor grounding screw (VAR). For disconnecting, see page 120 (IEC) or page 170 (North America) .

10	Two EMC filter grounding screws (EMC (DC)). For disconnecting, see page 120 (IEC) or page 170 (North America) .
11	Input power connection (L1, L2, L3), motor connection (T1/U, T2/V, T3/W) and DC connection (UDC+, UDC-)
12	PE connection (power line)
13	Grounding connection (motor)
14	Cable entry
15	Main cooling fan
16	Cable tie mounts for I/O cables
17	Auxiliary cooling fan. For IP55/UL Type 12 drives only.
18	Auxiliary cooling fan connector
19	Additional grounding connection

R4 v2 IP21 / UL Type 1¹⁾

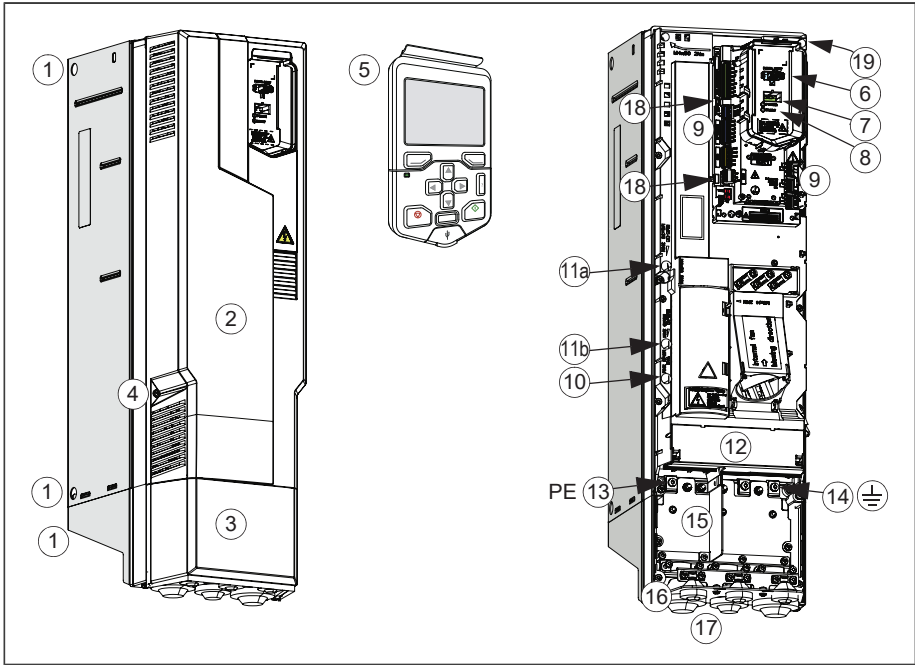


1	Mounting points (4 pieces)
2	Cover
3	Cover screw
4	Control panel
5	Control panel connection
6	Cold configuration connection for CCA-01
7	Power OK and Fault LEDs. See section LEDs (page 227) .
8	I/O connections. See External control connection terminals, frames R1...R5 (page 43) .
9	Varistor grounding screw (VAR). For disconnecting, see page 120 (IEC) or page 170 (North America) .

10	EMC filter grounding screw (EMC). For disconnecting, see page 120 (IEC) or page 170 (North America) .
11	Input power connection (L1, L2, L3), motor connection (T1/U, T2/V, T3/W) and DC connection (UDC+, UDC-)
12	PE connection (power line)
13	Grounding connection (motor)
14	Cable entry
15	Main cooling fan
16	Cable tie mounts for I/O cables
17	Auxiliary cooling fan. For IP55/UL Type 12 drives only.
18	Auxiliary cooling fan connector
19	Additional grounding connection

Frame R5

R5 IP21 / UL Type 1



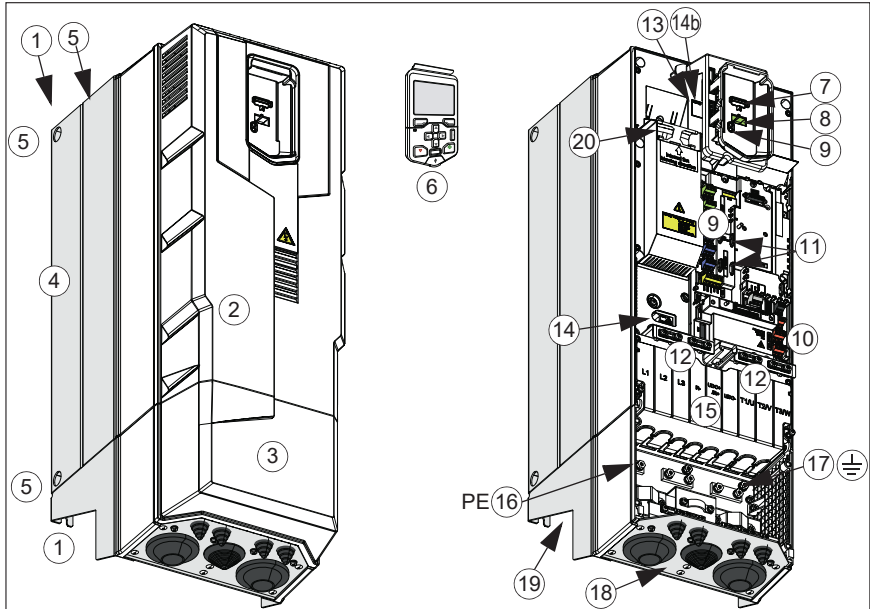
1	Mounting points (6 pieces: 2 at the top, 2 at the bottom of the main part of the frame, 2 at the top of the cable box)
2	Cover
3	Cable/conduit box
4	Cover screws (2 pieces)
5	Control panel
6	Control panel connection
7	Cold configuration connection for CCA-01
8	Power OK and Fault LEDs. See section LEDs (page 227) .
9	I/O connections. See External control connection terminals, frames R1...R5 (page 43) .
10	Varistor grounding screw (VAR). For disconnecting, see page 120 (IEC) or page 170 (North America) .

11	Two EMC filter grounding screws, 11a: EMC (DC) and 11b: EMC (AC). For disconnecting, see page 120 (IEC) or page 170 (North America) .
12	Input power connection (L1, L2, L3), motor connection (T1/U, T2/V, T3/W) and DC connection (UDC+, UDC-)
13	PE connection (power line)
14	Grounding connection (motor)
15	Cable box plate
16	Cable entry
17	Main cooling fan
18	Cable tie mounts for I/O cables
19	Auxiliary cooling fan connector

Frames R6...R9

R6 IP21 / UL Type 1

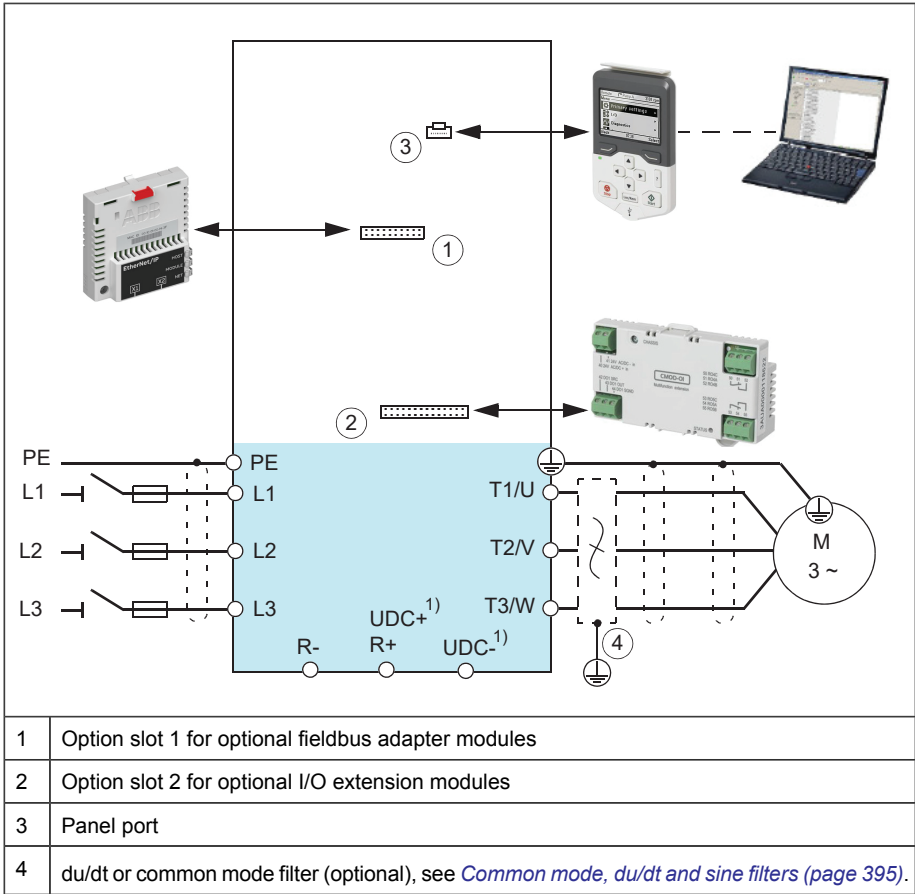
The layout of a frame R6 drive is presented below. The constructions of frames R6...R9 differ to some extent.



1	Mounting points (6 pieces: 2 at the top, 2 at the bottom of the main part of the frame, 2 at the top of the cable box)	13	Varistor grounding screw (VAR), under the control panel platform. For disconnecting, see page 120 (IEC) or page 170 (North America).
2	Cover	14	Two EMC filter grounding screws, 14a: EMC (DC) under the control panel platform and 14b: (EMC (AC) at the left, above the shroud. For disconnecting, see page 120 (IEC) or page 170 (North America).
3	Cable/conduit box	15	Shroud. Under the shroud: Input power connection (L1, L2, L3), motor connection (T1/U, T2/V, T3/W) and DC connection (UDC+, UDC-)
4	Heatsink	16	PE connection (power line)
5	Lifting holes (6 pieces)	17	Grounding connection (motor), under the shroud (15)
6	Control panel	18	Cable entry
7	Control panel connection	19	Main cooling fan
8	Cold configuration connection for CCA-01	20	Auxiliary cooling fan
9	Power OK and Fault LEDs. See section LEDs (page 227) .		
10	I/O connections. See External control connection terminals, frames R1...R5 (page 43) .		
11	Cable tie mounts for I/O cables		
12	Clamps for I/O cable mechanical support		

Overview of power and control connections

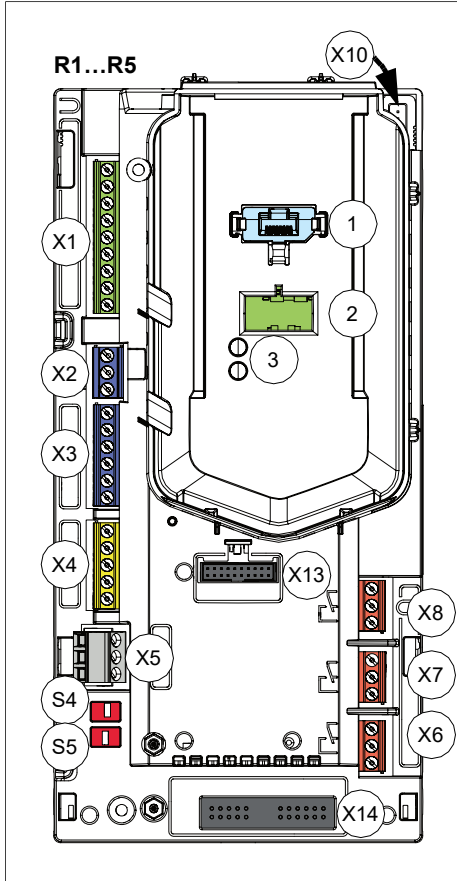
The logical diagram below shows the power connections and control interfaces of the drive.



¹⁾Not in all frame sizes

■ External control connection terminals, frames R1...R5

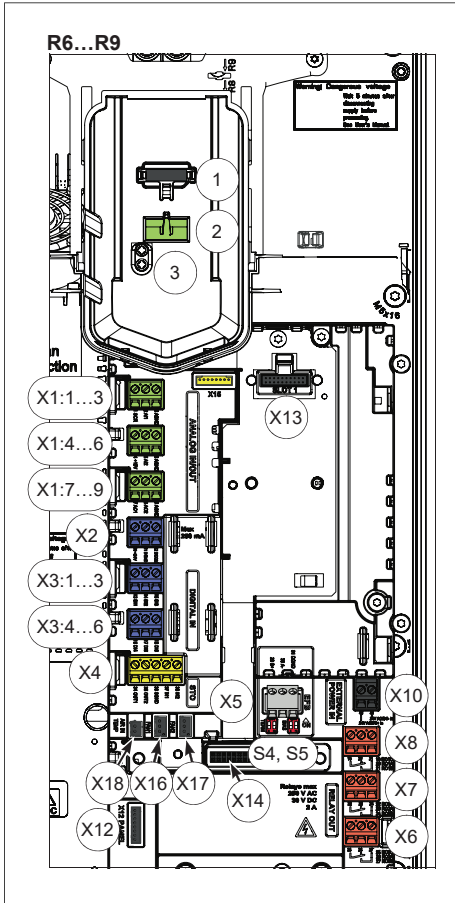
The layout of the external control connection terminals of the R1 frame is shown below. Layout of the external control connection terminals is identical in frames R1...R5 but the location of the control unit with the terminals is different in frames R3...R5.



	Description
X1	Analog inputs and outputs
X2	Aux. voltage output
X3	Programmable digital inputs
X4	Safe torque off connection
X5	Embedded fieldbus
X6	Relay output 3
X7	Relay output 2
X8	Relay output 1
X10	Auxiliary fan connection (IP55)
X13	Option slot 1 (fieldbus adapter modules)
X14	Option slot 2 (I/O extension modules)
S4,S5	Termination switch (S4), bias resistor switch (S5), see <i>Switches (page 144)</i> (IEC) or <i>Switches (page 191)</i> (North America)
1	Panel port (control panel connection)
2	Cold configuration connection. This connector is used with the CCA-01 configuration adapter.
3	Power OK and Fault LEDs. See section <i>LEDs (page 227)</i> .

■ External control connection terminals, frames R6...R9

The layout of the external control connection terminals of frames R6...R9 is shown below.



	Description
X1	Analog inputs and outputs
X2	Aux. voltage output
X3	Digital inputs
X4	Safe torque off connection
X5	Connection to embedded EIA-485 fieldbus adapter module
X6	Relay output 3
X7	Relay output 2
X8	Relay output 1
X10	External +24 V AC/DC input connection
X12	Panel connection
X13	Option slot 1 (fieldbus adapter modules)
X14	Option slot 2 (I/O extension modules)
X16	Auxiliary fan 1 connection
X17	Auxiliary fan 2 connection
X18	Air in temperature sensor connection
S4, S5	Termination switch (S4), bias resistor switch (S5), see Switches (page 144) (IEC) or Switches (page 191) (North America)
1	Panel port (control panel connection)
2	Cold configuration connection. This connector is used with the CCA-01 configuration adapter.
3	Power OK and Fault LEDs. See section LEDs (page 227) .

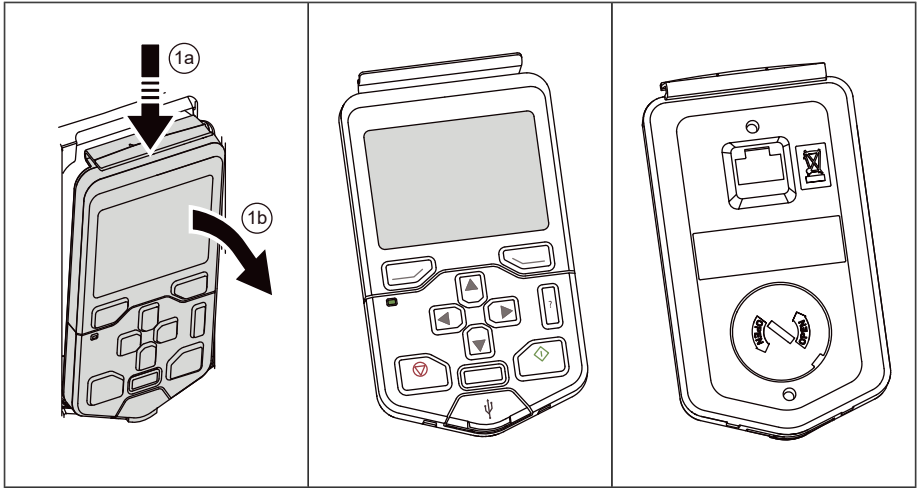


WARNING!

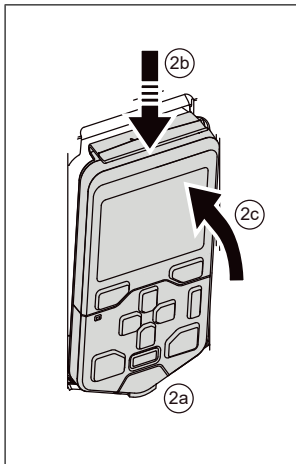
Do not connect the +24 V AC cable to the control unit ground when the control unit is powered from an external 24 V AC supply.

Control panel

To remove the control panel, press the retaining clip at the top (1a) and pull the panel forward from the top edge (1b).



To reinstall the control panel, put the bottom of the container in position (2a), press the retaining clip at the top (2b) and push the control panel in at the top edge (2c).



For the use of the control panel, see the firmware manual and *ACS-AP-I, -S, -W and ACH-AP-H, -W assistant control panel user's manual* ([3AUA0000085685](https://www.3com.com/3AUA0000085685) [English]).

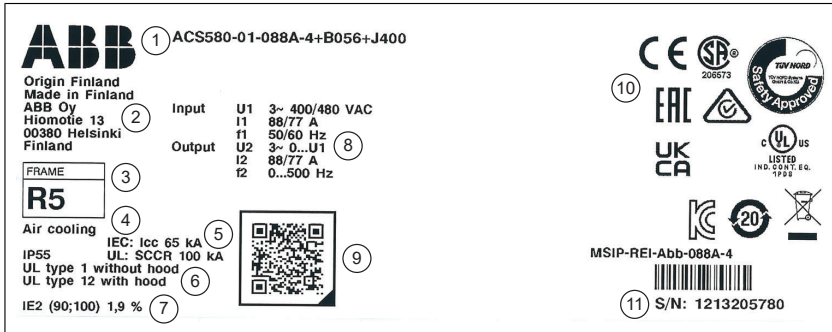
■ **Control panel door mounting kits**

You can use a mounting platform to mount the control panel on the cabinet door. Mounting platforms for control panels are available as options from ABB. For more information, see

Manual	Code (English)
DPMP-01 mounting platform for control panels installation guide	3AJUA0000100140
DPMP-02/03 mounting platform for control panels installation guide	3AJUA0000136205
DPMP-04 and DPMP-05 mounting platform for control panels installation guide	3AXD50000308484
DPMP-06 / 07 mounting platform for control panels installation guide	3AXD50000289561

Type designation label

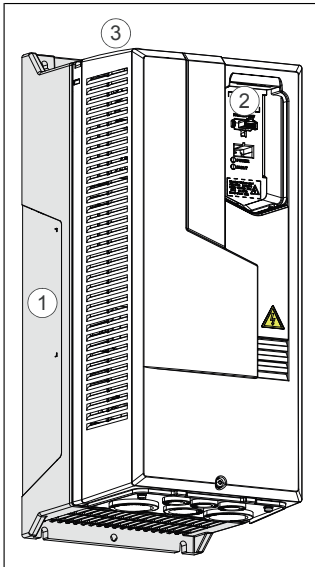
The type designation label includes IEC and UL (NEC) ratings, appropriate markings and the type designation and serial number, which allow identification of each drive. The type designation label is located on the left side of the drive, see section [Locations of the labels on the drive \(page 47\)](#). An example label is shown below.















No.	Description
1	Type designation, see section Type designation key (page 48) .
2	Name and address of the manufacturer
3	Frame (size) (New design of frame R4 types are marked as R4 v2)
4	Type of the drive, for example, with Air cooling or Liquid cooling, and so on.
5	IEC: Icc (Rated conditional short-circuit current) = 65 kA, UL (NEC): SCCR (Short circuit current rating) = 100 kA
6	Degree of protection
7	Typical drive losses when it operates at 90% of the motor nominal frequency and 100% of the drive nominal output current

No.	Description
8	Nominal ratings in the supply voltage range, see Ratings (page 231) , Electrical power network specification (page 286) and Motor connection data (page 288) .
9	Link to the product data sheet
10	Valid markings
11	<p>S/N: Serial number of format MYYWWXXXXX, where</p> <p>M: Manufacturing plant</p> <p>YY: 16, 17, 18, ... for 2016, 2017, 2018, ...</p> <p>WW: 01, 02, 03, ... for week 1, week 2, week 3, ...</p> <p>XXXXX: Digits making the serial number unique</p>

■ **Locations of the labels on the drive**



1	 <p>ACS580-01-088A-4+B056+J400</p> <p>Origin Finland Made in Finland ABB Oy Hiomotie 13 00380 Helsinki Finland</p> <div style="border: 1px solid black; padding: 2px; display: inline-block;"> FRAME R5 </div> <p>Air cooling</p> <p>IEC: Icc 65 kA UL: SCCR 100 kA</p> <p>IP55 UL type 1 without hood UL type 12 with hood</p> <p>IE2 (90/100) 1,9 %</p> 	<p>Input U1 3~ 400/480 VAC I1 88/77 A T1 50/60 Hz</p> <p>Output U2 3~ 0...U1 I2 88/77 A T2 0...500 Hz</p>	         <p>S/N: 1213205780</p>
2	<p>ACS580-01-088A-4 S/N: 1213205780 SW v2.14.0.3</p>		
3	<p>U1 3~ 400/480 VAC I2 88/77 A P 45 kW/60 hp</p>	<p>ACS580-01-088A-4</p>  <p>S/N: 1213205780</p>	
<p>Note: P_n is not shown in UL (NEC) drive labels</p>			

Type designation key

The type designation contains information on the specifications and configuration of the drive. You find the type designation on the type designation label attached to the drive. The first digits from the left express the basic configuration, for example, ACS580-01-12A7-4. The optional selections are given after that, separated by plus signs, for example, +L501. The main selections are described below. Not all selections are available for all types.

Code	Description
Basic codes	
ACS580-01	Product series
01	When no options are selected: Wall mounted, IP21 (UL Type 1), ACS-AP-S Assistant control panel, choke, EMC C2 filter (internal EMC filter), safe torque off, braking chopper in frames R1, R2, R3, coated boards, cable entry from the bottom, cable box or the conduit plate with cable entries, quick installation and start-up guide (multilingual kit).
Size	
xxxx	See the rating tables
Voltage rating	

Code	Description
4	2 = 208...240 V 4 = 380...480 V 6 = 525...600 V See the technical data for further information.

■ Option codes

Code	Description
B056	IP55 (UL Type 12)
C135	Flange mounting
C219	Chemical gases contamination class 3C3/C4 level resistance for ammonia, frames R1...R5.
H358	Cable conduit entry (US/UK).
J400	ACS-AP-S control panel (included as standard)
J404	ACS-BP-S basic control panel
J424	Blank control panel cover (no control panel)
J425	ACS-AP-I control panel
J429	ACS-AP-Wcontrol panel with Bluetooth interface
K451	FDNA-01 DeviceNet™ adapter module
K454	FPBA-01 PROFIBUS DP adapter module
K457	FCAN-01 CANopen adapter module
K458	FSCA-01 RS-485 (Modbus/RTU) adapter module
K462	FCNA-01 ControlNet™ adapter module
K469	FECA-01 EtherCat adapter module
K470	FEPL-02 EtherPOWERLINK adapter module
K475	FENA-21 Ethernet adapter module for EtherNet/IP™, Modbus TCP and PROFINET IO protocols, 2-port
K490	FEIP-21 EtherNet/IP adapter module
K491	FMBT-21 Modbus/TCP adapter module
K492	FPNO-21 PROFINET IO adapter module
L500	CBAI-01 bipolar analog IO adapter module
L501	CMOD-01 External 24 V AC/DC and digital I/O extension (2×RO and 1×DO)
L512	CHDI-01 115/230 V digital input module (six digital inputs and two relay outputs)

Code	Description
L523	CMOD-02 External 24 V and isolated PTC interface
L537	CPTC-02 ATEX-certified thermistor protection module
P931	Extended warranty 36 months from delivery
P932	Extended warranty 60 months from delivery
P944	Version for cabinet mounting (drive module with front covers but without cable box) for frames R5...R9.
Q971	ATEX-certified safe disconnection function
Q986	PROFIsafe safety functions module, FSPS-21

Manual kit ordering codes

Hardware and firmware manuals are not included as default. They can be ordered as a kit using the following ordering codes:

Language	Ordering code
EN	3AXD50000683666
DA	3AXD50000683703
DE	3AXD50000683673
ES	3AXD50000683949
FI	3AXD50000683925
FR	3AXD50000697625
IT	3AXD50000683680
NL	3AXD50000683697
PT	3AXD50000683956
RU	3AXD50000683970
SV	3AXD50000683918
TR	3AXD50000683987

4

Mechanical installation

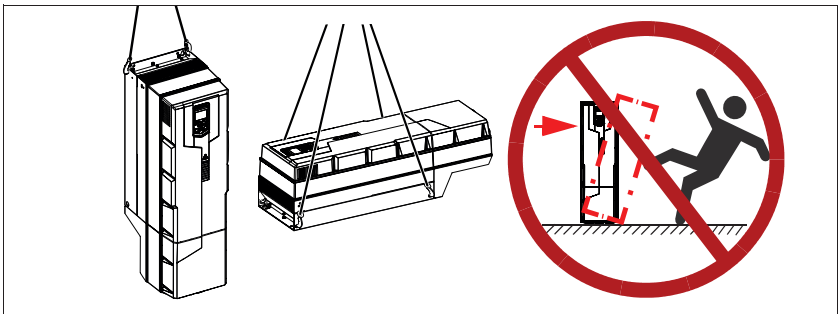
Contents of this chapter

This chapter tells how to examine the installation site, unpack and examine the delivery and install the drive mechanically.

Safety

**WARNING!**

Frames R5...R9: Lift the drive with a lifting device. Use the lifting eyes of the drive. Do not tilt the drive. **The drive is heavy and its center of gravity is high. An overturning drive can cause physical injury.**

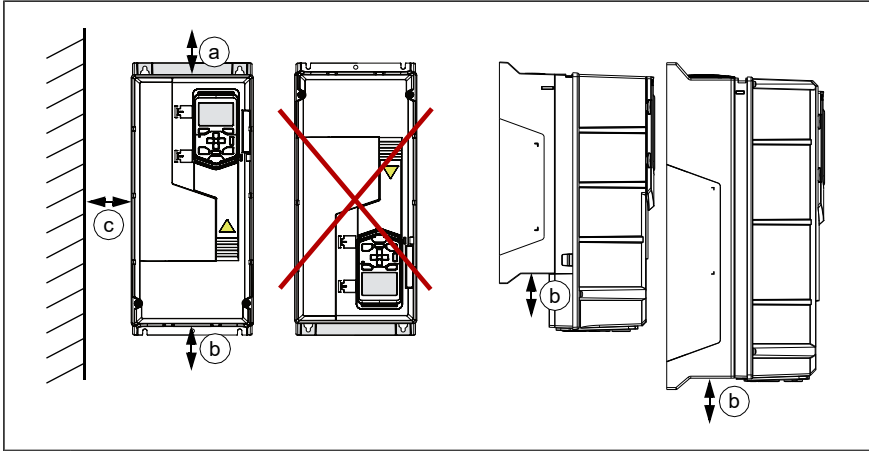


Examining the installation site

The drive must be installed on the wall or an enclosure. There are three alternative ways to install it:

- Vertical

Note: Do not install the drive upside down.



Frame size	Vertical installation - Free space											
	IP21 (UL Type 1)						IP55 (UL Type 12)					
	Above (a) ¹⁾		Below (b) ²⁾		Beside (c) ³⁾		Above (a) ¹⁾		Below (b) ²⁾		Beside (c) ³⁾	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
R1	150	5.91	86	3.39	150	5.91	137	5.39	116	4.57	150	5.91
R2	150	5.91	86	3.39	150	5.91	137	5.39	116	4.57	150	5.91
R3	200	7.87	53	2.09	150	5.91	200	7.87	53	2.09	150	5.91
R4	53	2.09	200	7.87	150	5.91	53	2.09	200	7.87	150	5.91
R5	100	3.94	200	7.87	150	5.91	100	3.94	200	7.87	150	5.91
R6	155	6.10	300	11.81	150	5.91	155	6.10	300	11.81	150	5.91
R7	155	6.10	300	11.81	150	5.91	155	6.10	300	11.81	150	5.91
R8	155	6.10	300	11.81	150	5.91	155	6.10	300	11.81	150	5.91
R9	200	7.87	300	11.81	150	5.91	200	7.87	300	11.81	150	5.91

¹⁾ Free space above is measured from the frame, not from the hood used in UL Type 12 frames.

Note: The height of the hood for frames R4 and R9 exceeds the requirement of free space above for these frames

Frame size	Hood height (mm)	Hood height (in)
R4	72	2.83
R9	230	9.06

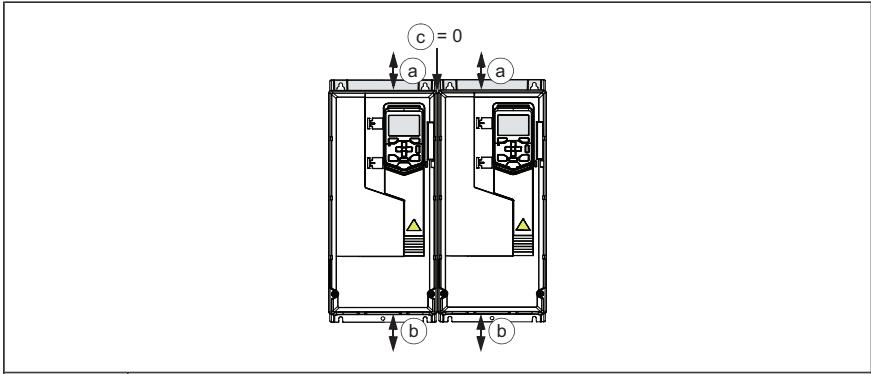
2) Free space below is always measured from the drive frame, not from the cable box.

3) Free space between the drive and other objects, e.g. wall.

Note: The recommended free space above and below the drive is for installations where the drive is mounted on a wall indoors. For ABB cabinet-built drives, which are thermally tested and approved for a specified temperature range, free space could vary from this recommendation.



- Vertical side by side or between walls



Frame size	Vertical installation side by side - Free space, IP21 (UL Type 1) and IP55 (UL Type 12)					
	Above (a) ¹⁾		Below (b) ²⁾		Between (c) ³⁾	
	mm	in	mm	in	mm	in
R1	200	7.87	200	7.87	0	0
R2	200	7.87	200	7.87	0	0
R3	200	7.87	200	7.87	0	0
R4	200	7.87	200	7.87	0	0
R5	200	7.87	200	7.87	0	0
R6	200	7.87	300	11.8	0	0
R7	200	7.87	300	11.8	0	0
R8	200	7.87	300	11.8	0	0
R9	200	7.87	300	11.8	0	0

1) Free space above is measured from the frame, not from the hood used in UL Type 12 frames.

Note: The height of the hood for frame R9 exceeds the requirement of free space above for these frames

Frame size	Hood height (mm)	Hood height (in)
R9	230	9.06

2) Free space below is always measured from the drive frame, not from the cable box.

3) Free space between the drives.

Note: The recommended free space above and below the drive is for installations where the drive is mounted on a wall indoors. For ABB cabinet-built drives, which are thermally tested and approved for a specified temperature range, free space could vary from this recommendation.

Note: IP21 (UL Type 1) frames R1...R2: The cover fastening clips can be removed to make the front cover opening easier.

Note: IP55 (UL Type 12) frames R1...R2: Auxiliary fan maintenance cannot be performed without removing every second drive from installation to get access to the fan.



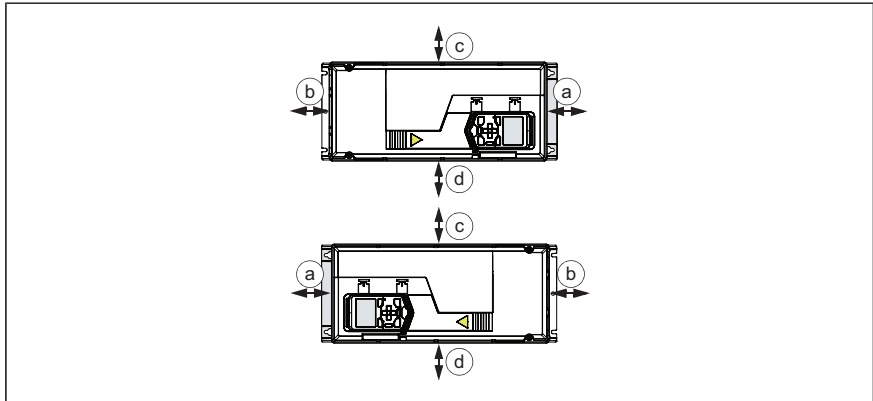
- Horizontal, IP20 and IP55, R1...R5 only

Note 1: You can install IP21/UL Type 1 drives horizontally but the installation meets IP20 requirements only.

Note 2: IP55/UL Type 12 drives mounted horizontally meets IP21/UL Type 1 ratings.

Note 3: In the horizontal mounting, the drive is not protected from dripping water.

Note 4: The vibration specification in *Ambient conditions (page 300)* may not be fulfilled.



Frame size	Horizontal installation - Free space							
	IP21 (IP20)				IP55 (UL Type 12)			
	Above (a)		Below (b) ¹⁾		Above (a)		Below (b) ¹⁾	
	mm	in	mm	in	mm	in	mm	in
R1	150	5.91	86	3.39	137	5.39	116	4.57
R2	150	5.91	86	3.39	137	5.39	116	4.57
R3	200	7.87	53	2.09	200	7.87	53	2.09
R4	30	1.18	200	7.87	30	1.18	200	7.87
R5	30	1.18	200	7.87	30	1.18	200	7.87
Frame size	Side up (c)		Side down (d)		Side up (c)		Side down (d)	
	mm	in	mm	in	mm	in	mm	in
R1	30	1.18	200	7.87	30	1.18	200	7.87
R2	30	1.18	200	7.87	30	1.18	200	7.87
R3	30	1.18	200	7.87	30	1.18	200	7.87
R4	30	1.18	200	7.87	30	1.18	200	7.87
R5	30	1.18	200	7.87	30	1.18	200	7.87

¹⁾ Free space below is always measured from the drive frame, not from the cable box.

Make sure that the installation site complies with the requirements below:

- The installation site is sufficiently ventilated or cooled to remove the heat away from the drive. See *Losses, cooling data and noise (page 273)*.
- The operation conditions of the drive meet the specifications given in *Ambient conditions (page 300)*.
- The wall is as close to vertical as possible, of non-flammable material and strong enough to carry the weight of the drive, see *Dimensions, weights and free space requirements (page 265)*.
- The floor/material below the installation is non-flammable.
- There is enough free space above and below the drive to enable cooling air flow, service and maintenance. See the required free space tables for each of the different mounting alignments on page 52 (or page 265).

Required tools

To install the drive mechanically, you need the following tools:

- drill with suitable bits
- screwdriver set (Torx, flat and/or Phillips, as appropriate)
- socket set (metric)
- tape measure, if you will not be using the provided mounting template.

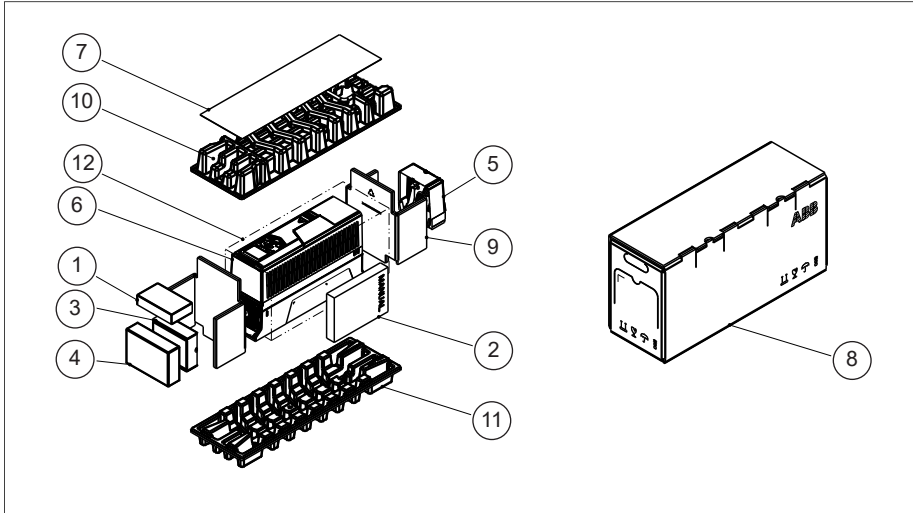
Moving the drive

Frames R5...R9: Move the transport package by pallet truck to the installation site.



Unpacking and examining delivery, frames R1 and R2

The figure below shows the layout of the transport package. Examine that all items are present and there are no signs of damage. Read the data on the type designation label of the drive to make sure that the drive is of the correct type. See section [Type designation label \(page 46\)](#).



1	Control panel selected in the order. North America: Control panel factory installed.
2	Manuals <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers
3	I/O option box
4	Fieldbus option box
<p>Note: Possible options in separate packages, if they have been ordered with a plus code, such as for example +K490 (FEIP-21 Two-port EtherNet/IP adapter module) in the fieldbus option box.</p> <p>North America: Options may be ordered as factory installed.</p>	

5	Cable box Note: The cable box is mounted to the IP55 drive module frame at the factory.
6	Drive
7	Mounting template
8	Cardboard box
9	End support (2 pcs)

1	Control panel selected in the order. North America: Control panel factory installed.
2	Manuals <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers
3	I/O option box
4	Fieldbus option box
<p>Note: Possible options in separate packages, if they have been ordered with a plus code, such as for example +K490 (FEIP-21 Two-port EtherNet/IP adapter module) in the fieldbus option box.</p> <p>North America: Options may be ordered as factory installed.</p>	

5	Cable box Note: The cable box is mounted to the IP55 drive module frame at the factory.
6	Drive
7	Mounting template
8	Cardboard box
9	End support (2 pcs)
10	Top cushion
11	Bottom cushion

1	Control panel selected in the order. North America: Control panel factory installed.
2	Manuals <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers
3	I/O option box
4	Fieldbus option box
<p>Note: Possible options in separate packages, if they have been ordered with a plus code, such as for example +K490 (FEIP-21 Two-port EtherNet/IP adapter module) in the fieldbus option box.</p> <p>North America: Options may be ordered as factory installed.</p>	

5	Cable box Note: The cable box is mounted to the IP55 drive module frame at the factory.
6	Drive
7	Mounting template
8	Cardboard box
9	End support (2 pcs)
10	Top cushion
11	Bottom cushion
12	Plastic bag
<p>Note: Hood included with option +B056 (IP55/UL Type 12) in North America</p> <p>Note: Hardware and firmware manuals can be ordered as a separate kit, see Manual kit ordering codes (page 50)</p>	



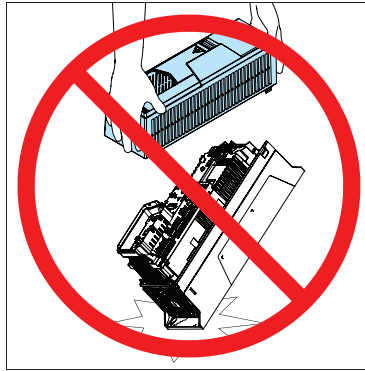
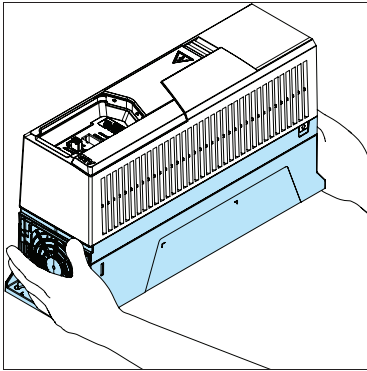
To unpack:

- Open the cardboard box (8)
- Remove the mounting template (7) and top cushion (10)

60 Mechanical installation

- Remove the control panel, option boxes and cable box (1,3,4,5)
- Remove the end supports (9)
- Remove the plastic bag (12)
- Lift the drive (6).

WARNING! R1...R2, IP21: Do not lift the drive by holding it from the cover. The drive can fall and become damaged or damage the surroundings.

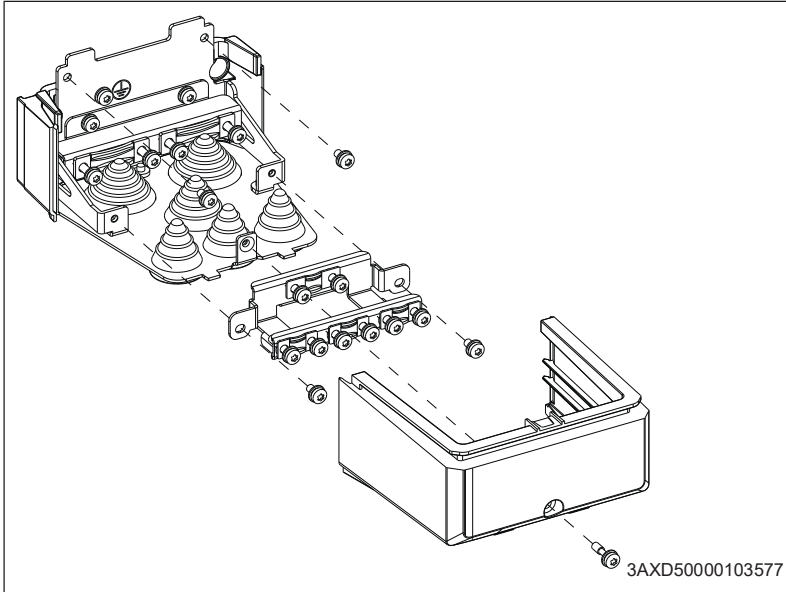


Recycle the package material according to local regulations.

■ Frames R1 and R2 cable box (IP21, UL Type 1)

This illustration shows the contents of the cable box package. The package also includes an assembly drawing which shows how to install the cable box to the drive module frame.

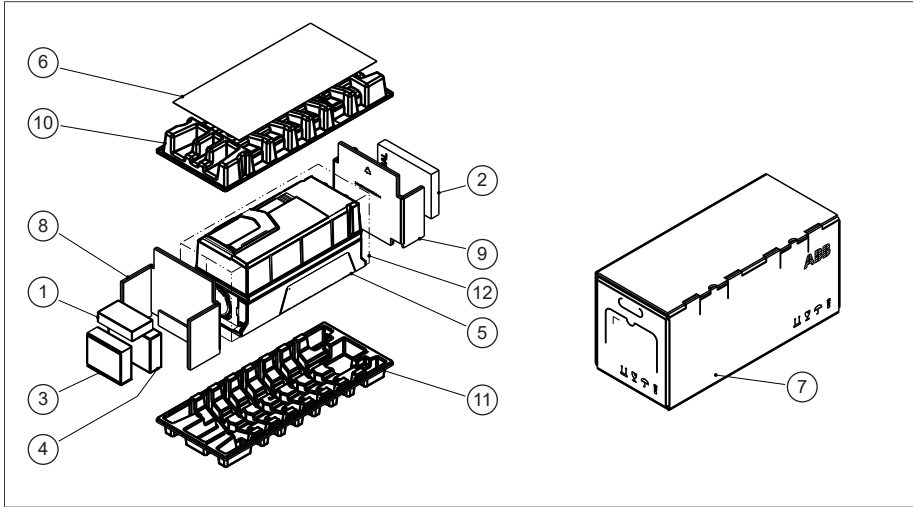
Follow the installation instructions in section *Installing the drive vertically, frames R1...R4* (page 74).



Note: Cable box is shipped with grommet cones pointing in. They must be removed and inserted back pointing out.

Unpacking and examining delivery, frame R3

The figure below shows the layout of the transport package. Examine that all items are present and there are no signs of damage. Read the data on the type designation label of the drive to make sure that the drive is of the correct type. See section [Type designation label \(page 46\)](#).



1	Control panel selected in the order. North America: Control panel factory installed.
2	Manuals <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers
3	I/O option box
4	Fieldbus option box
5	Drive
6	Mounting template

7	Cardboard box
8	End support
9	End support
10	Top cushion
11	Bottom cushion
12	Plastic bag
<p>Note: Hood included with option +B056 (IP55/UL Type 12) in North America</p> <p>Note: Hardware and firmware manuals can be ordered as a separate kit, see Manual kit ordering codes (page 50)</p>	

To unpack:

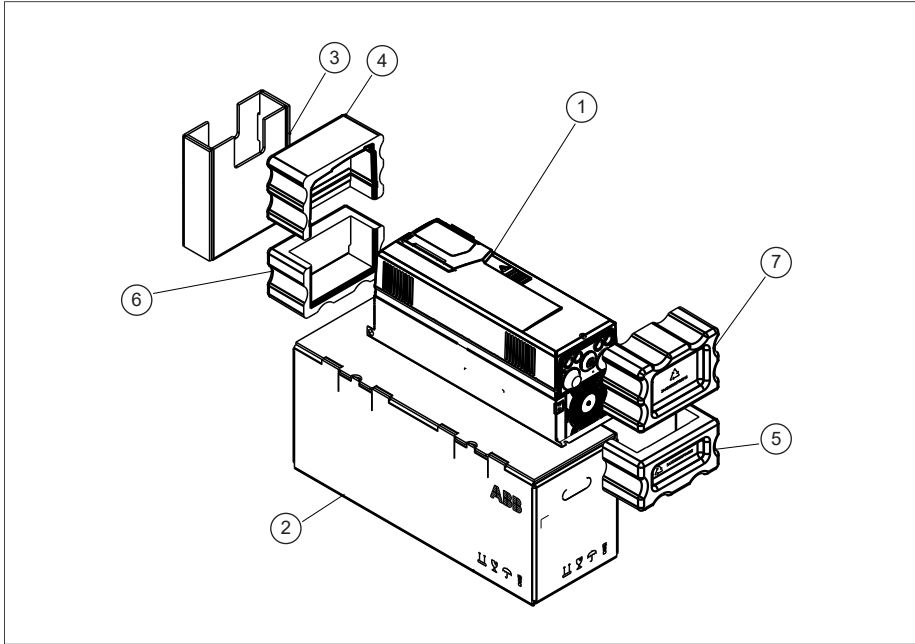
- Open the cardboard box (7)
- Remove the mounting template (6) and top cushion (10)
- Remove the control panel and option boxes (1,3,4)
- Remove the end supports (9)
- Remove the plastic bag (12)
- Lift the drive (5).

Recycle the package material according to local regulations.



Unpacking and examining delivery, frames R4

The figure below shows the layout of the transport package. Examine that all items are present and there are no signs of damage. Read the data on the type designation label of the drive to make sure that the drive is of the correct type. See section [Type designation label](#) (page 46).



1	Drive	4	Top cushion
2	Cardboard box. Mounting template in the cardboard box.	5	Bottom cushion
3	Option support: <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers • Control panel selected in the order (in a separate package) in the option box • North America: Control panel factory installed • Possible options in separate packages, if they have been ordered with a plus code, such as for example +K490 (FEIP-21 Two-port EtherNet/IP adapter module) in the option box • North America: Options may be ordered as factory installed. 	6	Bottom cushion
		7	Top cushion
		<p>Note: Hood included with option +B056 (IP55/UL Type 12) in North America</p> <p>Note: Hardware and firmware manuals can be ordered as a separate kit, see Manual kit ordering codes (page 50)</p>	

To unpack:

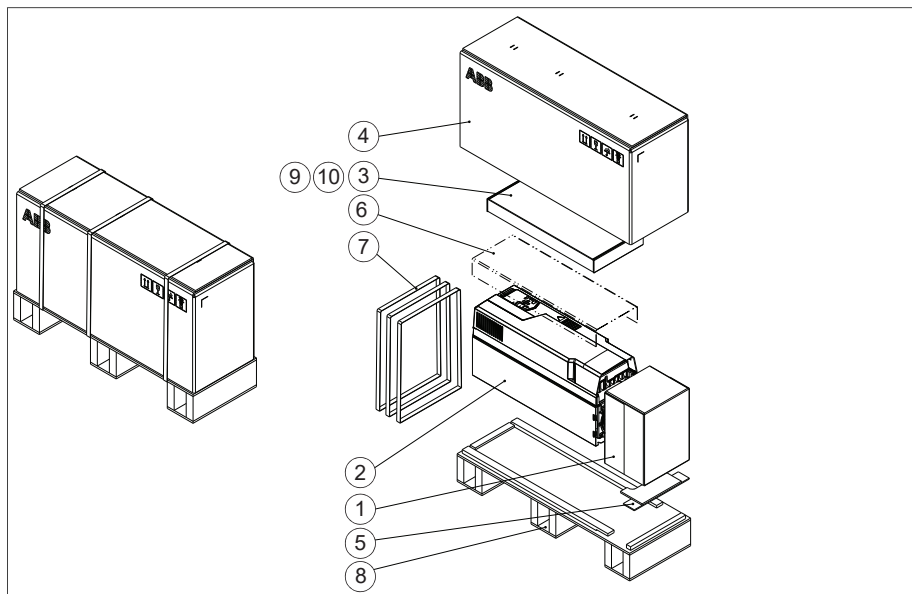
- Open box (2)
- Remove option support (3)
- Remove top cushions (4,7)
- Lift the drive (1) and remove bottom cushions (5,6).

Recycle the package material according to local regulations.



Unpacking and examining delivery, frame R5

The figure below shows the layout of the transport package. Examine that all items are present and there are no signs of damage. Read the data on the type designation label of the drive to make sure that the drive is of the correct type. See section [Type designation label](#) (page 46).



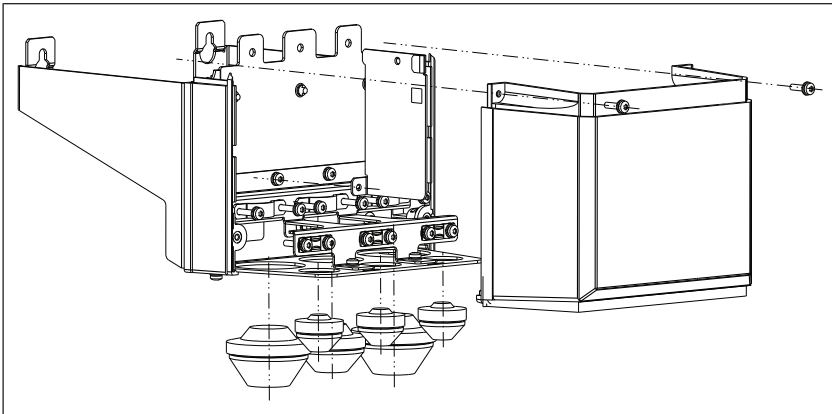
1	Cable box package. Note: The cable box is mounted to the IP55 drive module frame at the factory.	6	Cover protecting film
2	Drive	7	Straps
3	In the option box <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers 	8	Pallet
4	Cardboard box. Mounting template in the cardboard box.	9	Control panel selected in the order (in a separate package) in the option box North America: Control panel factory installed
5	Stopper	10	Possible options in separate packages, if they have been ordered with a plus code, such as for example +K490 (FEIP-21 Two-port EtherNet/IP adapter module) in the option box. North America: Options may be ordered as factory installed.
6	Cover protecting film	Note: Hood included with option +B056 (IP55/UL Type 12) in North America Note: Hardware and firmware manuals can be ordered as a separate kit, see Manual kit ordering codes (page 50)	

To unpack:

- Cut the straps (7).
- Remove the cardboard box (4) and option box (3).
- Remove the cover protecting film (6).
- Lift the drive (2).

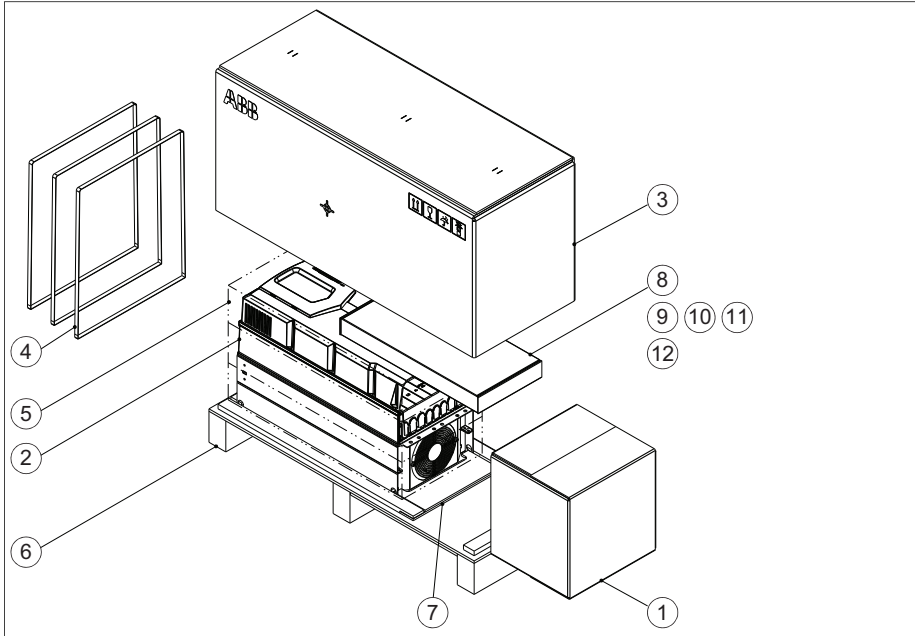
■ **Frame R5 cable box (IP21, UL Type 1)**

This illustration shows the contents of the cable box package. The package also includes an assembly drawing which shows how to install the cable box to the drive module frame.



Unpacking and examining delivery, frames R6...R9

The figure below shows the layout of the transport package. Examine that all items are present and there are no signs of damage. Read the data on the type designation label of the drive to make sure that the drive is of the correct type. See section [Type designation label](#) (page 46).



1	Cable box. Power and control cable grounding shelves in a plastic bag, assembly drawing. Note: The cable box is mounted to the IP55 drive module frame at the factory.	<ul style="list-style-type: none"> • North America: Quick installation and start-up guide • Multilingual residual voltage warning stickers 	
2	Drive with factory installed options	10	Control panel selected in the order (in a separate package) in the option tray North America: Control panel factory installed
3	Cardboard box		
4	Straps	11	Possible options in separate packages, if they have been ordered with a plus code, such as for example +K490 (FEIP-21 Two-port EtherNet/IP adapter module) in the option box. North America: Options may be ordered as factory installed
5	VCI bag for protecting against corrosion		
6	Pallet		
7	Stopper		
8	Option tray		
9	In the option tray <ul style="list-style-type: none"> • Europe: Quick installation and start-up guide kit (6 languages) 		
		12	Mounting template on top of the option tray
		Note: Hood included with option +B056 (IP55/UL Type 12) in North America Note: Hardware and firmware manuals can be ordered as a separate kit, see Manual kit ordering codes (page 50)	

To unpack:

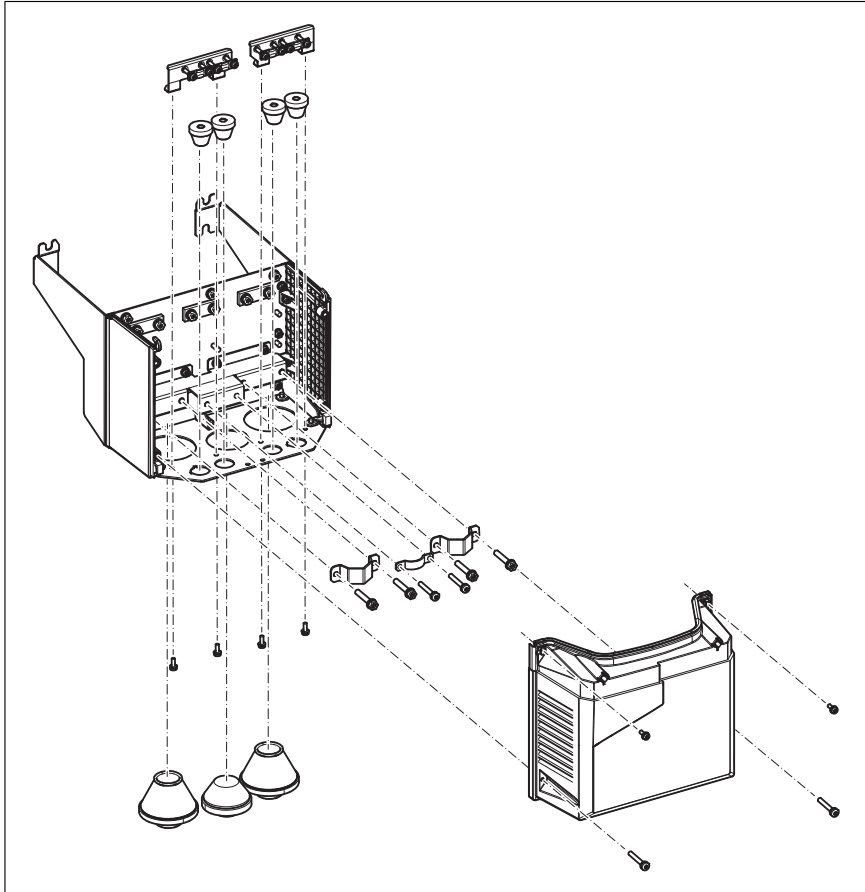
- Cut the straps (4).
- Remove the cardboard box (3) and option tray (8).
- Remove the VCI bag (5).
- Attach lifting hooks to the lifting eyes of the drive (see the figure in section [Safety \(page 51\)](#)).
- Lift the drive with a hoist.

Recycle the package material according to local regulations.



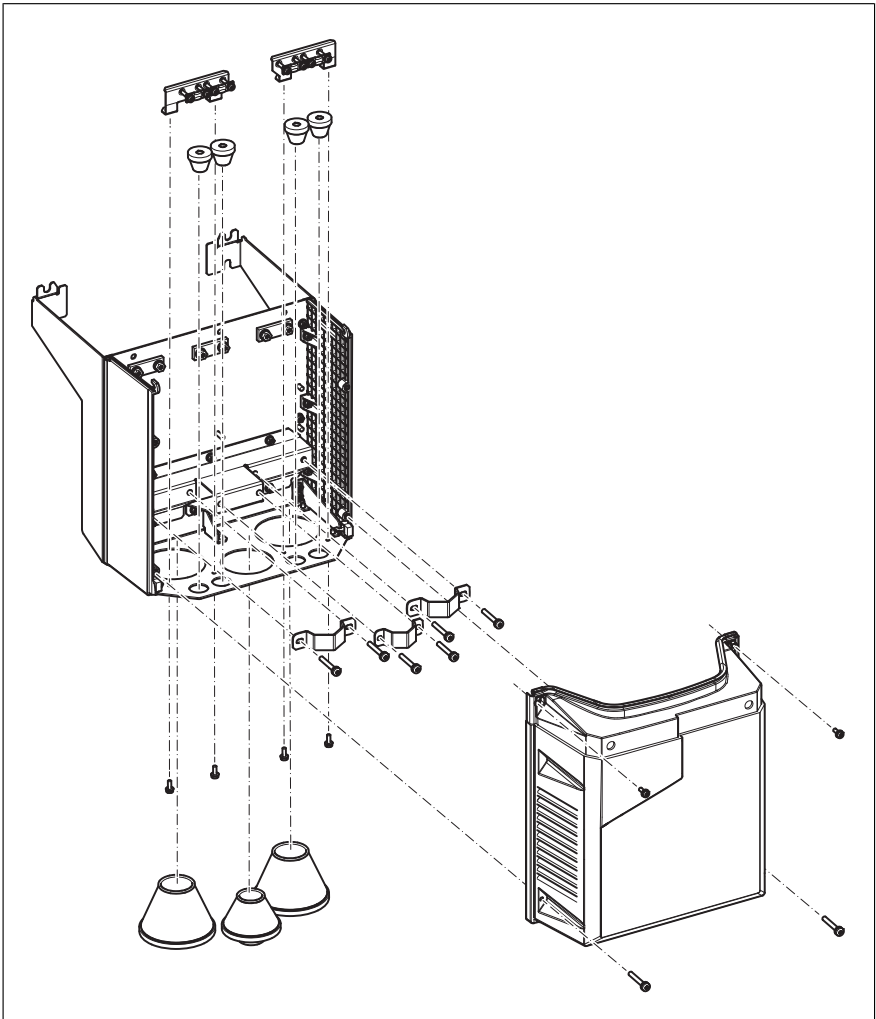
■ **Frame R6 cable box (IP21, UL Type 1)**

The figure below shows the contents of the cable box package. The package also includes an assembly drawing which shows how to install the cable box to the drive frame.



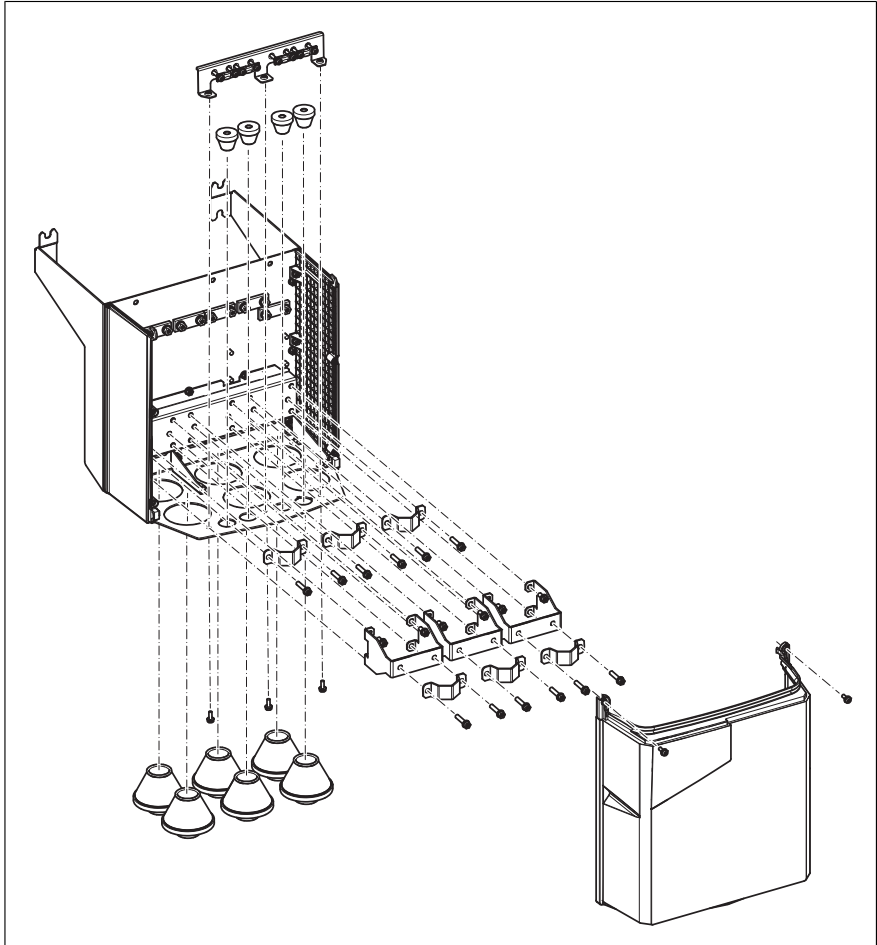
■ **Frame R7 cable box (IP21, UL Type 1)**

The figure below shows the contents of the cable box package. The package also includes an assembly drawing which shows how to install cable box to the drive frame.



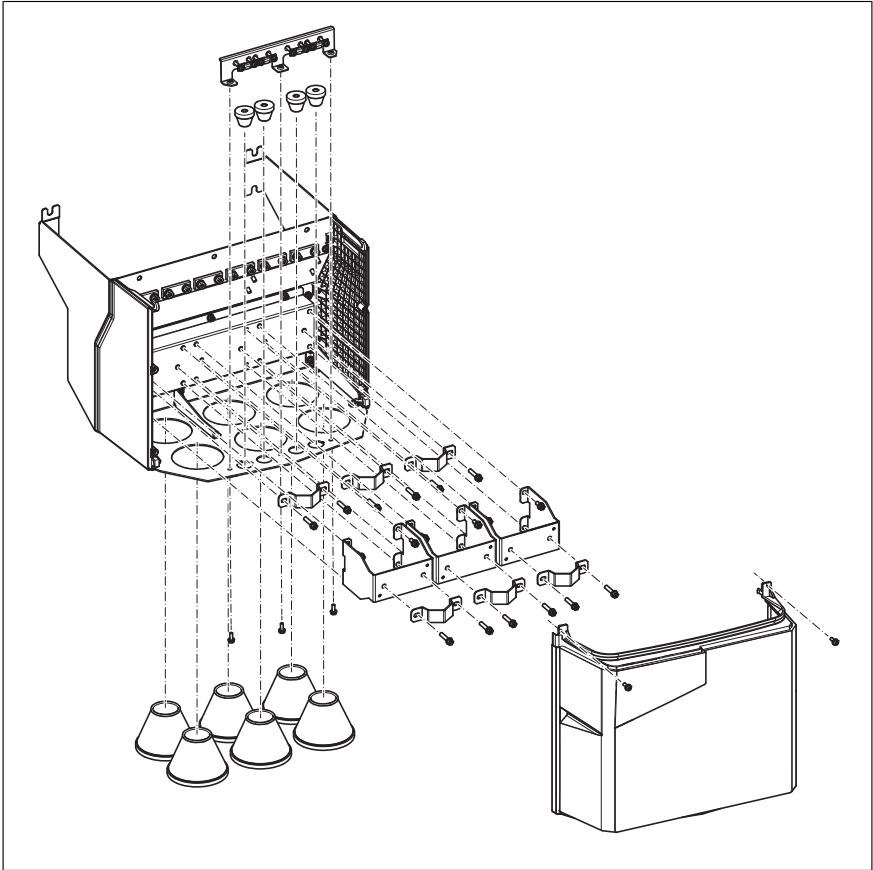
■ **Frame R8 cable box (IP21, UL Type 1)**

The figure below shows the contents of the cable box package. The package also includes an assembly drawing which shows how to install the cable box to the drive frame.



■ **Frame R9 cable box (IP21, UL Type 1)**

The figure below shows the contents of the cable box package. The package also includes an assembly drawing which shows how to install the cable box to the drive frame.



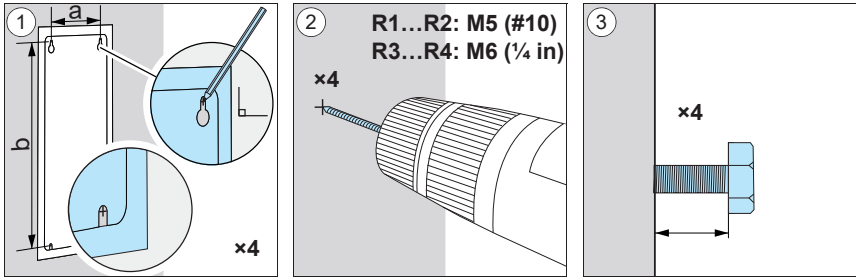
Installing the drive

■ Installing the drive vertically, frames R1...R4

The figures show frame R3 as an example.

Select fasteners and their application to meet local requirements appropriate to wall surface materials, drive weight and application.

1. Mark the hole locations using the mounting template included in the package. Do not leave the mounting template under the drive. The drive dimensions and hole locations are also shown in the drawings in chapter *Dimension drawings (page 309)*.
2. Drill the mounting holes.
3. Insert anchors or plugs into the holes and start the bolts into the anchors or plugs.



	R1		R2		R3		R4		R4 v2	
	mm	in	mm	in	mm	in	mm	in	mm	in
a	98	3.86	98	3.86	160	6.30	160	6.30	160	6.30
b	317	12.48	417	16.42	473	18.62	619	24.37	619	24.37
Weight IP21 (UL Type 1)	kg	lb	kg	lb	kg	lb	kg	lb	kg	lb
	4.6	10.1	6.6	14.6	11.8	26.0	19.0	41.9	22.0	48.5
Weight IP55 (UL Type 12)	kg	lb	kg	lb	kg	lb	kg	lb	kg	lb
	4.8	10.6	6.8	15.0	13.0	28.7	20.0	44.1	23.0	50.7

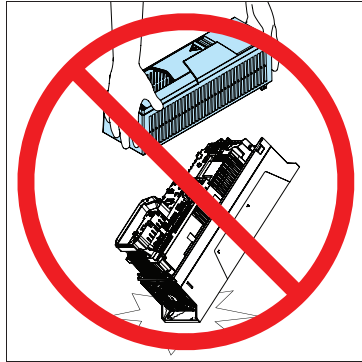
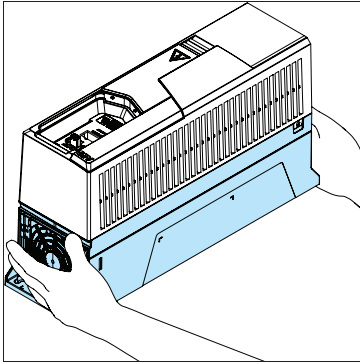


4. Position the drive onto the lower bolts (4a) on the wall to support the weight of the drive. Rotate drive to the wall and place drive over the upper bolts (4b).

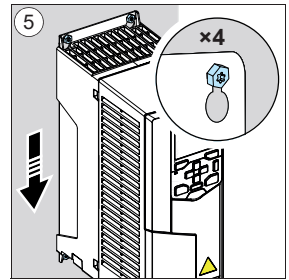
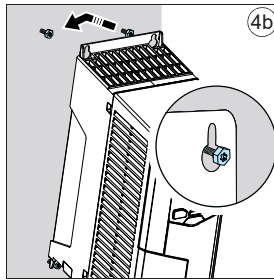
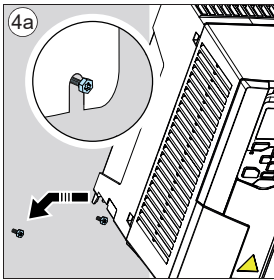


WARNING!

R1...R2, IP21: Do not lift the drive by holding it from the cover. The drive can fall and become damaged or damage the surroundings.



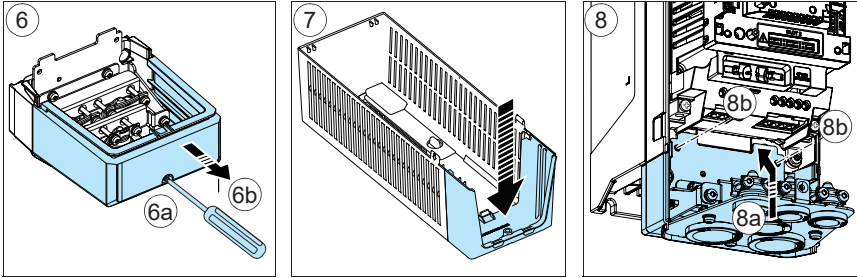
5. Tighten the bolts in the wall securely.



Installing the cable box, frames R1...R2

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6. Remove the screw (6a) and lift the cover off (6b) from the separate cable box.
7. Attach the cable box cover to the front cover.
8. Install the cable box to the frame. Position the cable box (8a) and tighten the screws (8b).



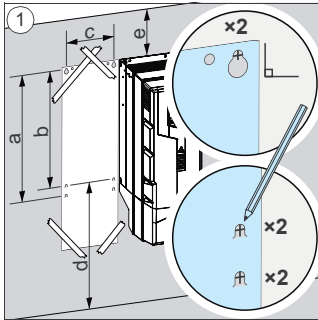
Note: Install the hood to UL Type 12 drives after you have installed the drive electrically and reinstalled covers, see [Installing UL Type 12 hood \(page 207\)](#).



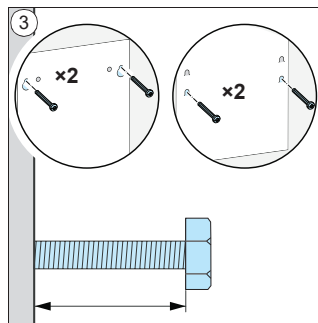
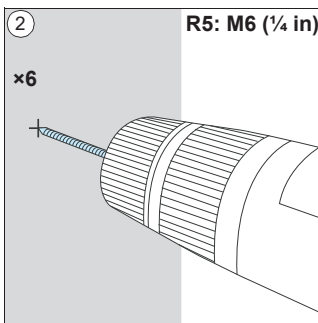
■ Installing the drive vertically, frame R5

Select fasteners and their application to meet local requirements appropriate to wall surface materials, drive weight and application.

1. Mark the hole locations using the mounting template included in the package. Do not leave the mounting template under the drive. The drive dimensions and hole locations are also shown in the drawings in chapter *Dimension drawings (page 309)*.
2. Drill the mounting holes.
3. Insert fixing anchors or plugs into the holes. Start the two upper bolts and the two lowest bolts into the anchors or plugs.

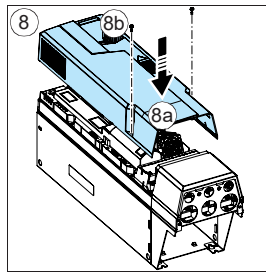
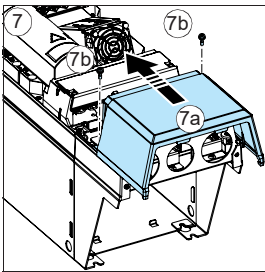
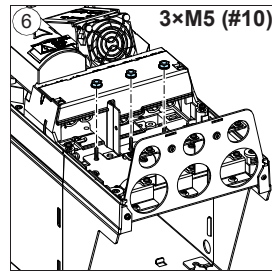
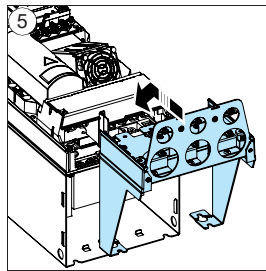
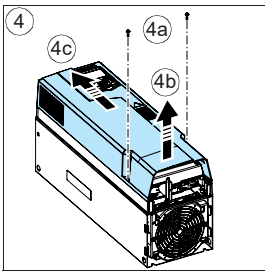


	R5 IP21 (UL Type 1)		R5 IP55 (UL Type 12)	
	mm	in	mm	in
a	612	24.09	612	24.09
b	581	22.87	581	22.87
c	160	6.30	160	6.30
d >	200	7.87	200	7.87
e >	100	3.94	100	3.94
	kg	lb	kg	lb
	28.3	62.4	29.0	64.0



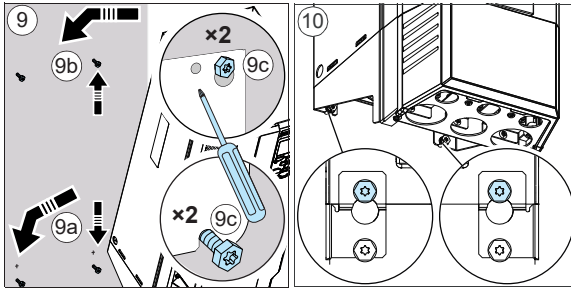
IP21 (UL Type 1)

4. Remove the front cover: Remove the fastening screws (4a) with a T20 Torx screwdriver and lift the cover from the bottom upwards (4b) and then to the top side (4c).
5. Attach the cable box to the drive frame.
6. Tighten the box nuts.
7. Slide the box cover from the bottom (7a) and tighten the retaining screws (7b).
8. Put the tabs at the top of the front cover in their counterparts on the housing and then press at the bottom (8a) and tighten the retaining screws (8b).



IP21 (UL Type 1), IP55 (UL Type 12)

9. Position the drive onto the lower bolts (9a) on the wall to support the weight of the drive. Rotate drive to the wall and place drive over the upper bolts (9b). Lift the drive with another person or with a lifting device as it is heavy. Tighten the bolts in the wall securely (9c).
10. Tighten the two remaining bolts securely.



Note: Install the hood to UL Type 12 drives after you have installed the drive electrically and reinstalled covers, see [Installing UL Type 12 hood \(page 207\)](#).

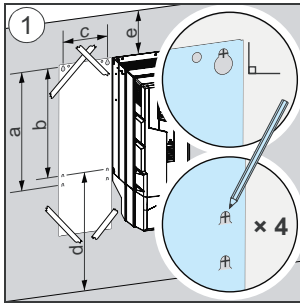


■ **Installing the drive vertically, frames R6...R9**

Select fasteners and their application to meet local requirements appropriate to wall surface materials, drive weight and application.

1. Mark the hole locations for the six mounting holes using the mounting template included in the package. Do not leave the mounting template under the drive.
The drive dimensions and hole locations are also shown in the drawings in chapter *Dimension drawings (page 309)*.

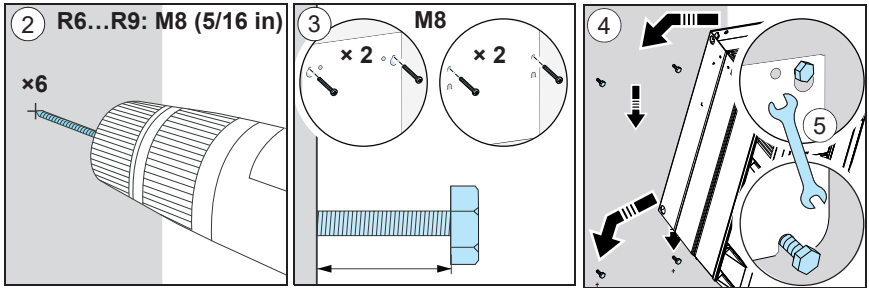
Note: You can use only two bolts instead of four to attach the lower part of the drive.



	R6		R7		R8		R9	
	mm	in	mm	in	mm	in	mm	in
a	571	22.5	623	24.5	701	27.6	718	28.3
b	531	20.9	583	23.0	658	25.9	658	25.9
c	213	8.4	245	9.7	263	10.3	345	13.6
d	300	11.8	300	11.8	300	11.8	300	11.8
e	155	6.1	155	6.1	155	6.19	200	7.9
IP21, UL Type 1	kg	lb	kg	lb	kg	lb	kg	lb
	42.4	93.5	54	119.1	69	152.2	97	213.9
IP55, UL Type 12	kg	lb	kg	lb	kg	lb	kg	lb
	43	94.8	56	123.5	77	169.8	103	227.1

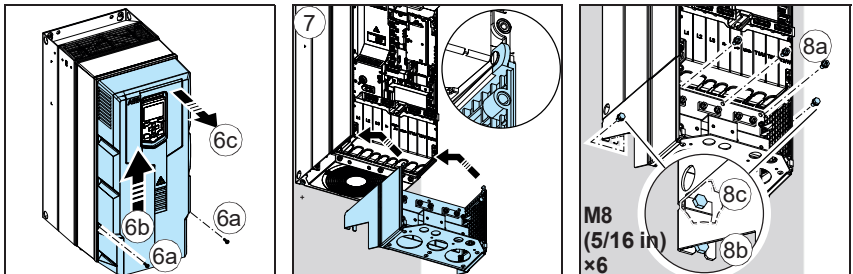
2. Drill the mounting holes.
3. Insert fixing anchors or plugs into the holes and start the bolts into the anchors or plugs.
4. Position the drive onto the bolts on the wall. Lift the drive with a lifting device as it is heavy.
5. Tighten the top two bolts in the wall securely.





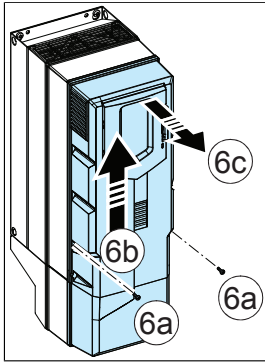
IP21 (UL Type 1)

6. Remove the front cover: Remove the fastening screws (a) with a T20 Torx screwdriver, move the cover to the top side (b) and then up (c).
7. Attach the cable box to the drive frame.
8. Tighten the box bolts: three at the top (8a) and two at the bottom (8b). Also tighten the bottom bolts started in step 3 (8c).



IP55 (UL Type 12)

9. Remove the front cover: Remove the fastening screws (a) with a T20 Torx screwdriver, move the cover to the top side (b) and then up (c).



Note: Install the hood to UL Type 12 drives after you have installed the drive electrically and reinstalled covers, see [Installing UL Type 12 hood \(page 207\)](#).

■ Installing the drive vertically side by side

Install the drive following the steps in the appropriate section [Installing the drive vertically, frames R1...R4 \(page 74\)](#), [Installing the drive vertically, frame R5 \(page 77\)](#) or [Installing the drive vertically, frames R6...R9 \(page 80\)](#).

■ Installing the drive horizontally, frames R1...R5

Install the drive following the steps in the appropriate section [Installing the drive vertically, frames R1...R4 \(page 74\)](#) or [Installing the drive vertically, frame R5 \(page 77\)](#). The drive can be installed either the left or right side up.



Flange mounting

Instructions for flange mounting are delivered with the flange mounting kit:

Flange mounting kit quick installation guide for ACX580-01 frames R1 to R3 (3AXD50000119172 [English])

Flange mounting kit quick installation guide for ACX580-01 frames R4 to R5 (3AXD50000287093 [English])

Flange mounting kit quick installation guide for ACS880-01 and ACX580-01 frames R6 to R9 (3AXD50000019099 [English])

For more information on flange mounting, see [Flange mounting kit installation supplement \(3AXD50000019100 \[English\]\)](#).

Strut channel installation (US only)

Contents of the mounting kit:

- Upper mounting clip labeled “Top”
- Lower mounting clip labeled “Bottom”

■ **Installation instructions**

Install clips when mounting frame sizes R1...R3 to strut channel.

1. Slide clips onto respective upper and lower mounting flanges of the drive.
2. Push until they click into place.



5

Guidelines for planning the electrical installation

Contents of this chapter

This chapter contains guidelines for planning the electrical installation of the drive.

Limitation of liability

The installation must always be designed and made according to applicable local laws and regulations. ABB does not assume any liability whatsoever for any installation which breaches the local laws and/or other regulations. Furthermore, if the recommendations given by ABB are not followed, the drive may experience problems that the warranty does not cover.

Selecting the main supply disconnecting device

You must equip the drive with a main supply disconnecting device which meets the local safety regulations. You must be able to lock the disconnecting device to the open position for installation and maintenance work.

■ European Union and United Kingdom

To meet the European Union Directives and United Kingdom Regulations, according to standard EN 60204-1, *Safety of Machinery*, the disconnecting device must be one of the following types:

- switch-disconnector of utilization category AC-23B (IEC 60947-3)
- disconnector that has an auxiliary contact that in all cases causes switching devices to break the load circuit before the opening of the main contacts of the disconnector (EN 60947-3)
- circuit-breaker suitable for isolation in accordance with IEC 60947-2.

■ North America

Installations must be compliant with NFPA 70 (NEC)¹⁾ and/or Canadian Electrical Code (CE) along with state and local codes for your location and application.

¹⁾ National Fire Protection Association 70 (National Electric Code).

■ Other regions

The disconnecting device must conform to the applicable local safety regulations.

Examining the compatibility of the motor and drive

Use asynchronous AC induction motors, permanent magnet synchronous motors or ABB synchronous reluctance motors (SynRM motors) with the drive.

Select the motor size and drive type from the rating table on basis of the AC line voltage and motor load. You can find the rating table in the appropriate hardware manual. You can also use the DriveSize PC tool.

Make sure that the motor can be used with an AC drive. See [Requirements table \(page 87\)](#). For basics of protecting the motor insulation and bearings in drive systems, see [Protecting the motor insulation and bearings \(page 86\)](#).

Note:

- Consult the motor manufacturer before using a motor with nominal voltage that differs from the AC line voltage connected to the drive input.
- The voltage peaks at the motor terminals are relative to the supply voltage of the drive, not to the drive output voltage.

■ Protecting the motor insulation and bearings

The drive employs modern IGBT inverter technology. Regardless of frequency, the drive output comprises pulses of approximately the drive DC bus voltage with a very short rise time. The pulse voltage can almost double at the motor terminals, depending on

the attenuation and reflection properties of the motor cable and the terminals. This can cause additional stress on the motor and motor cable insulation.

Modern variable speed drives with their fast rising voltage pulses and high switching frequencies can generate current pulses that flow through the motor bearings. This can gradually erode the bearing races and rolling elements.

du/dt filters protect motor insulation system and reduce bearing currents. Common mode filters mainly reduce bearing currents. Insulated N-end (non-drive end) bearings protect the motor bearings.

■ **Requirements table**

These tables show how to select the motor insulation system and when a drive du/dt and common mode filters and insulated N-end (non-drive end) motor bearings are required. Ignoring the requirements or improper installation may shorten motor life or damage the motor bearings and voids the warranty.

This table shows the requirements when an ABB motor is in use.

Motor type	Nominal AC line voltage	Requirement for			
		Motor insulation system	ABB du/dt and common mode filters, insulated N-end motor bearings		
			$P_n < 100 \text{ kW}$ and frame size < IEC 315	$100 \text{ kW} \leq P_n < 350 \text{ kW}$ or IEC 315 \leq frame size < IEC 400	$P_n \geq 350 \text{ kW}$ or frame size \geq IEC 400
$P_n < 134 \text{ hp}$ and frame size < NEMA 500	$134 \text{ hp} \leq P_n < 469 \text{ hp}$ or NEMA 500 \leq frame size \leq NEMA 580	$P_n \geq 469 \text{ hp}$ or frame size > NEMA 580			
Random-wound M2_, M3_ and M4_	$U_n \leq 500 \text{ V}$	Standard	-	+ N	+ N + CMF
	$500 \text{ V} < U_n \leq 600 \text{ V}$	Standard	+ du/dt	+ N + du/dt	+ N + du/dt + CMF
		or	Reinforced	-	+ N
	$600 \text{ V} < U_n \leq 690 \text{ V}$ (cable length $\leq 150 \text{ m}$)	Reinforced	+ du/dt	+ N + du/dt	+ N + du/dt + CMF
	$600 \text{ V} < U_n \leq 690 \text{ V}$ (cable length > 150 m)	Reinforced	-	+ N	+ N + CMF
Form-wound HX_ and AM_	$380 \text{ V} < U_n \leq 690 \text{ V}$	Standard	n.a.	+ N + CMF	$P_n < 500 \text{ kW}$: +N + CMF
					$P_n \geq 500 \text{ kW}$: +N + du/dt + CMF
Old ¹⁾ form-wound HX_ and modular	$380 \text{ V} < U_n \leq 690 \text{ V}$	Check with the motor manufacturer.	+ N + du/dt with voltages over 500 V + CMF		
Random-wound HX_ and AM_ ²⁾	$0 \text{ V} < U_n \leq 500 \text{ V}$	Enamelled wire with fiber glass taping	+ N + CMF		
	$500 \text{ V} < U_n \leq 690 \text{ V}$		+ N + du/dt + CMF		
HDP	Consult the motor manufacturer.				

1) manufactured before 1.1.1998

2) For motors manufactured before 1.1.1998, check for additional instructions with the motor manufacturer.

This table shows the requirements when a non-ABB motor is in use.

Motor type	Nominal AC line voltage	Requirement for			
		Motor insulation system	ABB du/dt and common mode filters, insulated N-end motor bearings		
			$P_n < 100$ kW and frame size $< IEC 315$	$100 \text{ kW} \leq P_n < 350$ kW or $IEC 315 \leq$ frame size $< IEC 400$	$P_n \geq 350$ kW or frame size $\geq IEC 400$
$P_n < 134$ hp and frame size $< NEMA 500$	$134 \text{ hp} \leq P_n < 469$ hp or $NEMA 500 \leq$ frame size $\leq NEMA 580$	$P_n \geq 469$ hp or frame size $> NEMA 580$			
Random-wound and form-wound	$U_n \leq 420$ V	Standard: $\dot{U}_{LL} = 1300$ V	-	+ N or CMF	+ N + CMF
	$420 \text{ V} < U_n \leq 500$ V	Standard: $\dot{U}_{LL} = 1300$ V	+ du/dt	+ du/dt + (N or CMF)	+ N + du/dt + CMF
		or	Reinforced: $\dot{U}_{LL} = 1600$ V, 0.2 microsecond rise time	-	+ N or CMF
	$500 \text{ V} < U_n \leq 600$ V	Reinforced: $\dot{U}_{LL} = 1600$ V	+ du/dt	+ du/dt + (N or CMF)	+ N + du/dt + CMF
		or	Reinforced: $\dot{U}_{LL} = 1800$ V	-	+ N or CMF
	$600 \text{ V} < U_n \leq 690$ V	Reinforced: $\dot{U}_{LL} = 1800$ V	+ du/dt	+ du/dt + N	+ N + du/dt + CMF
		Reinforced: $\dot{U}_{LL} = 2000$ V, 0.3 microsecond rise time ¹⁾	-	+ N + CMF	+ N + CMF

¹⁾ If the intermediate DC circuit voltage of the drive is increased from the nominal level due to long term resistor braking cycles, check with the motor manufacturer if additional output filters are needed.

The abbreviations used in the tables are defined below.

Abbr.	Definition
U_n	Nominal AC line voltage
\hat{U}_{LL}	Peak line-to-line voltage at motor terminals which the motor insulation must withstand
P_n	Motor nominal power
du/dt	du/dt filter at the output of the drive
CMF	Common mode filter of the drive
N	N-end bearing: insulated motor non-drive end bearing
n.a.	Motors of this power range are not available as standard units. Consult the motor manufacturer.

Availability of du/dt filter and common mode filter by drive type

See chapter *Common mode, du/dt and sine filters*

Additional requirements for explosion-safe (EX) motors

If you use an explosion-safe (EX) motor, follow the rules in the requirements table above. In addition, consult the motor manufacturer for any further requirements.

Additional requirements for ABB motors of types other than M2_, M3_, M4_, HX_ and AM_

Use the selection criteria given for non-ABB motors.

Additional requirements for braking applications

When the motor brakes the machinery, the intermediate circuit DC voltage of the drive increases, the effect being similar to the motor supply voltage increasing by up to 20 percent. Consider this voltage increase when specifying the motor insulation requirements if the motor will be braking a large part of its operation time.

Example: Motor insulation requirement for a 400 V AC line voltage application must be selected as if the drive were supplied with 480 V.

Additional requirements for the regenerative and low harmonics drives

It is possible to increase the intermediate circuit DC voltage from the nominal (standard) level with a parameter in the control program. If you choose to do this, select the motor insulation system which withstands the increased DC voltage level.

Additional requirements for ABB high-output and IP23 motors

The rated output power of high output motors is higher than what is stated for the particular frame size in EN 50347 (2001).

This table shows the requirements for protecting the motor insulation and bearings in drive systems for ABB random-wound motor series (for example, M3AA, M3AP and M3BP).

Nominal AC supply voltage	Requirement for			
	Motor insulation system	ABB du/dt and common mode filters, insulated N-end motor bearings		
		$P_n < 100 \text{ kW}$	$100 \text{ kW} \leq P_n < 200 \text{ kW}$	$P_n \geq 200 \text{ kW}$
		$P_n < 140 \text{ hp}$	$140 \text{ hp} \leq P_n < 268 \text{ hp}$	$P_n \geq 268 \text{ hp}$
$U_n \leq 500 \text{ V}$	Standard	-	+ N	+ N + CMF
$500 \text{ V} < U_n \leq 600 \text{ V}$	Standard	+ du/dt	+ du/dt + N	+ du/dt + N + CMF
	or Reinforced	-	+ N	+ N + CMF
$600 \text{ V} < U_n \leq 690 \text{ V}$	Reinforced	+ du/dt	+ du/dt + N	+ du/dt + N + CMF

Additional requirements for non-ABB high-output and IP23 motors

The rated output power of high-output motors is higher than what is stated for the particular frame size in EN 50347 (2001).

If you plan to use a non-ABB high-output motor or an IP23 motor, consider these additional requirements for protecting the motor insulation and bearings in drive systems:

- If motor power is below 350 kW: Equip the drive and/or motor with the filters and/or bearings according to the table below.
- If motor power is above 350 kW: Consult the motor manufacturer.

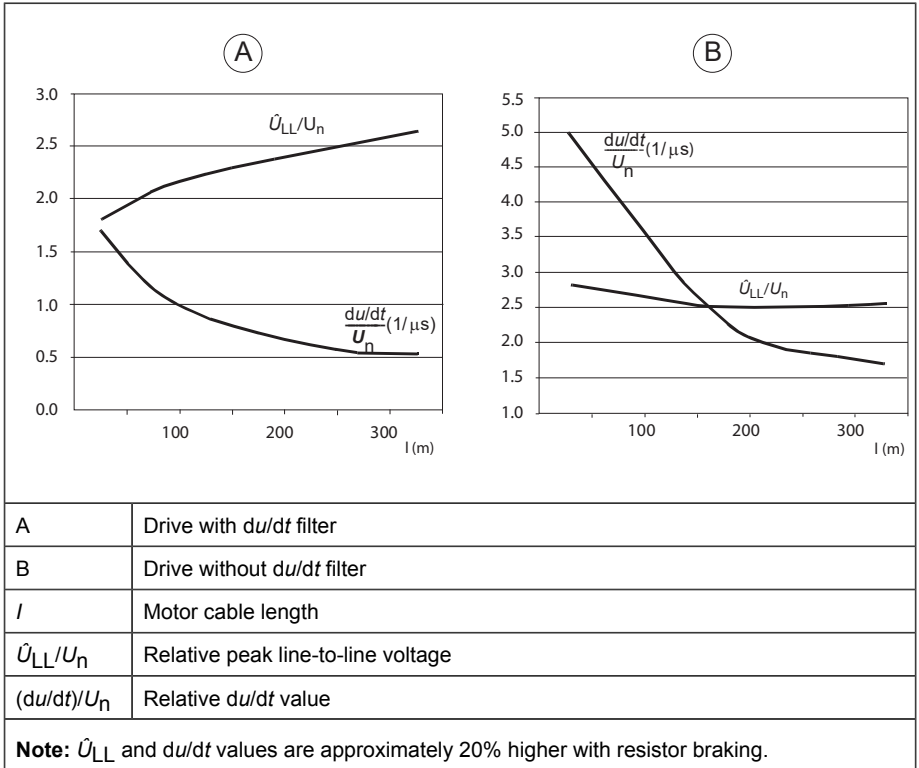
Nominal AC supply voltage	Requirement for		
	Motor insulation system	ABB du/dt and common mode filters, insulated N-end motor bearings	
		$P_n < 100 \text{ kW}$ or frame size < IEC 315	$100 \text{ kW} < P_n < 350 \text{ kW}$ or IEC 315 < frame size < IEC 400
	$P_n < 134 \text{ hp}$ or frame size < NEMA 500	$134 \text{ hp} < P_n < 469 \text{ hp}$ or NEMA 500 < frame size < NEMA 580	
$U_n \leq 420 \text{ V}$	Standard: $\hat{U}_{LL} = 1300 \text{ V}$	+ N or CMF	+ N or CMF
$420 \text{ V} < U_n < 500 \text{ V}$	Standard: $\hat{U}_{LL} = 1300 \text{ V}$	+ du/dt + (N or CMF)	+ N + du/dt + CMF
	or Reinforced: $\hat{U}_{LL} = 1600 \text{ V}$, 0.2 micro-second rise time	+ N or CMF	+ N or CMF
$500 \text{ V} < U_n \leq 600 \text{ V}$	Reinforced: $\hat{U}_{LL} = 1600 \text{ V}$	+ du/dt + (N or CMF)	+ N + du/dt + CMF
	or Reinforced: $\hat{U}_{LL} = 1800 \text{ V}$	+ N or CMF	+ N + CMF
$600 \text{ V} < U_n \leq 690 \text{ V}$	Reinforced: $\hat{U}_{LL} = 1800 \text{ V}$	+ N + du/dt	+ N + du/dt + CMF
	Reinforced: $\hat{U}_{LL} = 2000 \text{ V}$, 0.3 micro-second rise time ¹⁾	+ N + CMF	+ N + CMF

¹⁾ If the intermediate DC circuit voltage of the drive is increased from the nominal level due to long term resistor braking cycles, check with the motor manufacturer if additional output filters are needed.

Additional data for calculating the rise time and the peak line-to-line voltage

The diagrams below show the relative peak line-to-line voltage and rate of change of voltage as a function of the motor cable length. If you need to calculate the actual peak voltage and voltage rise time considering the actual cable length, proceed as follows:

- Peak line-to line voltage: Read the relative \hat{U}_{LL}/U_n value from the diagram below and multiply it by the nominal supply voltage (U_n).
- Voltage rise time: Read the relative values \hat{U}_{LL}/U_n and $(du/dt)/U_n$ from the diagram below. Multiply the values by the nominal supply voltage (U_n) and substitute into equation $t = 0.8 \cdot \hat{U}_{LL}/(du/dt)$.



Additional note for sine filters

A sine filter also protects the motor insulation system. The peak phase-to-phase voltage with a sine filter is approximately $1.5 \cdot U_n$.

Selecting the power cables

■ General guidelines

Select the input power and motor cables according to local regulations.

- **Current:** Select a cable capable of carrying the maximum load current and suitable for the prospective short-circuit provided by the supply network. The method of installation and ambient temperature affect the cable current carrying capacity. Obey local regulations and laws.
- **Temperature:** For an IEC installation, select a cable rated for at least 70 °C (158 °F) maximum permissible temperature of conductor in continuous use. For North America, select a cable rated for at least 75 °C (167 °F). Important: For certain product types or option configurations higher temperature rating may be required. See the technical data for details.
- **Voltage:** 600 V AC cable is accepted for up to 500 V AC. 750 V AC cable is accepted for up to 600 V AC. 1000 V AC cable is accepted for up to 690 V AC.

To comply with the EMC requirements of the CE mark, use one of the preferred cable types. See [Preferred power cable types \(page 94\)](#).

Symmetrical shielded cable reduces electromagnetic emission of the whole drive system as well as the stress on motor insulation, bearing currents and wear.

Metal conduit reduces electromagnetic emission of the whole drive system.

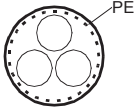
■ Typical power cable sizes

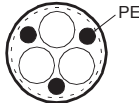

See the technical data.

■ Power cable types

Preferred power cable types



This section presents the preferred cable types. Make sure that the selected cable type also complies with local/state/country electrical codes.


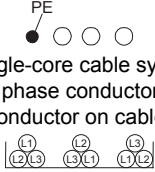

Cable type	Use as input power cabling	Use as motor cabling
 <p data-bbox="90 1305 372 1406">Symmetrical shielded (or armored) cable with three phase conductors and concentric PE conductor as shield (or armor)</p>	Yes	Yes

Cable type	Use as input power cabling	Use as motor cabling
 <p>Symmetrical shielded (or armored) cable with three phase conductors and symmetrically constructed PE conductor and a shield (or armor)</p>	Yes	Yes
 <p>Symmetrical shielded (or armored) cable with three phase conductors and a shield (or armor), and separate PE conductor/cable¹⁾</p>	Yes	Yes

1) A separate PE conductor is required if the conductivity of the shield (or armor) is not sufficient for the PE use.


Alternate power cable types

Cable type	Use as input power cabling	Use as motor cabling
 <p>Four-conductor cabling in PVC conduit or jacket (three phase conductors and PE)</p>	Yes with phase conductor smaller than 10 mm ² (8 AWG) Cu.	Yes with phase conductor smaller than 10 mm ² (8 AWG) Cu, or motors up to 30 kW (40 hp). Note: Shielded or armored cable, or cabling in metal conduit is always recommended to minimize radio frequency interference.
 <p>Four-conductor cabling in metal conduit (three phase conductors and PE). For example, EMT, or four-conductor armored cable</p>	Yes	Yes with phase conductor smaller than 10 mm ² (8 AWG) Cu, or motors up to 30 kW (40 hp)

Cable type	Use as input power cabling	Use as motor cabling
 <p>Shielded (Al/Cu shield or armor)¹⁾ four-conductor cable (three phase conductors and a PE)</p>	<p>Yes</p>	<p>Yes with motors up to 100 kW (135 hp). A potential equalization between the frames of motor and driven equipment is required.</p>
 <p>A single-core cable system: three phase conductors and PE conductor on cable tray</p> <p>Preferable cable arrangement to avoid voltage or current unbalance between the phases</p>	<p>Yes</p> <p> WARNING! If you use unshielded single-core cables in an IT network, make sure that the non-conductive outer sheath (jacket) of the cables have good contact with a properly grounded conductive surface. For example, install the cables on a properly grounded cable tray. Otherwise voltage may become present on the non-conductive outer sheath of the cables, and there is even a risk of an electric shock.</p>	<p>No</p>

¹⁾ Armor may act as an EMC shield, as long as it provides the same performance as a concentric EMC shield of a shielded cable. To be effective at high frequencies, the shield conductivity must be at least 1/10 of the phase conductor conductivity. The effectiveness of the shield can be evaluated based on the shield inductance, which must be low and only slightly dependent on frequency. The requirements are easily met with a copper or aluminum shield/armor. The cross-section of a steel shield must be ample and the shield helix must have a low gradient. A galvanized steel shield has a better high-frequency conductivity than a non-galvanized steel shield.

Not allowed power cable types

Cable type	Use as input power cabling	Use as motor cabling
 <p>Symmetrical shielded cable with individual shields for each phase conductor</p>	<p>No</p>	<p>No</p>

■ Additional guidelines, North America

ABB recommends the use of conduit for power wiring to the drive and between the drive and the motor(s). Due to the variety of application needs, metallic and non-metallic conduit can be used. ABB recommends the use of metallic conduit.

The following table shows examples of various materials and methods for wiring the drive in the intended application. See NEC 70 along with state and local codes for the appropriate materials for your application.

In all applications, ABB prefers the use of symmetrical shielded VFD cable between drive and motor(s).

Wiring method	Notes
Conduit - Metallic ^{1) 2)}	
Electrical metallic tubing: Type EMT	Prefer symmetrical shielded VFD cable. Use separate conduit run for each motor. Do not run input power wiring and motor wiring in the same conduit.
Rigid metal conduit: Type RMC	
Liquid-tight flexible metal electrical conduit: Type LFMC	
Conduit - Non-metallic ^{2) 3)}	
Liquid-tight flexible non-metallic conduit: Type LFNC	Prefer symmetrical shielded VFD cable. Use separate conduit run for each motor. Do not run input power wiring and motor wiring in the same conduit.
Wireways ²⁾	
Metallic	Prefer symmetrical shielded VFD cable. Separate motor wiring from input power wiring and other low voltage wiring. Do not run outputs of multiple drives parallel. Bundle each cable (wiring) together and use separators where possible.
Free air ²⁾	
Enclosures, air handlers, etc.	Prefer symmetrical shielded VFD cable. Allowed internally in enclosures when in accordance with UL.

1) Metallic conduit may be used as an additional ground path, provided this path is a solid path capable of handling ground currents.

2) See NFPA NEC 70, UL, and local codes for your application.

3) Non-metallic conduit use underground is allowed; however, these installations inherently have an increased chance for nuisance problems due to the potential for water/moisture in the conduit. Water/moisture in the conduit increases the likelihood of VFD faults or warnings. Proper installation is required to make sure there is no intrusion of water/moisture.

Metal conduit

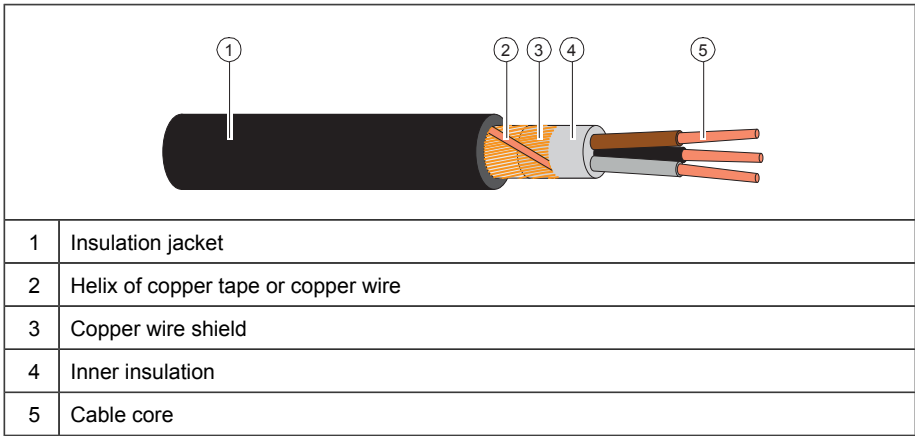
Couple separate parts of a metal conduit together: bridge the joints with a ground conductor bonded to the conduit on each side of the joint. Also bond the conduits to the drive enclosure and motor frame. Use separate conduits for input power, motor, brake

resistor, and control wiring. Do not run motor wiring from more than one drive in the same conduit.

■ **Power cable shield**

If the cable shield is used as the sole protective earth (PE) conductor, make sure that its conductivity agrees with the PE conductor requirements.

To effectively suppress radiated and conducted radio-frequency emissions, the cable shield conductivity must be at least 1/10 of the phase conductor conductivity. The requirements are easily met with a copper or aluminum shield. The minimum requirement of the motor cable shield of the drive is shown below. It consists of a concentric layer of copper wires with an open helix of copper tape or copper wire. The better and tighter the shield, the lower the emission level and bearing currents.



Grounding requirements

This section gives general requirements for grounding the drive. When you plan the grounding of the drive, obey all the applicable national and local regulations.

The conductivity of the protective earth conductor(s) must be sufficient.

Unless local wiring regulations state otherwise, the cross-sectional area of the protective earth conductor must agree with the conditions that require automatic disconnection of the supply required in 411.3.2 of IEC 60364-4-41:2005 and be capable of withstanding the prospective fault current during the disconnection time of the protective device. The cross-sectional area of the protective earth conductor must be selected from the table below or calculated according to 543.1 of IEC 60364-5-54.

This table shows the minimum cross-sectional area of the protective earth conductor related to the phase conductor size according to IEC/UL 61800-5-1 when the phase conductor(s) and the protective earth conductor are made of the same metal. If this is not so, the cross-sectional area of the protective earth conductor must be determined

in a manner which produces a conductance equivalent to that which results from the application of this table.

Cross-sectional area of the phase conductors S (mm ²)	Minimum cross-sectional area of the corresponding protective earth conductor S_p (mm ²)
$S \leq 16$	$S^1)$
$16 < S \leq 35$	16
$35 < S$	$S/2$

1) For the minimum conductor size in IEC installations, refer to *Additional grounding requirements – IEC*.

If the protective earth conductor is not part of the input power cable or input power cable enclosure, the minimum permitted cross-sectional area is:

- 2.5 mm² if the conductor is mechanically protected,
or
- 4 mm² if the conductor is not mechanically protected. If the equipment is cord-connected, the protective earth conductor must be the last conductor to be interrupted if there is a failure in the strain relief mechanism.

■ Additional grounding requirements – IEC

This section gives grounding requirements according to standard IEC/EN 61800-5-1.

Because the normal touch current of the drive is more than 3.5 mA AC or 10 mA DC:

- the minimum size of the protective earth conductor must comply with the local safety regulations for high protective earth conductor current equipment, and
- you must use one of these connection methods:
 1. a fixed connection and:
 - a protective earth conductor with a minimum cross-sectional area of 10 mm² Cu or 16 mm² Al (as an alternative when aluminum cables are permitted),
or
 - a second protective earth conductor of the same cross-sectional area as the original protective earth conductor,
or
 - a device that automatically disconnects the supply if the protective earth conductor is damaged.
 2. a connection with an industrial connector according to IEC 60309 and a minimum protective earth conductor cross-section of 2.5 mm² as part of a multi-conductor power cable. Sufficient strain relief must be provided.

If the protective earth conductor is routed through a plug and socket, or similar means of disconnection, it must not be possible to disconnect it unless power is simultaneously removed.

Note: You can use power cable shields as grounding conductors only when their conductivity is sufficient.

■ Additional grounding requirements – UL (NEC)

This section gives grounding requirements according to standard UL 61800-5-1.

The protective earth conductor must be sized as specified in Article 250.122 and table 250.122 of the National Electric Code, ANSI/NFPA 70.

For cord-connected equipment, it must not be possible to disconnect the protective earth conductor before power is removed.

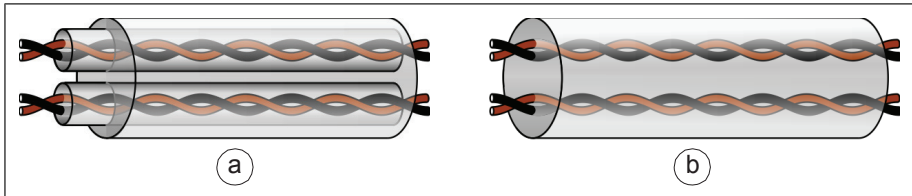
Selecting the control cables

■ Shielding

Only use shielded control cables.

Use a double-shielded twisted pair cable for analog signals. ABB recommends this type of cable also for the pulse encoder signals. Use one individually shielded pair for each signal. Do not use common return for different analog signals.

A double-shielded cable (a) is the best alternative for low-voltage digital signals, but single-shielded (b) twisted pair cable is also acceptable.



■ Signals in separate cables

Run analog and digital signals in separate, shielded cables. Do not mix 24 V DC and 115/230 V AC signals in the same cable.

■ Signals that can be run in the same cable

If their voltage does not exceed 48 V, relay-controlled signals can be run in the same cables as digital input signals. The relay-controlled signals should be run as twisted pairs.

■ Relay cable

The cable type with braided metallic shield (for example ÖLFLEX by LAPPKABEL, Germany) has been tested and approved by ABB.

■ Control panel to drive cable

Use EIA-485, Cat 5e (or better) cable with male RJ-45 connectors. The maximum length of the cable is 100 m (328 ft).

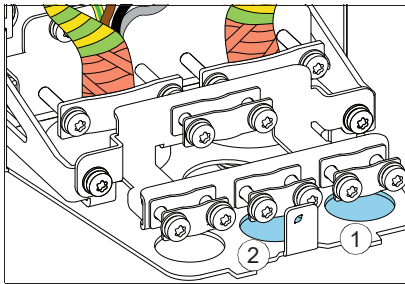
■ PC tool cable

Connect the Drive Composer PC tool to the drive through the USB port of the control panel. Use a USB Type A (PC) - Type Mini-B (control panel) cable. The maximum length of the cable is 3 m (9.8 ft).

■ FPBA-01 PROFIBUS DP adapter module connectors

Frames R1...R3: The following connector types have been tested to fit in the tight space for option slot 1.

- Phoenix Contact SUBCON-PLUS-PROFIB/PG/SC2, part number 2708245. Lead the cable through the control cable hole on the right in the entry plate (1).
- Siemens, part number 6GK1 500 0EA02. Lead the cable through the middle control cable hole in the entry plate (2).



Routing the cables

■ General guidelines – IEC

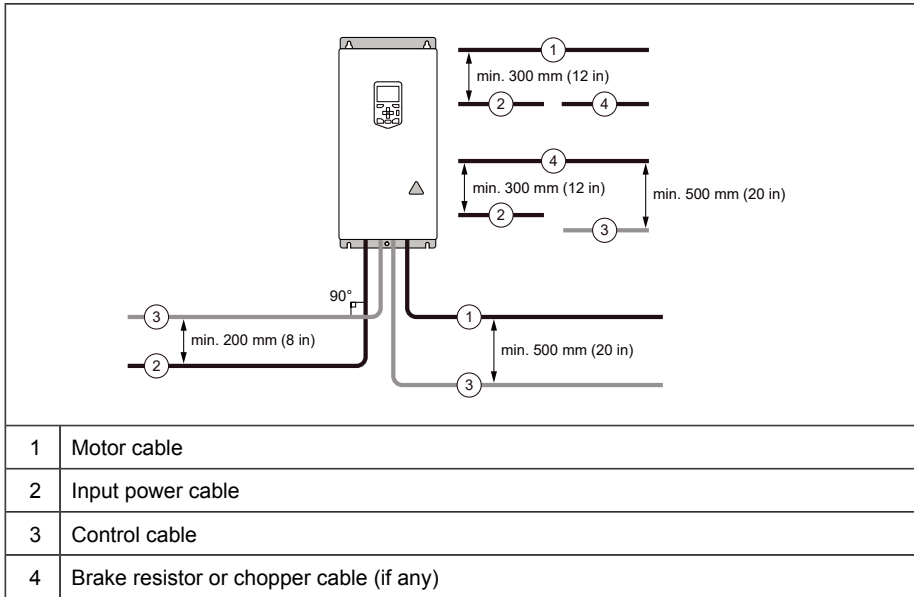
- Route the motor cable away from other cables. Motor cables of several drives can be run in parallel installed next to each other.
 - Install the motor cable, input power cable and control cables on separate trays.
 - Avoid long parallel runs of motor cables with other cables.
-

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- Where control cables must cross power cables, make sure that they are arranged at an angle as near to 90 degrees as possible.
- Do not run extra cables through the drive.
- Make sure that the cable trays have good electrical bonding to each other and to the grounding electrodes. Aluminum tray systems can be used to improve local equalizing of potential.

The following figure illustrates the cable routing guidelines with an example drive.

Note: When motor cable is symmetrical and shielded and it has short parallel runs with other cables (< 1.5 m / 5 ft), distances between the motor cable and other cables can be reduced by half.

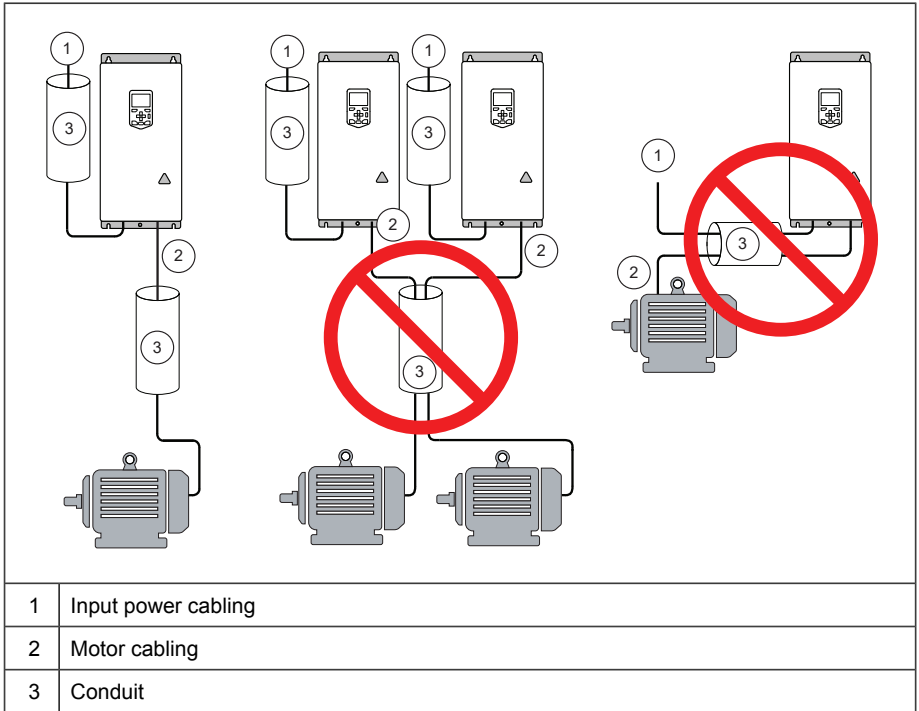


■ General guidelines – North America

Make sure that the installation is in accordance with national and local codes. Obey these general guidelines:

- Use separate conduits for the input power, motor, brake resistor (optional), and control cabling.
- Use separate conduit for each motor cabling.

The following figure illustrates the cable routing guidelines with an example drive.



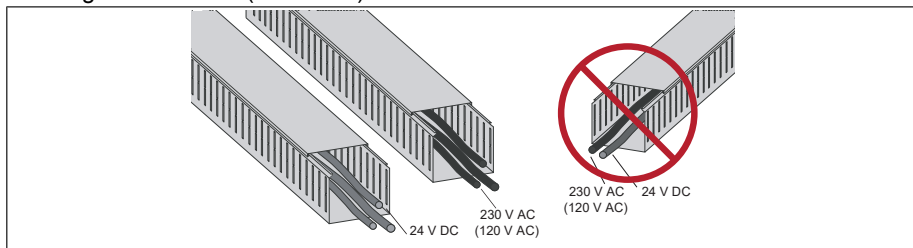
■ **Continuous motor cable shield/conduit or enclosure for equipment on the motor cable**

To minimize the emission level when safety switches, contactors, connection boxes or similar equipment are installed on the motor cable between the drive and the motor:

- Install the equipment in a metal enclosure.
- Use either a symmetrical shielded cable, or install the cabling in a metal conduit.
- Make sure that there is a good and continuous galvanic connection in the shield/conduit between drive and motor.
- Connect the shield/conduit to the protective ground terminal of the drive and the motor.

■ Separate control cable ducts

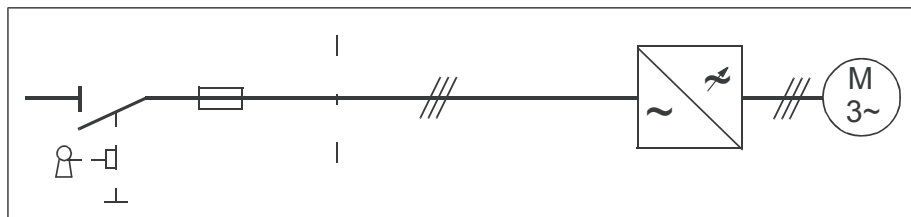
Put 24 V DC and 230 V AC (120 V AC) control cables in separate ducts, unless the 24 V DC cable is insulated for 230 V AC (120 V AC) or insulated with an insulation sleeving for 230 V AC (120 V AC).



Implementing short-circuit and thermal overload protection

■ Protecting the drive and the input power cable in short-circuits

Protect the drive with fuses and the input cable with fuses or a circuit breaker.



Size the fuses or circuit breakers according to local regulations for the input cable protection. Select the fuses or circuit breakers for the drive according to the instructions given in the technical data. The fuses for the drive protection will restrict drive damage and prevent damage to adjoining equipment in case of a short-circuit inside the drive.

Note: If the fuses or circuit breakers for the drive protection are placed at the distribution board and the input cable is dimensioned according to the nominal input current of the drive given in the technical data, the fuses or circuit breakers protect also the input cable in short-circuit situations, restrict drive damage and prevent damage to adjoining equipment in case of a short-circuit inside the drive. No separate fuses or circuit breakers for the input cable protection are needed.



WARNING!

Due to the inherent operating principle and construction of circuit breakers, independent of the manufacturer, hot ionized gases can escape from the breaker enclosure in case of a short-circuit. To ensure safe use, pay special attention to the installation and placement of the breakers. Obey the manufacturer's instructions.

■ Protecting the motor and motor cable in short-circuits

The drive protects the motor cable and motor in a short-circuit situation when the motor cable is sized according to the nominal output current of the drive.

■ Protecting the motor cables against thermal overload

The drive protects the motor cables against thermal overload when the cables are sized according to the nominal output current of the drive. No additional thermal protection devices are needed.



WARNING!

If the drive is connected to multiple motors, use a separate overload protection for each motor cable and motor. The drive overload protection is tuned for the total motor load. It may not detect an overload in one motor circuit only.

North America: The local code (NEC) requires an overload protection and a short-circuit protection for each motor circuit. Use, for example:

- a manual motor protector
- circuit breaker, contactor and overload relay or
- fuses, contactor and overload relay.

■ Protecting the motor against thermal overload

According to regulations, the motor must be protected against thermal overload and the current must be switched off when overload is detected. The drive includes a motor thermal protection function that protects the motor and switches off the current when necessary. Depending on a drive parameter value, the function either monitors a calculated temperature value (based on a motor thermal model) or an actual temperature indication given by motor temperature sensors.

The motor thermal protection model supports thermal memory retention and speed sensitivity. The user can tune the thermal model further by feeding in additional motor and load data.

The most common temperature sensor types are PTC or Pt100.

For more information, see the firmware manual.

■ Protecting the motor against overload without thermal model or temperature sensors

Motor overload protection protects the motor against overload without using motor thermal model or temperature sensors.

Motor overload protection is required and specified by multiple standards including the US National Electric Code (NEC) and the common UL/IEC 61800-5-1 standard in

conjunction with UL/IEC 60947-4-1. The standards allow for motor overload protection without external temperature sensors.

The protection feature allows the user to specify the class of operation in the same manner as the overload relays are specified in standards UL/IEC 60947-4-1 and NEMA ICS 2.

The motor overload protection supports thermal memory retention and speed sensitivity.

For more information, see drive firmware manual.

Protecting the drive against ground faults

The drive is equipped with an internal ground fault protective function to protect the unit against ground faults in the motor and motor cable. This function is not a personnel safety or a fire protection feature. See the firmware manual for more information.

■ Residual current device compatibility

The drive is suitable to be used with residual current devices of Type B.

Note: As standard, the drive contains capacitors connected between the main circuit and the frame. These capacitors and long motor cables increase the ground leakage current and may cause nuisance faults in residual current devices.

Implementing the emergency stop function

For safety reasons, install the emergency stop devices at each operator control station and at other operating stations where the emergency stop may be needed. Implement the emergency stop according to relevant standards.

Note: You can use the Safe torque off function of the drive to implement the Emergency stop function.

Implementing the Safe torque off function

See [The Safe torque off function \(page 347\)](#).

Implementing an ATEX-certified motor thermal protection

With option +Q971, the drive provides ATEX-certified safe motor disconnection without contactor using the drive Safe torque off function. To implement the thermal protection of a motor in explosive atmosphere (Ex motor), you must also:

- use an ATEX-certified Ex motor
- order an ATEX-certified thermistor protection module for the drive (option +L537), or acquire and install an ATEX-compliant protection relay
- do the necessary connections.

For more information, see:

User's manual	Manual code (English)
<i>CPTC-02 ATEX-certified thermistor protection module, Ex II (2) GD (option +L537+Q971) user's manual</i>	3AXD50000030058

Using a safety switch between the drive and the motor

ABB recommends to install a safety switch between the permanent magnet motor and the drive output. The switch is needed to isolate the motor from the drive during maintenance work on the drive.

Implementing the Power-loss ride-through function

See the firmware manual.

Controlling a contactor between drive and motor

The control of the output contactor depends on how you use the drive, that is, which motor control mode and which motor stop mode you select.

If you have the vector control mode and motor ramp stop selected, open the contactor as follows:

1. Give a stop command to the drive.
2. Wait until the drive decelerates the motor to zero speed.
3. Open the contactor.

If you have the vector control mode and motor coast stop, or scalar control mode selected, open the contactor as follows:

1. Give a stop command to the drive.
2. Open the contactor.



WARNING!

When the vector control mode is in use, never open the output contactor while the drive controls the motor. The vector control operates extremely fast, much faster than it takes for the contactor to open its contacts. When the contactor starts opening while the drive controls the motor, the vector control will try to maintain the load current by immediately increasing the drive output voltage to the maximum. This will damage, or even burn, the contactor completely.

Implementing a bypass connection

If bypassing is required, employ mechanically or electrically interlocked contactors between the motor and the drive and between the motor and the power line. Make sure

with interlocking that the contactors cannot be closed simultaneously. The installation must be clearly marked as defined in IEC/EN/UL 61800-5-1, subclause 6.5.3, for example, "THIS MACHINE STARTS AUTOMATICALLY".

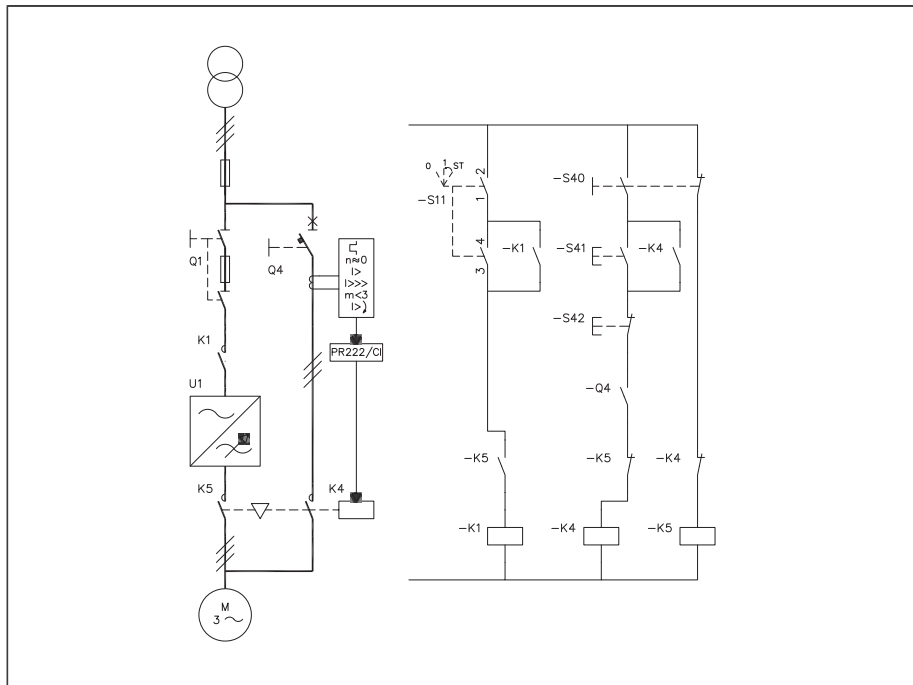


WARNING!

Never connect the drive output to the electrical power network. The connection may damage the drive.

■ **Example bypass connection**

An example bypass connection is shown below.



Q1	Drive main switch
Q4	Bypass circuit breaker
K1	Drive main contactor
K4	Bypass contactor
K5	Drive output contactor
S11	Drive main contactor on/off control
S40	Motor power supply selection (drive or direct-on-line)

S41	Start when motor is connected direct-on-line
S42	Stop when motor is connected direct-on-line

Switching the motor power supply from drive to direct-on-line

1. Stop the drive and the motor with the drive control panel stop key (drive in the local control mode) or the external stop signal (drive in the remote control mode).
2. Open the main contactor of the drive with S11.
3. Switch the motor power supply from the drive to direct-on-line with S40.
4. Wait for 10 seconds to allow the motor magnetization to dissipate.
5. Start the motor with S41.

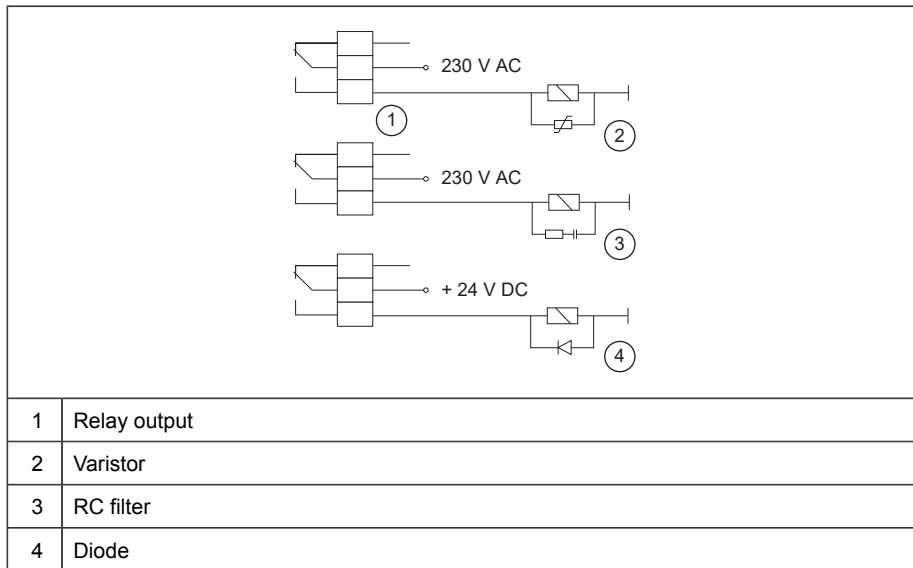
Switching the motor power supply from direct-on-line to drive

1. Stop the motor with S42.
2. Switch the motor power supply from direct-on-line to the drive with S40.
3. Close the main contactor of the drive with switch S11 (-> turn to position ST for two seconds and leave to position 1).
4. Start the drive and the motor with the drive control panel start key (drive in the local control mode) or the external start signal (drive in the remote control mode).

Protecting the contacts of relay outputs

Inductive loads (relays, contactors, motors) cause voltage transients when switched off.

Install the protective component as close to the inductive load as possible. Do not install protective components at the relay outputs.



Limiting relay output maximum voltages at high installation altitudes

See *Isolation areas, R1...R5* (page 294) and *Isolation areas, R6...R9* (page 295).

Implementing a motor temperature sensor connection



WARNING!

IEC 61800-5-1 requires double or reinforced insulation between live parts and accessible parts when:

- the accessible parts are not conductive, or
- the accessible parts are conductive, but not connected to the protective earth.

Obey this requirement when you plan the connection of the motor temperature sensor to the drive.

To connect a motor temperature sensor and other similar components to the drive, you have four alternatives:

1. If there is double or reinforced insulation between the sensor and the live parts of the motor, you can connect the sensor directly to the inputs of the drive.
2. If there is basic insulation between the sensor and the live parts of the motor, you can connect the sensor to the analog/digital inputs of the drive if all circuits connected to the drive's digital and analog inputs (typically extra-low voltage circuits) are

protected against contact and insulated with basic insulation from other low-voltage circuits. The insulation must be rated for the same voltage level as the drive main circuit. Note that extra-low voltage circuits (such as 24 V DC) typically do not meet these requirements.

3. You can connect the sensor to the drive via an option module. The sensor and the module must form a double or reinforced insulation between the motor live parts and the drive control unit. See section [Connection of motor temperature sensor to the drive via an option module \(page 100\)](#).
4. You can connect the sensor to a digital input of the drive via a customer's external relay. The sensor and the relay must form a double or reinforced insulation between the motor live parts and the drive control unit. See section [Connection of motor temperature sensor to the drive via a relay \(page 101\)](#).

■ Connecting motor temperature sensor to the drive via an option module

This table shows:

- option module types that you can use for the motor temperature sensor connection
- insulation or isolation level that each option module forms between its temperature sensor connector and other connectors
- temperature sensor types that you can connect to each option module
- temperature sensor insulation requirement in order to form, together with the insulation of the option module, a reinforced insulation between the motor live parts and the drive control unit.

Option module		Temperature sensor type			Temperature sensor insulation requirement
Type	Insulation/Isolation	PTC	KTY	Pt100, Pt1000	
CMOD-02	Reinforced insulation between the sensor connector and the other connectors of the module (including drive control unit connector). → No special requirements for the thermistor insulation level. (The drive control unit is PELV compatible also when the module and a thermistor protection circuit are installed.)	x	-	-	No special requirement
CPTC-02		x	-	-	No special requirement

■ **Connection of motor temperature sensor to the drive via a relay**

PTC (IEC 60800-5-1)

Class A. This table shows the insulation requirement for a customer's external relay, and the insulation requirement for the sensor to fulfill decisive voltage class A (double insulation).

PTC relay		Temperature sensor insulation requirement
Type	Insulation	
External relay	Basic insulation 6 kV	Basic insulation

Class B. Decisive voltage class B (basic insulation) is provided with a 6 kV relay. Circuits connected to all motor protection relay inputs and outputs must be protected against direct contact.

Pt100 (IEC 90800-5-1)

Class B. Decisive voltage class B (basic insulation) can be achieved when there is basic insulation between the sensor and live parts of the motor. Circuits connected to all motor protection relay inputs and outputs must be protected against direct contact.

P100 relay		Temperature sensor insulation requirement between sensor and live parts of motor
Type	Insulation	
External relay	Basic insulation 6 kV	Basic insulation

6

Electrical installation – IEC

Contents of this chapter

This chapter describes how to:

- measure the insulation
- do the grounding system compatibility check
- change the EMC filter or ground-to-phase varistor connection
- connect the power and control cables
- install optional modules
- connect a PC.

Warnings



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.

Required tools

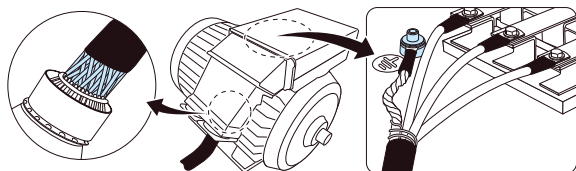
To do the electrical installation, you need these tools:

- wire stripper
 - screwdriver set (Torx, flat and/or Phillips, as appropriate)
 - torque wrench.
-



Grounding the motor cable shield at the motor end

For minimum radio-frequency interference, ground the cable shield 360 degrees at the cable entry of the motor terminal box.



Measuring the insulation

■ Measuring the insulation resistance of the drive

WARNING! Do not do any voltage withstand or insulation resistance tests on any part of the drive as testing can damage the drive. Every drive has been tested for insulation between the main circuit and the chassis at the factory. Also, there are voltage-limiting circuits inside the drive which cut down the testing voltage automatically.

■ Measuring the insulation resistance of the input power cable

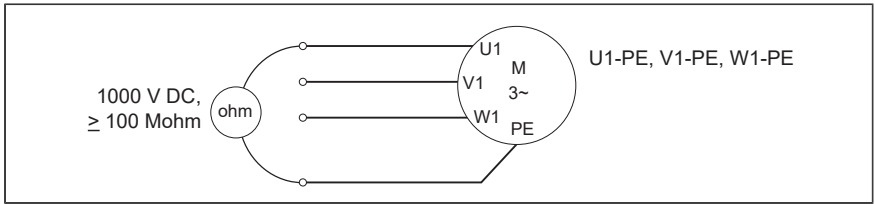
Before you connect the input power cable to the drive, measure its insulation resistance according to local regulations.

■ Measuring the insulation resistance of the motor and motor cable

WARNING! Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.

1. Do the steps in section *Electrical safety precautions (page 22)* before you start the work.
2. Make sure that the motor cable is disconnected from the drive output terminals.
3. Measure the insulation resistance between each phase conductor and the protective earth conductor. Use a measuring voltage of 1000 V DC. The insulation resistance of an ABB motor must be more than 100 Mohm (reference value at 25 °C [77 °F]). For the insulation resistance of other motors, refer to the manufacturer's instructions.

Note: Moisture inside the motor reduces the insulation resistance. If you think that there is moisture in the motor, dry the motor and do the measurement again.



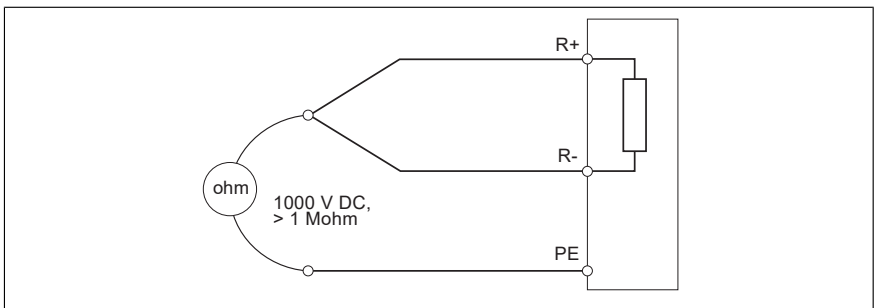
■ Brake resistor assembly for R1...R3



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.

1. Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.
2. Make sure that the resistor cable is connected to the resistor and disconnected from the drive output terminals.
3. At the drive end, connect the R+ and R- conductors of the resistor cable together. Measure the insulation resistance between the conductors and the PE conductor with a measuring voltage of 1000 V DC. The insulation resistance must be more than 1 Mohm.



Grounding system compatibility check

The standard drive can be installed to a symmetrically grounded TN-S system. For other systems, see sections *EMC filter* and *Ground-to-phase varistors (page 116)* below.

■ EMC filter

A drive with EMC filter connected can be installed to a symmetrically grounded TN-S system. If you install the drive to another system, you may need to disconnect the EMC

filter. See sections *When to disconnect EMC filter or ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems (page 116)*, and *Guidelines for installing the drive to a TT system (page 117)*.



WARNING!

Do not install the drive with the EMC filter connected to a system that the filter is not suitable for. This can cause danger, or damage the drive.

Note: When the internal EMC filter is disconnected, the drive EMC compatibility is considerably reduced. See *EMC compatibility and motor cable length (page 290)*.

■ **Ground-to-phase varistors**

A drive with the ground-to-phase varistor connected can be installed to a symmetrically grounded TN-S system. If you install the drive to another system, you may need to disconnect the varistor. See sections *When to disconnect EMC filter or ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems (page 116)*, and *Guidelines for installing the drive to a TT system (page 117)*.



WARNING!

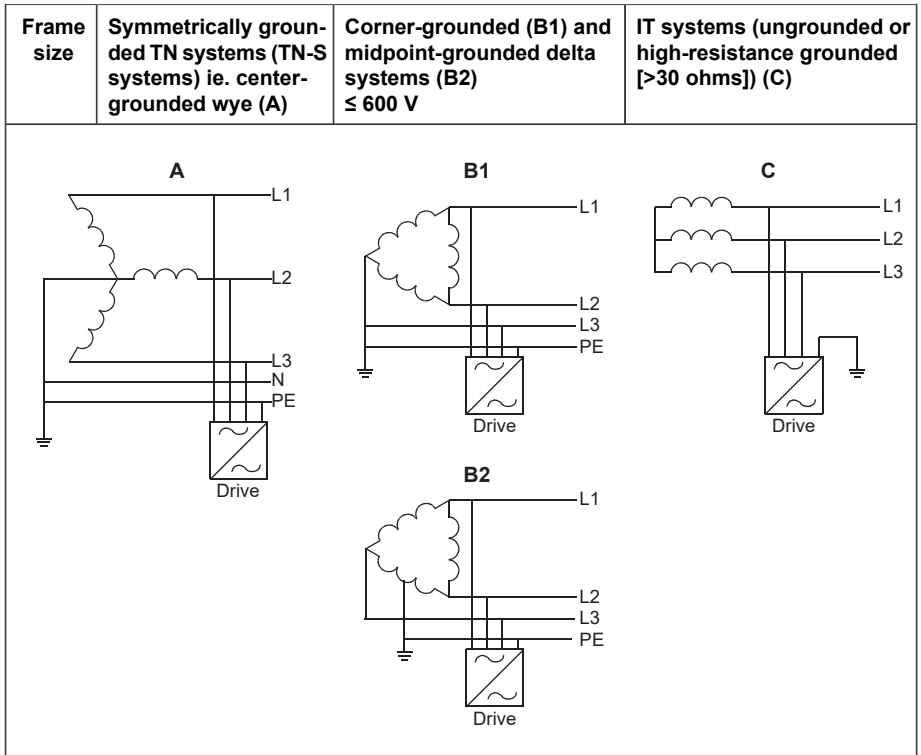
Do not install the drive with the ground-to-phase varistor connected to a system that the varistor is not suitable for. If you do, the varistor circuit can be damaged.

■ **When to disconnect EMC filter or ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems**

Requirements for disconnecting EMC filter and varistor and additional requirements for different electrical power systems are given below.

Frame size	Symmetrically grounded TN systems (TN-S systems) ie. center-grounded wye (A)	Corner-grounded (B1) and midpoint-grounded delta systems (B2) ≤ 600 V	IT systems (ungrounded or high-resistance grounded [>30 ohms]) (C)
R1...R3 R4 v2	Do not disconnect EMC or VAR screws.	Disconnect EMC screw. Do not disconnect VAR screw.	Disconnect EMC and VAR screws.
R4...R5	Do not disconnect EMC or VAR screws.	Not evaluated ¹⁾	Disconnect EMC screws (2 pcs) and VAR screw.
R6...R9	Do not disconnect EMC or VAR screws.	Do not disconnect EMC AC or VAR screws. Disconnect EMC DC screw.	Disconnect EMC screws (2 pcs) and VAR screw.





1) Frames R4 and R5 are not evaluated for use on corner-grounded systems or midpoint-grounded delta systems by IEC standards.

Note: These are the EMC filter and varistor screws of different drive frame sizes.

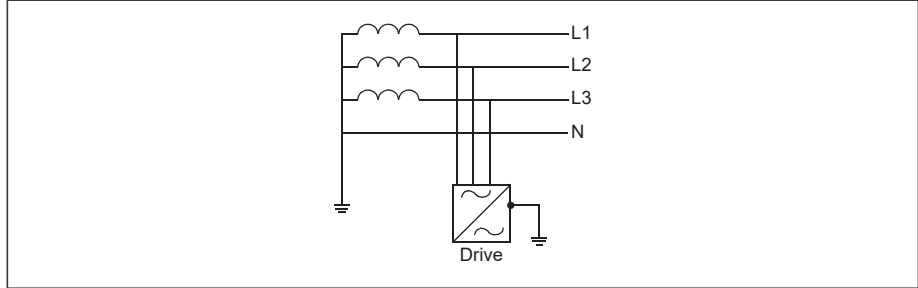
Frame size	EMC filter screws	Ground-to-phase varistor screws
R1...R3 R4 v2	EMC screw	VAR
R4...R5	Two EMC screws	VAR
R6...R9	Two EMC screws	VAR

■ Guidelines for installing the drive to a TT system

The drive can be installed to a TT system under these conditions:

1. Residual current device has been installed in the supply system.
2. These screws have been disconnected. Otherwise EMC filter and ground-to-phase varistor capacitor leakage current will cause the residual current device to trip.

Frame size	EMC filter screws	Ground-to-phase varistor screws
R1...R3 R4 v2	EMC screw	VAR
R4...R5	Two EMC screws	VAR
R6...R9	Two EMC screws	VAR



Note:

- Because the EMC filter screws have been disconnected, ABB does not guarantee the EMC category.
- ABB does not guarantee the functioning of the ground leakage detector built inside the drive.
- In large systems the residual current device can trip without a reason.



■ Identifying the grounding system of the electrical power network



WARNING!

Only a qualified electrical professional may do the work instructed in this section. Depending on the installation site, the work may even be categorized as live working. Continue only if you are an electrical professional certified for the work. Obey the local regulations. If you ignore them, injury or death can occur.

To identify the grounding system, examine the supply transformer connection. See the applicable electrical diagrams of the building. If that is not possible, measure these voltages at the distribution board, and use the table to define the grounding system type.

1. input voltage line to line (U_{L-L})
2. input voltage line 1 to ground (U_{L1-G})
3. input voltage line 2 to ground (U_{L2-G})
4. input voltage line 3 to ground (U_{L3-G}).

The table below shows the line-to-ground voltages in relation to the line-to-line voltage for each grounding system.

U_{L-L}	U_{L1-G}	U_{L2-G}	U_{L3-G}	Electrical power system type
X	$0.58 \cdot X$	$0.58 \cdot X$	$0.58 \cdot X$	Symmetrically grounded TN system (TN-S system)
X	$1.0 \cdot X$	$1.0 \cdot X$	0	Corner-grounded delta system (nonsymmetrical)
X	$0.866 \cdot X$	$0.5 \cdot X$	$0.5 \cdot X$	Midpoint-grounded delta system (nonsymmetrical)
X	Varying level versus time	Varying level versus time	Varying level versus time	IT systems (ungrounded or high-resistance-grounded [>30 ohms]) nonsymmetrical
X	Varying level versus time	Varying level versus time	Varying level versus time	TT system (the protective earth connection for the consumer is provided by a local earth electrode, and there is another independently installed at the generator)

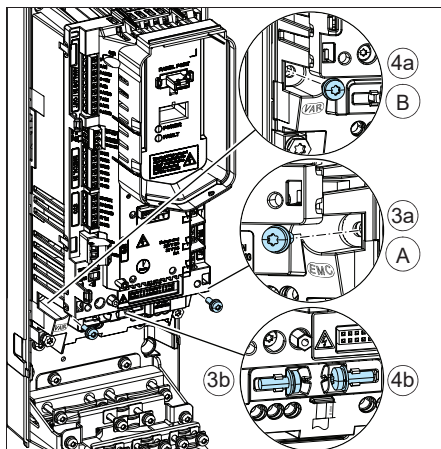
■ Disconnecting internal EMC filter or ground-to-phase varistor - frames R1...R3

To disconnect the internal EMC filter or ground-to-phase varistor, if needed, do as follows:

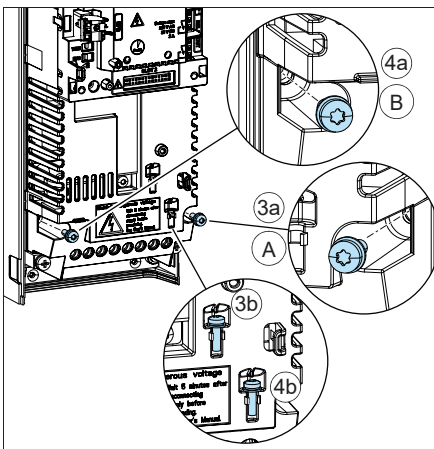
1. Switch off the power from the drive.
2. Open the front cover, if not already opened, see page 123.
3. To disconnect the internal EMC filter, remove the EMC screw (3a) and place it in the storage place (3b).

4. To disconnect the ground-to-phase varistor, remove the varistor screw (4a) and place it in the storage place (4b)

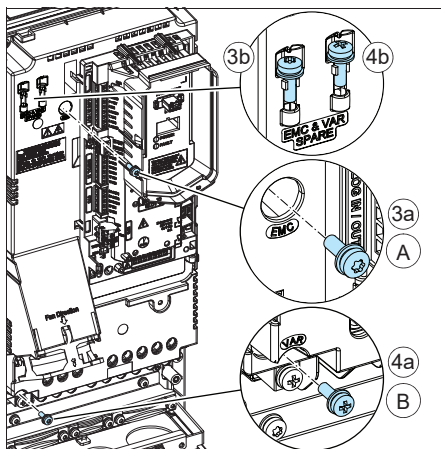
R1



R2



R3



	Screw
A	EMC (DC)
B	VAR

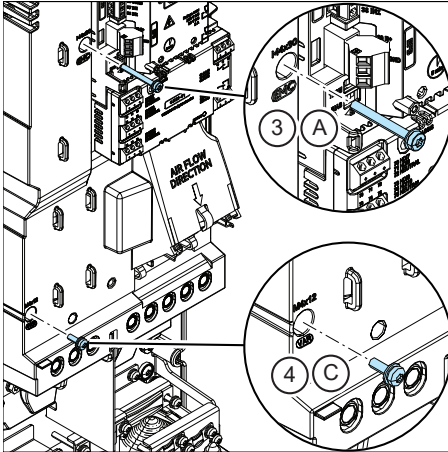
■ Disconnecting internal EMC filter or ground-to-phase varistor - frames R4...R9

To disconnect the internal EMC filter or ground-to-phase varistor, if needed, do as follows:

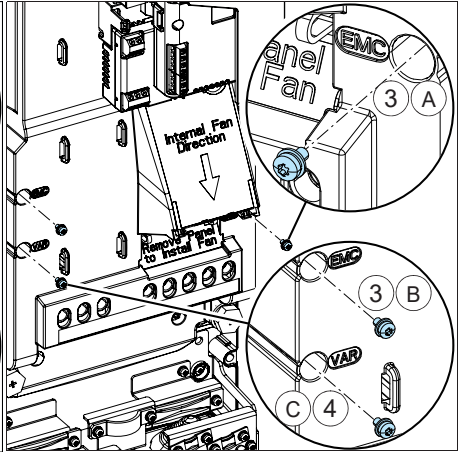
1. Switch off the power from the drive.
2. Open the cover, if not already opened. Frame R4: see page 123, frame R5: see page 129, frames R6...R9: see page 81.

3. To disconnect the internal EMC filter, remove the EMC screw(s).
4. To disconnect the ground-to-phase varistor, remove the varistor screw.

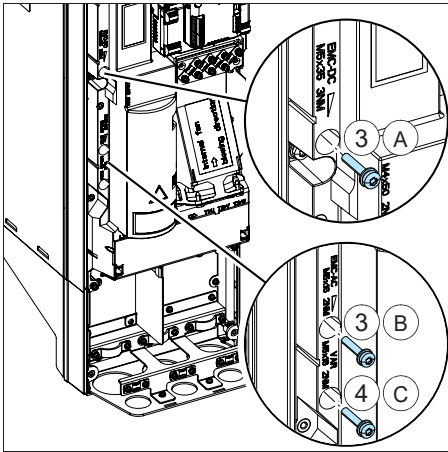
R4 v2



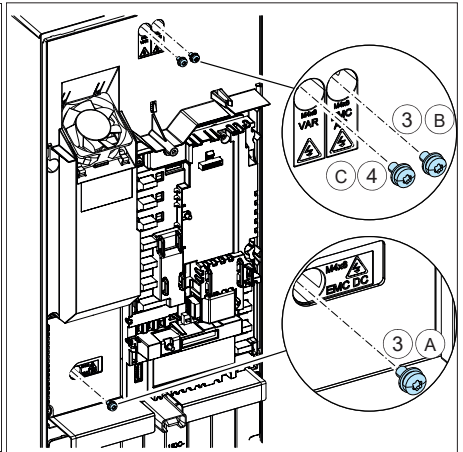
R4



R5



R6...R9

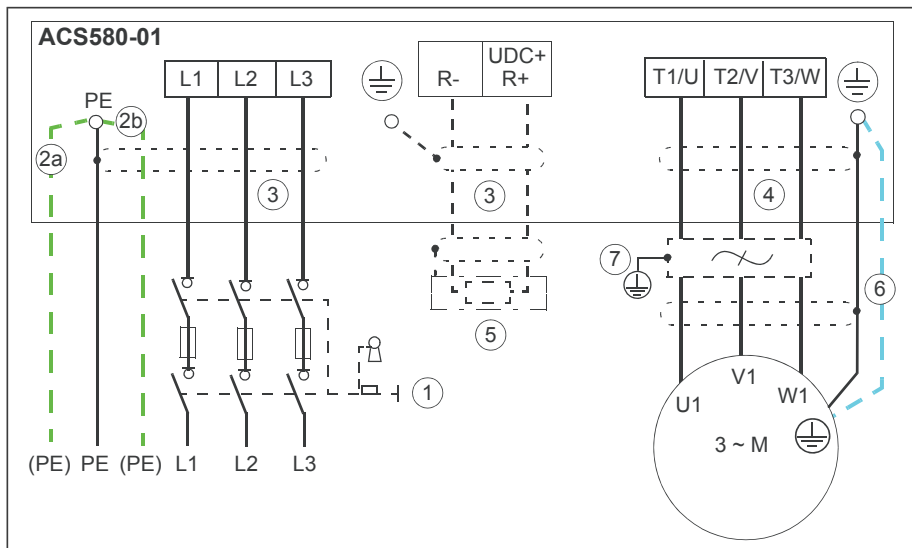


	Screw
A	EMC (DC)
B	EMC (AC)
C	VAR



Connecting the power cables

■ Connection diagram



1	For alternatives, see section Selecting the main supply disconnecting device (page 85)
2	Use a separate grounding PE cable (2a) or a cable with a separate PE conductor (2b) if the conductivity of the shield does not meet the requirements for the PE conductor (see Selecting the power cables (page 94))
3	360-degree grounding is recommended if shielded cable is used. Ground the other end of the input cable shield or PE conductor at the distribution board.
4	360-degree grounding is required
5	External brake resistor
6	Use a separate grounding cable if the shield does not meet the requirements of IEC 61439-1 (see Selecting the power cables (page 94))
7	du/dt or common mode filter (optional), see Common mode, du/dt and sine filters (page 395)

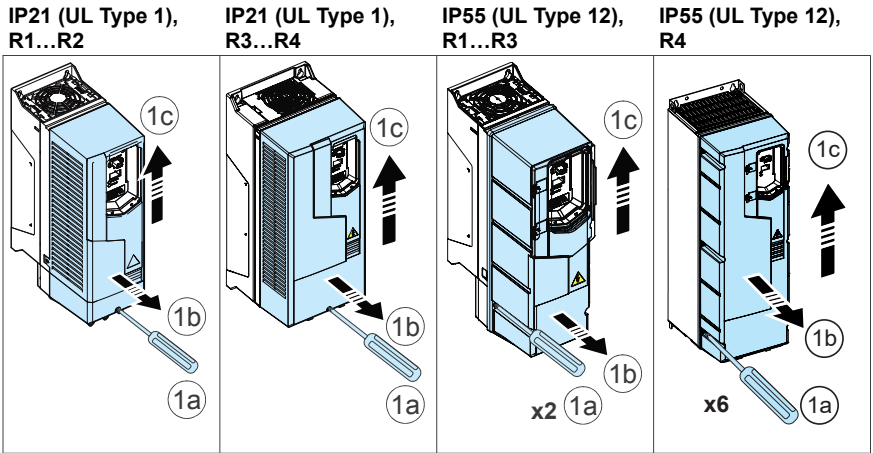
Note: If there is a symmetrically constructed grounding conductor on the motor cable in addition to the conductive shield, connect the grounding conductor to the grounding terminal at the drive and motor ends.

Do not use an asymmetrically constructed motor cable for motors above 30 kW (see section [General guidelines \(page 94\)](#)). Connecting its fourth conductor at the motor end increases bearing currents and causes extra wear.

For a single phase connection, use terminals L1 and L2.

■ **Connection procedure, frames R1...R4**

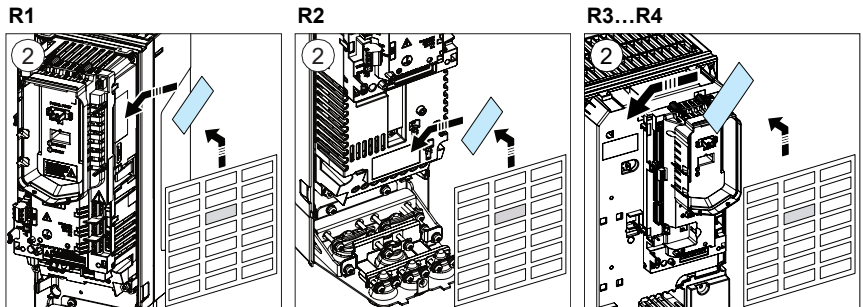
1. Remove the front cover: Loosen the retaining screw with a T20 Torx screwdriver (1a) and lift the cover from the bottom outwards (1b) and then up (1c).



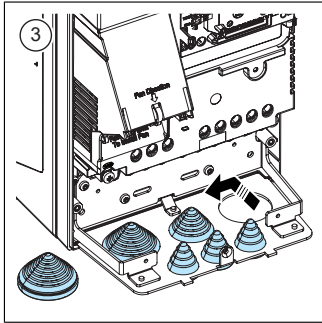
WARNING!

If you install the drive on any other system than symmetrically grounded TN-S system, see [Grounding system compatibility check \(page 115\)](#) if you have to disconnect the EMC filter and ground-to-phase varistor.

2. Attach the residual voltage warning sticker in the local language.



3. Remove the rubber grommets for the motor and input power cables, as well as brake resistor cable, if used.
Remove the grommets for the control cables when you are connecting them.

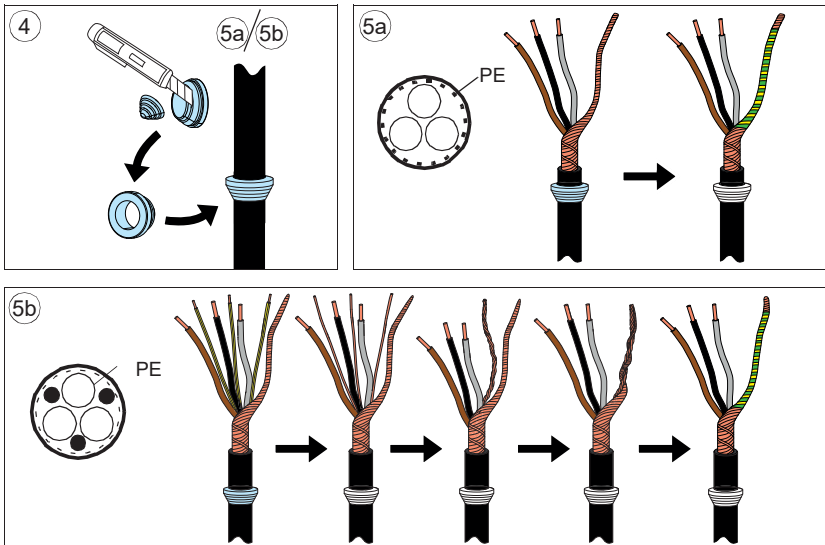


Note: The drive is shipped with grommet cones pointing up. They must be removed and inserted back pointing down.

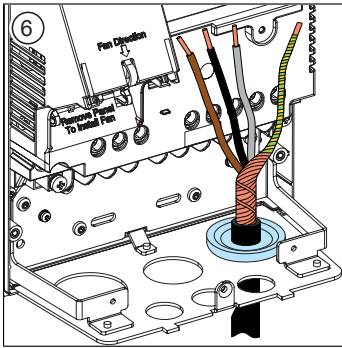
Motor cable

4. Cut an adequate hole into the rubber grommet. Slide the grommet onto the cable.
5. Prepare the ends of the cable as illustrated in the figures. In frames R1 and R2 there are markings on the drive frame near the power cable terminals helping you to strip the wires to the correct length of 8 mm.
Two different motor cable types are shown (6a, 6b).

Note: The bare shield will be grounded 360 degrees. Mark the pigtail made from the shield as a PE conductor with yellow-and-green color.



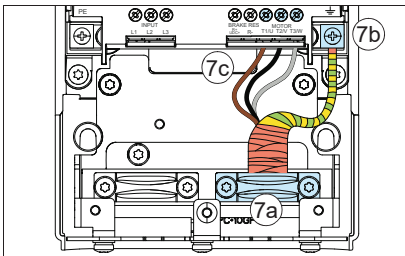
6. Slide the cable through the hole in the cable entry and attach the grommet to the hole.



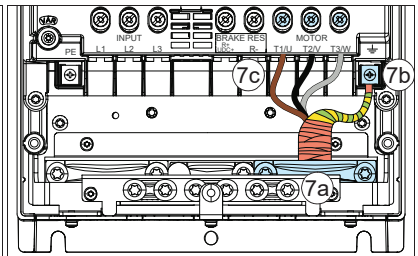
7. Connect the motor cable:

- Ground the shield 360 degrees by tightening the clamp of the power cable grounding shelf onto the stripped part of the cable. (7a)
- If you need more working space, open the screw (7d) and lift the EMC plate off. Remember to put it back after you have installed motor and input power cables.
- Connect the twisted shield of the cable to the grounding terminal. (7b)
- Connect the phase conductors of the cable to the T1/U, T2/V and T3/W terminals. Tighten the screws to the torque given in the table below (7c).

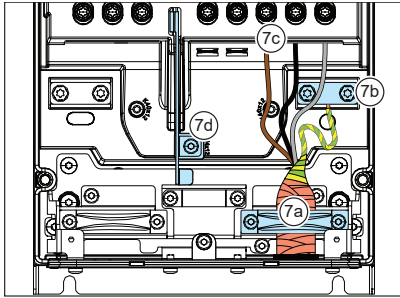
R1...R2



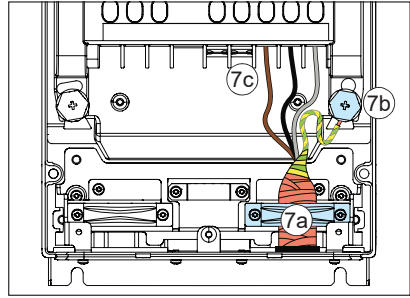
R3



R4 v2



R4

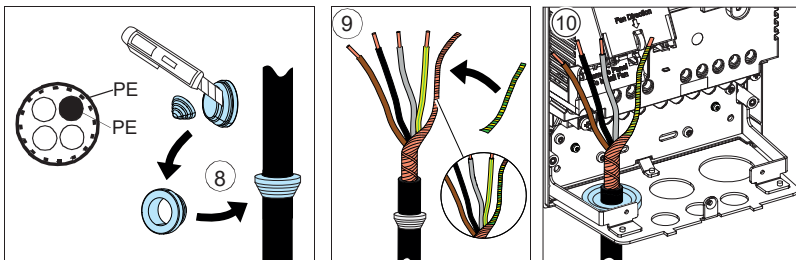


Frame size	R1		R2		R3		R4	
	N-m	lbf-ft	N-m	lbf-ft	N-m	lbf-ft	N-m	lbf-ft
T1/U, T2/V, T3/W	1.0	0.7	1.5	1.1	3.5	2.6	4.0	3.0
PE,	1.5	1.1	1.5	1.1	1.5	1.1	2.9	2.1
	1.2	0.9	1.2	0.9	1.2	0.9	1.2	0.9

Input power cable

8. Cut an adequate hole into the rubber grommet. Slide the grommet onto the cable. **Frame R1:** Make sure there is no optional I/O extension module installed in option slot 2 at this point.
9. Prepare the ends of the cable as illustrated in the figure.

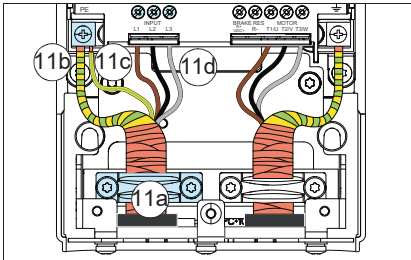
Note: The bare shield will be grounded 360 degrees. Mark the pigtail made from the shield as a PE conductor with yellow-and-green color.
10. Slide the cable through the hole in the cable entry and attach the grommet to the hole.



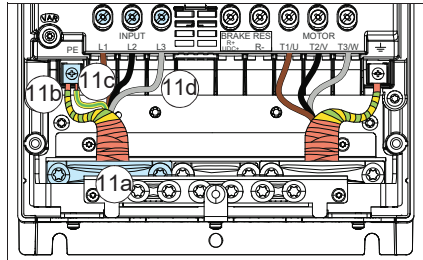
11. Connect the input power cable:

- Ground the shield 360 degrees by tightening the clamp of the power cable grounding shelf onto the stripped part of the cable (11a).
- Connect the twisted shield of the cable to the grounding terminal (11b).
- Connect the additional PE conductor of the cable (11c) (see the note in section [Additional instructions and notes \(page 23\)](#)).
- Connect the phase conductors of the cable to the L1, L2 and L3 terminals. Tighten the screws to the torque given below in the table (11d).

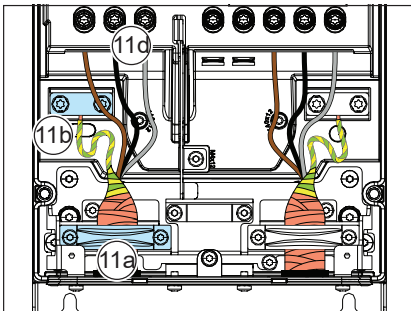
R1...R2



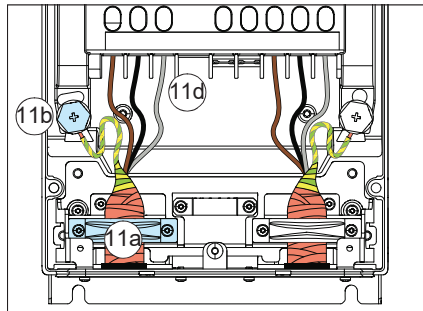
R3





R4 v2



R4



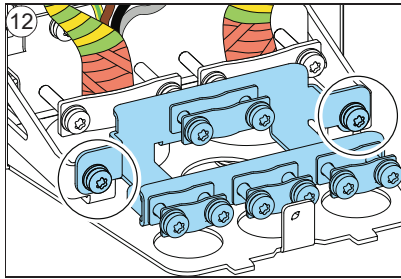
Frame size	R1		R2		R3		R4	
	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft
L1, L2, L3	1.0	0.7	1.5	1.1	3.5	2.6	4.0	3.0
PE, 	1.5	1.1	1.5	1.1	1.5	1.1	2.9	2.1
	1.2	0.9	1.2	0.9	1.2	0.9	1.2	0.9

Grounding shelf

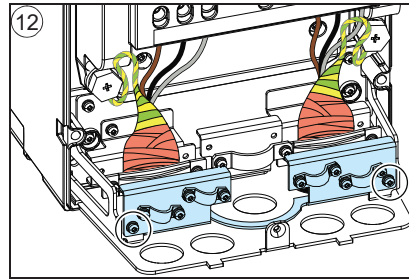
12. **Frames R1...R2, R4:** Install the grounding shelf (included with the mounting screws in a plastic bag in the delivery).



R1...R2



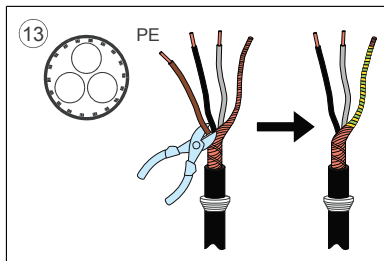
R4



Brake resistor cable (if used)

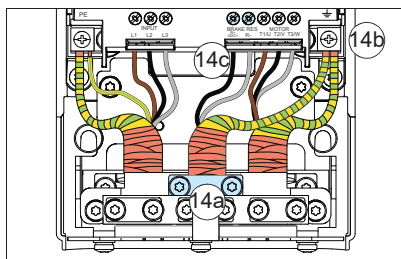
Frames R1...R3 only

13. Repeat steps 4...6 for the brake resistor cable. Cut off one phase conductor.

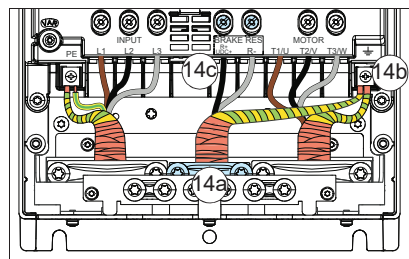




14. Connect the cable as the motor cable in step 7. Ground the shield 360 degrees (14a). Connect the twisted shield to the grounding terminal (14b) and the conductors to the R+ and R- terminals (14c) and tighten to the torque given in the table.

R1...R2



R3

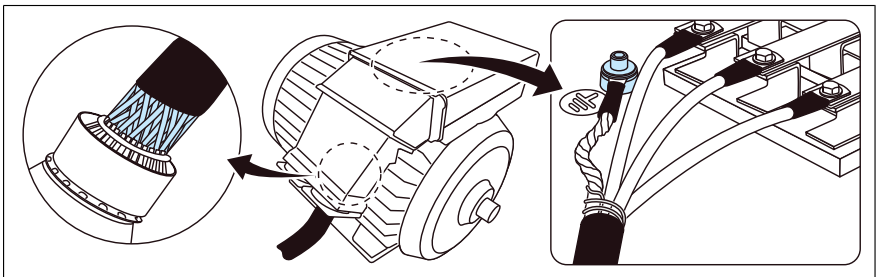


Frame size	R1		R2		R3	
	N-m	lbf-ft	N-m	lbf-ft	N-m	lbf-ft
R+, R-	1.0	0.7	1.5	1.1	3.5	2.6
PE, 	1.5	1.1	1.5	1.1	1.5	1.1
	1.2	0.9	1.2	0.9	1.2	0.9

Finalization

Note: Frame R1: You have to install any optional I/O extension module, if used, in options slot 2 at this point. See section *Installing option modules (page 153)*.

- Secure the cables outside the unit mechanically.
- Ground the motor cable shield at the motor end. For minimum radio frequency interference, ground the motor cable shield 360 degrees at the cable entry of the motor terminal box.



■ Connection procedure, frame R5

IP21 (UL Type 1)

- Remove the module cover: Loosen the retaining screws with a T20 Torx screwdriver (1a) and lift the cover from the bottom outwards (1b) and then up (1c).
Remove the box cover: Loosen the retaining screws with a screwdriver (1d) and slide the cover downwards (1e).

IP55 (UL Type 12)

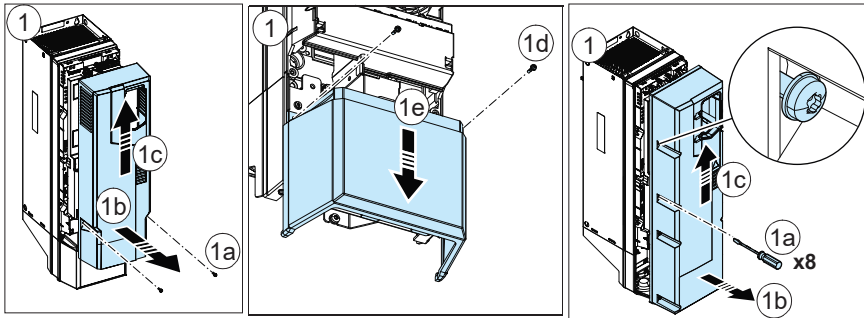
- Remove the front cover: Loosen the retaining screws with a T20 Torx screwdriver (1a) and lift the cover from the bottom outwards (1b) and then up (1c).

IP21 (UL Type 1)

IP21 (UL Type 1)

IP55 (UL Type 12)

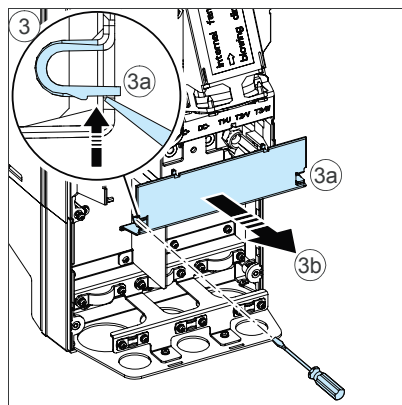
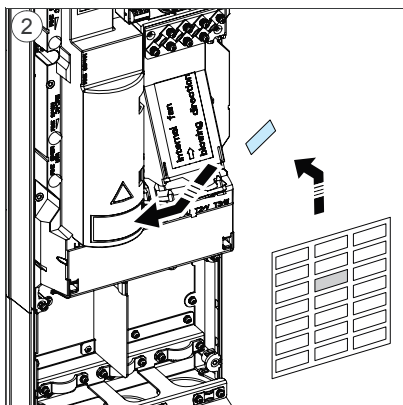




WARNING!

If you install the drive on any other system than symmetrically grounded TN-S system, see [Grounding system compatibility check \(page 115\)](#) if you have to disconnect the EMC filter and ground-to-phase varistor.

2. Attach the residual voltage warning sticker in the local language next to the control unit.
3. Remove the shroud on the power cable terminals by releasing the clips with a screwdriver (3a) and pulling the shroud out (3b).



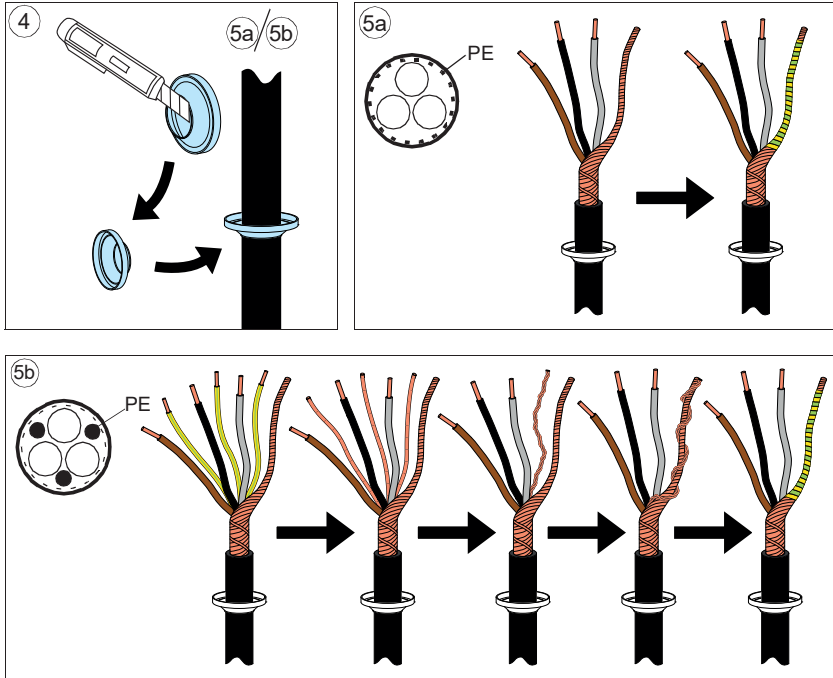
Motor cable

Use symmetrical shielded cable for motor cabling. If the cable shield is the sole PE conductor for drive or motor, make sure that it has sufficient conductivity for the PE.

4. Cut an adequate hole into the rubber grommet. Slide the grommet onto the cable.

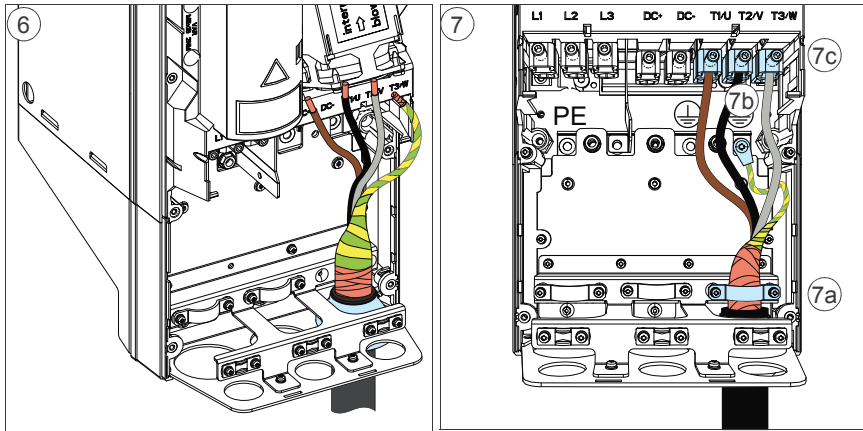
5. Prepare the ends of the motor cable as illustrated in figures 5a and 5b (two different motor cable types are shown). If you use aluminum cables, put grease to the peeled aluminum cable before connecting it to the drive.



Note: The bare shield will be grounded 360 degrees. Mark the pigtail made from the shield as a PE conductor with yellow-and-green color.



6. Slide the cable through the hole of the bottom plate and attach the grommet to the hole.
7. Connect the motor cable:
 - Ground the shield 360 degrees by tightening the clamp of the power cable grounding shelf onto the stripped part of the cable (7a).
 - Connect the twisted shield of the cable to the grounding terminal (7b).
 - Connect the phase conductors of the cable to the T1/U, T2/V and T3/W terminals (7c). Tighten the screws to the torque given in the table.

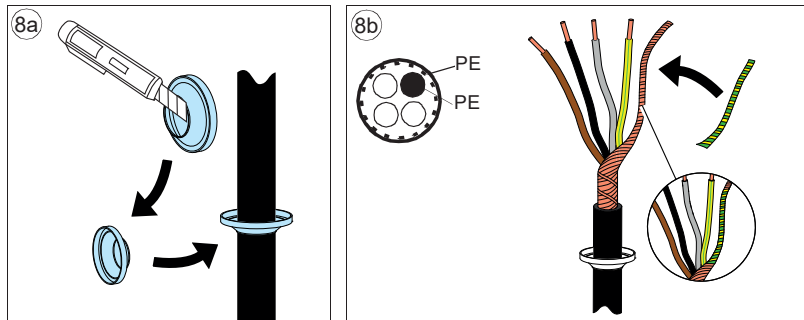




Frame size	T1/U, T2/V, T3/W		PE, 				
	N·m	lbf·ft	M	N·m	lbf·ft	N·m	lbf·ft
R5	5.6	4.1	M5	2.2	1.6	1.2	0.9

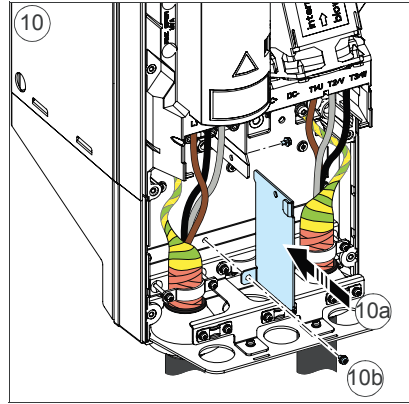
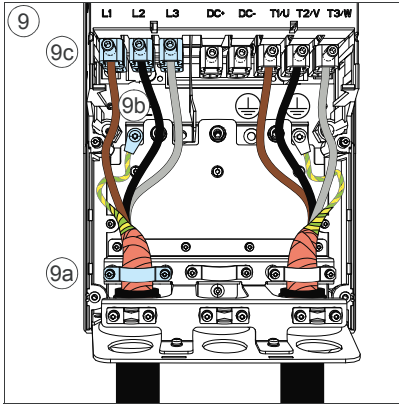
Input power cable



8. Repeat steps 4...6 for the input power cable



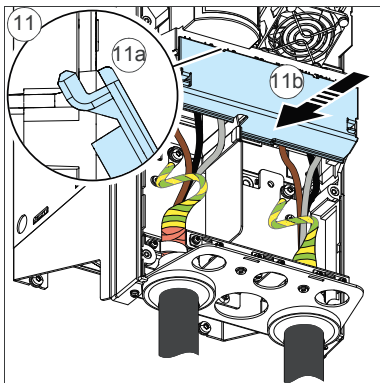
9. Connect the input power cable. Use terminals L1, L2 and L3. Tighten the screws to the torque given in the table.

10. Install the cable box plate. Position the plate (10a) and tighten the screw (10b).



Frame size	L1, L2, L3		PE, 				
	N·m	lbf·ft	M	N·m	lbf·ft	N·m	lbf·ft
R5	5.6	4.1	M5	2.2	1.6	1.2	0.9

11. Reinstall the shroud on the power terminals by putting the tabs at the top of the shroud in their counterparts on the drive frame (11a) and then pressing the shroud in place (11b).

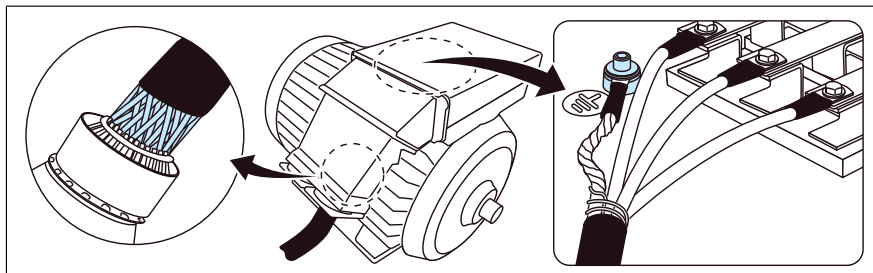


Finalization

12. Secure the cables outside the unit mechanically.



- Ground the motor cable shield at the motor end. For minimum radio frequency interference, ground the motor cable shield 360 degrees at the cable entry of the motor terminal box.



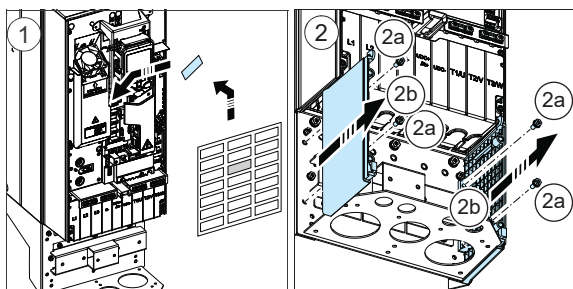
■ Connection procedure, frames R6...R9



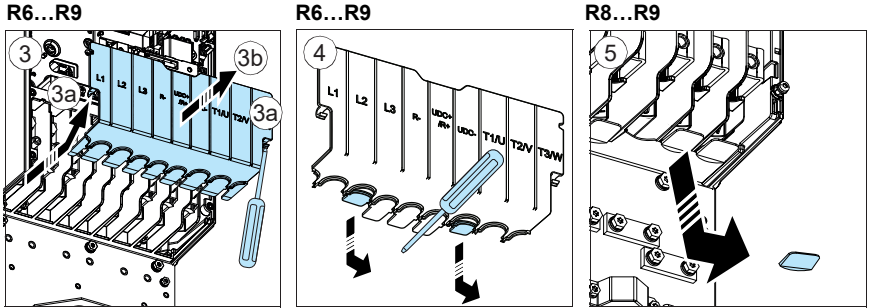
WARNING!

If you install the drive on any other system than symmetrically grounded TN-S system, see [Grounding system compatibility check \(page 115\)](#) if you have to disconnect the EMC filter and ground-to-phase varistor.

- Attach the residual voltage warning sticker in the local language next to the control unit.
- Remove the side plates of the cable box: Remove the retaining screws (2a) and slide the walls out (2b).



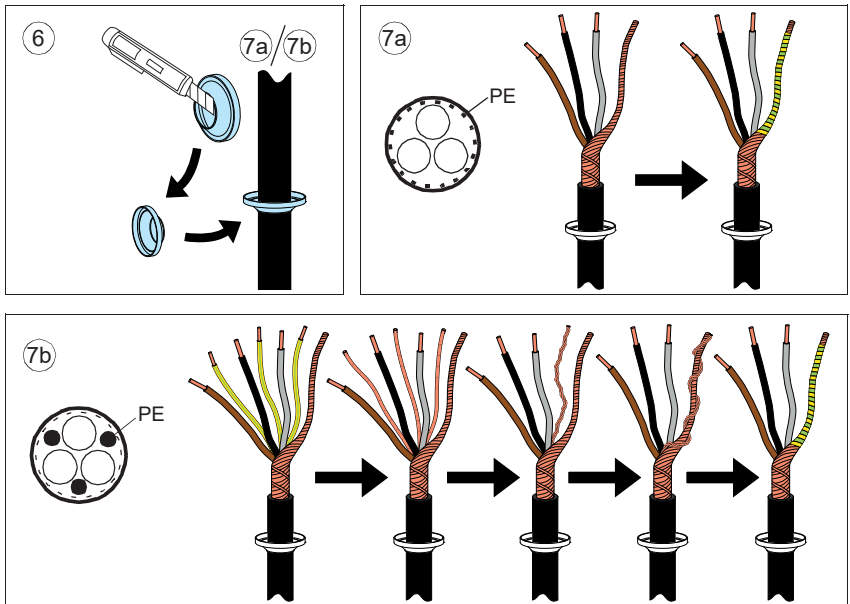
- Remove the shroud on the power cable terminals by releasing the clips with a screwdriver (3a) and pulling the shroud out (3b).
- Knock out holes in the shroud for the cables to be installed.
- Frames R8...R9: If you install parallel cables, also knock out holes in the lower shroud for the cables to be installed.



Motor cable

6. Cut an adequate hole into the rubber grommet. Slide the grommet onto the cable.
7. Prepare the ends of the input power cable and motor cable as illustrated in the figure. If you use aluminum cables, put grease to the peeled aluminum cable before connecting it to the drive. Two different motor cable types are shown in the figures (7a, 7b).

Note: The bare shield will be grounded 360 degrees. Mark the pigtail made from the shield as a PE conductor with yellow-and-green color.



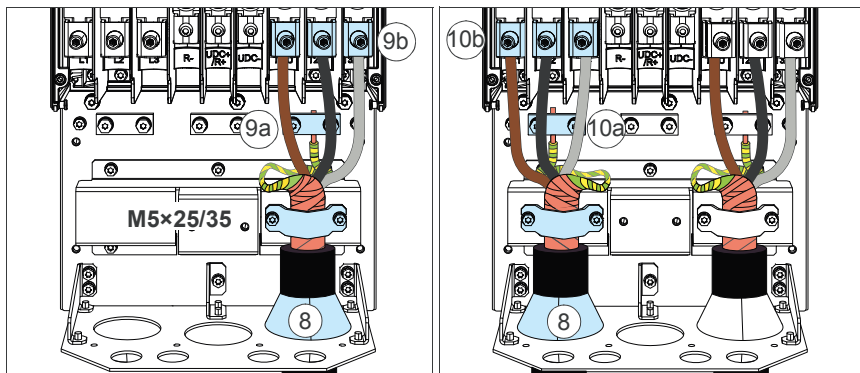
8. Slide the cables through the holes in the cable entry and attach the grommets to the holes (the motor cable to the right and the input power cable to the left).
9. Connect the motor cable:
 - Ground the shield 360 degrees under the grounding clamps.
 - Connect the twisted shield of the cable to the grounding terminal (9a).
 - Connect the phase conductors of the cable to terminals T1/U, T2/V and T3/W. Tighten the screws to the torque given in the table (9b).

Note 1 for frames R8...R9: If you connect only one conductor to the connector, ABB recommends that you put it under the upper pressure plate. If you use parallel power cables, put the first conductor under the lower pressure plate and the second under the upper one.

Note 2 for frames R8...R9: The connectors are detachable but ABB does not recommend that you detach them. If you do, detach and reinstall the connectors as described in *Detaching and reinstalling the connectors (page 136)*.

Input power cable

10. Connect the input power cable as in step 9. Use terminals L1, L2, L3.



Frame size	L1, L2, L3, T1/U, T2/V, T3/W		PE,			
	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft
R6	30	22	9.8	7.2	1.2	0.9
R7	40	30	9.8	7.2	1.2	0.9
R8	40	30	9.8	7.2	1.2	0.9
R9	70	52	9.8	7.2	1.2	0.9

Detaching and reinstalling the connectors

This is possible but not recommended.

Terminals T1/U, T2/V and T3/W

- Remove the nut that attaches the connector to its busbar.
- Put the conductor under the connector pressure plate and pre-tighten the conductor.
- Put the connector back to its busbar. Start the nut, and turn it at least two rotations by hand.



WARNING!

Before using tools, make sure that the nut/screw is not cross-threading. Cross-threading will damage the drive and cause danger.

- Tighten the nut to a torque of 30 N·m (22 lbf·ft).
- Tighten the conductor(s) to 40 N·m (30 lbf·ft) for frame R8 or to 70 N·m (52 lbf·ft) for frame R9.

Terminals L1, L2 and L3

- Remove the combi screw that attaches the connector to its terminal post, and pull the connector off.
- Put the conductor under the connector pressure plate and pre-tighten the conductor.
- Put the connector back onto the terminal post. Start the combi screw, and turn it at least two rotations by hand.



WARNING!

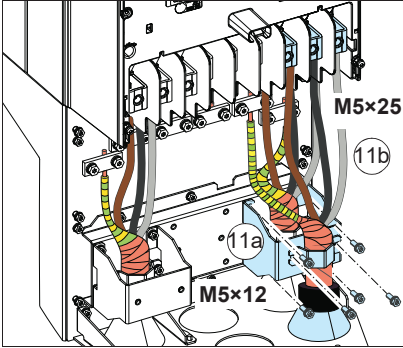
Before using tools, make sure that the nut/screw is not cross-threading. Cross-threading will damage the drive and cause danger.

- Tighten the combi screw to a torque of 30 N·m (22 lbf·ft).
- Tighten the conductor(s) to 40 N·m (30 lbf·ft) for frame R8 or to 70 N·m (52 lbf·ft) for frame R9.

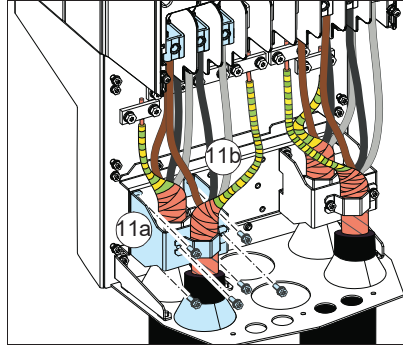
11. Frames R8...R9: If you install parallel cables, install the second grounding shelf for the parallel power cables (11a). Repeat steps 6...11 (11b).



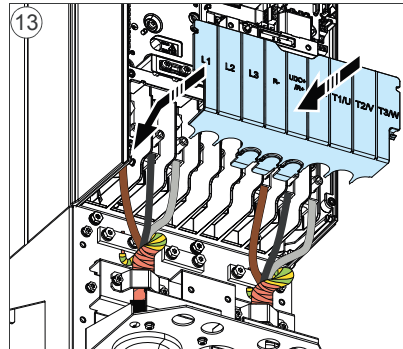
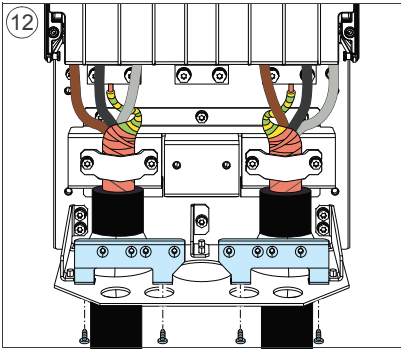
R8...R9



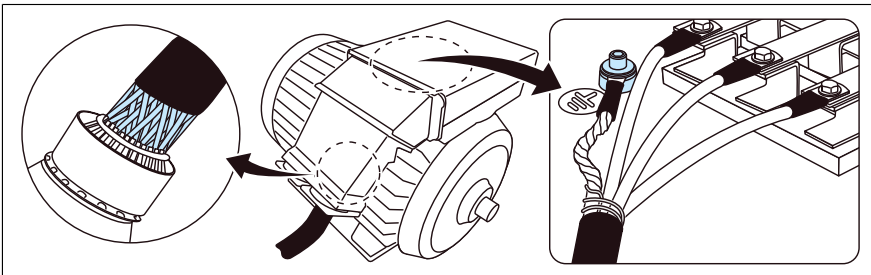
R8...R9



12. Install the grounding shelf of the control cables.
13. Reinstall the shroud on the power terminals.
14. Secure the cables outside the unit mechanically.



15. Ground the motor cable shield at the motor end. For minimum radio frequency interference, ground the motor cable shield 360 degrees at the cable entry of the motor terminal box.



DC connection

The UDC+ and UDC- terminals (as standard in frames R4...R9) are for using external brake chopper units.



Connecting the control cables

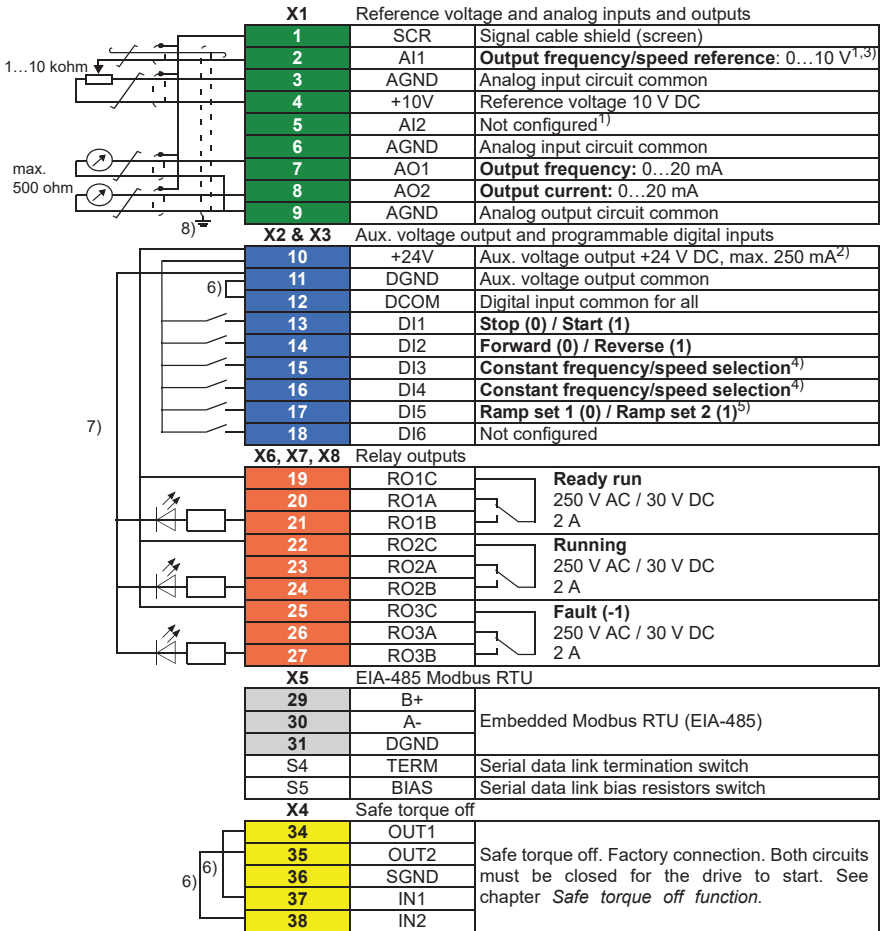
See [Default I/O connection diagram \(ABB standard macro\) \(page 141\)](#) for the default I/O connections of the ABB standard macro. For other macros, see ACS580 firmware manual (3AXD50000016097 [English]).

Connect the cables as described under [Control cable connection procedure R1...R9 \(page 148\)](#).



■ **Default I/O connection diagram (ABB standard macro)**

R1...R5



Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V DC).

Digital inputs DI1...DI5 also support 10 to 24 V AC.

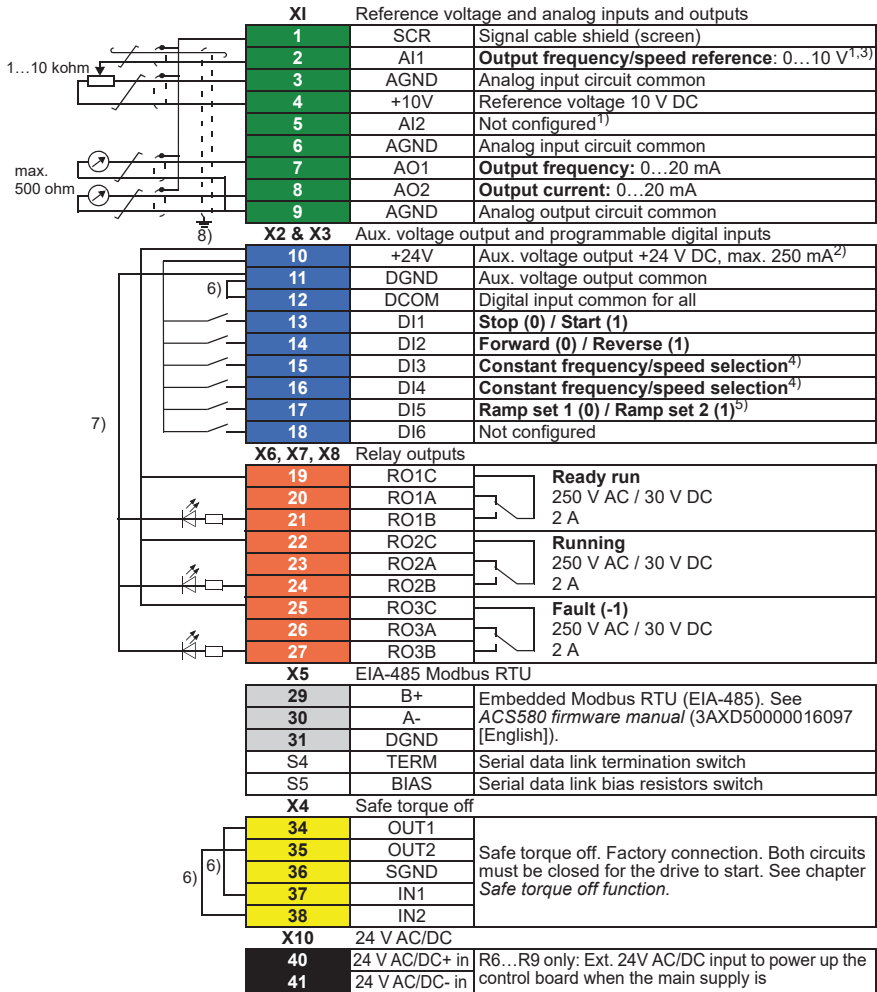
Wire sizes:

0.2...2.5 mm² (24...14 AWG): Terminals +24V, DGND, DCOM, B+, A-, DGND, Ext. 24V

0.14...1.5 mm² (26...16 AWG): Terminals DI, AI, AO, AGND, RO, STO

Tightening torques: 0.5...0.6 N·m (0.4 lbf·ft)

R6...R9



Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V DC).

Digital inputs DI1...DI5 also support 10 to 24 V AC.

Wire sizes: 0.14...2.5 mm² (26...14 AWG): All terminals

Tightening torques: 0.5...0.6 N·m (0.4 lbf·ft)

Notes:

1) Current [0(4)...20 mA, $R_{in} = 100 \text{ ohm}$] or voltage [0(2)...10 V, $R_{in} > 200 \text{ kohm}$]. Change of setting requires changing the corresponding parameter.

2) Total load capacity of the Auxiliary voltage output +24 V (X2:10) is 6.0 W (250 mA / 24 V).

3) AI1 is used as a speed reference if vector control is selected.

4) In scalar control (default): See **Menu > Primary settings > Start, stop, reference > Constants speeds / constant frequencies** or parameter group 28 Frequency reference chain.

In vector control: See **Menu > Primary setting > Start, stop, reference > Constant speeds / constant frequencies** or parameter group 22 Speed reference selection.

DI3	DI4	Operation/Parameter	
		Scalar control (default)	Vector control
0	0	Set frequency through AI1	Set speed through AI1
1	0	28.26 Constant frequency 1	22.26 Constant speed 1
0	1	28.27 Constant frequency 2	22.27 Constant speed 2
1	1	28.28 Constant frequency 3	22.28 Constant speed 3

5) In scalar control (default): See **Menu > Primary settings > Ramps** or parameter group 28 Frequency reference chain.

In vector control: See **Menu > Primary settings > Ramps** or parameter group 23 Speed reference ramp.

DI5	Ramp set	Parameters	
		Scalar control (default)	Vector control
0	1	28.72 Freq acceleration time 1 28.73 Freq deceleration time 1	23.12 Acceleration time 1 23.13 Deceleration time 1
1	2	28.74 Freq acceleration time 2 28.75 Freq deceleration time 2	23.14 Acceleration time 2 23.15 Deceleration time 2





6) Connected with jumpers at the factory.

7) Use shielded twisted-pair cables for digital signals.

8) Ground the outer shield of the cable 360 degrees under the grounding clamp on the grounding shelf for the control cables.

Further information on the usage of the connectors and switches is given in the sections below. See also section [Control connection data \(page 291\)](#).

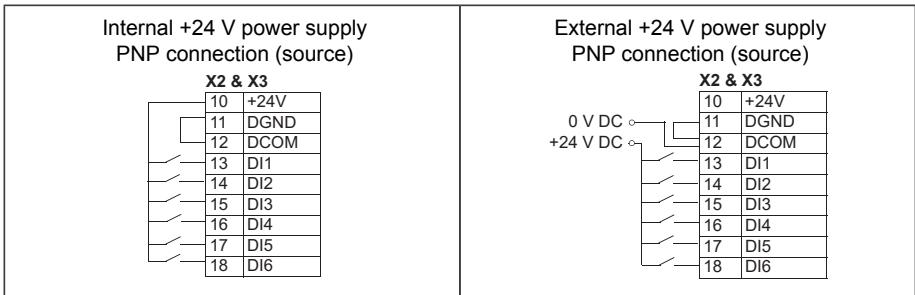
Switches


Switch	Description	Position	
S4 (TERM)	Modbus link termination. Must be set to the terminated (ON) position when the drive is the first or last unit on the link.		Bus not terminated (default)
			Bus terminated
S5 (BIAS)	Activates on the biasing voltages to the bus. One (and only one) device, preferably at the end of the bus must have the bias on.		Bias off (default)
			Bias on

■ **Additional information on I/O connections**

PNP configuration for digital inputs

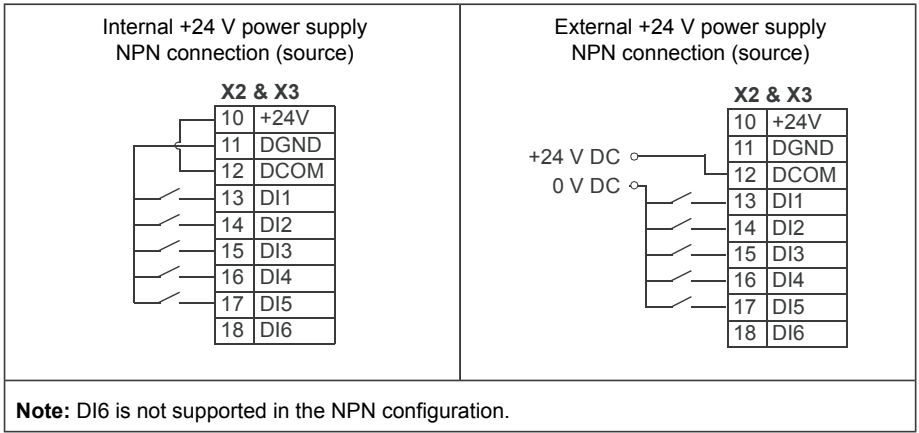
Internal and external +24 V power supply connections for PNP configuration are shown in the figure below.



 **WARNING!** Do not connect the +24 V AC cable to the control unit ground when the control unit is powered from an external 24 V AC supply.

NPN configuration for digital inputs

Internal and external +24 V power supply connections for NPN configuration are shown in the figure below.

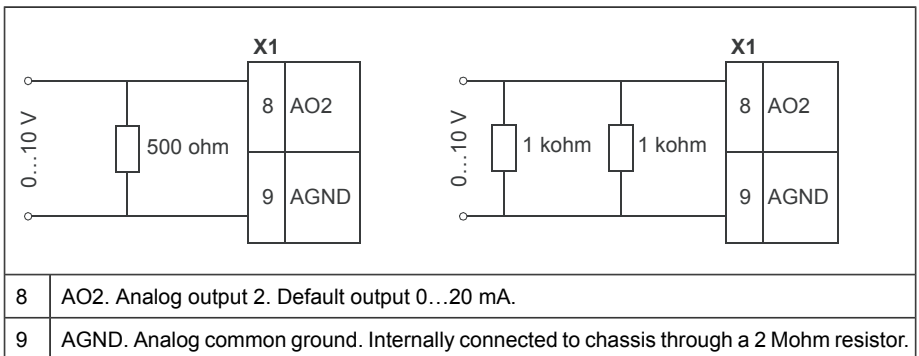


⚡ WARNING! Do not connect the +24 V AC cable to the control unit ground when the control unit is powered from an external 24 V AC supply.

Connection for obtaining 0...10 V from analog output 2 (AO2)

To obtain 0...10 V from analog output AO2, connect a 500 ohm resistor (or two 1 kohm resistors in parallel) between the analog output 2 AO2 and analog common ground AGND.

Examples are shown in the figure below.



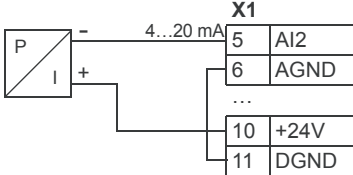
Connection examples of two-wire and three-wire sensors

Hand/Auto, Hand/PID, and PID macros (see *ACS580 firmware manual* (3AXD50000016097 [English])) use analog input 2 (AI2). The macro wiring diagrams on these pages use an externally powered sensor (connections not shown). The figures

below give examples of connections using a two-wire or three-wire sensor/transmitter supplied by the drive auxiliary voltage output.

Note: Maximum capability of the auxiliary 24 V DC (250 mA) output must not be exceeded.

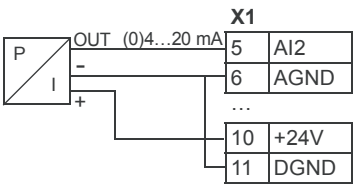
Two-wire sensor/transmitter



5	AI2	Process actual value measurement or reference, 0(4)...20 mA, $R_{in} = 100$ ohm
6	AGND	
10	+24V	Auxiliary voltage output, non-isolated, +24 V DC, max. 250 mA
11	DGND	

Three-wire sensor/transmitter

Note: The sensor is supplied through its current output and the drive feeds the supply voltage (+24 V DC). Thus the output signal must be 4...20 mA, not 0...20 mA.



5	AI2	Process actual value measurement or reference, 0(4)...20 mA, $R_{in} = 100$ ohm
6	AGND	
10	+24V	Auxiliary voltage output, non-isolated, +24 V DC, max. 250 mA
11	DGND	

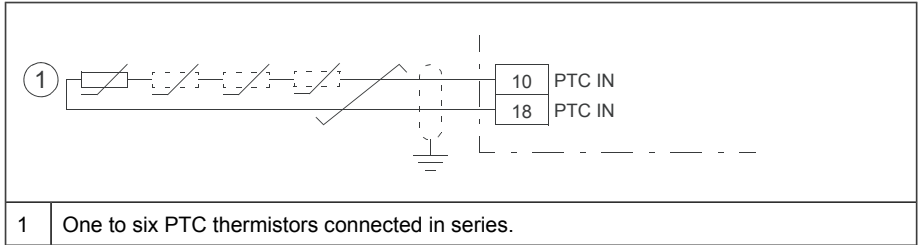
DI5 as frequency input

For setting the parameters for the digital frequency input, see *ACS580 standard control program firmware manual* (3AXD5000016097 [English]).

DI6 as PTC input

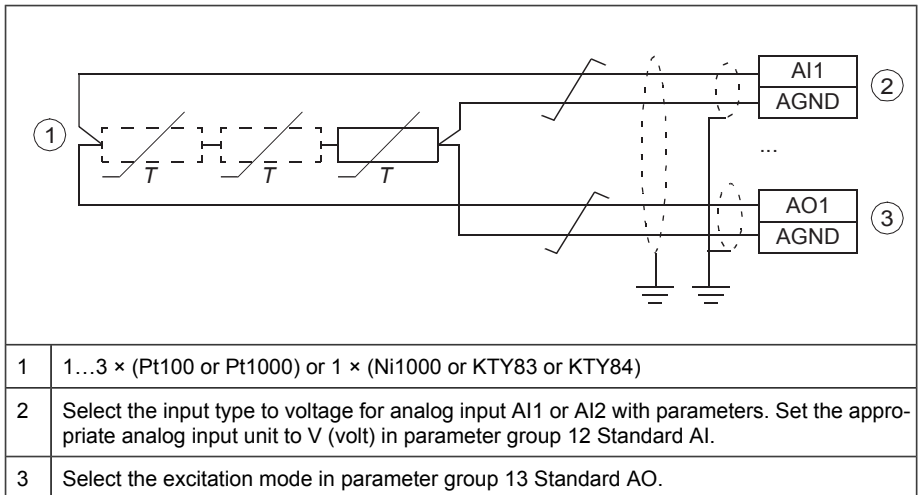
If DI6 is used as a PTC input, see *ACS580 standard control program firmware manual* (3AXD50000016097 [English]) for how to set parameters accordingly.

Note: If DI6 is used as PTC input, the wiring and the PTC sensor need to be double isolated. Otherwise the CMOD-02 I/O extension module must be used.



AI1 and AI2 as Pt100, Pt1000, Ni1000, KTY83 and KTY84 sensor inputs (X1)

One, two or three Pt100 sensors; one, two or three Pt1000 sensors; or one Ni1000, KTY83 or KTY84 sensor for motor temperature measurement can be connected between an analog input and output as shown below. Do not connect both ends of the cable shields directly to ground. If a capacitor cannot be used at one end, leave that end of the shield unconnected.



WARNING!

As the inputs pictured above are not insulated according to IEC 60664, the connection of the motor temperature sensor requires double or reinforced insulation between motor live parts and the sensor. If the assembly does not fulfill the requirement, the I/O board terminals must be protected against contact and must

not be connected to other equipment or the temperature sensor must be isolated from the I/O terminals.

Safe torque off (X4)

For the drive to start, both connections (+24 V DC to IN1 and +24 V DC to IN2) must be closed. By default, the terminal block has jumpers to close the circuit. Remove the jumpers before connecting an external Safe torque off circuitry to the drive. See chapter [The Safe torque off function \(page 347\)](#).

Note: Only 24 V DC can be used for STO. Only PNP input configuration can be used.

■ Control cable connection procedure R1...R9



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

-
1. Do the steps in section [Electrical safety precautions \(page 22\)](#) before you start the work.
 2. Remove the front cover(s) if not already removed. See page [123](#) (R1...R4), page [129](#) (R5) or page [81](#) (R6...R9).

Analog signals

The figures for frames R1...R2 and R3 (page [150](#)), R4 (page [151](#)), R5 (page [152](#)) and R6...R9 (page [153](#)) show an example of connecting a cable. Make the connections according to the macro in use.

3. Cut an adequate hole into the rubber grommet and slide the grommet onto the cable. Slide the cable through a hole in the cable entry and attach the grommet to the hole.
4. Ground the outer shield of the cable 360 degrees under the grounding clamp. Keep the cable unstripped as close to the terminals of the control unit as possible.
Frames R5...R9: Secure the cables mechanically at the clamps below the control unit.
Ground also the pair-cable shields and grounding wire at the SCR terminal.
5. Route the cable as shown in the figures for frames R1...R2 and R3 (page [150](#)), R4 (page [151](#)), R5 (page [152](#)) and R6...R9 (page [153](#)).
6. Connect the conductors to the appropriate terminals of the control unit and tighten to 0.5...0.6 N·m (0.4 lbf-ft).

Digital signals

The figures for frames R1...R2 and R3 (page [150](#)), R4 (page [151](#)), R5 (page [152](#)) and R6...R9 (page [153](#)) show an example of connecting a cable. Make the connections according to the macro in use.

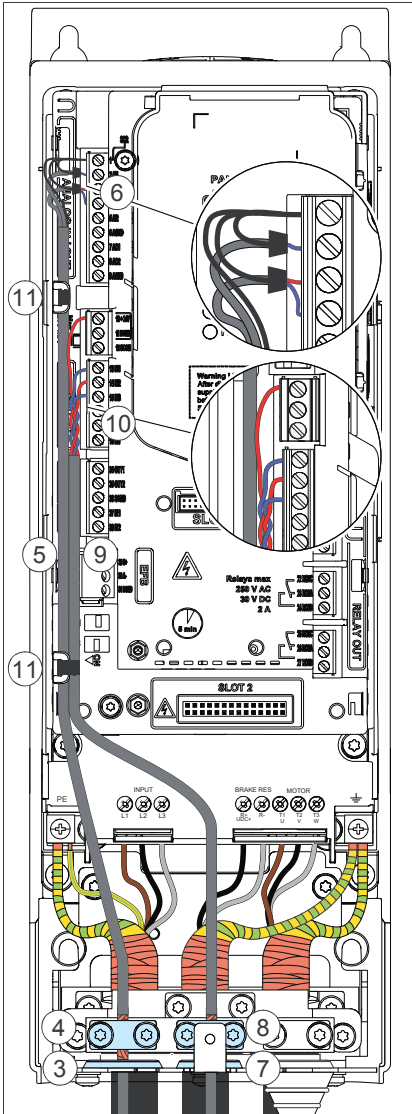
7. Cut an adequate hole into the rubber grommet and slide the grommet onto the cable. Slide the cable through the hole in the cable entry and attach the grommet to the hole.
8. Ground the outer shield of the cable 360 degrees under the grounding clamp. Keep the cable unstripped as close to the terminals of the control unit as possible.
Frames R5...R9: Secure the cables mechanically at the clamps below the control unit.
If you use double-shielded cables, ground also the pair-cable shields and grounding wire at the SCR terminal.
9. Route the cable as shown in the figures for frames R1...R2 and R3 (page 150), R4 (page 151), R5 (page 152) and R6...R9 (page 153).
10. Connect the conductors to the appropriate terminals of the control unit and tighten to 0.5...0.6 N·m (0.4 lbf·ft).
11. Tie all control cables to the provided cable tie mounts.

Note:

- Leave the other ends of the control cable shields unconnected or ground them indirectly via a high-frequency capacitor with a few nanofarads, eg, 3.3 nF / 630 V. The shield can also be grounded directly at both ends if they are in the same ground line with no significant voltage drop between the end points.
- Keep any signal wire pairs twisted as close to the terminals as possible. Twisting the wire with its return wire reduces disturbances caused by inductive coupling.

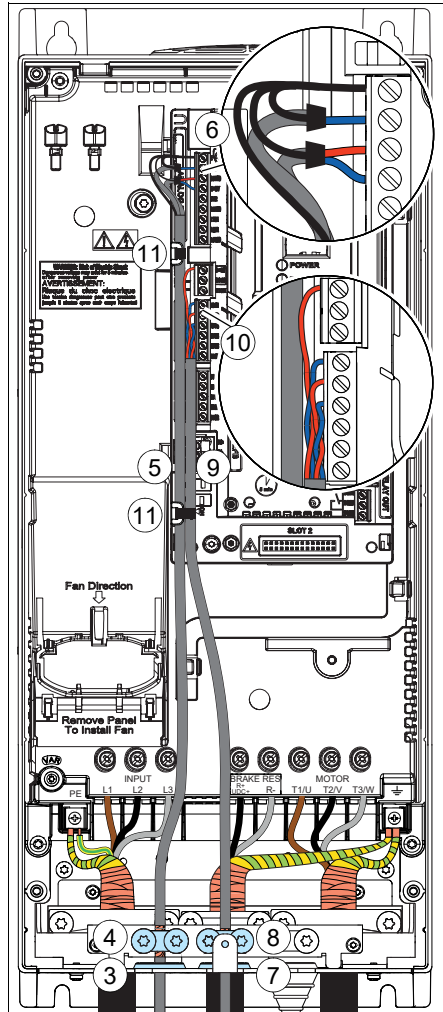


R1...R2



R1...R2: 0.5...0.6 N·m (0.4 lbf·ft)

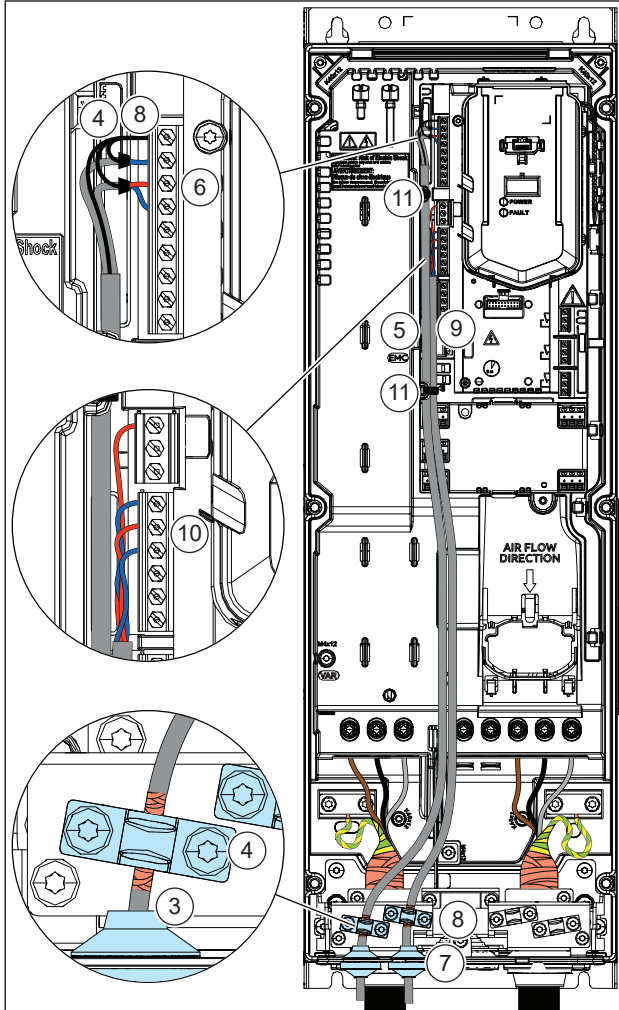
R3



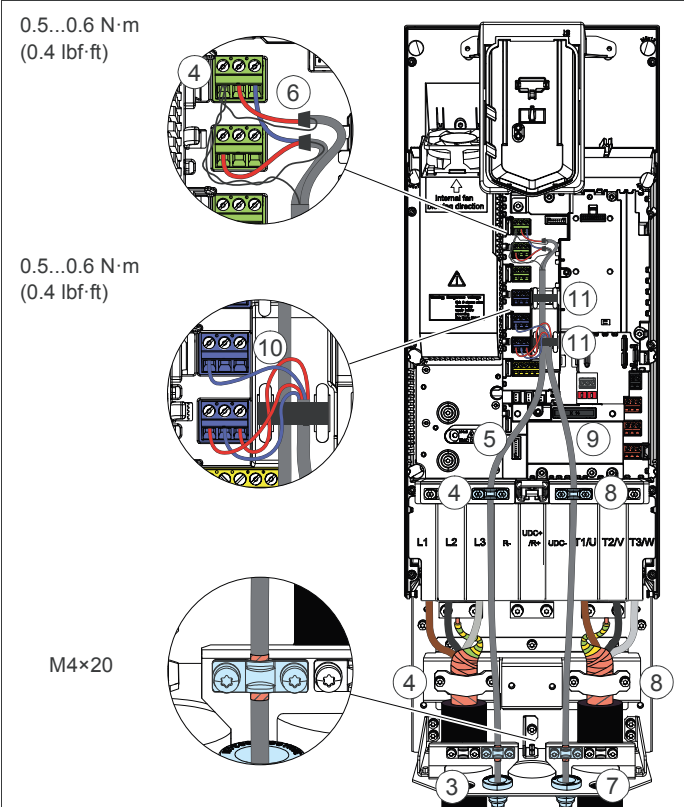
R3: 0.5...0.6 N·m (0.4 lbf·ft)



R4



R6...R9



Installing option modules



WARNING!

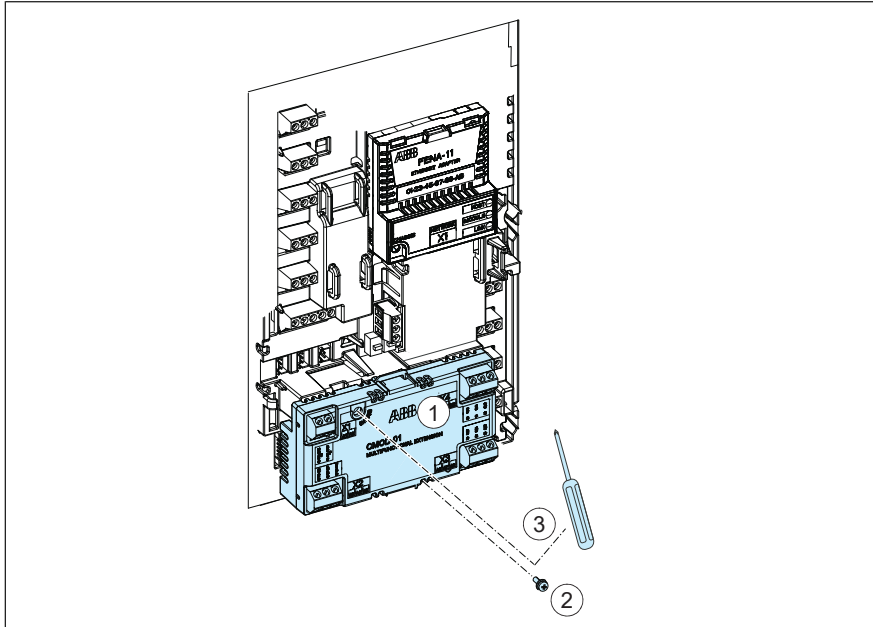
Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.



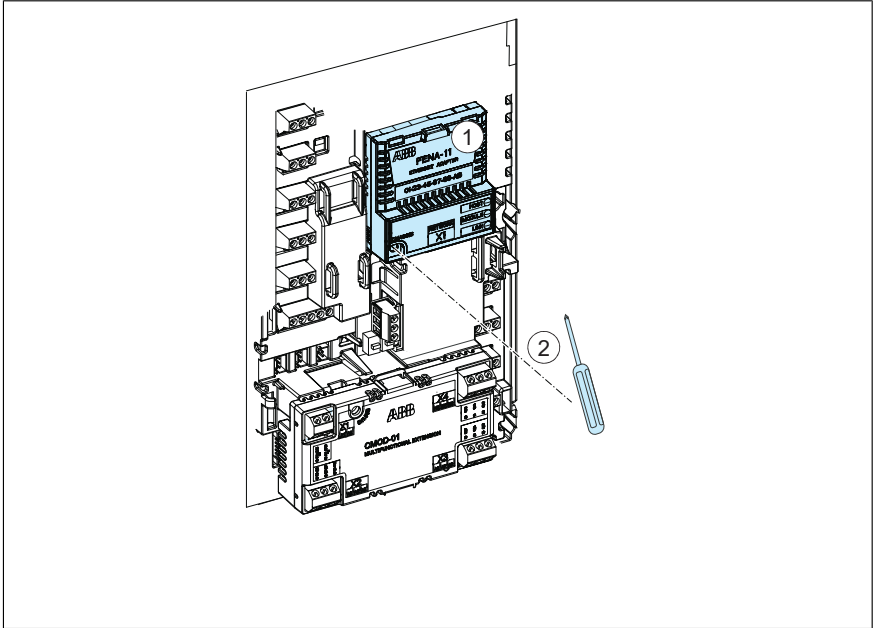
■ Option slot 2 (I/O extension modules)

1. Put the module carefully into its position on the control unit.
2. Tighten the mounting screw.
3. Tighten the grounding screw (CHASSIS) to 0.8 N·m (7 lbf·in). The screw grounds the module. It is necessary for fulfilling the EMC requirements and for correct operation of the module.



■ Option slot 1 (fieldbus adapter modules)

1. Put the module carefully into its position on the control unit.
2. Tighten the mounting screw (CHASSIS) to 0.8 N·m (7 lbf·in). The screw tightens the connections and grounds the module. It is necessary for fulfilling the EMC requirements and for correct operation of the module.



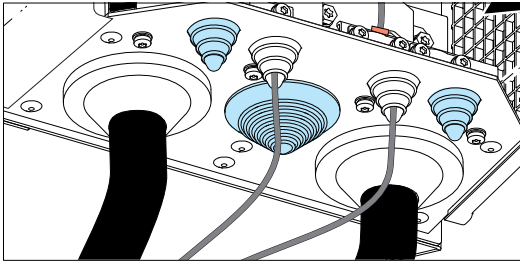
■ Wiring the optional modules

See the appropriate option module manual or for I/O options the appropriate chapter in this manual.



Reinstalling grommets

UL Type 12: To maintain UL Type 12, reinstall grommets (top of the grommets downwards) to all cable entry holes without conduits.

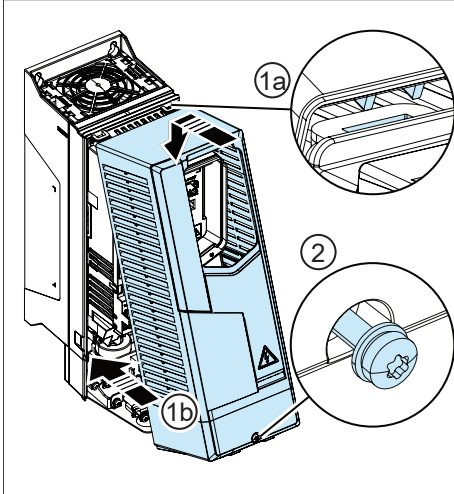


Reinstalling covers

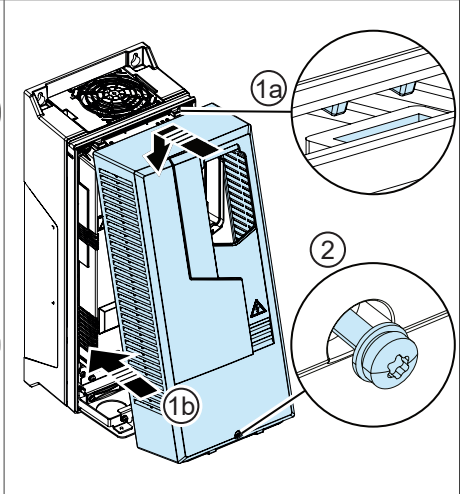
■ Reinstalling cover, frames R1...R4

1. Reinstall the cover: Put the tabs on the cover top in their counterparts on the housing (1a) and then press the cover (1b).
2. Tighten the retaining screw at the bottom with a T20 Torx screwdriver.

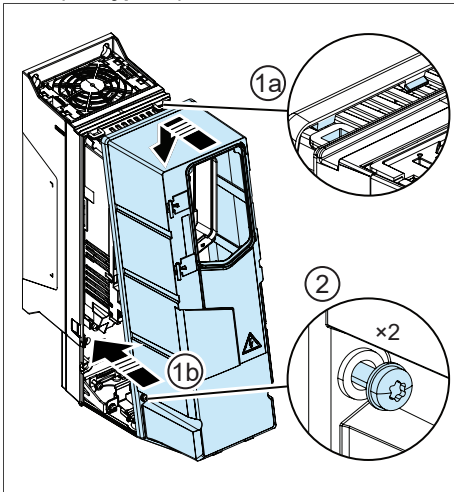
IP21 (UL Type 1) R1...R2



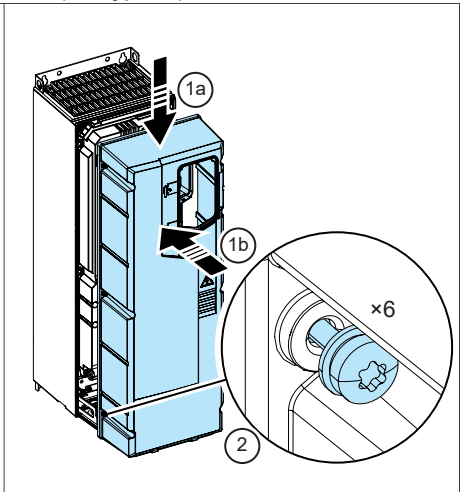
IP21 (UL Type 1) R3...R4



IP55 (UL Type 12) R1...R3



IP55 (UL Type 12) R4



■ Reinstalling covers, frame R5

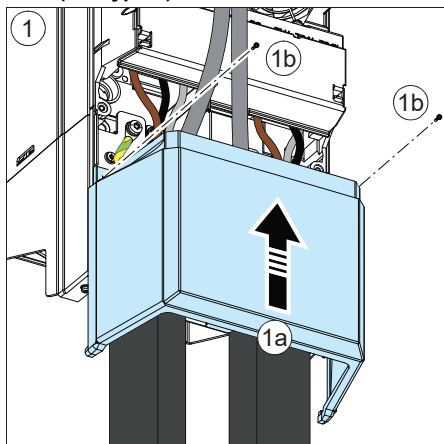
IP21 (UL Type 1)

1. Reinstall the box cover: Slide the cover upwards (1a) and tighten the retaining screws (1b) with a T20 Torx screwdriver.
2. Reinstall the module cover: Press the cover at the bottom (2a) and tighten the retaining screws (2b).

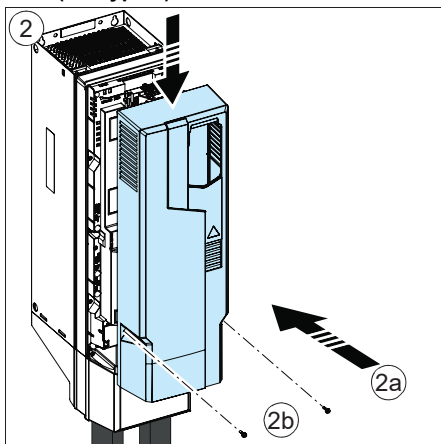
IP55 (UL Type 12)

1. Reinstall the front cover: Press the cover at the bottom (1a) and tighten the retaining screws (1b) with a T20 Torx screwdriver.

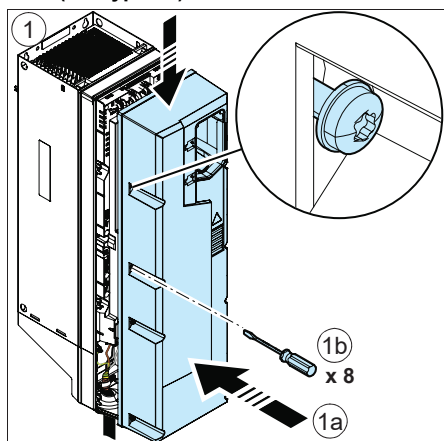
IP21 (UL Type 1)



IP21 (UL Type 1)



IP55 (UL Type 12)



■ Reinstalling side plates and covers, frames R6...R9

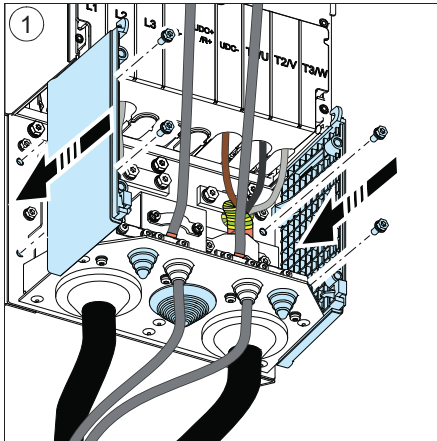
IP21 (UL Type 1)

1. Reinstall the side plates of the cable box. Tighten the retaining screws with a T20 Torx screwdriver.
2. Slide the cover of the cable box on the module from below until the cover snaps into place.
3. Reinstall the module cover. Tighten the two retaining screws with a screwdriver.

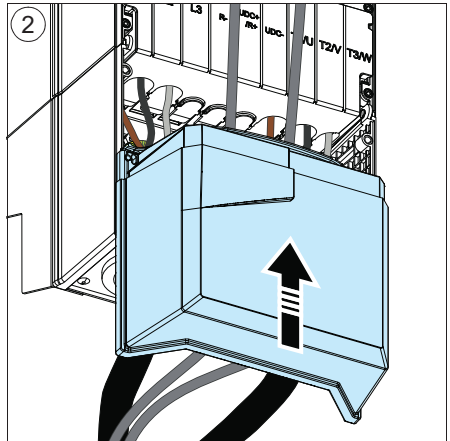
IP55 (UL Type 12)

1. Reinstall the module cover. Tighten the retaining screws with a T20 Torx screwdriver.

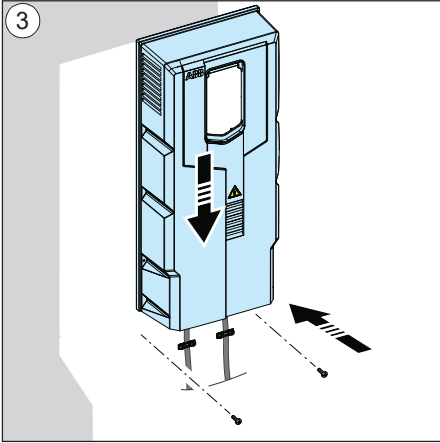
IP21 (UL Type 1)



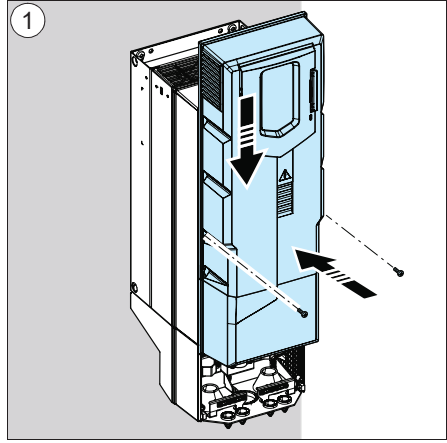
IP21 (UL Type 1)



IP21 (UL Type 1)



IP55 (UL Type 12)



Connecting a PC



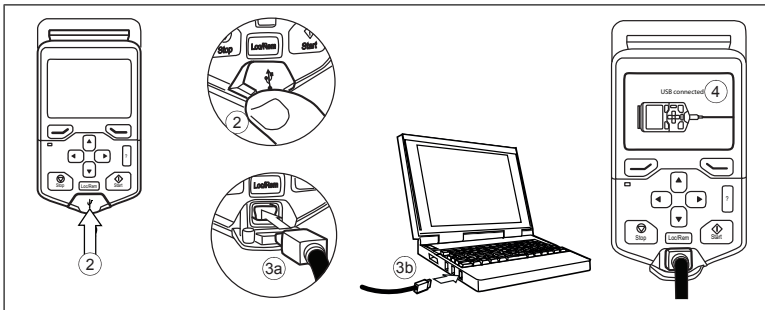
WARNING!

Do not connect the PC directly to the control panel connector of the control unit as this can cause damage.



A PC (with eg, the Drive composer PC tool) can be connected as follows:

1. Connect a ACS-AP-... or ACH-AP-... control panel to the unit either
 - by inserting the control panel into the panel holder or platform, or
 - by using an Ethernet (eg, Cat 5e) networking cable.
2. Remove the USB connector cover on the front of the control panel.
3. Connect an USB cable (Type A to Type Mini-B) between the USB connector on the control panel (3a) and a free USB port on the PC (3b).
4. The panel will display an indication whenever the connection is active.
5. See the documentation of the PC tool for setup instructions.



Connecting a remote panel, or chaining one panel to several drives

You can connect a drive control panel remotely to the drive, or chain the control panel or a PC to several drives on a panel bus with a CDPI-01 communication adapter module. See *CDPI-01 communication adapter module user's manual* ([3AXD50000009929](https://www.aegiautomation.com/3AXD50000009929) [English]).



7

Electrical installation – North America

Contents of this chapter

This chapter describes how to:

- measure the insulation
- do the grounding system compatibility check
- change the EMC filter or ground-to-phase varistor connection
- connect the power and control cables
- install optional modules
- connect a PC.

Warnings



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.



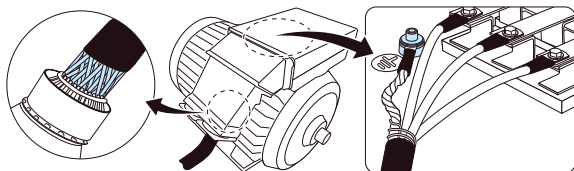
Required tools

To do the electrical installation, you need these tools:

- wire stripper
- screwdriver set (Torx, flat and/or Phillips, as appropriate)
- torque wrench.

Grounding the motor cable shield at the motor end

For minimum radio-frequency interference, ground the cable shield 360 degrees at the cable entry of the motor terminal box.



Measuring the insulation

Measuring the insulation is typically not required in North American installations.

■ Measuring the insulation resistance of the drive



WARNING!

Do not do any voltage withstand or insulation resistance tests on any part of the drive as testing can damage the drive. Every drive has been tested for insulation between the main circuit and the chassis at the factory. Also, there are voltage-limiting circuits inside the drive which cut down the testing voltage automatically.

■ Measuring the insulation resistance of the input power cable

Before you connect the input power cable to the drive, measure its insulation resistance according to local regulations.

■ Measuring the insulation resistance of the motor and motor cable

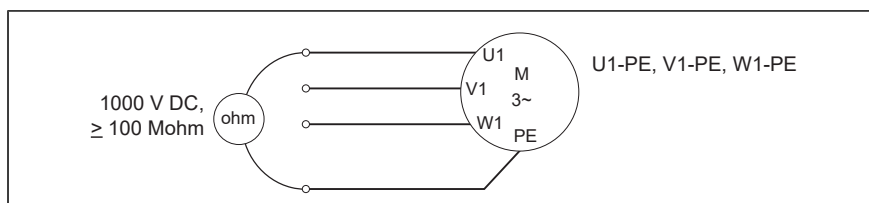


WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.

1. Do the steps in section *Electrical safety precautions (page 22)* before you start the work.
2. Make sure that the motor cable is disconnected from the drive output terminals.
3. Measure the insulation resistance between each phase conductor and the protective earth conductor. Use a measuring voltage of 1000 V DC. The insulation resistance of an ABB motor must be more than 100 Mohm (reference value at 25 °C [77 °F]). For the insulation resistance of other motors, refer to the manufacturer's instructions.

Note: Moisture inside the motor reduces the insulation resistance. If you think that there is moisture in the motor, dry the motor and do the measurement again.



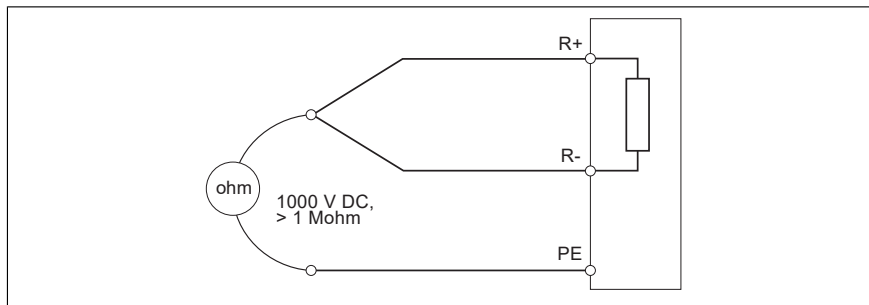
■ Brake resistor assembly for R1...R3



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.

1. Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.
2. Make sure that the resistor cable is connected to the resistor and disconnected from the drive output terminals.
3. At the drive end, connect the R+ and R- conductors of the resistor cable together. Measure the insulation resistance between the conductors and the PE conductor with a measuring voltage of 1000 V DC. The insulation resistance must be more than 1 Mohm.



Grounding system compatibility check

The standard drive can be installed to a symmetrically grounded TN-S system. For other systems, see sections [EMC filter](#) and [Ground-to-phase varistors](#) below.

■ EMC filter

To connect the drive to symmetrically grounded TN-S systems, you should connect the internal EMC filter if you are concerned with EMC issues. See section [When to connect EMC filter or disconnect ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems \(page 166\)](#).



WARNING!

Do not install the drive with the EMC filter connected to a system that the filter is not suitable for. This can cause danger, or damage the drive.

Note: When the internal EMC filter is disconnected, the drive EMC compatibility is considerably reduced.

■ Ground-to-phase varistors

A drive with the ground-to-phase varistor connected can be installed to a symmetrically grounded TN-S system. If you install the drive to another system, you may need to disconnect the varistor. See [When to connect EMC filter or disconnect ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems \(page 166\)](#), and [Guidelines for installing the drive to a TT system \(page 168\)](#).



WARNING!

Do not install the drive with the ground-to-phase varistor connected to a system that the varistor is not suitable for. If you do, the varistor circuit can be damaged.

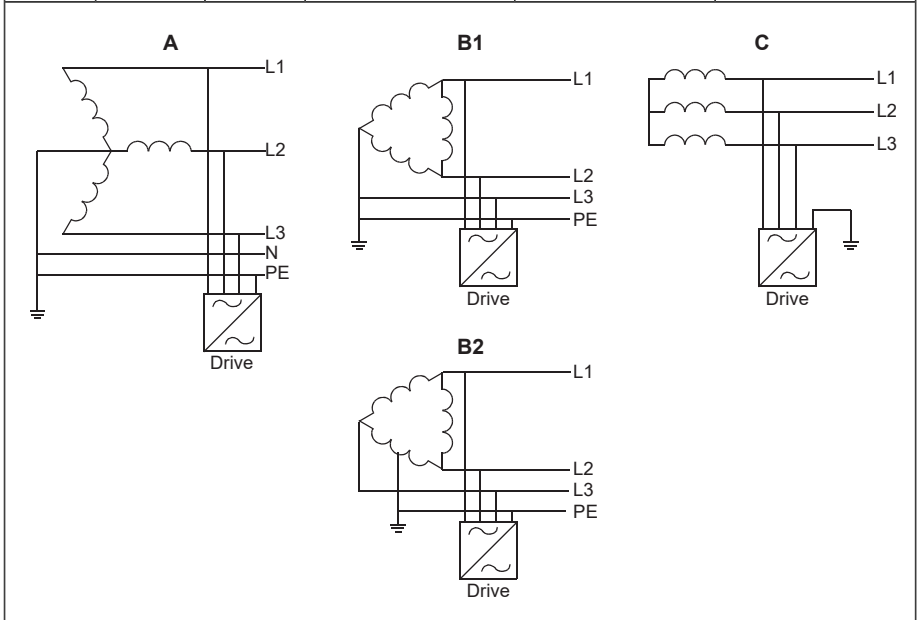
■ When to connect EMC filter or disconnect ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems

Requirements for disconnecting EMC filter and varistor and additional requirements for different electrical power systems are given below.

Note: Configure the EMC filter based on the electrical system of the installation site.



Frame size	Screw label	Factory default screw material	Symmetrically grounded TN systems (TN-S systems) ie. center-grounded wye (A)	Corner-grounded (B1) and midpoint-grounded delta systems (B2) ≤ 600 V	IT systems (un-grounded or high-resistance grounded [>30 ohms]) (C)
R1...R3 R4 v2	EMC (DC)	Plastic	Optional metal screw ¹⁾	Do not disconnect the plastic screw ²⁾	Do not disconnect the plastic screw ²⁾
	VAR	Metal	Do not disconnect the metal screw	Remove the metal screw	Remove the metal screw
R4...R5 ³⁾	EMC (AC)	Plastic	Optional metal screw ¹⁾	Do not disconnect the plastic screw ²⁾	Do not disconnect the plastic screw ²⁾
	EMC (DC)	Plastic	Optional metal screw ¹⁾	Do not disconnect the plastic screw ²⁾	Do not disconnect the plastic screw ¹⁶⁷
	VAR	Metal	Do not disconnect the metal screw	Do not disconnect the metal screw	Remove the metal screw



- 1) You can install metal screw and connect the EMC filter if you are concerned with EMC issues.
- 2) Metal screw must not be used, plastic screw may be maintained or removed from the AC EMC circuit.
- 3) Frames R4 and R5 are evaluated for use on corner-grounded delta networks by UL standards. (R4 and R5 frames are not to be used on IEC installations of corner grounded networks.)

Note: The VAR screw on R1...R3 also connects the EMC (AC) circuit internally within the drive.

Note: Failure to remove a metal screw, when indicated in the table above, may result in drive failure.

Note: These are the EMC filter and varistor screws and their materials in different drive frame sizes.

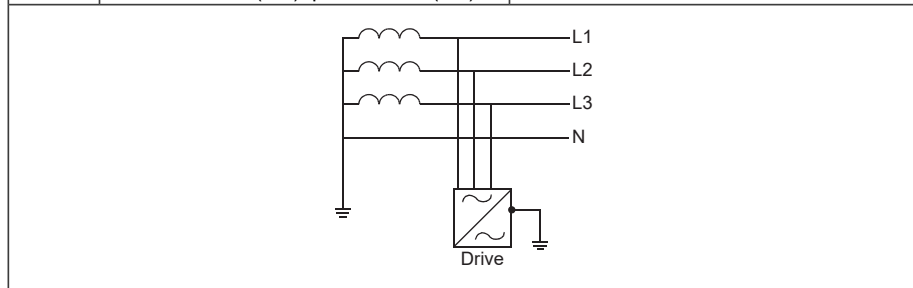
Frame size	EMC filter screws	Ground-to-phase varistor screws
R1...R3	Plastic EMC (DC)	Metal VAR
R4...R9	Plastic EMC (DC), plastic EMC (AC)	Metal VAR

■ **Guidelines for installing the drive to a TT system**

The drive can be installed to a TT system under these conditions:

1. Residual current device has been installed in the supply system.
2. EMC filter screws have been disconnected (= they are plastic screws or there is no screw). Otherwise EMC filter leakage current will cause the residual current device to trip. For R1...R3, the VAR screw must be plastic, and for R4...R9, the VAR screw must be metal.

Frame size	EMC filter screws	Ground-to-phase varistor screw
R1...R3	Plastic EMC (DC)	Plastic VAR (remove metal VAR screw)
R4...R9	Plastic EMC (DC), plastic EMC (AC)	Metal VAR



Note:



- ABB does not guarantee the EMC category because the EMC filter screws have been disconnected.
- ABB does not guarantee the functioning of the ground leakage detector built inside the drive.
- In large systems the residual current device can trip without a real reason.

■ Identifying the grounding system of the electrical power network



WARNING!

Only a qualified electrical professional may do the work instructed in this section. Depending on the installation site, the work may even be categorized as live working. Continue only if you are an electrical professional certified for the work. Obey the local regulations. If you ignore them, injury or death can occur.

To identify the grounding system, examine the supply transformer connection. See the applicable electrical diagrams of the building. If that is not possible, measure these voltages at the distribution board, and use the table to define the grounding system type.

1. input voltage line to line (U_{L-L})
2. input voltage line 1 to ground (U_{L1-G})
3. input voltage line 2 to ground (U_{L2-G})
4. input voltage line 3 to ground (U_{L3-G}).

The table below shows the line-to-ground voltages in relation to the line-to-line voltage for each grounding system.

U_{L-L}	U_{L1-G}	U_{L2-G}	U_{L3-G}	Electrical power system type
X	0.58·X	0.58·X	0.58·X	Symmetrically grounded TN system (TN-S system)
X	1.0·X	1.0·X	0	Corner-grounded delta system (nonsymmetrical)
X	0.866·X	0.5·X	0.5·X	Midpoint-grounded delta system (nonsymmetrical)
X	Varying level versus time	Varying level versus time	Varying level versus time	IT systems (ungrounded or high-resistance-grounded [>30 ohms]) nonsymmetrical
X	Varying level versus time	Varying level versus time	Varying level versus time	TT system (the protective earth connection for the consumer is provided by a local earth electrode, and there is another independently installed at the generator)

■ Frames R1...R3

Extra screws to configure the drive for different networks are provided in the drive shipment.

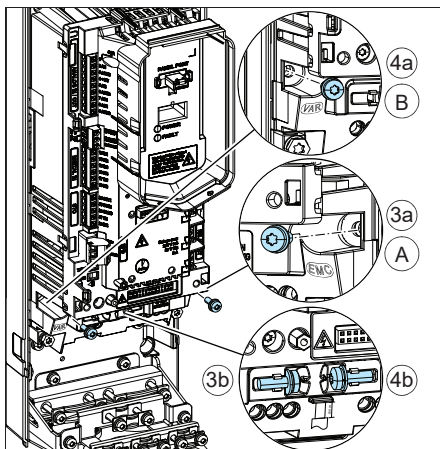
To disconnect the internal EMC filter or ground-to-phase varistor, if needed (see page 166), do as follows:

1. Switch off the power from the drive.
2. Open the front cover, if not already opened, see page 174.

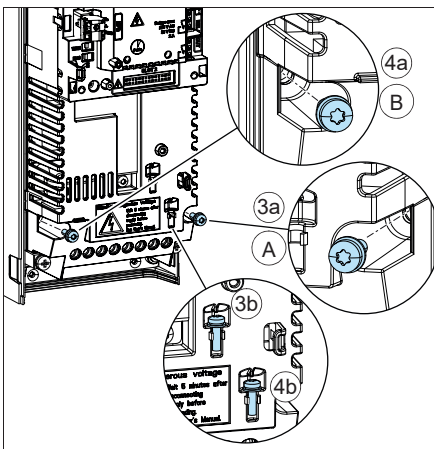


3. The internal DC EMC filter is disconnected by default with a plastic screw (3a).
4. To disconnect the ground-to-phase varistor, replace the metal varistor screw (4a) with the plastic screw provided in the package, and place it in the storage place (4b)

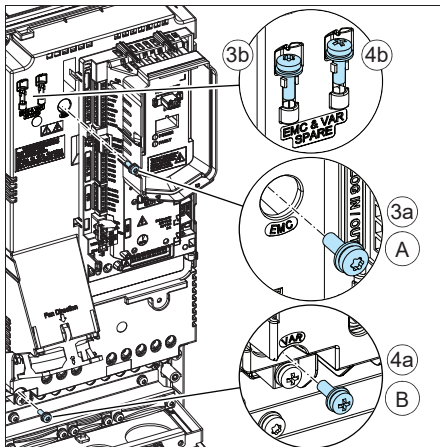
R1



R2



R3



	Screw	Default material
A	EMC (DC)	Plastic
B	VAR	Metal

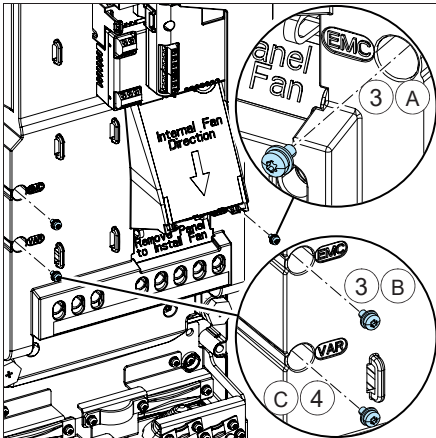
■ Frames R4...R9

Extra screws to configure the drive for different networks are provided in the drive shipment.

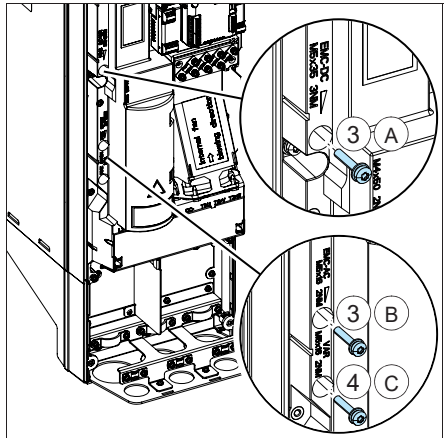
To disconnect the internal EMC filter or ground-to-phase varistor, if needed (see page 166), do as follows:

1. Switch off the power from the drive.
2. Open the cover, if not already opened. Frame R4: see page 174, frame R5: see page 178, frames R6...R9: see page 182.
3. To disconnect the internal EMC filters:
 - The DC EMC filter is disconnected by default with a plastic screw (3a).
 - The AC EMC filter is disconnected by default with a plastic screw (3b).
4. To disconnect the ground-to-phase varistor, replace the metal varistor screw (4) with the plastic screw provided in the package, or just remove the metal screw.

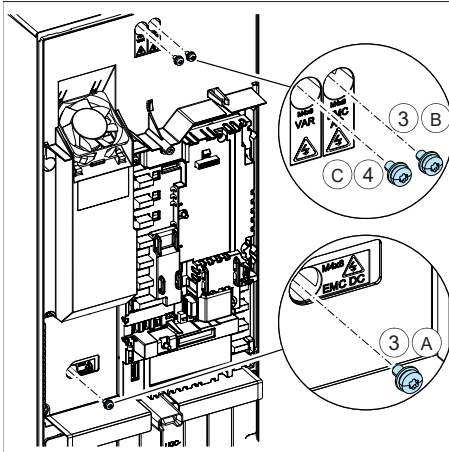
R4



R5



R6...R9

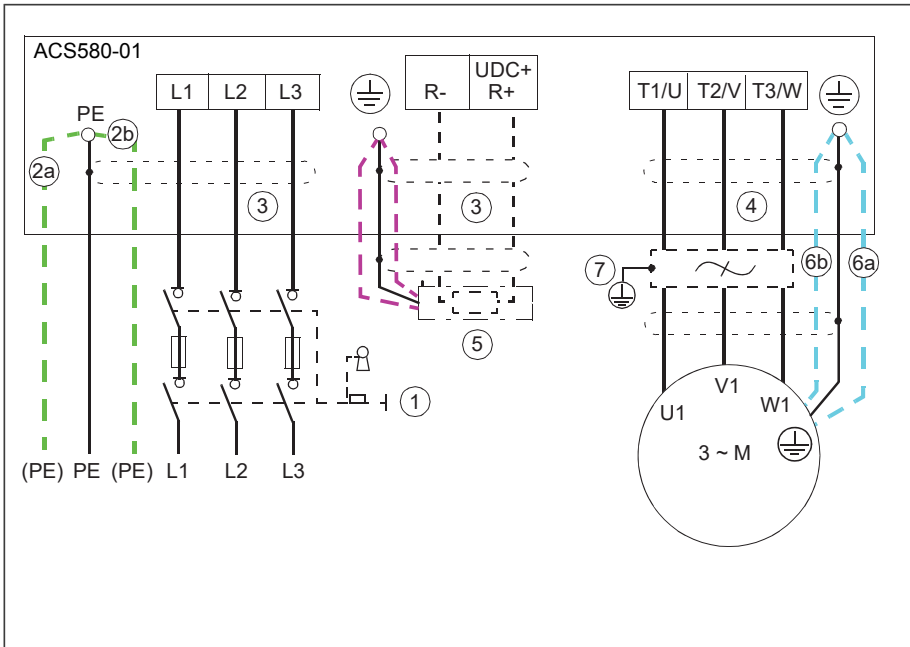


	Screw	Default material
A	EMC (DC)	Plastic
B	EMC (AC)	Plastic
C	VAR	Metal



Connecting the power cables

■ Connection diagram



1	For alternatives, see Selecting the main supply disconnecting device (page 85)
2	<p>With a conduit: Use a separate grounding PE cable (2a) or a PE conductor (2b) inside the conduit if the conductivity of the conduit does not meet the requirements for the PE conductor (see General guidelines (page 94)).</p> <p>With a shielded cable: Use a separate grounding PE cable (2a) or a cable with a separate PE conductor (2b) if the conductivity of the shield does not meet the requirements for the PE conductor (see General guidelines (page 94)).</p> <p>Note: If the cross-section of the Cu PE conductor is less than 8 AWG, install a second Cu PE conductor of the same cross-sectional area as the original PE conductor. Alternatively, you can use a Cu PE conductor with at least 10 mm² cross-section. See page 24.</p>
3	<p>With the conduit: Make sure of a proper grounding of the conduit at the cable entry. Ground the other end of the conduit and PE conductor (if used) at the distribution board.</p> <p>With a shielded cable: Do a 360-degree grounding if shielded cable is used. Ground the other end of the input cable shield and PE conductor (if used) at the distribution board.</p>
4	<p>With the conduit: Make sure of a proper grounding of the conduit at the cable entry.</p> <p>With a shielded cable: Do a 360-degree grounding of the shield.</p>

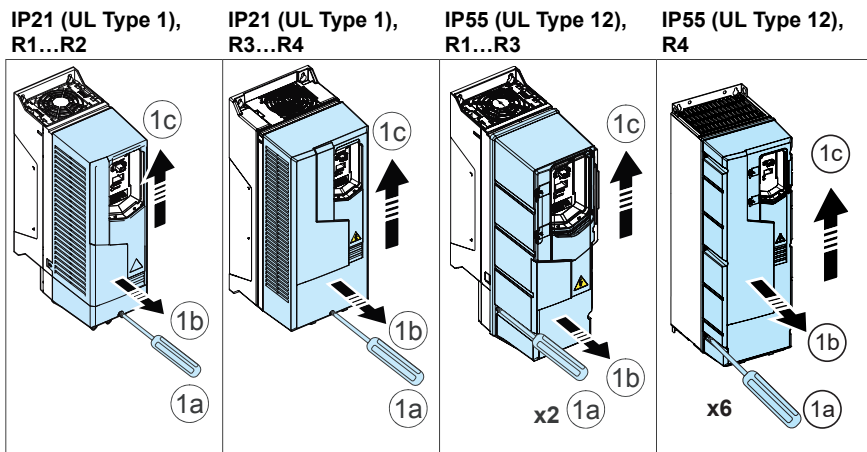


5	<p>External brake resistor.</p> <p><u>With a conduit:</u> Use a separate grounding PE cable (5a), or a PE conductor (5b) inside the conduit if the conductivity of the conduit does not meet the requirements for the PE conductor (see General guidelines (page 94)).</p> <p><u>With a shielded cable:</u> Use a separate grounding PE cable (5b) or a cable with a separate PE conductor (5b) if the conductivity of the shield does not meet the requirements for the PE conductor (see General guidelines (page 94)).</p>
6	<p><u>With a conduit:</u> Use a separate grounding cable if the conduit does not meet the requirements for the PE conductor (see General guidelines (page 94)) or there is no grounding conductor inside the conduit.</p> <p>Note: ABB prefers the use of a symmetrical shielded motor cable (VFD cable), see the note at the bottom of the table.</p> <p><u>With a shielded cable:</u> Use a separate grounding cable if the shield does not meet the requirements for the PE conductor (see General guidelines (page 94)) or there is no symmetrically constructed grounding conductor in the cable (see page 96).</p>
7	<p>du/dt or common mode filter (optional), see chapter Common mode, du/dt and sine filters (page 395).</p>
<p>Note: <u>With a shielded cable:</u> If there is a symmetrically constructed grounding conductor on the motor cable in addition to the conductive shield, connect the grounding conductor to the grounding terminal at the drive and motor ends.</p> <p>ABB does not recommend an asymmetrically constructed motor cable or a conduit for motor cabling for motors above 30 kW (40 hp) (see General guidelines (page 94)). Connecting its fourth conductor at the motor end increases bearing currents and causes extra wear.</p> <p>For a single phase connection, use terminals L1 and L2.</p>	



■ **Connection procedure, frames R1...R4**

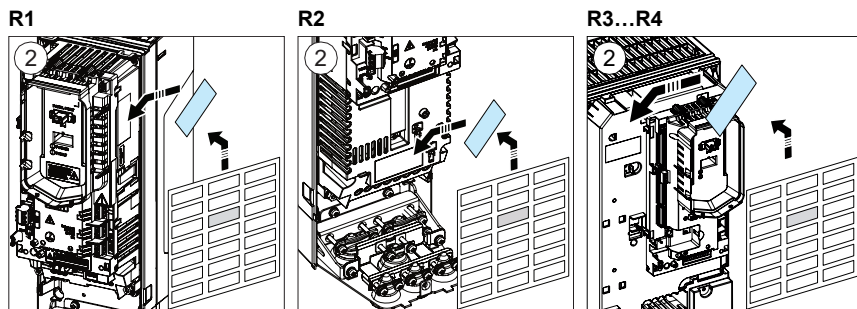
1. Remove the front cover: Loosen the retaining screw with a T20 Torx screwdriver (1a) and lift the cover from the bottom outwards (1b) and then up (1c).



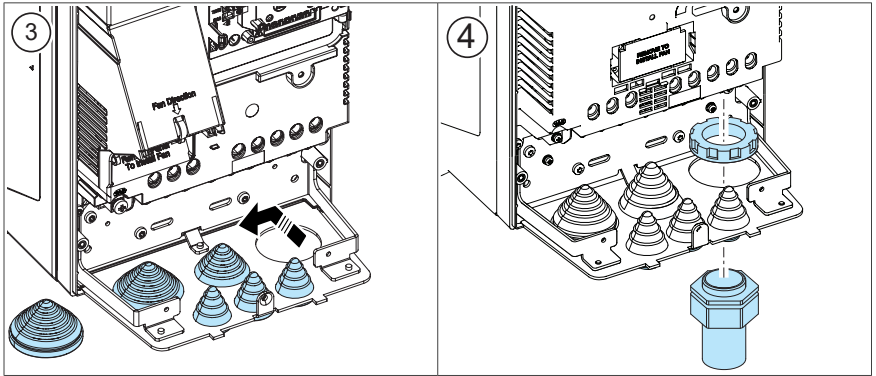
WARNING!

If you install the drive on any other system than symmetrically grounded TN-S system, see [Grounding system compatibility check \(page 166\)](#) if you have to disconnect the EMC filter and ground-to-phase varistor.

2. Attach the residual voltage warning sticker in the local language.



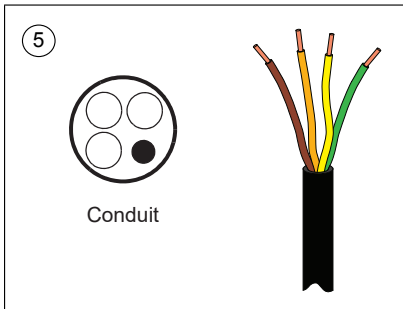
3. Remove the rubber grommets for the motor and input power cables, as well as brake resistor cable, if used.
Remove the grommets for the control cables when you are connecting them.
4. Attach the cable conduits to the cable entry holes in place of the removed grommets.



Note: The drive is shipped with grommet cones pointing up. They must be removed and inserted back pointing down.

Motor cabling

5. Strip the ends of the conductors.



6. Slide the conductors through the conduit.

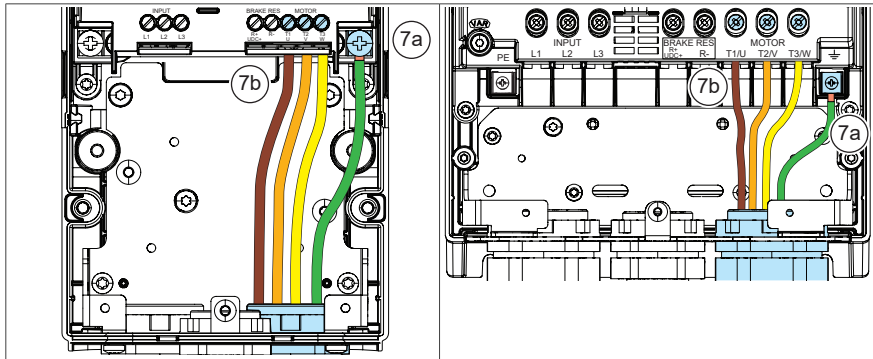
7. Connect the conductors:

- Connect the grounding conductor to the grounding terminal. (7a)
- Connect the phase conductors to the T1/U, T2/V and T3/W terminals (7b). Tighten the screws to the torque given in the table.

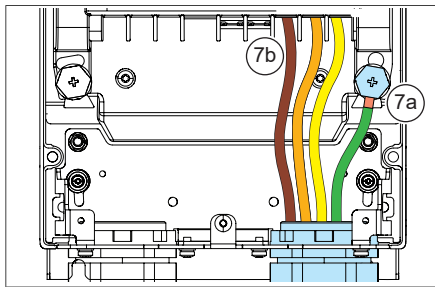
R1...R2

R3





R4



Frame size	R1		R2		R3		R4	
	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft
T1/U, T2/V, T3/W	1.0	0.7	1.5	1.1	3.5	2.6	4.0	3.0
PE, \oplus	1.5	1.1	1.5	1.1	1.5	1.1	2.9	2.1

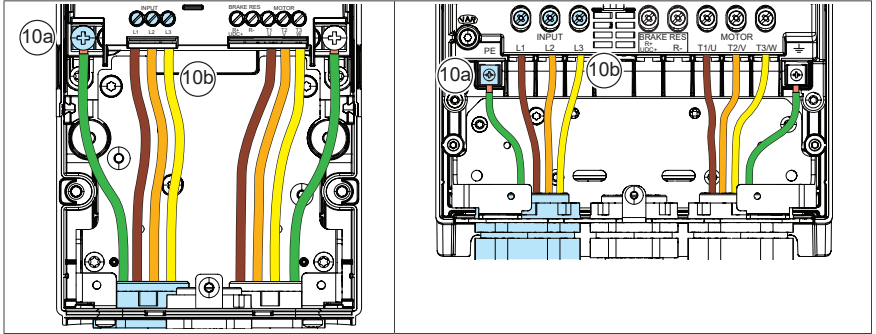
Input power cabling

8. Strip the ends of the conductors as for the motor cabling.
9. Slide the conductors through the conduit.
10. Connect the conductors:
 - Connect the grounding conductor to the grounding terminal. (10a)
 - Connect the phase conductors to the L1, L2 and L3 terminals. Tighten the screws to the torque given in the table. (10b).

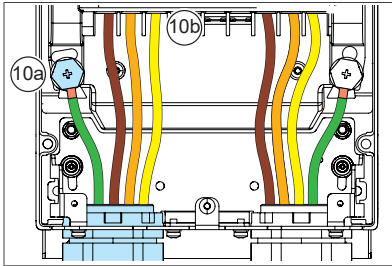
R1...R2


R3





R4

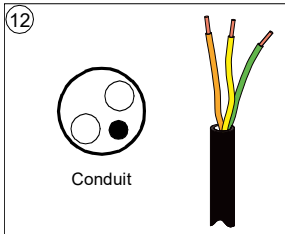


Frame size	R1		R2		R3		R4	
	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft
L1, L2, L3	1.0	0.7	1.5	1.1	3.5	2.6	4.0	3.0
PE, 	1.5	1.1	1.5	1.1	1.5	1.1	2.9	2.1

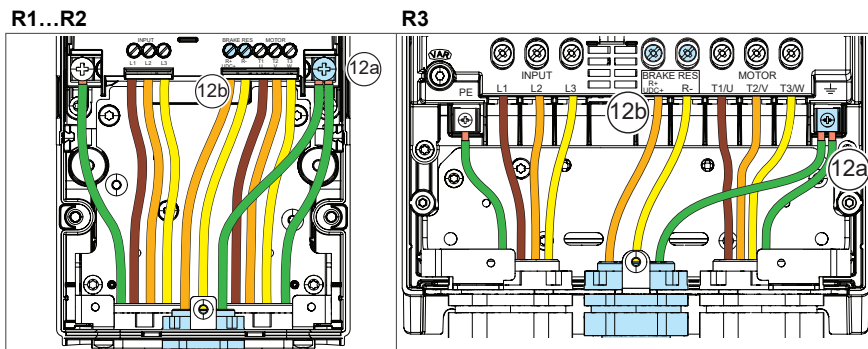
Brake resistor cabling (if used)

Frames R1...R3 only:

- Repeat steps 5...6 for the brake resistor conductors. Use only two phase conductors and the ground conductor.



- Connect the grounding conductor to the grounding terminal (12a) and the other conductors to the R+ and R- terminals (12b). Tighten the screws to the torque given in the table.



Frame size	R1		R2		R3	
	N·m	lbf·ft	N·m	lbf·ft	N·m	lbf·ft
R+, R-	1.0	0.7	1.5	1.1	3.5	2.6
PE, \oplus	1.5	1.1	1.5	1.1	1.5	1.1

Finalization

Note: Frame R1: You have to install any optional I/O extension module, if used, in options slot 2 at this point. See section [Installing option modules \(page 201\)](#).

- Secure the conduits outside the unit mechanically.

■ Connection procedure, frame R5

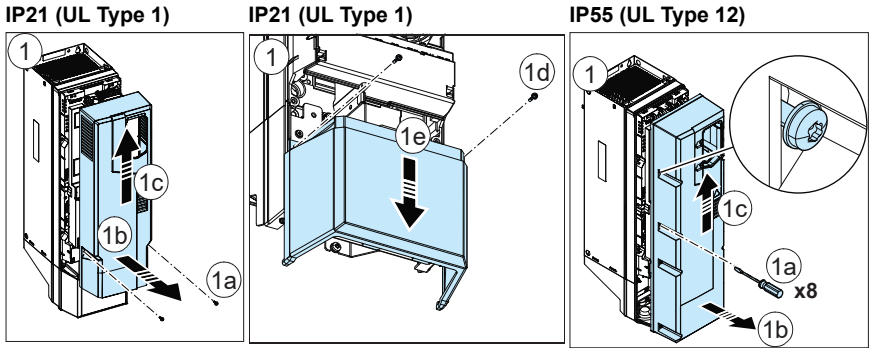
IP21 (UL Type 1)

- Remove the module cover: Loosen the retaining screws with a T20 Torx screwdriver (1a) and lift the cover from the bottom outwards (1b) and then up (1c).

Remove the box cover: Loosen the retaining screws with a screwdriver (1d) and slide the cover downwards (1e).

IP55 (UL Type 12)

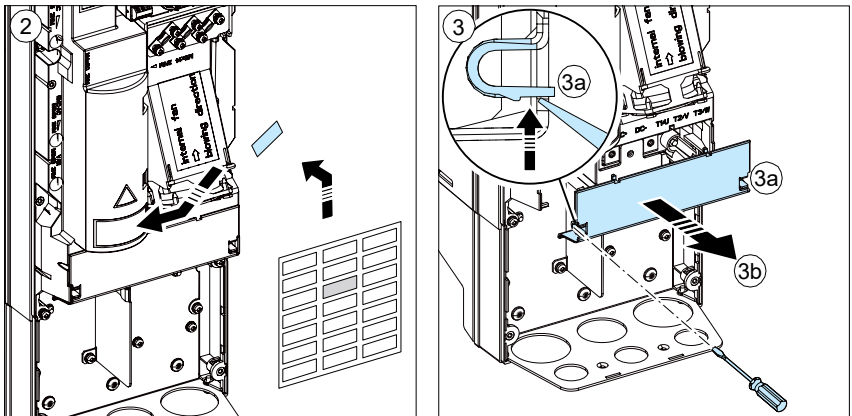
- Remove the front cover: Loosen the retaining screws with a T20 Torx screwdriver (1a) and lift the cover from the bottom outwards (1b) and then up (1c).



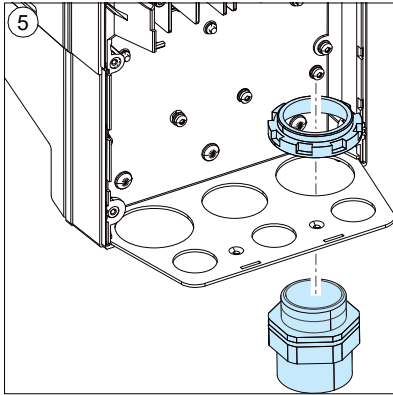
WARNING!

If you install the drive on any other system than symmetrically grounded TN-S system, see [Grounding system compatibility check \(page 166\)](#) if you have to disconnect the EMC filter and ground-to-phase varistor.

2. Attach the residual voltage warning sticker in the local language next to the control unit.
3. Remove the shroud on the power cable terminals by releasing the clips with a screwdriver (3a) and pulling the shroud out (3b).

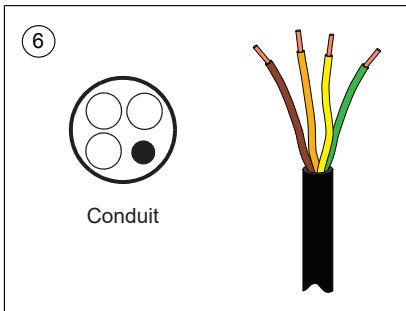


4. Remove the rubber grommets, if present, for the motor and input power cabling. Remove the grommets for the control cabling when you are connecting them.
5. Attach the cable conduits for the motor and input cabling to the cable entry holes.



Motor cabling

6. Strip the ends of the conductors.

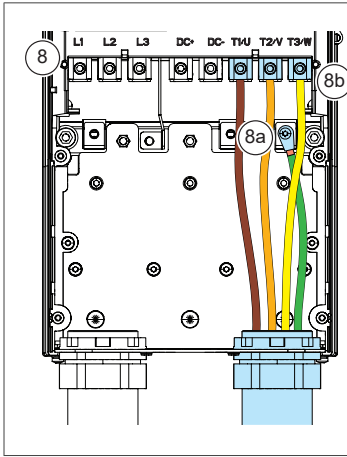


7. Slide the conductors through the conduit.

8. Connect the conductors:

- Connect the grounding conductor to the grounding terminal. (8a)
- Connect the phase conductors to the T1/U, T2/V and T3/W terminals (8b). Tighten the screws to the torque given in the table.

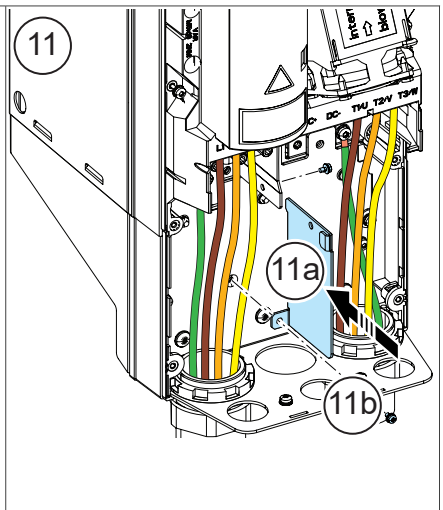
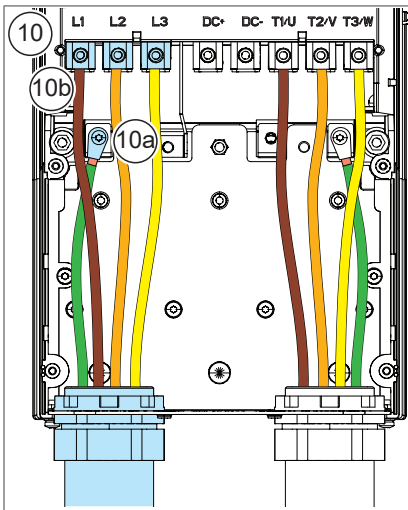





Frame size	T1/U, T2/V, T3/W		PE, 		
	N·m	lbf·ft	M	N·m	lbf·ft
R5	5.6	4.1	M5	2.2	1.6

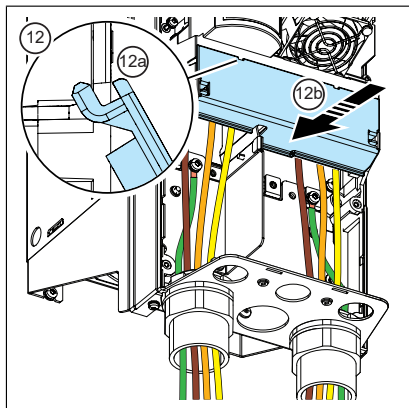
Input power cabling

9. Repeat steps 6...7 for the conductors.
10. Connect the conductors as for the motor cabling. Use terminals L1, L2 and L3. Tighten the screws to the torque given in the table.
11. Install the cable box plate. Position the plate (11a) and tighten the screw (11b).



Frame size	L1, L2, L3		PE, 		
	N·m	lbf·ft	M	N·m	lbf·ft
R5	5.6	4.1	M5	2.2	1.6

- Reinstall the shroud on the power terminals by putting the tabs at the top of the shroud in their counterparts on the drive frame (12a) and then pressing the shroud in place (12b).



Finalization

- Secure the conduits outside the unit mechanically.

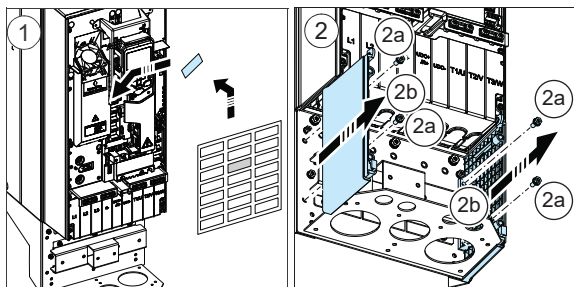
■ Connection procedure, frames R6...R9



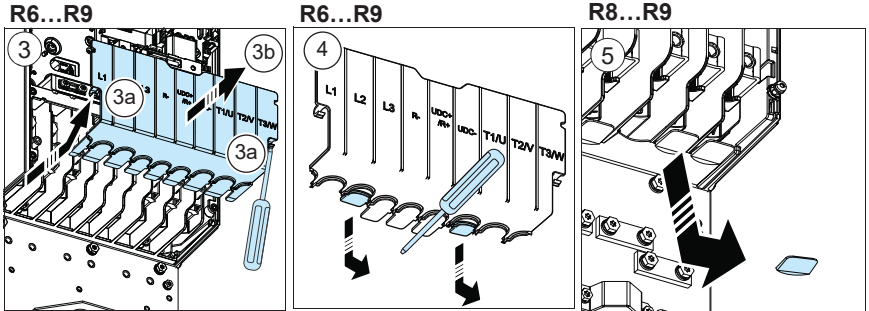
WARNING!

If you install the drive on any other system than symmetrically grounded TN-S system, see see [Grounding system compatibility check \(page 166\)](#) if you have to disconnect the EMC filter and ground-to-phase varistor.

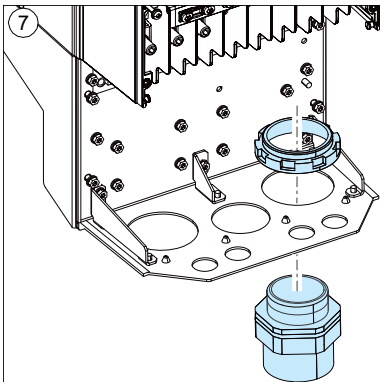
- Attach the residual voltage warning sticker in the local language next to the control unit.
- Remove the side plates of the cable box: Remove the retaining screws (2a) and slide the walls out (2b).



3. Remove the shroud on the power cable terminals by releasing the clips with a screwdriver (3a) and pulling the shroud out (3b).
4. Knock out holes in the shroud for the cabling to be installed.
5. Frames R8...R9: If you install parallel cabling, also knock out holes in the lower shroud.



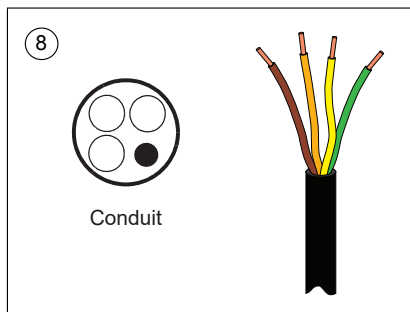
6. Remove the rubber grommets, if present, for the motor and input power cabling. Remove the grommets for the control cabling when you are connecting them.
7. Attach the cable conduits for the motor and input cabling to the cable entry holes.



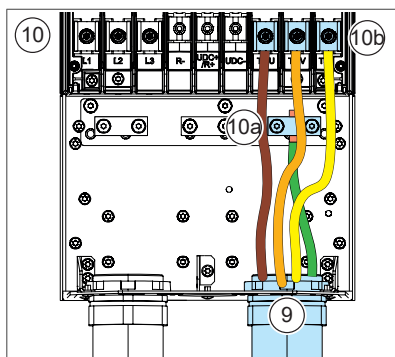
Motor cabling


8. Strip the ends of the conductors.





9. Slide the conductors through the conduit.
10. Connect the conductors:
 - Connect the grounding conductor to the grounding terminal (10a).
 - Connect the phase conductors to terminals T1/U, T2/V and T3/W. Tighten the screws to the torque given in the table (10b).



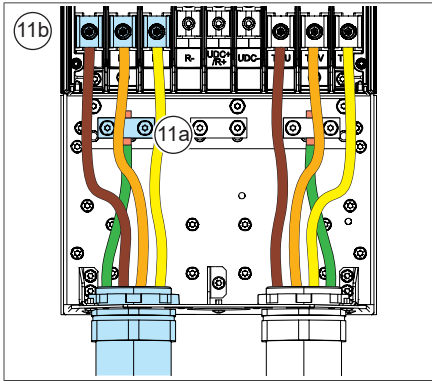
Frame size	L1, L2, L3, T1/U, T2/V, T3/W		PE, 	
	N-m	lbf-ft	N-m	lbf-ft
R6	30	22	9.8	7.2
R7	40	30	9.8	7.2
R8	40	30	9.8	7.2
R9	70	52	9.8	7.2


Note 1 for frames R8...R9: If you connect only one conductor to the connector, ABB recommends that you put it under the upper pressure plate. If you use parallel power cabling, put the first conductor under the lower pressure plate and the second under the upper one.

Note 2 for frames R8...R9: The connectors are detachable but ABB does not recommend that you detach them. If you do, detach and reinstall the connectors as described in *Detaching and reinstalling the connectors (page 185)*.

Input power cabling

11. Repeat steps 8...10 for the conductors. Use terminals L1, L2, L3.



Frame size	L1, L2, L3, T1/U, T2/V, T3/W		PE, 	
	N·m	lbf·ft	N·m	lbf·ft
R6	30	22	9.8	7.2
R7	40	30	9.8	7.2
R8	40	30	9.8	7.2
R9	70	52	9.8	7.2

Detaching and reinstalling the connectors

This is possible but not recommended.

Terminals T1/U, T2/V and T3/W

- Remove the nut that attaches the connector to its busbar.
- Put the conductor under the connector pressure plate and pre-tighten the conductor.
- Put the connector back to its busbar. Start the nut, and turn it at least two rotations by hand.



WARNING!

Before using tools, make sure that the nut/screw is not cross-threading. Cross-threading will damage the drive and cause danger.

- Tighten the nut to a torque of 30 N·m (22 lbf·ft).
- Tighten the conductor(s) to 40 N·m (30 lbf·ft) for frame R8 or to 70 N·m (52 lbf·ft) for frame R9.

Terminals L1, L2 and L3

- Remove the combi screw that attaches the connector to its terminal post, and pull the connector off.
- Put the conductor under the connector pressure plate and pre-tighten the conductor.
- Put the connector back onto the terminal post. Start the combi screw, and turn it at least two rotations by hand.



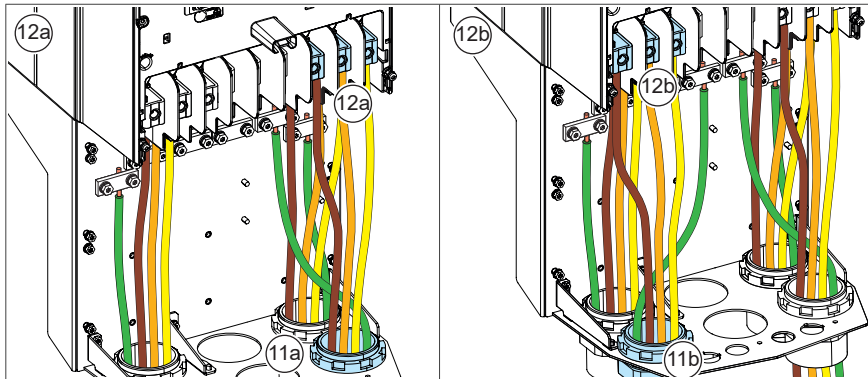
WARNING!

Before using tools, make sure that the nut/screw is not cross-threading. Cross-threading will damage the drive and cause danger.

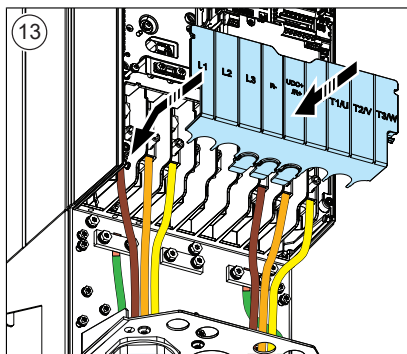


- Tighten the combi screw to a torque of 30 N·m (22 lbf·ft).
- Tighten the conductor(s) to 40 N·m (30 lbf·ft) for frame R8 or to 70 N·m (52 lbf·ft) for frame R9.

12. **Frames R8...R9:** Connect the parallel motor (11a) and input power (11b) cabling conductors, if used. Repeat steps 8...11.



13. Reinstall the shroud on the power terminals.



14. Secure the conduits outside the unit mechanically.

DC connection

The UDC+ and UDC- terminals (as standard in frames R4...R9) are for using external brake chopper units.

Connecting the control cables

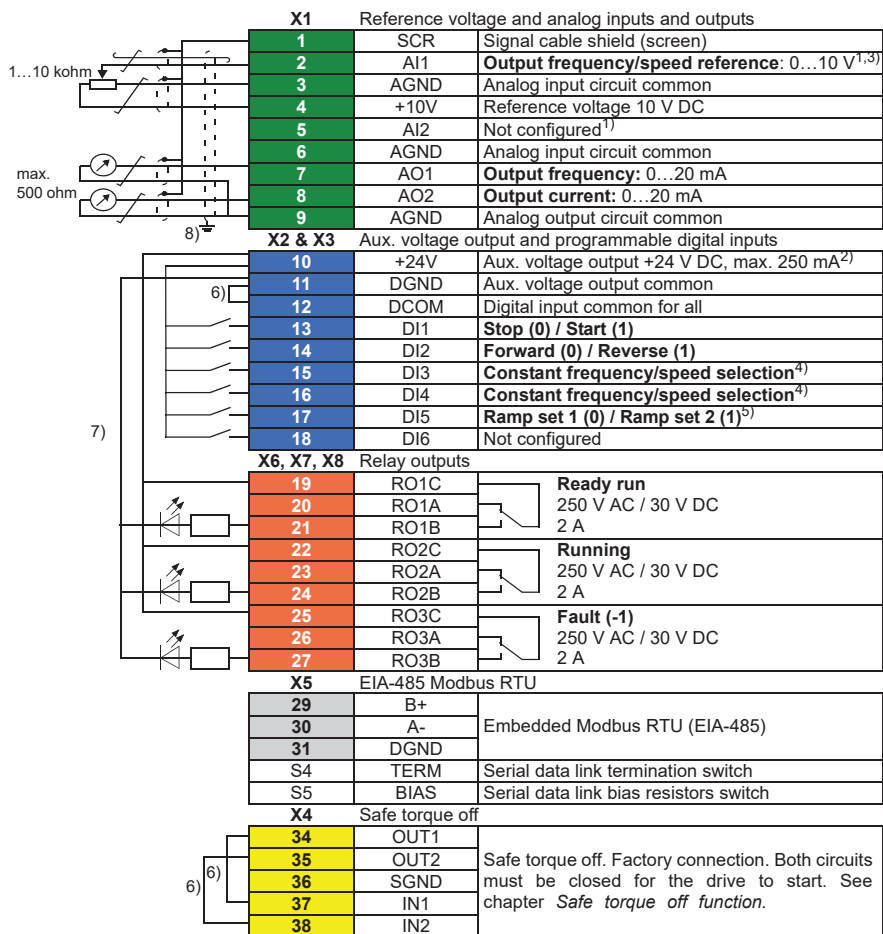
See section i1369542 for the default I/O connections of the ABB standard macro. For other macros, see ACS580 firmware manual (3AXD50000016097 [English]).

Connect the cables as described under [Control cable connection procedure R1...R9 \(page 195\)](#).



■ **Default I/O connection diagram (ABB standard macro)**

R1...R5



Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V DC).

Digital inputs DI1...DI5 also support 10 to 24 V AC.

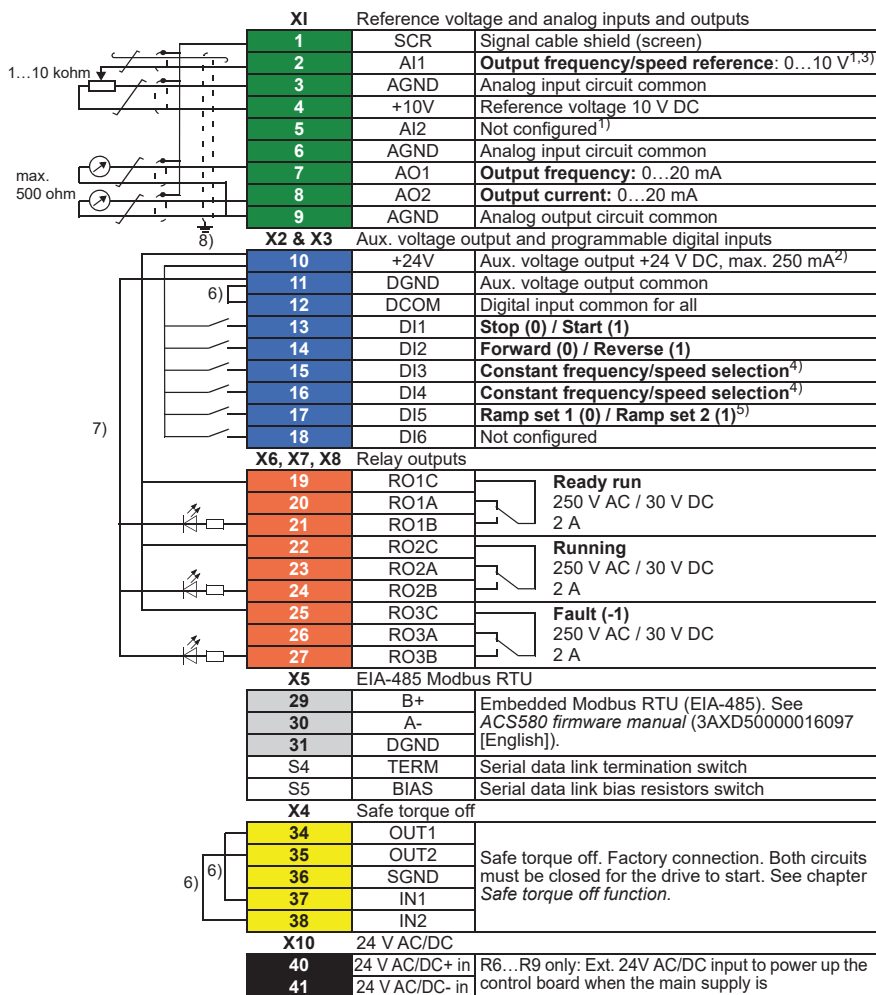
Wire sizes:

0.2...2.5 mm² (24...14 AWG): Terminals +24V, DGND, DCOM, B+, A-, DGND, Ext. 24V

0.14...1.5 mm² (26...16 AWG): Terminals DI, AI, AO, AGND, RO, STO

Tightening torques: 0.5...0.6 N·m (0.4 lbf·ft)

R6...R9



Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V DC).
 Digital inputs DI1...DI5 also support 10 to 24 V AC.
 Wire sizes: 0.14...2.5 mm² (26...14 AWG): All terminals
 Tightening torques: 0.5...0.6 N·m (0.4 lbf·ft)

Notes:

1) Current [0(4)...20 mA, $R_{in} = 100 \text{ ohm}$] or voltage [0(2)...10 V, $R_{in} > 200 \text{ kohm}$]. Change of setting requires changing the corresponding parameter.

2) Total load capacity of the Auxiliary voltage output +24V (X2:10) is 6.0 W (250 mA / 24 V) minus the power taken by the option modules installed on the board.

3) AI1 is used as a speed reference if vector control is selected.

4) In scalar control (default): See **Menu - Primary settings - Start, stop, reference - Constant frequencies** or parameter group 28 Frequency reference chain.

In vector control: See **Menu - Primary setting - Start, stop, reference - Constant speeds** or parameter group 22 Speed reference selection.

DI3	DI4	Operation/Parameter	
		Scalar control (default)	Vector control
0	0	Set frequency through AI1	Set speed through AI1
1	0	28.26 Constant frequency 1	22.26 Constant speed 1
0	1	28.27 Constant frequency 2	22.27 Constant speed 2
1	1	28.28 Constant frequency 3	22.28 Constant speed 3

5) In scalar control (default): See Menu - Primary settings - Ramps or parameter group 28 Frequency reference chain.

In vector control: See Menu - Primary settings - Ramps or parameter group 23 Speed reference ramp.

DI5	Ramp set	Parameters	
		Scalar control (default)	Vector control
0	1	28.72 Freq acceleration time 1 28.73 Freq deceleration time 1	23.12 Acceleration time 1 23.13 Deceleration time 1
1	2	28.74 Freq acceleration time 2 28.75 Freq deceleration time 2	23.14 Acceleration time 2 23.15 Deceleration time 2

6) Connected with jumpers at the factory.





7) Use shielded twisted-pair cables for digital signals.

8) Ground the outer shield of the cable 360 degrees under the grounding clamp on the grounding shelf for the control cables.

Further information on the usage of the connectors and switches is given in the sections below. See also section [Control connection data \(page 291\)](#).



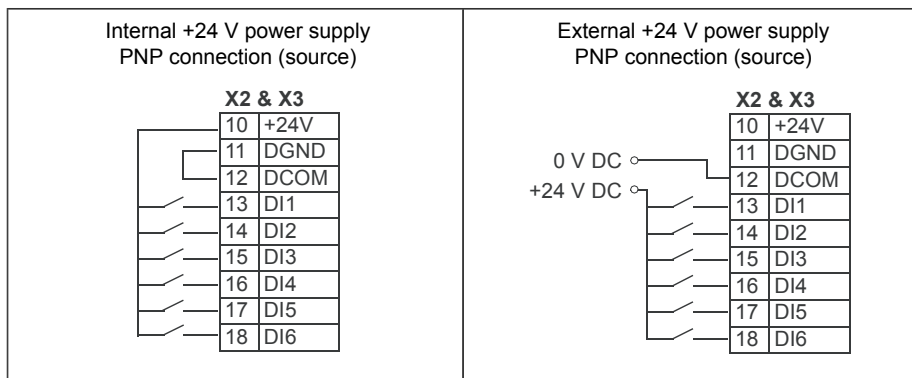
Switches

Switch	Description	Position	
S4 (TERM)	Modbus link termination. Must be set to the terminated (ON) position when the drive is the first or last unit on the link.	 ON TERM	Bus not terminated (default)
		 ON TERM	Bus terminated
S5 (BIAS)	Activates on the biasing voltages to the bus. One (and only one) device, preferably at the end of the bus must have the bias on.	 ON BIAS	Bias off (default)
		 ON BIAS	Bias on

■ Additional information on I/O connections

PNP configuration for digital inputs

Internal and external +24 V power supply connections for PNP configuration are shown in the figure below.

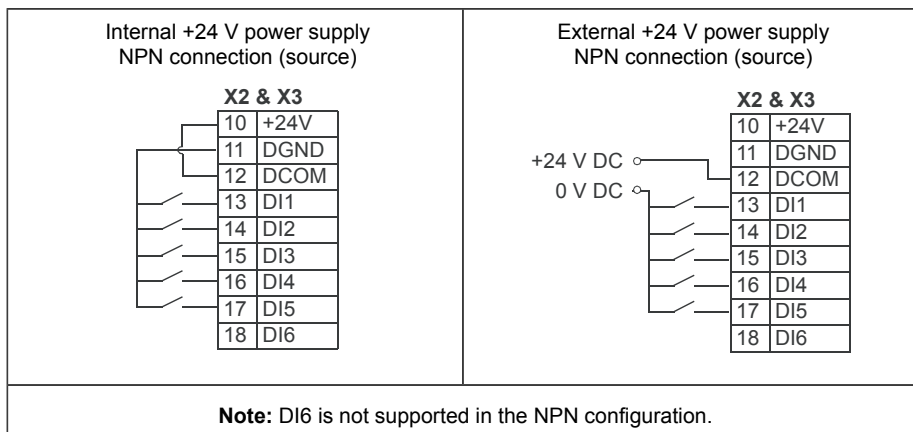


WARNING!

Do not connect the +24 V AC cable to the control unit ground when the control unit is powered using an external 24 V AC supply.

NPN configuration for digital inputs

Internal and external +24 V power supply connections for NPN configuration are shown in the figure below.

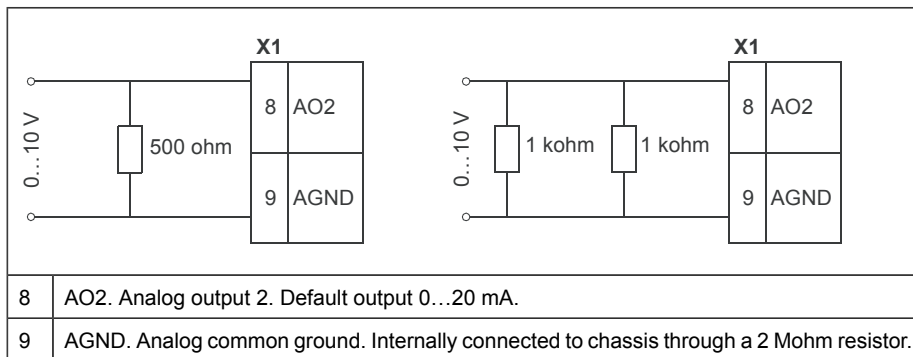


WARNING! Do not connect the +24 V AC cable to the control unit ground when the control unit is powered using an external 24 V AC supply.

Connection for obtaining 0...10 V from analog output 2 (AO2)

To obtain 0...10 V from analog output AO2, connect a 500 ohm resistor (or two 1 kohm resistors in parallel) between the analog output 2 AO2 and analog common ground AGND.

Examples are shown in the figure below.

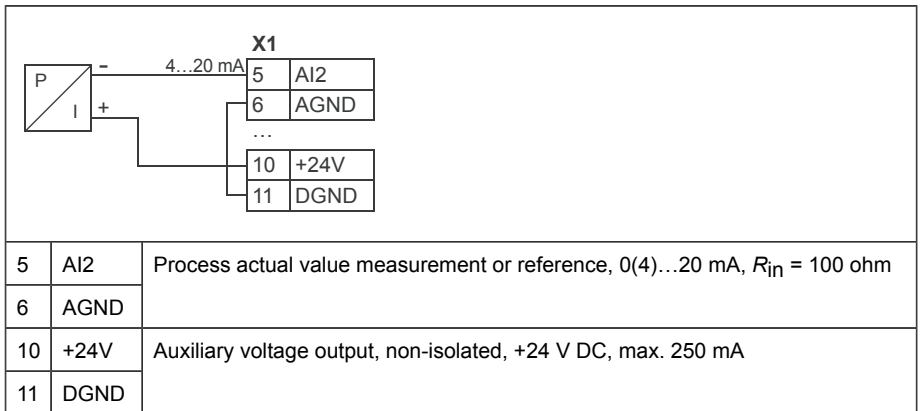


Connection examples of two-wire and three-wire sensors

Hand/Auto, Hand/PID, and PID macros (see *ACS580 firmware manual* (3AXD50000016097 [English])) use analog input 2 (AI2). The macro wiring diagrams on these pages use an externally powered sensor (connections not shown). The figures below give examples of connections using a two-wire or three-wire sensor/transmitter supplied by the drive auxiliary voltage output.

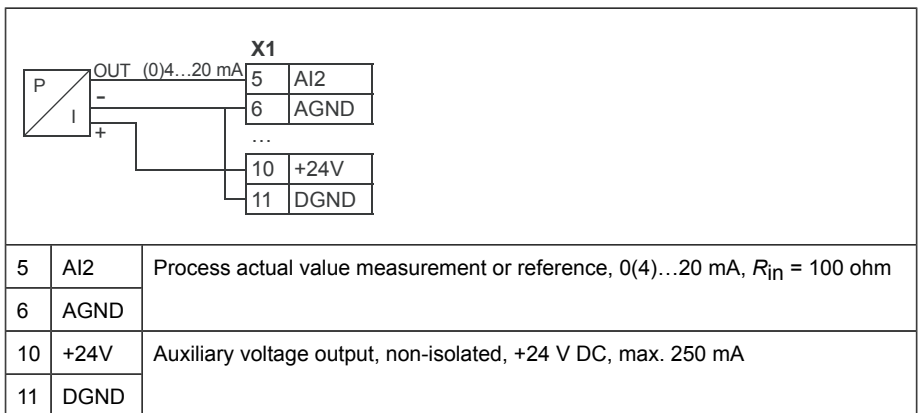
Note: Maximum capability of the auxiliary 24 V DC (250 mA) output must not be exceeded.

Two-wire sensor/transmitter



Three-wire sensor/transmitter

Note: The sensor is supplied through its current output and the drive feeds the supply voltage (+24 V DC). Thus the output signal must be 4...20 mA, not 0...20 mA.



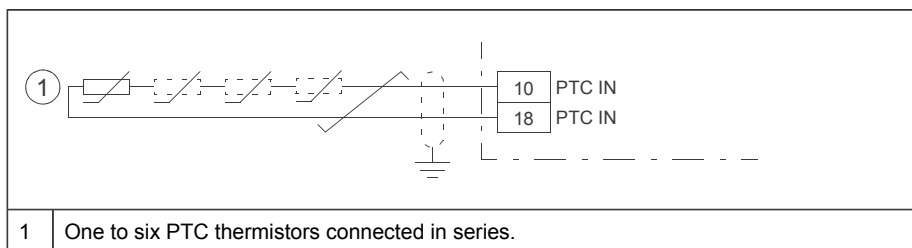
DI5 as frequency input

For setting the parameters for the digital frequency input, see *ACS580 standard control program firmware manual* (3AXD50000016097 [English]).

DI6 as PTC input

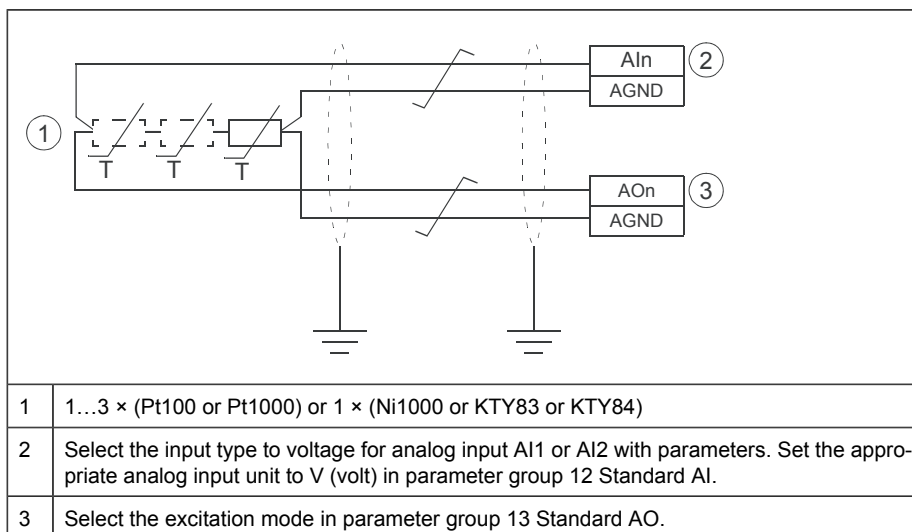
If DI6 is used as a PTC input, see *ACS580 standard control program firmware manual* (3AXD50000016097 [English]) for how to set parameters accordingly.

Note: If DI6 is used as PTC input, the wiring and the PTC sensor need to be double isolated. Otherwise the CMOD-02 I/O extension module must be used.



AI1 and AI2 as Pt100, Pt1000, Ni1000, KTY83 and KTY84 sensor inputs (X1)

One, two or three Pt100 sensors; one, two or three Pt1000 sensors; or one Ni1000, KTY83 or KTY84 sensor for motor temperature measurement can be connected between an analog input and output as shown below. Do not connect both ends of the cable shields directly to ground. If a capacitor cannot be used at one end, leave that end of the shield unconnected.



**WARNING!**

As the inputs pictured above are not insulated according to IEC 60664, the connection of the motor temperature sensor requires double or reinforced insulation between motor live parts and the sensor. If the assembly does not fulfill the requirement, the I/O board terminals must be protected against contact and must not be connected to other equipment or the temperature sensor must be isolated from the I/O terminals.

Safe torque off (X4)

For the drive to start, both connections (+24 V DC to IN1 and +24 V DC to IN2) must be closed. By default, the terminal block has jumpers to close the circuit. Remove the jumpers before connecting an external Safe torque off circuitry to the drive. See chapter [The Safe torque off function \(page 347\)](#).

Note: Only 24 V DC can be used for STO. Only PNP input configuration can be used.

■ **Control cable connection procedure R1...R9**

**WARNING!**

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Do the steps in section [Electrical safety precautions \(page 22\)](#) before you start the work.
2. Remove the front cover(s) if not already removed. See page [174](#) (R1...R4), page [178](#) (R5) or page [81](#) (R6...R9).

Analog signals

The figures for frames R1...R2 and R3 (page [197](#)), R4 (page [198](#)), R5 (page [199](#)) and R6...R9 (page [200](#)) show an example of connecting a cable. Make the connections according to the macro in use.

3. Remove the rubber grommets from the cable entry for the cables to be connected. Attach cable conduits to the empty cable entry holes. Slide the cables through the cable conduits.
4. **Frames R5...R9:** Secure the cables mechanically at the clamps below the control unit.
Ground also the pair-cable shields and grounding wire at the SCR terminal, or either, you may ground the shield at the source of the signal, but do not ground it at both the source of the signal and the SCR terminal.
5. Route the cable as shown in the figures for frames R1...R2 and R3 (page [197](#)), R4 (page [198](#)), R5 (page [199](#)) and R6...R9 (page [200](#)).
6. Connect the conductors to the appropriate terminals of the control unit and tighten to 0.5...0.6 N·m (0.4 lbf·ft).



Digital signals

The figures for frames R1...R2 and R3 (page 197), R4 (page 198), R5 (page 199) and R6...R9 (page 200) show an example of connecting a cable. Make the connections according to the macro in use.

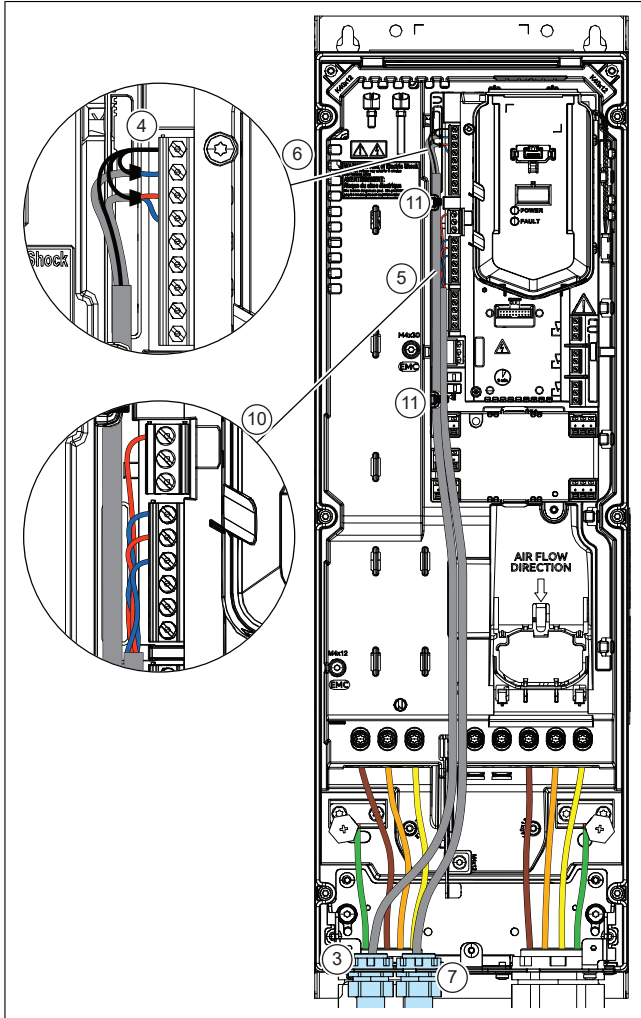
7. Remove the rubber grommets from the cable entry for the cables to be connected. Attach cable conduits to the empty cable entry holes. Slide the cables through the cable conduits.
8. Frames R5...R9: Secure the cables mechanically at the clamps below the control unit.
If you use double-shielded cables, ground also the pair-cable shields and grounding wire at the SCR terminal.
9. Route the cable as shown in the figures for frames R1...R2 and R3 (page 197), R4 (page 198), R5 (page 199) and R6...R9 (page 200).
10. Connect the conductors to the appropriate terminals of the control unit and tighten to 0.5...0.6 N·m (0.4 lbf·ft).
11. Tie all control cables to the provided cable tie mounts.

Note:

- Leave the other ends of the control cable shields unconnected or ground them indirectly via a high-frequency capacitor with a few nanofarads, eg, 3.3 nF / 630 V. The shield can also be grounded directly at both ends if they are in the same ground line with no significant voltage drop between the end points.
- Keep any signal wire pairs twisted as close to the terminals as possible. Twisting the wire with its return wire reduces disturbances caused by inductive coupling.

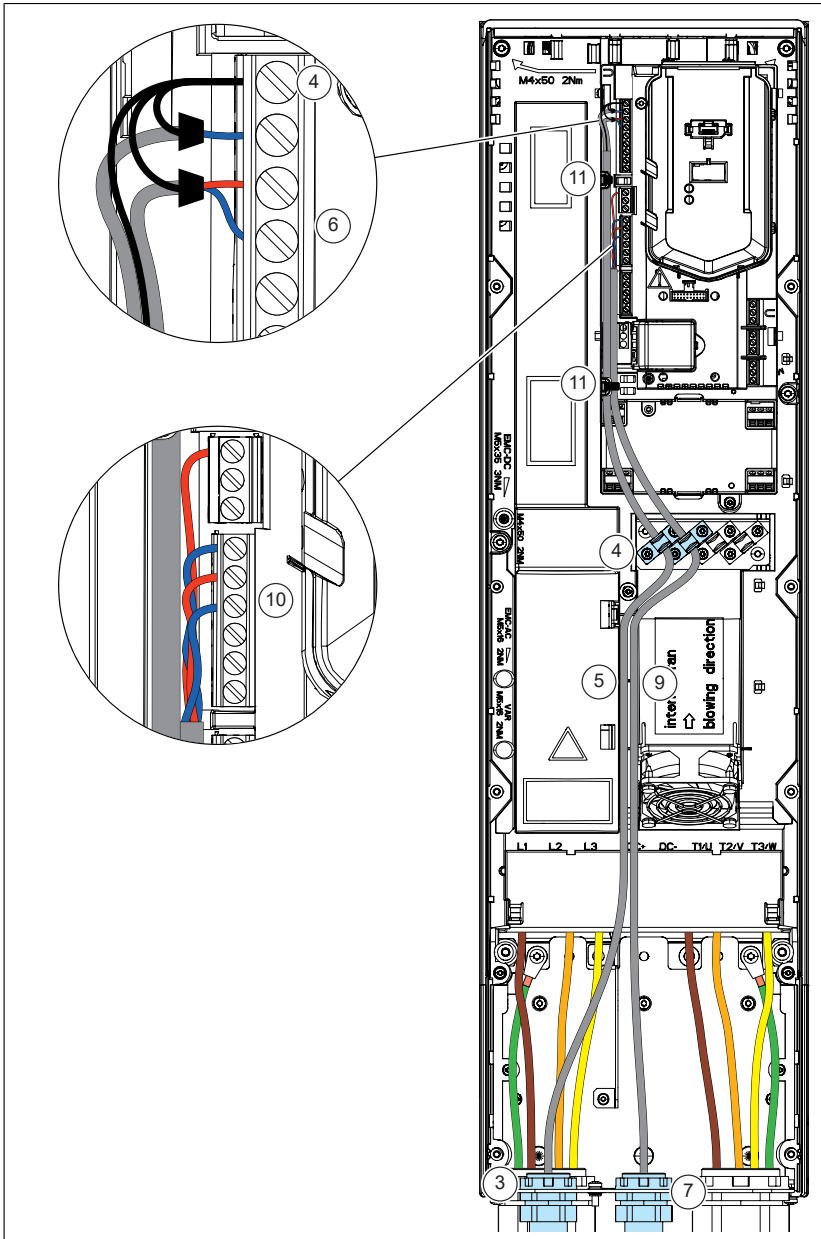


R4



R4: 0.4 lbf-ft

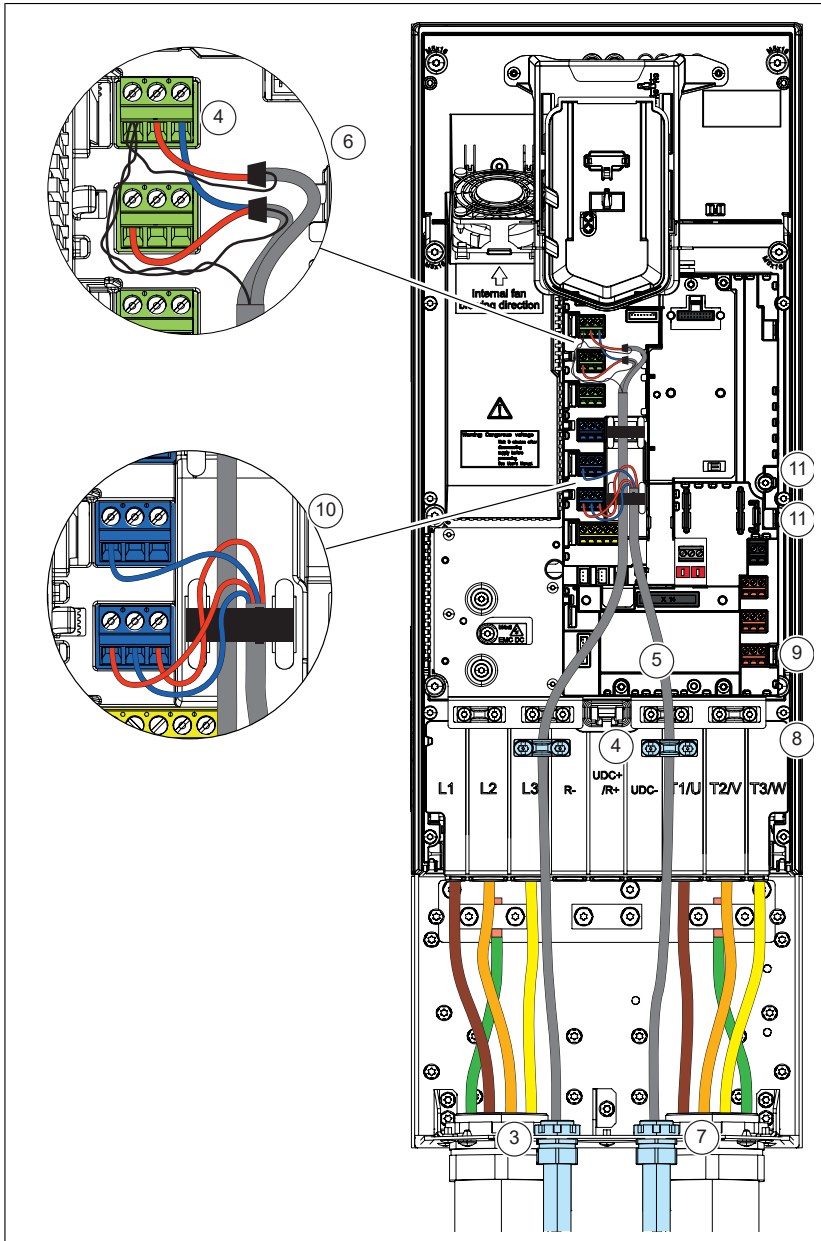
R5



R5: 0.4 lbf-ft



R6...R9



R6...R9: 0.4 lbf-ft

Installing option modules

Note: In North American deliveries, options may also be ordered as factory installed.

Note: If you will install the FPBA-01 module, see section [FPBA-01 PROFIBUS DP adapter module connectors \(page 101\)](#) for suitable connector types.

■ Mechanical installation of option modules

See section [Overview of power and control connections \(page 42\)](#) for the available slots for each module. Install the option modules as follows:



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

Note: Slot 2 in frames R1...R5 is at U_{DC} potential. You must disconnect power supplies before installing or removing an I/O extension module.

Stop the drive and do the steps in section [Electrical safety precautions \(page 22\)](#) before you start the work.

1. Remove the front cover(s) if not already removed. See section [Connection procedure, frames R1...R4 \(page 174\)](#), section [Connection procedure, frame R5 \(page 178\)](#) or section [IP21 \(UL Type 1\) \(page 81\)](#).

The figures for frames R1...R5 and R6...R9 show an example of installing option modules.

Option slot 2 (I/O extension modules)

2. Frame R1 only: Install the option mounting.
3. Put the module carefully into its position on the control unit.
4. Tighten the mounting screw.
5. Tighten the grounding screw (CHASSIS).

Note: The screw grounds the module. It is necessary for fulfilling the EMC requirements and for proper operation of the module.

Note: Frame R1: The module in option slot 2 covers the power terminals. Do not install a module in option slot 2 before you have installed the power cables.

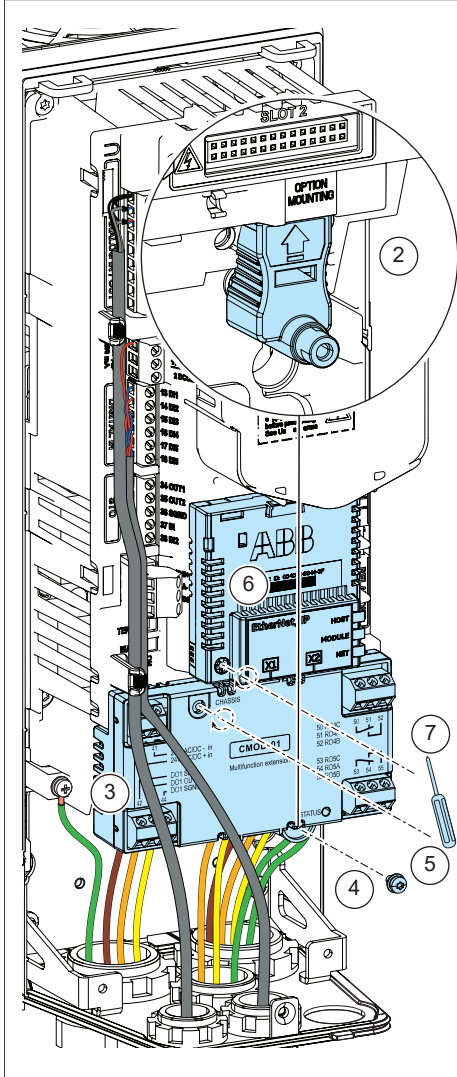
Option slot 1 (fieldbus adapter modules)

6. Put the module carefully into its position on the control unit.
7. Tighten the mounting screw (CHASSIS).

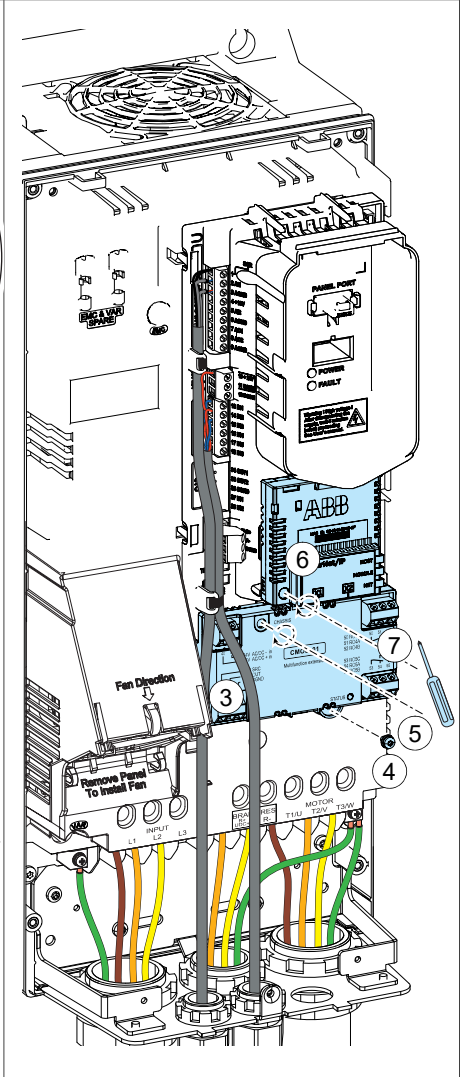
Note: The screw tightens the connections and grounds the module. It is necessary for fulfilling the EMC requirements and for proper operation of the module.



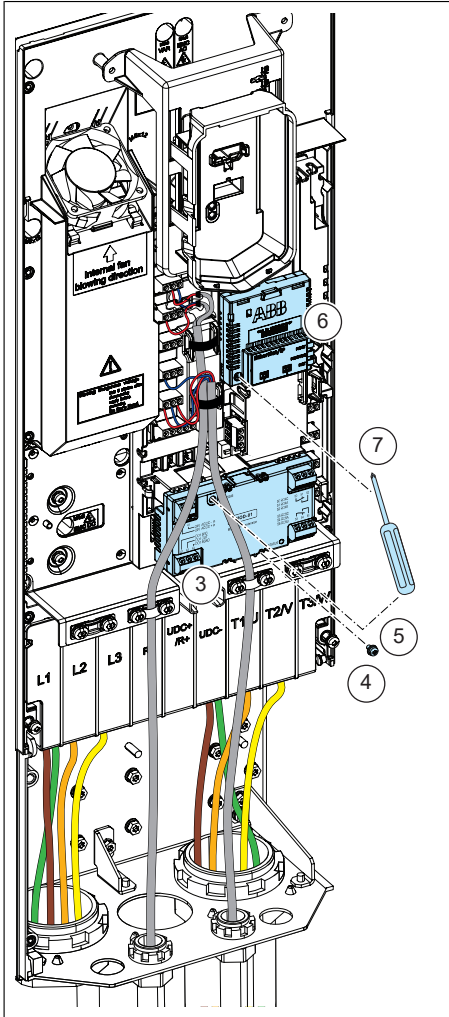
R1...R2



R3...R5



R6...R9

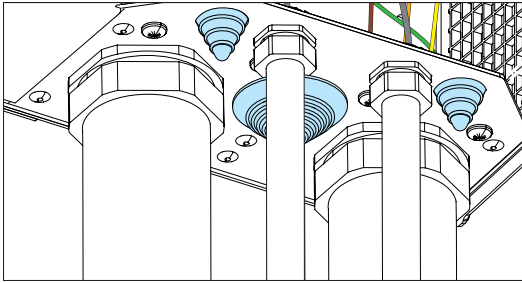


■ Wiring the modules

For the optional I/O extension modules CHDI-01, CMOD-01 and CMOD-02 and adapter module CBAI-01, see chapter Optional I/O extension and adapter modules for specific installation and wiring instructions. For other option modules, for example, CPTC-02, see the appropriate option module manual.

Reinstalling grommets

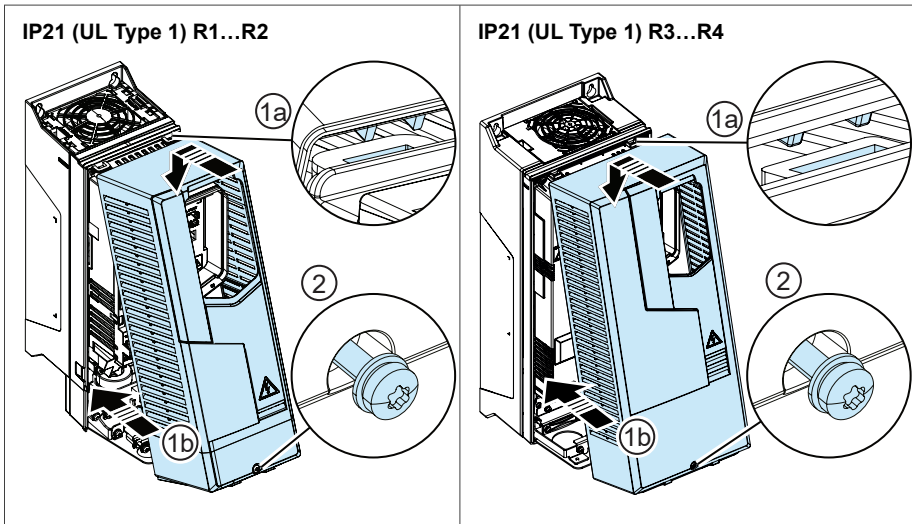
UL Type 12: To maintain UL Type 12, reinstall grommets (top of the grommets downwards) to all cable entry holes without conduits.

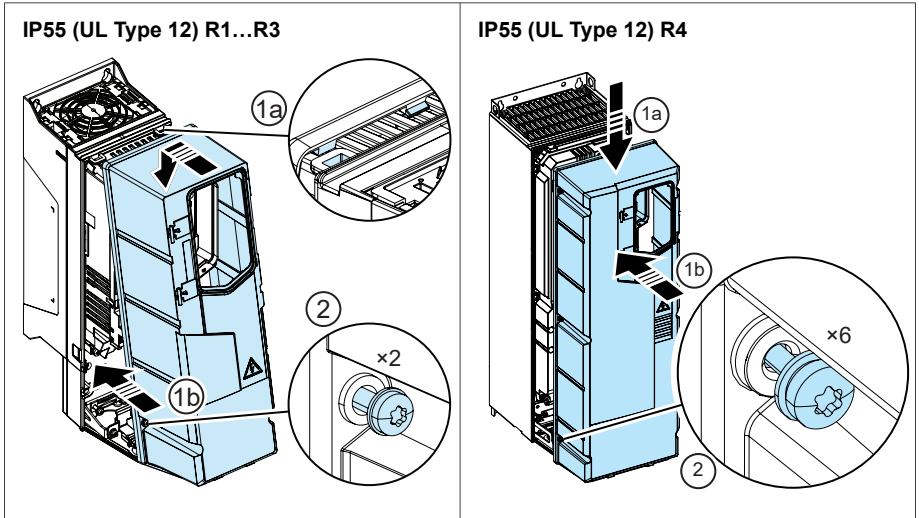


Reinstalling covers

■ Reinstalling cover, frames R1...R4

1. Reinstall the cover: Put the tabs on the cover top in their counterparts on the housing (1a) and then press the cover (1b).
2. Tighten the retaining screw at the bottom with a T20 Torx screwdriver.





■ Reinstalling covers, frame R5

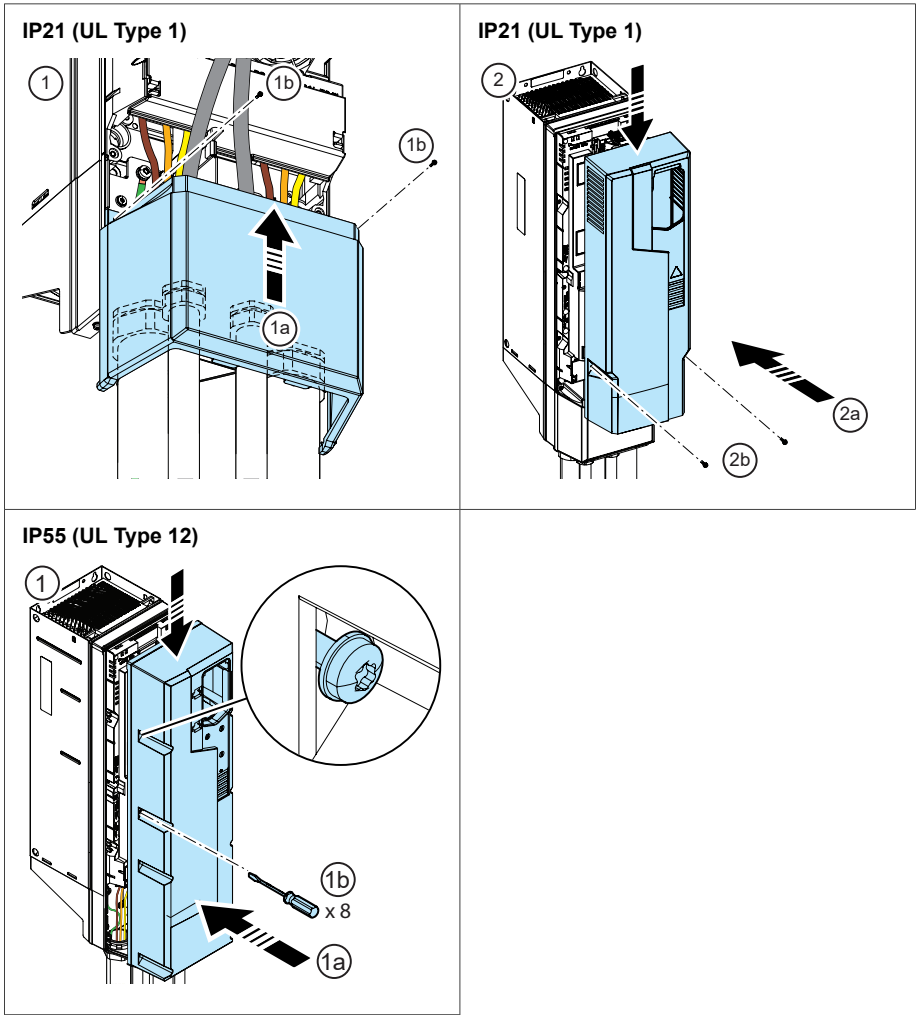
IP21 (UL Type 1)

1. Reinstall the box cover: Slide the cover upwards (1a) and tighten the retaining screws (1b) with a T20 Torx screwdriver.
2. Reinstall the module cover: Press the cover at the bottom (2a) and tighten the retaining screws (2b).

IP55 (UL Type 12)

1. Reinstall the front cover: Press the cover at the bottom (1a) and tighten the retaining screws (1b) with a T20 Torx screwdriver.





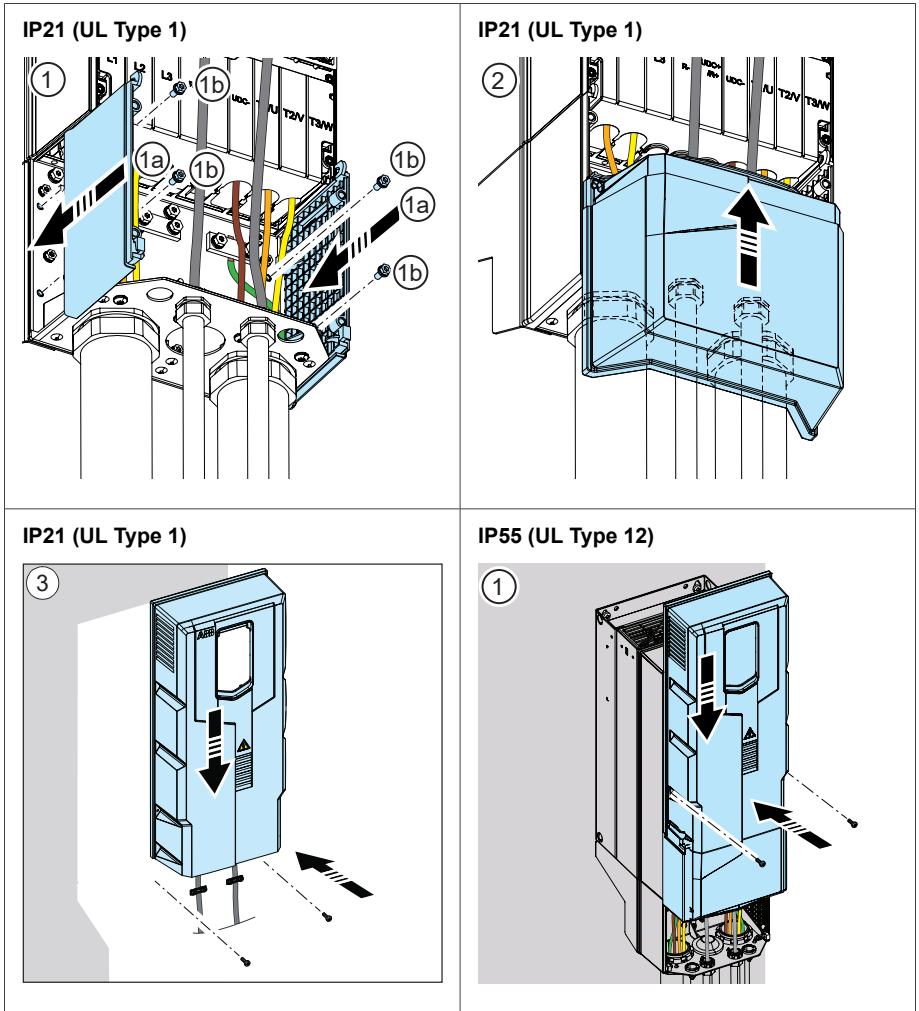
■ Reinstalling side plates and covers, frames R6...R9

IP21 (UL Type 1)

1. Reinstall the side plates of the cable box (1a). Tighten the retaining screws with a T20 Torx screwdriver (1b).
2. Slide the cover of the cable box on the module from below until the cover snaps into place.
3. Reinstall the module cover. Tighten the two retaining screws with a screwdriver.

IP55 (UL Type 12)


1. Reinstall the side plates of the cable box. Tighten the retaining screws with a T20 Torx screwdriver.



Installing UL Type 12 hood

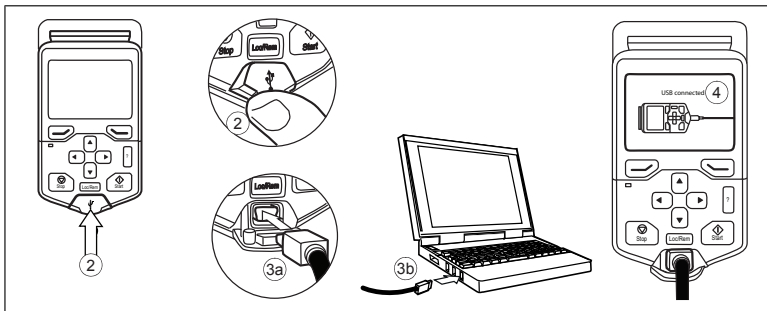
See *UL Type 12 hood quick installation guide for ACS580-01, ACH580-01 and ACQ580-01 frames R1 to R9* (3AXD50000196067 [English]) which is included in the hood package.

Connecting a PC


 **WARNING!** Do not connect the PC directly to the control panel connector of the control unit as this can cause damage.

A PC (with eg, the Drive composer PC tool) can be connected as follows:

1. Connect a ACS-AP-... or ACH-AP-... control panel to the unit either
 - by inserting the control panel into the panel holder or platform, or
 - by using an Ethernet (eg, Cat 5e) networking cable.
2. Remove the USB connector cover on the front of the control panel.
3. Connect an USB cable (Type A to Type Mini-B) between the USB connector on the control panel (3a) and a free USB port on the PC (3b).
4. The panel will display an indication whenever the connection is active.
5. See the documentation of the PC tool for setup instructions.



Connecting a remote panel, or chaining one panel to several drives

 You can connect a drive control panel remotely to the drive, or chain the control panel or a PC to several drives on a panel bus with a CDPI-01 communication adapter module. See *CDPI-01 communication adapter module user's manual* ([3AXD50000009929](https://www.abb.com/3AXD50000009929) [English]).

8

Installation checklist

Contents of this chapter

This chapter contains a checklist of the mechanical and electrical installation of the drive.

Checklist

Examine the mechanical and electrical installation of the drive before start-up. Go through the checklist together with another person.



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.



WARNING!

Stop the drive and do the steps in section [Electrical safety precautions \(page 22\)](#) before you start the work.

Make sure that ...	<input checked="" type="checkbox"/>
The ambient operating conditions meet the drive ambient conditions specification and enclosure rating (IP code).	<input type="checkbox"/>
The supply voltage matches the nominal input voltage of the drive. See the type designation label.	<input type="checkbox"/>

210 Installation checklist

Make sure that ...	<input checked="" type="checkbox"/>
The insulation resistance of the input power cable, motor cable and motor is measured according to local regulations and the manuals of the drive.	<input type="checkbox"/>
The drive is attached securely on an even, vertical and non-flammable wall.	<input type="checkbox"/>
The cooling air flows freely in and out of the drive.	<input type="checkbox"/>
<u>If the drive is connected to a network other than a symmetrically grounded TN-S system:</u> You have done all the required modifications (for example, you may need to disconnect the EMC filter or ground-to-phase varistor). See the electrical installation instructions.	<input type="checkbox"/>
Appropriate AC fuses and main disconnecting device are installed.	<input type="checkbox"/>
There is an adequately sized protective earth (ground) conductor(s) between the drive and the switchboard, the conductor is connected to correct terminal, and the terminal is tightened to the correct torque. Proper grounding has also been measured according to the regulations.	<input type="checkbox"/>
The input power cable is connected to the correct terminals, the phase order is correct, and the terminals are tightened to the correct torque.	<input type="checkbox"/>
There is an adequately sized protective earth (ground) conductor between the motor and the drive, and the conductor is connected to the correct terminal, and the terminal is tightened to the correct torque. Proper grounding has also been measured according to the regulations.	<input type="checkbox"/>
The motor cable is connected to the correct terminals, the phase order is correct, and the terminals are tightened to the correct torque.	<input type="checkbox"/>
The motor cable is routed away from other cables.	<input type="checkbox"/>
No power factor compensation capacitors are connected to the motor cable.	<input type="checkbox"/>
<u>If an external brake resistor is connected to the drive:</u> There is an adequately sized protective earth (ground) conductor between the brake resistor and the drive, and the conductor is connected to the correct terminal, and the terminals are tightened to the correct torque. Proper grounding has also been measured according to the regulations.	<input type="checkbox"/>
<u>If an external brake resistor is connected to the drive:</u> The brake resistor cable is connected to the correct terminals, and the terminals are tightened to the correct torque.	<input type="checkbox"/>
<u>If an external brake resistor is connected to the drive:</u> The brake resistor cable is routed away from other cables.	<input type="checkbox"/>
The control cables are connected to the correct terminals, and the terminals are tightened to the correct torque.	<input type="checkbox"/>
<u>If a drive bypass connection will be used:</u> The Direct On Line contactor of the motor and the drive output contactor are either mechanically and/or electrically interlocked, that is, they cannot be closed at the same time. A thermal overload device must be used for protection when bypassing the drive. Refer to local codes and regulations.	<input type="checkbox"/>
There are no tools, foreign objects or dust from drilling inside the drive.	<input type="checkbox"/>

Make sure that ...	<input checked="" type="checkbox"/>
The area in front of the drive is clean: the drive cooling fan cannot draw any dust or dirt inside.	<input type="checkbox"/>
Drive covers and cover of the motor connection box are in place.	<input type="checkbox"/>
The motor and the driven equipment are ready for power-up.	<input type="checkbox"/>

9

Maintenance

Contents of this chapter

This chapter contains maintenance instructions.

Maintenance intervals

The tables below show the maintenance tasks which can be done by the end user. The complete maintenance schedule is available on the Internet (<https://new.abb.com/drives/services/maintenance/preventive-maintenance>). For more information, consult your local ABB Service representative (www.abb.com/searchchannels).

■ Description of symbols

Action	Description
I	Inspection (visual inspection and maintenance action if needed)
P	Performance of on/off-site work (commissioning, tests, measurements or other work)
R	Replacement

■ Recommended maintenance intervals after start-up

Action	Description
P	Quality of supply voltage
I	Spare parts
P	Capacitor reforming for spare modules and spare capacitors, see Capacitors (page 227)
I	Tightness of terminals
I	Dustiness, corrosion or temperature
I	Heatsink cleaning, see Cleaning the heatsink (page 216)

Component	Years from start-up						
	3	6	9	12	15	18	21
Cooling							
Fans, IP21 (UL Type 1) frames R1 to R9							
Main cooling fan R1...R4: page 218 , R5: page 220		R		R		R	
Main cooling fan LONGLIFE R6...R8: page 220 , R9; page 221			R			R	
Auxiliary cooling fan for circuit boards R4 v2 drive type 089A-4: page 225		R		R		R	
Auxiliary cooling fan (LONGLIFE) for circuit boards, R5: page 225 , R6...R9: page 222			R			R	
Fans, IP55 (UL Type 12) frames R1 to R9							
Main cooling fan R1...R4: page 218 , R5: page 220		R		R		R	
Main cooling fan LONGLIFE R6...R8: page 220 , R9; page 221			R			R	
Auxiliary cooling fan for circuit boards R1...R2: page 223	R	R	R	R	R	R	R
Auxiliary cooling fan for circuit boards R4 v2: page 225		R		R		R	
Auxiliary cooling fan (LONGLIFE) for circuit boards R3: page 224 , R4...R5: page 225 , R6...R9: page 222			R			R	
Second auxiliary cooling fan (LONGLIFE) R8 and R9: page 226			R			R	
Aging							
Control panel battery: page 227			R			R	
Functional safety							
Safety function test							I See the maintenance information of the safety function.
Safety component expiry (Mission time, T_M)	20 years						

Note:

- Maintenance and component replacement intervals are based on the assumption that the equipment is operated within the specified ratings and ambient conditions. ABB recommends annual drive inspections to ensure the highest reliability and optimum performance.
- Long term operation near the specified maximum ratings or ambient conditions may require shorter maintenance intervals for certain components. Consult your local ABB Service representative for additional maintenance recommendations.

Cleaning the exterior of the drive

**WARNING!**

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrical professional, do not do installation, commissioning or maintenance work.

1. Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.
 2. Clean the exterior of the drive. Use:
 - vacuum cleaner with an antistatic hose and nozzle
 - soft brush
 - dry or damp (not wet) cleaning cloth. Moisten with clean water, or mild detergent (pH 5-9 for metal, pH 5-7 for plastic).
-

**WARNING!**

Prevent water from entering the drive. Never use excessive amount of water, a hose, steam, etc.

Cleaning the heatsink

The drive module heatsink fins pick up dust from the cooling air. The drive runs into overtemperature warnings and faults if the heatsink is not clean. When necessary, clean the heatsink as follows.



WARNING!

Use the required personal protective equipment. Wear protective gloves and long sleeves. Some parts have sharp edges.



WARNING!

Use a vacuum cleaner with antistatic hose and nozzle, and wear a grounding wristband. Using a normal vacuum cleaner creates static discharges which can damage circuit boards.

1. Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.
 2. Remove the module cooling fan(s). See the separate instructions.
 3. Blow dry, clean and oil-free compressed air from bottom to top and simultaneously use a vacuum cleaner at the air outlet to trap the dust. If there is a risk of dust entering adjoining equipment, do the cleaning in another room.
 4. Reinstall the cooling fan.
-

Fans

See [Maintenance intervals \(page 213\)](#) for the fan replacement interval in average operation conditions.

Parameter 05.04 Fan on-time counter indicates the running time of the cooling fan. Reset the counter after a fan replacement. See the firmware manual.

In a speed-controlled fan, the speed of the fan matches the cooling needs. This increases the life span of the fan.

Main fans are speed controlled. When the drive is stopped, the main fan runs at low speed until the drive cools down. IP21 (UL Type 1) frames R5...R9 and all IP55 (UL Type 12) frames have auxiliary fans that are not speed controlled and run all the time when the control unit is powered.

Replacement fans are available from the manufacturer. Do not use other than specified spare parts.

■ Replacing the main cooling fan, IP21 and IP55 (UL Type 1 and UL Type 12) frames R1...R4



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section [Electrical safety precautions \(page 22\)](#) before you start the work.

R1...R3

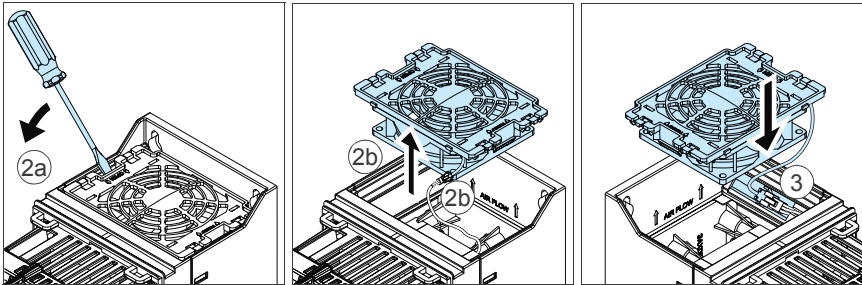
2. Lever the fan assembly off the drive frame with for example a screwdriver (2a) and pull out the fan assembly (2b) until you can unplug the fan power supply wires from the fan assembly (2c).

3. Install the fan assembly in reverse order.

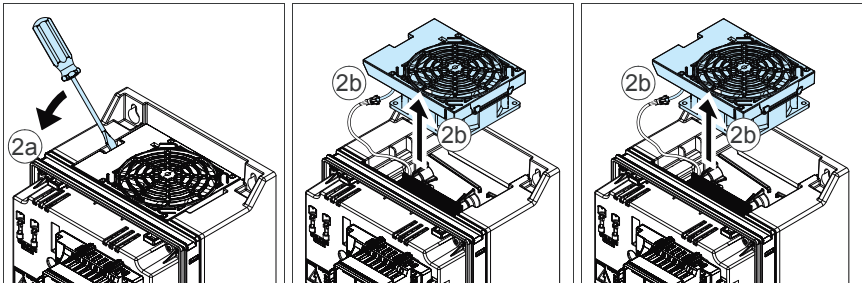
R1...R2: Put the connector and extra length of wires in the groove so that the wires do not get caught in the revolving fan.

R3: Put the extra length of wires under the fan assembly so that the wires do not get caught in the revolving fan.

R1...R2



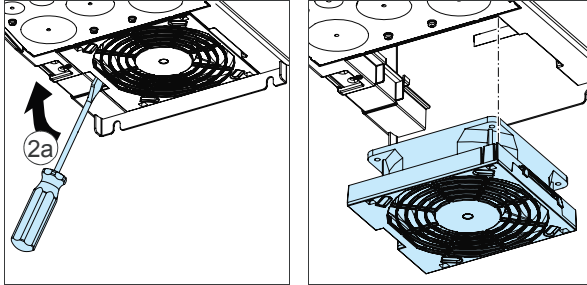
R3



R4

1. Lever the fan assembly off the drive frame with for example a screwdriver (2a) and pull out the fan assembly (2b).
2. Install the fan assembly in reverse order.

R4



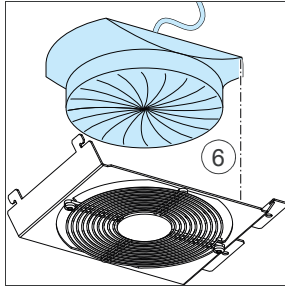
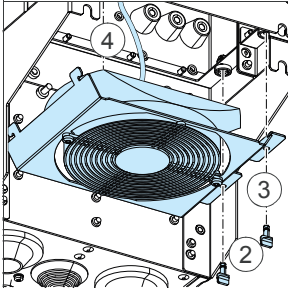
■ Replacing the main cooling fan, IP21 and IP55 (UL Type 1 and UL Type 12) frames R5...R8



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section *Electrical safety precautions (page 22)* before you start the work.
2. Remove the two mounting screws of the fan mounting plate at the bottom of the drive.
3. Pull the fan mounting plate down from the side edge.
4. Unplug the fan power supply wires from the drive.
5. Lift the fan mounting plate off.
6. Remove the fan from the mounting plate.
7. Install the new fan in reverse order.



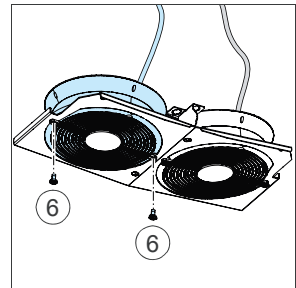
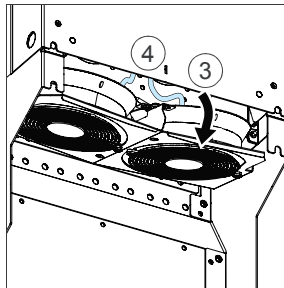
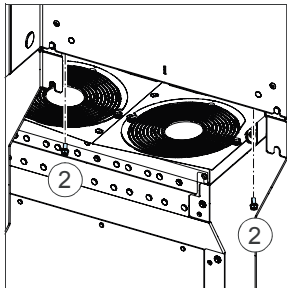
■ Replacing the main cooling fans, IP21 and IP55 (UL Type 1 and UL Type 12) frame R9



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section *Electrical safety precautions (page 22)* before you start the work.
2. Remove the two mounting screws of the fan mounting plate.
3. Turn the mounting plate downwards.
4. Unplug the fan power supply wires from the drive.
5. Remove the fan mounting plate.
6. Remove the fans by removing the two mounting screws.
7. Install the new fans in reverse order.



■ Replacing the auxiliary cooling fan, IP21 and IP55 (UL Type 1 and UL Type 12) frames R6...R9

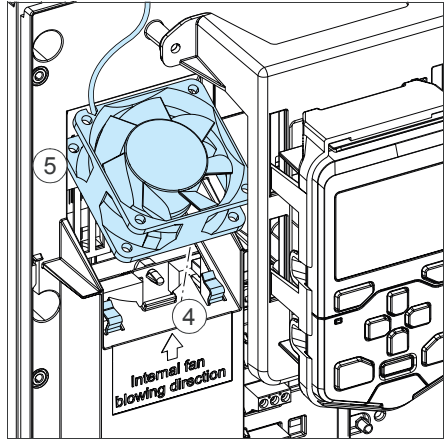
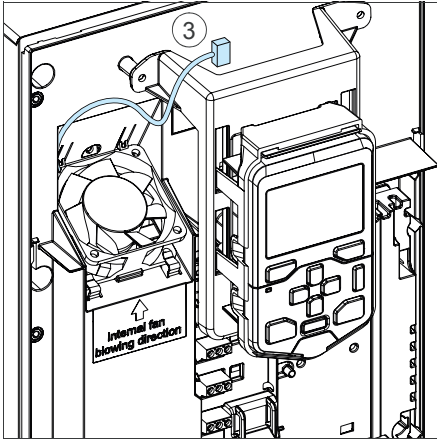


WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section *Electrical safety precautions (page 22)* before you start the work.
2. Remove the front cover (see section *IP21 (UL Type 1) (page 81)*).
3. Unplug fan power supply wires from the drive.
4. Release the retaining clips.
5. Lift the fan off.
6. Install the new fan in reverse order.

Note: Make sure that the arrow on the fan points up.



■ Replacing the auxiliary cooling fan, IP55 (UL Type 12) frames R1...R2

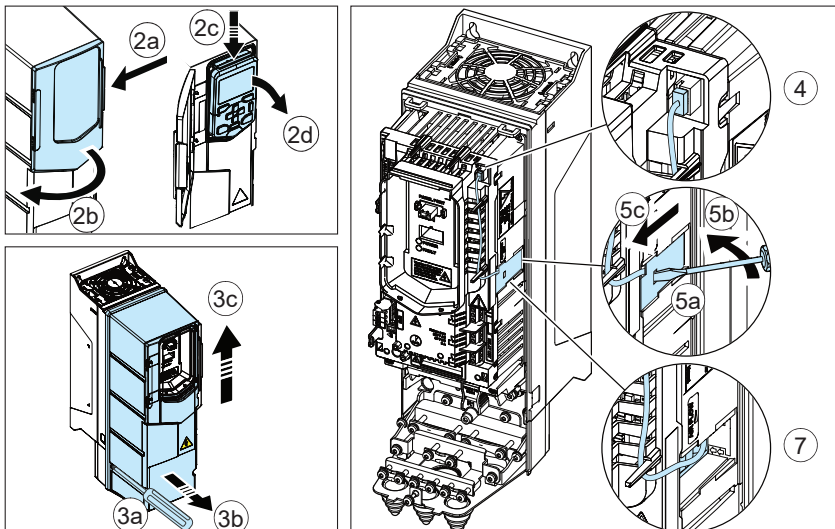


WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section *Electrical safety precautions* (page 22) before you start the work.
2. Remove the control panel: Press the retaining clip of the IP55 panel cover (2a) and open the cover (2b). Press the retaining clip of the control panel at the top (2c) and pull it forward from the top edge (2d).
3. Remove the front cover: Loosen the retaining screws with a screwdriver (3a) and lift the cover from the bottom outwards (3b) and then up (3c).
4. Unplug the fan power supply wires from the drive.
5. Remove the fingerguard: Insert a screwdriver into the hole of the fingerguard (5a), bend the front edge of the fingerguard a little away from the drive frame with the screwdriver (5b) and pull the fingerguard out of the groove (5c).
6. Pull off the fan.
7. Install the new fan assembly in reverse order. Route the wires round the pins.

Note: Make sure that the arrow on the fan points to the same direction as the arrow on the drive frame.



■ Replacing the auxiliary cooling fan, IP55 (UL Type 12) frame R3

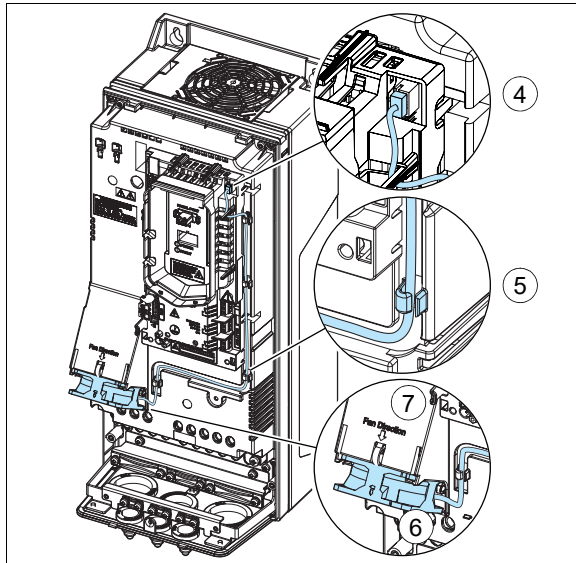
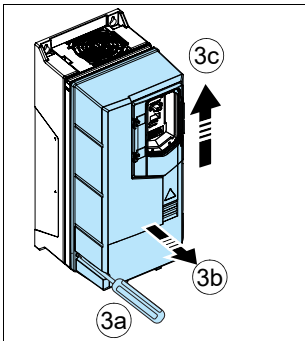
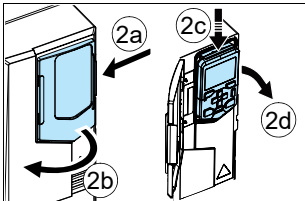


WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section *Electrical safety precautions (page 22)* before you start the work.
2. Remove the control panel: Press the retaining clip of the IP55 panel cover (2a) and open the cover (2b). Press the retaining clip of the control panel at the top (2c) and pull it forward from the top (2d).
3. Remove the front cover: Loosen the retaining screw with a screwdriver (3a) and lift the cover from the bottom outwards (3b) and then up (3c).
4. Unplug the fan power supply wires from the drive.
5. Detach the fan cable from the holders.
6. Pull off the plastic housing.
7. Pull off the fan.
8. Install the new fan and housing in reverse order.

Note: Make sure that the arrow on the fan points to the same direction as the arrow on the plastic housing (down).



■ Replacing the auxiliary cooling fan, IP55 (UL Type 12) frame R4; IP21 and IP55 (UL Type 1 and UL Type 12) frame R5

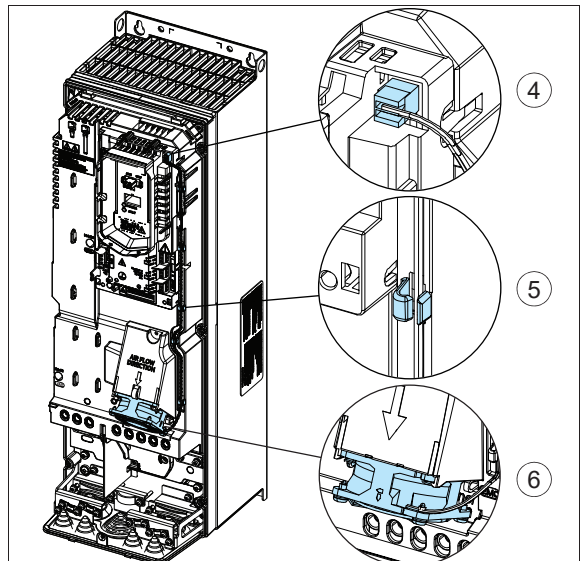
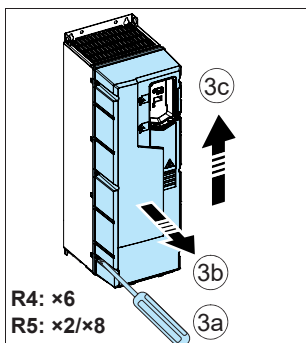
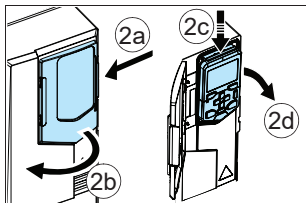


WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section [Electrical safety precautions \(page 22\)](#) before you start the work.
2. Remove the control panel: Press the retaining clip of the IP55 panel cover (2a) and open the cover (2b). Press the retaining clip of the control panel at the top (2c) and pull it forward from the top edge (2d).
3. Remove the front cover: Loosen the retaining screws (R4: 6 pieces, R5: IP21 2 pieces; IP55 8 pieces) with a screwdriver (3a) and lift the cover from the bottom outwards (3b) and then up (3c).
4. Unplug the fan power supply wires from the drive.
5. Detach the fan cable from the clips.
6. Pull the fan off.
7. Install the new fan in reverse order.

Note: Make sure that the arrow on the fan points down.



■ Replacing the second auxiliary cooling fan, IP55 (UL Type 12) frames R8...R9

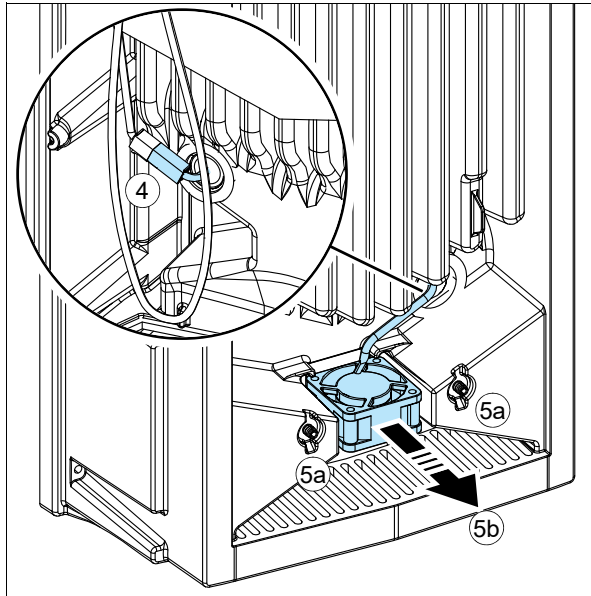
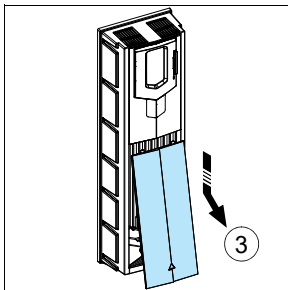
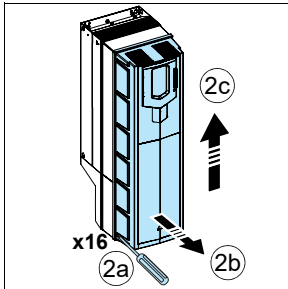


WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

1. Stop the drive and disconnect it from the power line. Wait for 5 minutes and then make sure by measuring that there is no voltage. See section [Electrical safety precautions \(page 22\)](#) before you start the work.
2. Remove the front cover: Loosen the retaining screws (16 pieces) with a screwdriver (2a) and lift the cover from the bottom outwards (2b) and then up (2c).
3. Remove the lower cover panel from the cover.
4. Unplug the fan power supply wires from the connector on the other side of the IP55 (UL Type 12) front cover.
5. Remove the retaining screws (5a) and pull off the fan (5b).
6. Install the new fan in reverse order.

Note: Make sure that the arrow on the fan points up.



Capacitors

The DC link of the drive contains several electrolytic capacitors. Operating time, load, and surrounding air temperature have an effect on the life of the capacitors. Capacitor life can be extended by decreasing the surrounding air temperature.

Capacitor failure is usually followed by damage to the unit and an input cable fuse failure, or a fault trip. If you think that any capacitors in the drive have failed, contact ABB.

■ Reforming the capacitors

The capacitors must be reformed if the drive has not been powered (either in storage or unused) for a year or more. The manufacturing date is on the type designation label. For information on reforming the capacitors, see *Capacitor reforming instructions* ([3BFE64059629](https://library.abb.com/en) [English]) in the ABB Library (<https://library.abb.com/en>).

Control panel

See *ACS-AP-I, -S, -W and ACH-AP-H, -W assistant control panels user's manual* ([3AUA0000085685](https://library.abb.com/en) [English]).

LEDs

■ Drive LEDs

There is a green POWER and a red FAULT LED on the front of the drive. They are visible through the panel cover but invisible if a control panel is attached to the drive. The table below describes the drive LED indications.

Drive LEDs POWER and FAULT, on the front of the drive, under the control panel / panel cover				
If a control panel is attached to the drive, switch to remote control (otherwise a fault will be generated), and then remove the panel to be able to see the LEDs				
LEDs off	LED lit and steady		LED blinking	
No power	Green (POWER)	Power supply on the board OK	Green (POWER)	<u>Blinking:</u> Drive in an alarm state <u>Blinking for one second:</u> Drive selected on the control panel when multiple drives are connected to the same panel bus.
	Red (FAULT)	Active fault in the drive. To reset the fault, press RESET from the control panel or switch off the drive power.	Red (FAULT)	Active fault in the drive. To reset the fault, switch off the drive power.

■ **Control panel LEDs**

The assistant control panel has one LED. The table below describes the control panel LED indications. For more information see *ACS-AP-I, -S, -W and ACH-AP-H, -W assistant control panels user's manual* (3AUJA0000085685 [English]).

Control panel LED, at the left edge of the control panel			
LED off	LED lit and steady		LED blinking/flickering
Panel has no power	Green	Drive functioning normally. Connection between the drive and control panel may be faulty or lost, or the panel and drive may be incompatible. Check the control panel display.	Green <u>Blinking:</u> Active warning in the drive <u>Flickering:</u> Data transferred between the PC tool and drive through the USB connection of the control panel
	Red	Check the display to see where the fault is. <ul style="list-style-type: none"> • Active fault in the drive. Reset the fault. • Active fault in another drive in the panel bus. Switch to the drive in question and check and reset the fault. 	Red Active fault in the drive. To reset the fault, cycle the drive power.
			Blue Panels with a Bluetooth interface only. <u>Blinking:</u> Bluetooth interface is enabled. It is in discoverable mode and ready for pairing. <u>Flickering:</u> Data is transferred through the Bluetooth interface of the control panel.

Functional safety components

The mission time of functional safety components is 20 years which equals the time during which failure rates of electronic components remain constant. This applies to the components of the standard Safe torque off circuit as well as any modules, relays and, typically, any other components that are part of functional safety circuits.

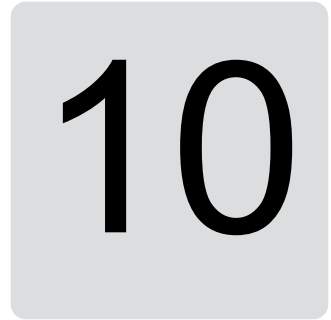
The expiry of mission time terminates the certification and SIL/PL classification of the safety function. The following options exist:

- Renewal of the whole drive and all optional functional safety module(s) and components.
- Renewal of the components in the safety function circuit. In practice, this is economical only with larger drives that have replaceable circuit boards and other components such as relays.

Note that some of the components may already have been renewed earlier, restarting their mission time. The remaining mission time of the whole circuit is however determined by its oldest component.

Contact your local ABB service representative for more information.





Technical data

Contents of this chapter

This chapter contains the technical specifications of the drive including the ratings, sizes and technical requirements, provisions for fulfilling the requirements for CE, UL and other approval marks.

Ratings

■ IEC

ACS580-01-	Input rating	Output ratings							Frame
		Max. current	Nominal use		Light-duty use		Heavy-duty use		
	I_1	I_{max}	I_2	P_n	I_{Ld}	P_{Ld}	I_{Hd}	P_{Hd}	
	A	A	A	kW	A	kW	A	kW	
3-phase $U_n = 230$ V									
04A7-2	4.7	6.3	4.7	0.75	4.6	0.75	3.5	0.55	R1
06A7-2	6.7	8.9	6.7	1.1	6.6	1.1	4.6	0.75	R1
07A6-2	7.6	11.9	7.6	1.5	7.5	1.5	6.6	1.1	R1
012A-2	12.0	19.1	12.0	3.0	11.8	3.0	7.5	2.2	R1
018A-2	16.9	22.0	16.9	4.0	16.7	4.0	10.6	3.0	R1
025A-2	24.5	32.7	24.5	5.5	24.2	5.5	16.7	4.0	R2
032A-2	31.2	43.6	31.2	7.5	30.8	7.5	24.2	5.5	R2
047A-2	46.7	62.4	46.7	11	46.2	11	30.8	7.5	R3
060A-2	60	83.2	60	15	59.4	15	46.2	11	R3
089A-2	89	135	89	22	88	22	74.8	18.5	R5

ACS580-01-	Input rating	Output ratings							Frame
		Max. current	Nominal use		Light-duty use		Heavy-duty use		
	I_1 A	I_{max} A	I_2 A	P_N kW	I_{Ld} A	P_{Ld} kW	I_{Hd} A	P_{Hd} kW	
115A-2	115	158	115	30	114	30	88.0	22	R5
144A-2	144	205	144	37	143	37	114	30	R6
171A-2	171	257	171	45	169	45	143	37	R7
213A-2	213	304	213	55	211	55	169	45	R7
276A-2	276	380	276	75	273	75	211	55	R8

ACS580-01-	Input rating	Output ratings			Frame
	I_1	I_2	P_N		
	A	A ¹⁾	kW		
1-phase $U_N = 230\text{ V}$					
04A7-2	3.3	2.2	0.37	R1	
06A7-2	4.6	3.2	0.55	R1	
07A6-2	6.3	4.2	0.75	R1	
012A-2	8.9	6.0	1.1	R1	
018A-2	11.8	6.8	1.5	R1	
025A-2	17.3	9.6	2.2	R2	
032A-2	30.4	15.2	4.0	R2	
047A-2	42	22	5.5	R3	
060A-2	55	28	7.5	R3	
089A-2	81	42	11	R5	
115A-2	111	54	15	R5	
144A-2	137	68	18.5	R6	
171A-2	153	80	22	R7	
213A-2	209	104	30	R7	
276A-2	258	130	37	R8	

¹⁾ Continuous current, no overloadability

See definitions and notes in section [Definitions \(page 234\)](#)

ACS580-01-	Input rating	Output ratings							Frame
		Max. current	Nominal use		Light-duty use		Heavy-duty use		
	I_1 A	I_{max} A	I_2 A	P_N kW	I_{Ld} A	P_{Ld} kW	I_{Hd} A	P_{Hd} kW	
3-phase $U_N = 400\text{ V (380...415 V)}$									

ACS580-01-	Input rating	Output ratings							Frame
		Max. current	Nominal use		Light-duty use		Heavy-duty use		
			I_1	I_2	P_N	I_{Ld}	P_{Ld}	I_{Hd}	
A	A	A	kW	A	kW	A	kW		
02A7-4	2.6	3.2	2.6	0.75	2.5	0.75	1.8	0.6	R1
03A4-4	3.3	4.7	3.3	1.1	3.1	1.1	2.6	0.8	R1
04A1-4	4.0	5.9	4.0	1.5	3.8	1.5	3.3	1.1	R1
05A7-4	5.6	7.2	5.6	2.2	5.3	2.2	4.0	1.5	R1
07A3-4	7.2	10.1	7.2	3.0	6.8	3.0	5.6	2.2	R1
09A5-4	9.4	13.0	9.4	4.0	8.9	4.0	7.2	3.0	R1
12A7-4	12.6	15.3	12.6	5.5	12.0	5.5	9.4	4.0	R1
018A-4	17.0	22.7	17.0	7.5	16.2	7.5	12.6	5.5	R2
026A-4	25.0	30.6	25.0	11.0	23.8	11.0	17.0	7.5	R2
033A-4	32.0	44.3	32.0	15.0	30.4	15.0	24.6	11.0	R3
039A-4	38.0	56.9	38.0	18.5	36.1	18.5	31.6	15.0	R3
046A-4	45.0	67.9	45.0	22.0	42.8	22.0	37.7	18.5	R3
062A-4	62	81	62	30	58	30	45	22	R4
062A-4	62	81	62	30	58	30	45	22	R4 v2
073A-4	73	110	73	37	68	37	61	30	R4
073A-4	73	110	73	37	68	37	61	30	R4 v2
089A-4	89	130	89	45	83	45	72	37	R4 v2
088A-4	88	130	88	45	83	45	72	37	R5
106A-4	106	157	106	55	100	55	87	45	R5
145A-4	145	178	145	75	138	75	105	55	R6
169A-4	169	247	169	90	161	90	145	75	R7
206A-4	206	287	206	110	196	110	169	90	R7
246A-4	246	350	246	132	234	132	206	110	R8
293A-4	293	418	293	160	278	160	246 ¹⁾	132	R8
363A-4	363	498	363	200	345	200	293	160	R9
430A-4	430	545	430	250	400	200	363 ²⁾	200	R9

ACS580-01-	Input rating	Output ratings							Frame
		Max. current	Nominal use			Heavy-duty use			
			I_1	I_{Ld}	P_{Ld}	I_{Hd}	P_{Hd}		
A	A	A	kW	hp	A	kW	hp		
3-phase $U_N = 480\text{ V}$									
02A7-4	2.1	2.9	2.1	0.75	1.0	1.6	0.55	0.75	R1
03A4-4	3.0	3.8	3.0	1.1	1.5	2.1	0.75	1.0	R1

ACS580-01-	Input rating	Output ratings							Frame
		Max. current	Nominal use			Heavy-duty use			
	I_1		I_{max}	I_{Ld}	P_{Ld}		I_{Hd}	P_{Hd}	
	A	A	A	kW	hp	A	kW	hp	
04A1-4	3.4	5.4	3.5	1.5	2.0	3.0	1.1	1.5	R1
05A7-4	4.8	6.1	4.8	2.2	3.0	3.4	1.5	2.0	R1
07A3-4	6.0	7.2	6.0	3.0	3.0	4.0	2.2	3.0	R1
09A5-4	7.6	8.6	7.6	4.0	5.0	4.8	3.0	3.0	R1
12A7-4	11.0	13.7	12.0	5.5	7.5	7.6	4.0	5.0	R1
018A-4	14.0	19.8	14.0	7.5	10.0	11.0	5.5	7.5	R2
026A-4	21.0	25.2	23.0	11.0	15.0	14.0	7.5	10.0	R2
033A-4	27.0	37.8	27.0	15.0	20.0	21.0	11.0	15.0	R3
039A-4	34.0	48.6	34.0	18.5	25.0	27.0	15.0	20.0	R3
046A-4	40.0	61.2	44.0	22.0	30.0	34.0	18.5	25.0	R3
062A-4	52	76	52	30	40	40	22	30	R4
062A-4	52	72	52	30	40	40	22	30	R4 v2
073A-4	65	94	65	37	50	52	30	40	R4
073A-4	65	94	65	37	50	52	30	40	R4 v2
089A-4	77	117	77	45	60	65	37	50	R4 v2
088A-4	77	122	77	45	60	65	37	50	R5
106A-4	96	148	96	55	75	77	45	60	R5
145A-4	124	178	124	75	100	96	55	75	R6
169A-4	156	247	156	90	125	124	75	100	R7
206A-4	180	287	180	110	150	156	90	125	R7
246A-4	240	350	240	132	200	180	110	150	R8
293A-4	260	418	260	160	200	240 ¹⁾	132	150	R8
363A-4	361	542	361	200	300	302	160	250	R9
430A-4	414	542	414	250	350	361 ²⁾	200	300	R9

¹⁾ Continuous current, no overloadability

See definitions and notes in section [Definitions \(page 234\)](#)

Definitions

U_n Nominal output voltage of the drive. For input voltage range [U_1], see section [Electrical power network specification \(page 286\)](#). 50 Hz for IEC ratings and 60 Hz for UL (NEC) ratings.

I_1 Nominal input current (rms) at 40 °C (104 °F).

I_{max} Maximum output current. Available for two seconds at start.

- I_2** Nominal output current. Maximum continuous rms output current allowed (no overload).
- P_n** Nominal power of the drive. Typical motor power (no overload). The kilowatt ratings apply to most IEC 4-pole motors. The horsepower ratings apply to most NEMA 4-pole motors.
- I_{Ld}** Maximum current with 10% overload, allowed for one minute every ten minutes.
- P_{Ld}** Typical motor power in light-duty use (10% overload). The horsepower (hp) ratings apply to most NEMA 4-pole motors.
- I_{Hd}** Maximum current with 50% overload, allowed for one minute every ten minutes.
 1) Maximum current with 30% overload, allowed for one minute every ten minutes.
 2) Maximum current with 25% overload, allowed for one minute every ten minutes.
- P_{Hd}** Typical motor power in heavy-duty use (50% overload).

■ **UL (NEC)**

ACS580-01-	Input rating	Output ratings					Frame size
		Max. current	Light-duty use		Heavy-duty use		
	I_1	I_{max}	I_{Ld}	P_{Ld}	I_{Hd}	P_{Hd}	
	A	A	A	hp	A	hp	
3-phase $U_1 = 208...240$ V, P_n at $U_n = 208/230$ V, 60 Hz							
04A6-2	4.6	6.3	4.6	1.0	3.5	0.8	R1
06A6-2	6.6	8.9	6.6	1.5	4.6	1.0	R1
07A5-2	7.5	11.9	7.5	2.0	6.6	1.5	R1
10A6-2	10.6	14.3	10.6	3.0	7.5	2.0	R1
017A-2	16.7	22.6	16.7	5.0	10.6	3.0	R1
024A-2	24	32.7	24.2	7.5	16.7	5.0	R2
031A-2	31	43.6	30.8	10	24.2	7.5	R2
046A-2	46	62.4	46.2	15	30.8	10	R3
059A-2	59	83.2	59.4	20	46.2	15	R3
088A-2	88	135	88	30	74.8	25	R5
114A-2	114	158	114	40	88.0	30	R5
143A-2	143	205	143	50	114	40	R6
169A-2	169	257	169	60	143	50	R7
211A-2	211	304	211	75	169	60	R7
273A-2	273	380	273	100	211	75	R8
343A-2	343	492	343	125	273	100	R9
396A-2	396	560	396	150	343	125	R9

ACS580-01-	Input rating	Output ratings		Frame size
	I_1	I_2	P_n	
	A	A ¹⁾	hp	
1-phase $U_1 = 208...240$ V, P_n at $U_n = 208/230$ V, 60 Hz				
04A6-2	3.3	2.2	0.5	R1
06A6-2	4.6	3.2	0.75	R1
07A5-2	6.3	4.2	1	R1
10A6-2	8.9	6.0	1.5	R1
017A-2	11.8	6.8	2.2	R1
024A-2	17.3	9.6	3	R2
031A-2	30.4	15.2	5	R2
046A-2	42	22	7.5	R3
059A-2	55	28	10	R3
075A-2	-	28	10	R4
088A-2	81	42	15	R5
114A-2	111	54	20	R5
143A-2	137	68	25	R6
169A-2	153	80	30	R7
211A-2	209	104	40	R7
273A-2	258	130	50	R8
343A-2	343	154	60	R9
396A-2	396	192	75	R9

ACS580-01-	Input rating	Output ratings					Frame size
		Max. current	Light-duty use		Heavy-duty use		
	I_1	I_{max}	I_{Ld}	P_{Ld}	I_{Hd}	P_{Hd}	
	A	A	A	hp	A	hp	
3-phase $U_n = 480$ V (440...480 V)							
02A1-4	2.1	2.9	2.1	1.0	1.6	0.75	R1
03A0-4	3.0	4.1	3.0	1.5	2.1	1.0	R1
03A5-4	3.5	5.4	3.5	2.0	3.0	1.5	R1
04A8-4	4.8	6.5	4.8	3.0	3.4	2.0	R1
06A0-4	6.0	8.6	6.0	3.0	4.0	3.0	R1
07A6-4	7.6	10.8	7.6	5.0	4.8	3.0	R1
012A-4	12.0	15.3	12.0	7.5	7.6	5.0	R1
014A-4	14.0	21.6	14.0	10.0	11.0	7.5	R2
023A-4	23.0	30.5	23.0	15.0	14.0	10.0	R2
027A-4	27.0	41.4	27.0	20.0	21.0	15.0	R3
034A-4	34.0	48.6	34.0	25.0	27.0	20.0	R3

ACS580-01-	Input rating	Output ratings					Frame size	
		Max. current	Light-duty use		Heavy-duty use			
			I_{\max}	I_{Ld}	P_{Ld}	I_{Hd}		P_{Hd}
			A	A	hp	A		hp
044A-4	44.0	61.2	44.0	30.0	34.0	25.0	R3	
052A-4	52	72	52	40	40	30	R4	
065A-4	65	94	65	50	52	40	R4	
077A-4	77	117	77	60	65	50	R4	
078A-4	77	117	77	60	65	50	R5	
096A-4	96	139	96	75	77	60	R5	
124A-4	124	173	124	100	96	75	R6	
156A-4	156	223	156	125	124	100	R7	
180A-4	180	281	180	150	156	125	R7	
240A-4	240	324	240	200	180	150	R8	
260A-4	260	418	260	200	240	150	R8	
302A-4	302	468	302	250	260	200	R9	
361A-4	361	498	361	300	302	250	R9	
414A-4	414	544	414	350	361	300	R9	

ACS580-01-	Input rating	Output ratings					Frame size	
		Max. current	Light-duty use		Heavy-duty use			
			I_{\max}	I_{Ld}	P_{Ld}	I_{Hd}		P_{Hd}
			A	A	hp	A		hp
3-phase $U_n = 575 \text{ V (500...600 V)}$								
02A7-6	2.7	4.3	2.7	2.0	2.4	1.5	R2	
03A9-6	3.9	5.3	3.9	3.0	2.7	2.0	R2	
06A1-6	6.1	8.2	6.1	5.0	3.9	3.0	R2	
09A0-6	9.0	12.2	9.0	7.5	6.1	5.0	R2	
011A-6	11.0	16.2	11.0	10	9.0	7.5	R2	
017A-6	17.0	23.0	17.0	15	11.0	10	R2	
022A-6	22	30.6	22	20	17	15	R3	
027A-6	27	39.6	27	25	22	20	R3	
032A-6	32	48.6	32	30	27	25	R3	
041A-6	41	58	41	40	32	30	R5	
052A-6	52	74	52	50	41	40	R5	
062A-6	62	94	62	60	52	50	R5	
077A-6	77	112	77	75	62	60	R5	
099A-6	99	139	99	100	77	75	R7	

ACS580-01- U_n	Input rating	Output ratings					Frame size
		Max. current	Light-duty use		Heavy-duty use		
	I_1	I_{max}	I_{Ld}	P_{Ld}	I_{Hd}	P_{Hd}	
	A	A	A	hp	A	hp	
125A-6	125	178	125	125	99	100	R7
144A-6	144	225	144	150	125	125	R8
192A-6	192	259	192	200	144	150	R9
242A-6	242	346	242	250	192	200	R9
271A-6	271	411	271	250	242	250	R9

Definitions

- U_n Nominal output voltage of the drive. For input voltage range [U_1 , see section [Electrical power network specification \(page 286\)](#)]. 50 Hz for IEC ratings and 60 Hz for UL (NEC) ratings.
- I_1 Nominal input current (rms) at 40 °C (104 °F).
- I_{max} Maximum output current. Available for two seconds at start.
- I_{Ld} Maximum current with 10% overload, allowed for one minute every ten minutes.
- P_{Ld} Typical motor power in light-duty use (10% overload). The horsepower (hp) ratings apply to most NEMA 4-pole motors.
- I_{Hd} Maximum current with 50% overload, allowed for one minute every ten minutes.
¹⁾ Maximum current with 40% overload, allowed for one minute every ten minutes.
- P_{Hd} Typical motor power in heavy-duty use (50% overload).

■ Conversion tables for IEC and North American type codes

IEC type ACS580-01	North American type ACS580-01	Frame size
3-phase $U_n = 230 V$		
04A7-2	04A6-2	R1
06A7-2	06A6-2	R1
07A6-2	07A5-2	R1
012A-2	10A6-2	R1
018A-2	017A-2	R1
025A-2	024A-2	R2
032A-2	031A-2	R2
047A-2	046A-2	R3
060A-2	059A-2	R3
-	075A-2	R4
089A-2	088A-2	R5

IEC type ACS580-01	North American type ACS580-01	Frame size
115A-2	114A-2	R5
144A-2	143A-2	R6
171A-2	169A-2	R7
213A-2	211A-2	R7
276A-2	273A-2	R8
346A-2	343A-2	R9
400A-2	396A-2	R9

IEC type ACS580-01	North American type ACS580-01	Frame size
3-phase $U_n = 480\text{ V}$		
02A7-4	02A1-4	R1
03A4-4	03A0-4	R1
04A1-4	03A5-4	R1
05A7-4	04A8-4	R1
07A3-4	06A0-4	R1
09A5-4	07A6-4	R1
12A7-4	012A-4	R1
018A-4	014A-4	R2
026A-4	023A-4	R2
033A-4	027A-4	R3
039A-4	034A-4	R3
046A-4	044A-4	R3
062A-4	052A-4	R4
073A-4	065A-4	R4
089A-4	077A-4	R4 v2
088A-4	078A-4	R5
106A-4	096A-4	R5
145A-4	124A-4	R6
169A-4	156A-4	R7
206A-4	180A-4	R7
246A-4	240A-4	R8
293A-4	260A-4	R8
293A-4	302A-4	R9
363A-4	361A-4	R9
430A-4	414A-4	R9

■ Sizing

Drive sizing is based on the rated motor current, voltage and power. To achieve the rated motor power given in the table, the rated current of the drive must be higher than or equal to the rated motor current. Also the rated power of the drive must be higher than or equal to the rated motor power. The power ratings are the same regardless of the supply voltage within one voltage range.

Note: The ratings apply at ambient temperature of 40 °C (104 °F) for I_2 (I_{Ld} for UL (NEC)). Above these temperatures derating is required.

Note: The DriveSize dimensioning PC tool available from ABB (<http://new.abb.com/drives/software-tools/drivesize>) is recommended for selecting the drive, motor and gear combination.

■ Deratings

The output load capacity (I_2 , I_{Ld} , I_{Hd} ; note that I_{max} is not derated) decreases in certain situations. In situations, where full motor power is required, oversize the drive so that the total derated output current provides sufficient capacity to supply the required nominal voltage to run the motor.

Note: The DriveSize dimensioning PC tool available from ABB (<http://new.abb.com/drives/software-tools/drivesize>) is also suitable for derating.

Note: If several situations are present at a time, the effects of derating are cumulative:

I_2 (derated) or I_{Ld} (derated) or I_{Hd} (derated) = (I_2 or I_{Ld} or I_{Hd}) x (switching frequency derating) x (altitude derating) x (ambient temperature derating), where no derating = 1.0.

Note: The motor may have a derating on it too.

Example 1, IEC: How to calculate the derated current

The IP21 / UL Type 1 drive type is ACS580-01-01-062A-4, which has drive output current of 62 A. Calculate the derated drive output current (I_2) at 4kHz switching frequency, at 1500 m altitude and at 50 °C ambient temperature as follows:

1. *Switching frequency derating by derating factor (page 246):*
No derating needed for 4 kHz.
2. *Altitude derating (page 245):*
The derating factor for 1500 m is $1 - 1/10\,000\text{ m} \cdot (1500 - 1000)\text{ m} = 0.95$.
The derated drive output current becomes $I_2 = 0.95 \cdot 62\text{ A} = 58.9\text{ A}$.
3. *Surrounding air temperature derating, IP21 (UL Type 1) (page 242):*
The derating factor for 50 °C ambient temperature = 0.90.
The derated drive output current becomes then $I_2 = 0.90 \cdot 58.9\text{ A} = 53.01\text{ A}$.

Example 1, UL (NEC): How to calculate the derated current

The IP21 / UL Type 1 drive type is ACS580-01-01-052A-4, which has drive output current of 52 A. Calculate the derated drive output current (I_{Ld}) at 4kHz switching frequency, at 4921 ft (1500 m) altitude and at 50 °C ambient temperature as follows:

1. *Switching frequency derating by derating factor (page 246):*
No derating needed for 4 kHz.
2. *Altitude derating (page 245):*
The derating factor for 4921 ft (1500 m) is $1 - 1/10\,000\text{ m} \cdot (1500 - 1000)\text{ m} = 0.95$.
The derated drive output current becomes $I_{Ld} = 0.95 \cdot 52\text{ A} = 49.4\text{ A}$.
3. *Surrounding air temperature derating, IP21 (UL Type 1) (page 242):*
The derating factor for 50 °C ambient temperature = 0.90.
The derated drive output current becomes then $I_{Ld} = 0.90 \cdot 49.4\text{ A} = 44.46\text{ A}$.

Example 2, IEC: How to calculate the required drive

If your application requires continuous 12.0 A of motor current (I_2) at 8 kHz switching frequency, the supply voltage is 400 V and the drive is situated at 1500 m altitude and at 35 °C ambient temperature, calculate the appropriate IP21 / (UL Type 1) drive size requirement as follows:

1. *Switching frequency derating by derating factor (page 246):*
The minimum size required is $I_2 = 12.0\text{ A} / 0.65 = 18.46\text{ A}$,
where 0.65 is the derating for 8 kHz switching frequency (frames R2...R3).
2. *Altitude derating (page 245):*
The derating factor for 1500 m is $1 - 1/10\,000\text{ m} \cdot (1500 - 1000)\text{ m} = 0.95$.
The minimum size required becomes then $I_2 = 18.46\text{ A} / 0.95 = 19.43\text{ A}$.
3. *Surrounding air temperature derating, IP21 (UL Type 1) (page 242):*
No derating needed for 35 °C ambient temperature.

Referring to I_2 in the ratings tables (starting from page 232), drive type ACS580-01-01-026A-4 exceeds the I_2 requirement of 19.43 A.

Example 2, UL (NEC): How to calculate the required drive

If your application requires continuous maximum current with 10% overload 12.0 A of motor current (I_{Ld}) at 8 kHz switching frequency, the supply voltage is 480 V and the drive is situated at 4921 ft (1500 m) altitude and at 35 °C ambient temperature, calculate the appropriate IP21 / UL Type 1 drive size requirement as follows:

1. *Switching frequency derating by derating factor (page 246):*
The minimum size required is $I_{Ld} = 12.0\text{ A} / 0.65 = 18.46\text{ A}$,
where 0.65 is the derating for 8 kHz switching frequency (frames R2...R3).
2. *Altitude derating (page 245):*
The derating factor for 4921 ft (1500 m) is $1 - 1/10\,000\text{ m} \cdot (1500 - 1000)\text{ m} = 0.95$.
The minimum size required becomes then $I_{Ld} = 18.46\text{ A} / 0.95 = 19.43\text{ A}$.

3. *Surrounding air temperature derating, IP21 (UL Type 1) (page 242):*

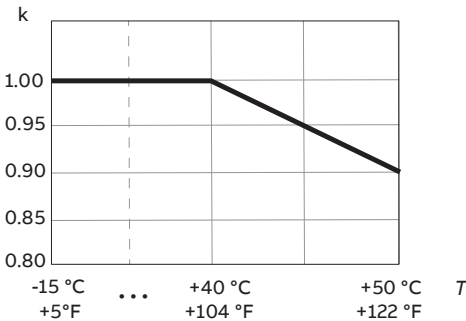
No derating needed for 35 °C ambient temperature.

Referring to I_{LD} in the ratings tables (starting from page 236), drive type ACS580-01-01-026A-4 exceeds the I_{Ld} requirement of 19.43 A.

Surrounding air temperature derating, IP21 (UL Type 1)

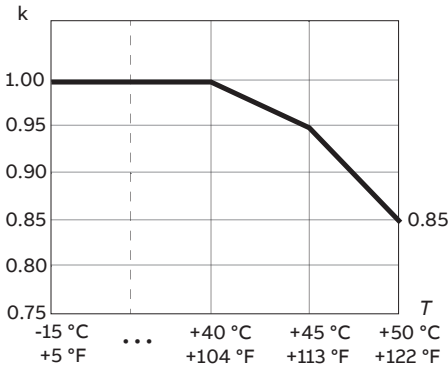
IP21 (UL Type 1) drive types, other than the exceptions below

In the temperature range +40...50 °C (+104...122 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k, in the diagram below).

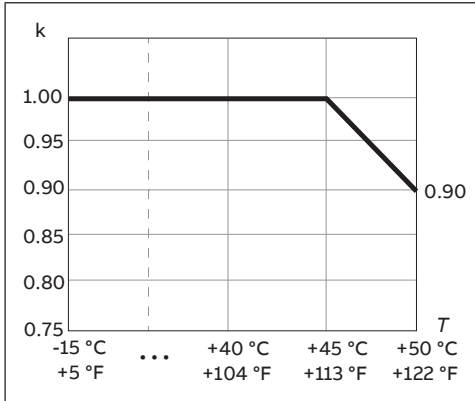


IP21 (UL Type 1) drive type -078A-4; -099A-6, -125A-6, -144A-6

-078A-4: In the temperature range +40...45 °C (+104...113 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). In the temperature range +45...50 °C (+113...122 °F), the rated output current is derated by 2% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):



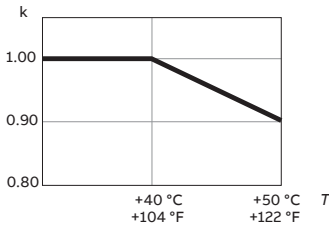
-099A-6, -125A-6, -144A-6: In the temperature range +40...45 °C (+104...113 °F), the rated output current is not derated at all. In the temperature range +45...50 °C (+113...122 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):



Surrounding air temperature derating, IP55 (UL Type 12)

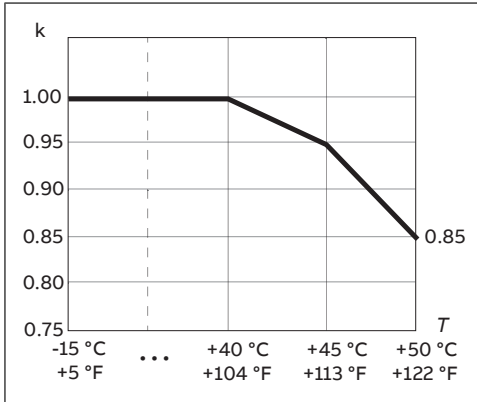
IP55 (UL Type 12) drive types, other than the exceptions below

In the temperature range +40...50 °C (+104...122 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):

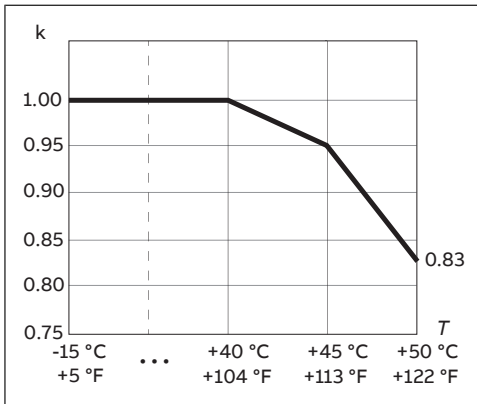


IP55 (UL Type 12) drive type -077A-4, -078A-4, -260A-4, -293A-4; -075A-2, -273A-2, -276A-2; -099A-6, -125A-6, -144A-6

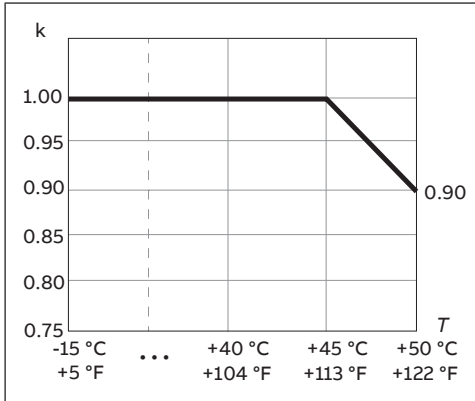
-077A-4 and -078A-4; -075A-2: In the temperature range +40...45 °C (+104...113 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). In the temperature range +45...50 °C (+113...122 °F), the rated output current is derated by 2.5% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):



-260A-4, -293A-4; -273A-2, -276A-2: In the temperature range +40...45 °C (+104...113 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). In the temperature range +45...50 °C (+113...122 °F), the rated output current is derated by 2.5% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):



-099A-6, -125A-6, -144A-6: In the temperature range +40...45 °C (+104...113 °F), the rated output current is not derated at all. In the temperature range +45...50 °C (+113...122 °F), the rated output current is derated by 1% for every added 1 °C (1.8 °F). The output current can be calculated by multiplying the current given in the rating table by the derating factor (k):



Altitude derating

In altitudes 1000...4000 m (3300...13120 ft) above sea level, the derating is 1% for every 100 m (330 ft).

Note: There are special considerations in corner-grounded installations above 2000 m. Contact your local ABB representative for further information.

The output current is calculated by multiplying the current given in the rating table by the derating factor k, which for x meters (1000 m <= x <= 4000 m) is:

$$K = 1 - 1/10000m * (X - 1000)m$$

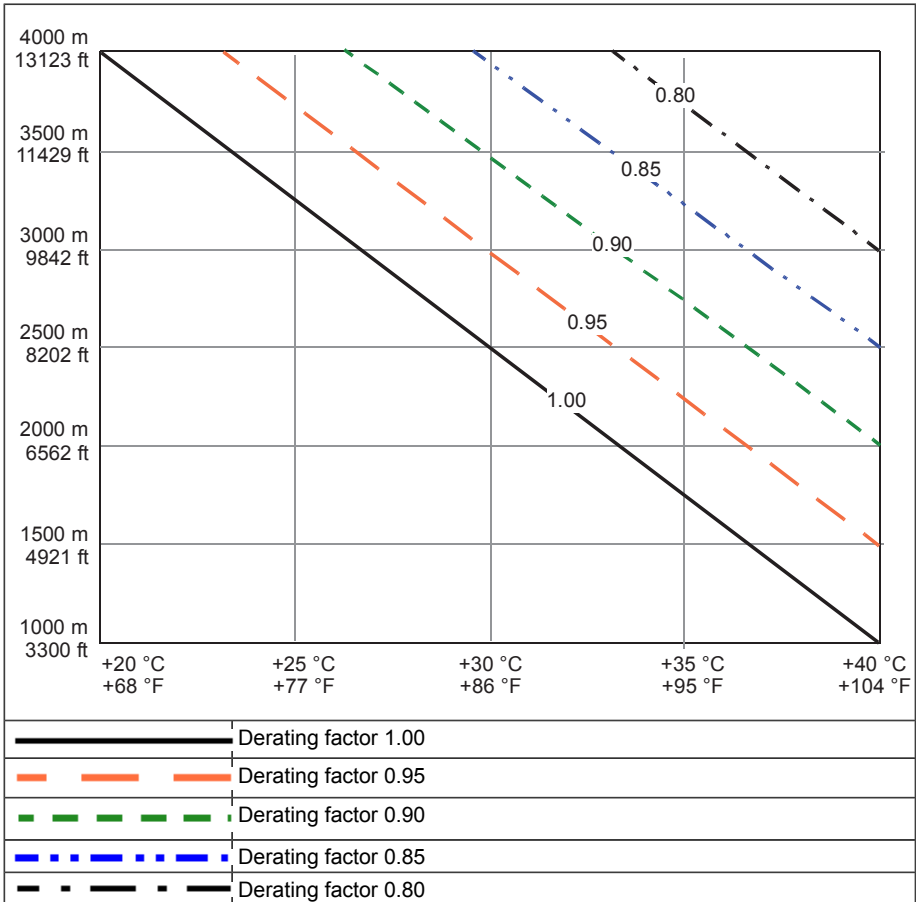
Altitude and surrounding air temperature

At altitudes from 1000...4000 m (3281...13123 ft) above sea level and temperature +40 °C (+104 °F), the derating is 1 percentage point for every additional 100 m (328 ft).

If surrounding air temperature is below +40 °C, the derating can be reduced by 1.5 percentage point for every 1 °C reduction in temperature.

A few combined altitude and temperature derating curves for 1000...4000 m are shown below. For example, if the temperature is 30 °C, the derating factor is 1 - 1.5% · 10 = 0.85.

For a more accurate derating, use the DriveSize PC tool.



Note: Check the supply network compatibility restrictions above 2000 m (6562 ft), see [Installation site altitude \(page 300\)](#). Check also PELV limitation on relay output terminals above 2000 m (6562 ft), see sections [Isolation areas, R1...R5 \(page 294\)](#) and [Isolation areas, R6...R9 \(page 295\)](#).

Switching frequency derating by derating factor

The output current is calculated by multiplying the current given in the rating table by the derating factor given in the table below.

Note: If you change the minimum switching frequency with parameter 97.02, derate according to the table below. Changing parameter 97.01 does not require derating.

IEC

Frame size	ACS580-01-	Derating factor (k) for the minimum switching frequencies at 40 °C (+104 °F)				
		1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
3-phase $U_n = 230\text{ V}$						
R1	04A7-2...18A2-2	1	1	1	0.89	0.80
R2	025A-2...032A-2	1	1	1	0.86	0.74
R3	047A-2...060A-2	1	1	1	0.85	0.72
R5	089A-2...115A-2	1	1	1	0.89	0.79
R6	144A-2	1	1	1	0.90	0.80
R7	171A-2...213A-2	1	1	1	0.90	0.80
R8	276A-2	1	1	1	-	-
3-phase $U_n = 400\text{ V}$						
R1	02A7-4...12A7-4	1	1	1	0.67	0.50
R2	018A-4...026A-4	1	1	1	0.65	0.48
R3	033A-4...046A-4	1	1	1	0.65	0.48
R4	062A-4	1	1	1	0.82	0.64
R4 v2	062A-4	1	1	1	0.65	0.48
R4	073A-4	1	1	1	0.73	0.55
R4 v2	073A-4...089A-4	1	1	1	0.65	0.47
R5	088A-4...106A-4	1	1	1	0.71	0.57
R6	145A-4	1	0.97	0.84	0.66	0.52
R7	169A-4...206A-4	1	0.98	0.89	0.71	0.53
R8	246A-4...293A-4	1	0.96	0.82	0.61	0.45
R9	363A-4...430A-4	1	0.95	0.79	0.58	0.43

UL (NEC)

Frame size	ACS580-01-	Derating factor (k) for the minimum switching frequencies at 40 °C (+104 °F)				
		1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
3-phase $U_1 = 200...240\text{ V}$, P_n at $U_n = 208/230\text{ V}$, 60 Hz						
R1	04A6-2...17A2-2	1	1	1	0.89	0.80
R2	024A-2...031A-2	1	1	1	0.86	0.74
R3	046A-2...059A-2	1	1	1	0.85	0.72
R4	075A-2	1	1	1	0.86	0.74
R5	088A-2...114A-2	1	1	1	0.89	0.79
R6	143A-2	1	1	1	0.90	0.80
R7	169A-2...213A-2	1	1	1	0.90	0.80
R8	273A-2	1	1	1	N/A	N/A
R9	343A-2...396A-2	1	1	1	0.90	0.80

Frame size	ACS580-01-	Derating factor (k) for the minimum switching frequencies at 40 °C (+104 °F)				
		1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz						
R1	02A1-4...012A-4	1	1	1	0.67	0.50
R2	014A-4...023A-4	1	1	1	0.65	0.48
R3	027A-4...044A-4	1	1	1	0.65	0.48
R4	052A-4...065A-4	1	1	1	0.82	0.64
R4	077A-4	1	1	1	0.73	0.55
R5	078A-4...096A-4	1	1	1	0.71	0.57
R6	124A-4	1	0.97	0.84	0.66	0.52
R7	156A-4...180A-4	1	0.98	0.89	0.71	0.53
R8	240A-4...260A-4	1	0.96	0.82	0.61	0.45
R9	302A-4	1	1	1	0.58	0.43
R9	361A-4...414A-4	1	0.95	0.79	0.58	0.43
3-phase $U_1 = 500...600$ V, P_n at $U_n = 575$ V, 60 Hz						
R2	02A7-6...017A-6	1	1	1	0.72	0.54
R3	022A-6...032A-6	1	1	1	0.74	0.50
R5	041A-6...077A-6	1	1	1	0.70	0.51
R7	099A-6...125A-6	1	1	1	0.66	0.50
R8	144A-6	1	1	1	0.66	0.50
R9	192A-6	1	1	1	0.66	0.50
R9	242A-6	1	1	0.83	0.66	0.50
R9	271A-6	1	1	0.74	0.66	0.50

Switching frequency derating with actual output current values

These tables show the output current values with different switching frequencies. Note that other derating factors, for example ambient temperature and altitude, may also affect to the output current.

IEC

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)					
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
		A	A	A	A	A	A	A
3-phase $U_n = 230$ V								
R1	04A7-2	4.7	4.7	4.7	4.7	4.2	3.8	3.4
R1	06A7-2	6.7	6.7	6.7	6.7	6.0	5.4	4.8
R1	07A6-2	7.6	7.6	7.6	7.6	6.8	6.1	5.5
R1	012A-2	12.0	12.0	12.0	12.0	10.7	9.6	8.6

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)						
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz	16 kHz
			A	A	A	A	A	A	A
R1	018A-2	18.0	16.9	16.9	16.9	15.0	13.5	12.1	
R2	025A-2	24.5	24.5	24.5	24.5	21.1	18.1	15.9	
R2	032A-2	31.2	31.2	31.2	31.2	26.8	23.1	20.3	
R3	047A-2	46.7	46.7	46.7	46.7	39.7	33.6	29.4	
R3	060A-2	60	60	60	60	51	43.2	37.8	
R5	089A-2	89	89	89	89	79	70	62	
R5	115A-2	115	115	115	115	103	91	81	
R6	144A-2	144	144	144	144	130	116	101	
R7	171A-2	171	171	171	171	154	137	120	
R7	213A-2	213	213	213	213	192	171	149	
R8	276A-2	276	276	276	276	N/A	N/A	N/A	

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)						
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz	16 kHz
			A	A	A	A	A	A	A
3-phase $U_n = 400$ V									
R1	02A7-4	2.6	2.6	2.6	2.6	1.7	1.3	N/A	
R1	03A4-4	3.3	3.3	3.3	3.3	2.2	1.7	N/A	
R1	04A1-4	4.0	4.0	4.0	4.0	2.7	2.0	N/A	
R1	05A7-4	5.6	5.6	5.6	5.6	3.8	2.8	N/A	
R1	07A3-4	7.2	7.2	7.2	7.2	4.8	3.6	N/A	
R1	09A5-4	9.4	9.4	9.4	9.4	6.3	4.7	N/A	
R1	12A7-4	12.6	12.6	12.6	12.6	8.4	6.3	N/A	
R2	018A-4	17.0	17.0	17.0	17.0	11.1	8.2	N/A	
R2	026A-4	25.0	25.0	25.0	25.0	16.3	12.0	N/A	
R3	033A-4	32.0	32.0	32.0	32.0	20.8	15.4	N/A	
R3	039A-4	38.0	38.0	38.0	38.0	24.7	18.2	N/A	
R3	046A-4	45.0	45.0	45.0	45.0	29.3	21.6	N/A	
R4	062A-4	62	62	62	62	51	39.7	N/A	
R4 v2	062A-4	62	62	62	62	40.1	29.7	N/A	
R4	073A-4	73	73	73	73	53	40.2	N/A	
R4 v2	073A-4	73	73	73	73	47.2	34.6	N/A	
R4 v2	089A-4	89	89	89	89	57.6	41.8	N/A	
R5	088A-4	88	88	88	88	62	50	N/A	
R5	106A-4	106	106	106	106	75	60	N/A	

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)					
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
		A	A	A	A	A	A	A
R6	145A-4	145	145	141	122	96	75	N/A
R7	169A-4	169	169	166	150	120	90	N/A
R7	206A-4	206	206	202	183	146	109	N/A
R8	246A-4	246	246	236	202	150	111	N/A
R8	293A-4	293	293	281	240	179	132	N/A
R9	363A-4	363	363	345	287	211	156	N/A
R9	430A-4	430	430	409	340	249	185	N/A

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)					
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
		A	A	A	A	A	A	A
3-phase $U_n = 480$ V								
R2	02A7-6	2.7	2.7	2.7	2.7	1.9	1.5	1.1
R2	03A9-6	3.9	3.9	3.9	3.9	2.8	2.1	1.6
R2	06A1-6	6.1	6.1	6.1	6.1	4.4	3.3	2.4
R2	09A0-6	9.0	9.0	9.0	9.0	6.5	4.9	3.6
R2	011A-6	11.0	11.0	11.0	11.0	7.9	5.9	4.4
R2	017A-6	17.0	17.0	17.0	17.0	12.2	9.2	6.8
R3	022A-6	22.0	22.0	22.0	22.0	15.4	11.0	7.5
R3	027A-6	27.0	27.0	27.0	27.0	18.9	13.5	9.2
R3	032A-6	32.0	32.0	32.0	32.0	22.4	16.0	10.9
R5	041A-6	41.0	41.0	41.0	41.0	28.7	20.9	14.8
R5	052A-6	52	52	52	52	36.4	26.5	18.7
R5	062A-6	62	62	62	62	43.4	31.6	22.3
R5	077A-6	77	77	77	77	54	39.3	27.7
R7	099A-6	99	99	99	99	65	50	N/A
R7	125A-6	125	125	125	125	83	63	N/A
R8	144A-6	144	144	144	144	95	72	N/A
R8	192A-6	192	192	192	192	127	96	N/A
R9	242A-6	242	242	242	201	160	121	N/A
R9	271A-6	271	271	271	201	179	136	N/A

UL (NEC)

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)					
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
		A	A	A	A	A	A	A
3-phase $U_1 = 200...240$ V, P_n at $U_n = 208/230$ V, 60 Hz								
R1	04A6-2	4.7	4.7	4.7	4.7	4.2	3.8	3.4
R1	06A6-2	6.7	6.7	6.7	6.7	6.0	5.4	4.8
R1	07A5-2	7.6	7.6	7.6	7.6	6.8	6.1	5.5
R1	10A6-2	12.0	12.0	12.0	12.0	10.7	9.6	8.6
R1	017A-2	16.9	16.9	16.9	16.9	15.0	13.5	12.1
R2	024A-2	24.5	24.5	24.5	24.5	21.1	18.1	15.9
R2	031A-2	31.2	31.2	31.2	31.2	26.8	23.1	20.3
R3	046A-2	46.7	46.7	46.7	46.7	39.7	33.6	29.4
R3	059A-2	60	60	60	60	51	43.2	37.8
R5	088A-2	89	89	89	89	79	70	62
R5	114A-2	115	115	115	115	103	91	81
R6	143A-2	144	144	144	144	130	116	101
R7	169A-2	171	171	171	171	154	137	120
R7	211A-2	213	213	213	213	192	171	149
R8	273A-2	276	276	276	276	N/A	N/A	N/A
R9	343A-2	343	343	343	343	309	274	N/A
R9	396A-2	396	396	396	396	356	317	N/A

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)					
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz
		A	A	A	A	A	A	A
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz								
R1	02A1-4	2.6	2.6	2.6	2.6	1.7	1.3	N/A
R1	03A0-4	3.3	3.3	3.3	3.3	2.2	1.7	N/A
R1	03A5-4	4.0	4.0	4.0	4.0	2.7	2.0	N/A
R1	04A8-4	5.6	5.6	5.6	5.6	3.8	2.8	N/A
R1	06A0-4	7.2	7.2	7.2	7.2	4.8	3.6	N/A
R1	07A6-4	9.4	9.4	9.4	9.4	6.3	4.7	N/A
R1	012A-4	12.6	12.6	12.6	12.6	8.4	6.3	N/A
R2	014A-4	17.0	17.0	17.0	17.0	11.1	8.2	N/A
R2	023A-4	25.0	25.0	25.0	25.0	16.3	12.0	N/A
R3	027A-4	32.0	32.0	32.0	32.0	20.8	15.4	N/A
R3	034A-4	38.0	38.0	38.0	38.0	24.7	18.2	N/A

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)						
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz	16 kHz
			A	A	A	A	A	A	A
R3	044A-4	45.0	45.0	45.0	45.0	29.3	21.6	N/A	
R4	052A-4	62	62	62	62	51	39.7	N/A	
R4 v2	052A-4	62	62	62	62	40.1	29.7	N/A	
R4	065A-4	73	73	73	73	53	40.2	N/A	
R4 v2	065A-4	73	73	73	73	47.2	34.6	N/A	
R4 V2	077A-4	88	88	88	88	57.6	41.8	N/A	
R5	078A-4	88	88	88	88	62	50	N/A	
R5	096A-4	106	106	106	106	75	60	N/A	
R6	124A-4	145	145	141	122	96	75	N/A	
R7	156A-4	169	169	166	150	120	90	N/A	
R7	180A-4	206	206	202	183	146	109	N/A	
R8	240A-4	246	246	236	202	150	111	N/A	
R8	260A-4	293	293	281	240	179	132	N/A	
R9	302A-4	302	N/A	N/A	N/A	N/A	N/A	N/A	
R9	361A-4	363	363	345	287	211	156	N/A	
R9	414A-4	430	430	409	340	249	185	N/A	

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)						
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz	16 kHz
			A	A	A	A	A	A	A
3-phase $U_1 = 500...600$ V, P_n at $U_n = 575$ V, 60 Hz									
R2	02A7-6	2.7	2.7	2.7	2.7	1.9	1.5	1.1	
R2	03A9-6	3.9	3.9	3.9	3.9	2.8	2.1	1.6	
R2	06A1-6	6.1	6.1	6.1	6.1	4.4	3.3	2.4	
R2	09A0-6	9.0	9.0	9.0	9.0	6.5	4.9	3.6	
R2	011A-6	11.0	11.0	11.0	11.0	7.9	5.9	4.4	
R2	017A-6	17.0	17.0	17.0	17.0	12.2	9.2	6.8	
R3	022A-6	22.0	22.0	22.0	22.0	15.4	11.0	7.5	
R3	027A-6	27.0	27.0	27.0	27.0	18.9	13.5	9.2	
R3	032A-6	32.0	32.0	32.0	32.0	22.4	16.0	10.9	
R5	041A-6	41.0	41.0	41.0	41.0	28.7	20.9	14.8	
R5	052A-6	52	52	52	52	36.4	26.5	18.7	
R5	062A-6	62	62	62	62	43.4	31.6	22.3	
R5	077A-6	77	77	77	77	54	39.3	27.7	
R7	099A-6	99	99	99	99	65	50	N/A	

Frame size	ACS580-01-	Nominal output	Nominal output current (I_2) for the minimum switching frequencies at 40 °C (+104 °F)						
			I_2	1 kHz	2 kHz	4 kHz	8 kHz	12 kHz	16 kHz
			A	A	A	A	A	A	A
R7	125A-6	125	125	125	125	83	63	N/A	
R8	144A-6	144	144	144	144	95	72	N/A	
R9	192A-6	192	192	192	192	127	96	N/A	
R9	242A-6	242	242	242	201	160	121	N/A	
R9	271A-6	271	271	271	201	179	136	N/A	

Output frequency derating

Output frequency derating applies for ratings up to ACS580-01-106A-4 (R5). Inverter output current is limited by the following factor k below 5 Hz absolute inverter output frequency f_{abs} .

$$k = 2/3 + 1/3 \cdot (f_{abs} / 5 \text{ Hz})$$

Fuses (IEC)

gG as well as uR or aR fuses for protection against short-circuit in the input power cable or drive are listed below. Either fuse type can be used for frames R1...R9 if it operates rapidly enough. The operating time depends on the supply network impedance and the cross-sectional area and length of the supply cable.

Note 1: See also [Implementing short-circuit and thermal overload protection \(page 104\)](#).

Note 2: Fuses with higher current rating than the recommended ones must not be used.

Note 3: Fuses from other manufacturers can be used if they meet the ratings and the melting curve of the fuse does not exceed the melting curve of the fuse mentioned in the table.

■ gG fuses

Check on the fuse time-current curve to ensure the operating time of the fuse is below 0.5 seconds. Obey the local regulations.

ACS580-01-	Min. short-circuit current ¹⁾	Input current	gG (IEC 60269)				
			Nominal current	I^2t	Voltage rating	ABB type	IEC 60269 size
			A	A ² s	V		
3-phase $U_n = 230 \text{ V}$							
04A7-2	200	4.7	25	2500	500	OFAF000H25	000
06A7-2	200	6.7	25	2500	500	OFAF000H25	000
07A6-2	200	7.6	25	2500	500	OFAF000H25	000

ACS580-01-	Min. short-circuit current ¹⁾	Input current	gG (IEC 60269)				
			Nominal current	I^2t	Voltage rating	ABB type	IEC 60269 size
			A	A ² s	V		
012A-2	200	12.0	25	2500	500	OFAF000H25	000
018A-2	200	16.9	25	2500	500	OFAF000H25	000
025A-2	320	24.5	40	7700	500	OFAF000H40	000
032A-2	320	31.2	40	7700	500	OFAF000H40	000
047A-2	500	46.7	63	20100	500	OFAF000H63	000
060A-2	500	60	63	20100	500	OFAF000H63	000
089A-2	1300	89	125	103000	500	OFAF000H125	00
115A-2	1300	115	125	103000	500	OFAF000H125	00
144A-2	1700	144	200	300000	500	OFAF000H200	0
171A-2	2300	171	250	600000	500	OFAF000H250	0
213A-2	3300	213	315	710000	500	OFAF1H315	1
276A-2	5500	276	400	110000	500	OFAF2H400	2
3-phase $U_n = 400$ or 480 V							
02A7-4	32	2.6	4	55	500	OFAF000H4	000
03A4-4	48	3.3	6	110	500	OFAF000H6	000
04A1-4	48	4.0	6	110	500	OFAF000H6	000
05A7-4	80	5.6	10	360	500	OFAF000H10	000
07A3-4	80	7.2	10	360	500	OFAF000H10	000
09A5-4	128	9.4	16	740	500	OFAF000H16	000
12A7-4	128	12.6	16	740	500	OFAF000H16	000
018A-4	200	17.0	25	2500	500	OFAF000H25	000
026A-4	256	25.0	32	4000	500	OFAF000H32	000
033A-4	320	32.0	40	7700	500	OFAF000H40	000
039A-4	400	38.0	50	16000	500	OFAF000H50	000
046A-4	500	45.0	63	20100	500	OFAF000H63	000
062A-4	800	62	80	37500	500	OFAF000H80	000
073A-4	1000	73	100	65000	500	OFAF000H100	000
089A-4	1000	89	100	65000	500	OFAF000H100	000
088A-4	1000	88	100	65000	500	OFAF000H100	000
106A-4	1300	106	125	103000	500	OFAF000H125	00
145A-4	1700	145	160	185000	500	OFAF000H160	00
169A-4	3300	169	250	600000	500	OFAF000H250	0
206A-4	5500	206	315	710000	500	OFAF1H315	1
246A-4	6400	246	355	920000	500	OFAF1H355	1
293A-4	7800	293	425	1300000	500	OFAF2H425	2
363A-4	9400	363	500	2000000	500	OFAF2H500	2

ACS580-01-	Min. short-circuit current ¹⁾	Input current	gG (IEC 60269)				
			Nominal current	I^2t	Voltage rating	ABB type	IEC 60269 size
			A	A ² s	V		
430A-4	10200	430	630	2800000	500	OFAF3H630	3

1) Minimum short-circuit current of the installation

■ uR and aR fuses

ACS580-01-	Min. short-circuit current ¹⁾	Input current	uR or aR (DIN 43620 blade style)				
			Nominal current	I^2t	Voltage rating	Bussmann type	IEC 60269 size
			A	A ² s	V		
3-phase $U_n = 230\text{ V}$							
04A7-2	120	4.7	40	460	690	170M1563	000
06A7-2	120	6.7	40	460	690	170M1563	000
07A6-2	120	7.6	40	460	690	170M1563	000
012A-2	120	12.0	40	460	690	170M1563	000
018A-2	120	16.9	40	460	690	170M1563	000
025A-2	170	24.5	63	1450	690	170M1565	000
032A-2	170	31.2	63	1450	690	170M1565	000
047A-2	280	46.7	80	2550	690	170M1566	000
060A-2	280	60	80	2550	690	170M1566	000
089A-2	700	89	200	15000	690	170M3815	1
115A-2	700	115	200	15000	690	170M3815	1
144A-2	1000	144	315	46500	690	170M3817	1
171A-2	1280	171	450	105000	690	170M5809	2
213A-2	1450	213	500	155000	690	170M5810	2
276A-2	2050	276	630	220000	690	170M6810	3
3-phase $U_n = 400\text{ or }480\text{ V}$							
02A7-4	65	2.6	25	130	690	170M1561	000
03A4-4	65	3.3	25	130	690	170M1561	000
04A1-4	65	4.0	25	130	690	170M1561	000
05A7-4	65	5.6	25	130	690	170M1561	000
07A3-4	65	7.2	25	130	690	170M1561	000
09A5-4	65	9.4	25	130	690	170M1561	000
12A7-4	65	12.6	25	130	690	170M1561	000
018A-4	120	17.0	40	460	690	170M1563	000
026A-4	120	25.0	40	460	690	170M1563	000

ACS580-01-	Min. short-circuit current ¹⁾	Input current	uR or aR (DIN 43620 blade style)				
			Nominal current	I^2t	Voltage rating	Bussmann type	IEC 60269 size
			A	A ² s	V		
033A-4	170	32.0	63	1450	690	170M1565	000
039A-4	170	38.0	63	1450	690	170M1565	000
046A-4	280	45.0	80	2550	690	170M1566	000
062A-4	380	62	100	4650	690	170M1567	000
073A-4	480	73	125	8500	690	170M1568	000
089A-4	700	89	160	16000	690	170M1569	000
088A-4	700	88	160	16000	690	170M1569	000
106A-4	1280	106	315	46500	690	170M3817	1
145A-4	1280	145	315	46500	690	170M3817	1
169A-4	1800	169	450	105000	690	170M5809	2
206A-4	2210	206	500	145000	690	170M5810	2
246A-4	3010	246	630	275000	690	170M5812	2
293A-4	4000	293	800	490000	690	170M6812D	3
363A-4	5550	363	1000	985000	690	170M6814D	3
430A-4	7800	430	1250	2150000	690	170M8554D	3

1) Minimum short-circuit current of the installation

ACS580-01-	Min. short-circuit current ¹⁾	Input current	uR or aR (DIN 43653 bolted tags)				
			Nominal current	I^2t	Voltage rating	Bussmann type	IEC 60269 size
			A	A ² s	V		
3-phase $U_N = 400$ or 480 V							
02A7-4	65	2.6	25	130	690	170M1311	0
03A4-4	65	3.3	25	130	690	170M1311	0
04A1-4	65	4.0	25	130	690	170M1311	0
05A7-4	65	5.6	25	130	690	170M1311	0
07A3-4	65	7.2	25	130	690	170M1311	0
09A5-4	65	9.4	25	130	690	170M1311	0
12A7-4	65	12.6	25	130	690	170M1311	0
018A-4	120	17.0	40	460	690	170M1313	0
026A-4	120	25.0	40	460	690	170M1313	0
033A-4	170	32.0	63	1450	690	170M1315	0
039A-4	170	38.0	63	1450	690	170M1315	0
046A-4	280	45.0	80	2550	690	170M1316	0
062A-4	380	62	100	4650	690	170M1417	0

ACS580-01-	Min. short-circuit current ¹⁾	Input current	uR or aR (DIN 43653 bolted tags)				
			Nominal current	I^2t	Voltage rating	Bussmann type	IEC 60269 size
			A	A ² s	V		
073A-4	480	73	125	8500	690	170M1318	0
089A-4	700	88	160	16000	690	170M1319	0
088A-4	700	88	160	16000	690	170M1319	0
106A-4	700	106	200	15000	690	170M3015	1
145A-4	1000	145	250	28500	690	170M3016	1
169A-4	1280	169	315	46500	690	170M3017	1
206A-4	1520	206	350	68500	690	170M3018	1
246A-4	3010	246	450	105000	690	170M5009	2
293A-4	4000	293	500	145000	690	170M5010	2
363A-4	5550	363	630	275000	690	170M5012	2
430A-4	7800	430	700	405000	690	170M5013	2

¹⁾ Minimum short-circuit current of the installation

Circuit breakers (IEC)

This section does not apply to the North American market. See section Circuit breakers (UL).

The protective characteristics of circuit breakers depend on the type, construction and settings of the breakers. There are also limitations pertaining to the short-circuit capacity of the supply network.



WARNING!

Due to the inherent operating principle and construction of circuit breakers, independent of the manufacturer, hot ionized gases can escape from the breaker enclosure in case of a short-circuit. To make sure of safe use, pay special attention to the installation and placement of the breakers. Obey the manufacturer's instructions.

You can use the circuit breakers listed below. Other circuit breakers can be used with drive if they provide the same electrical characteristics. ABB does not assume any liability whatsoever for the correct function and protection with circuit breakers not listed below. Furthermore, if the recommendations given by ABB are not obeyed, the drive can experience problems that the warranty does not cover.

ACS580-01-	MCBs and MCCBs					
	ABB type ¹⁾	Max. short-circuit	T _{max} frame XT / T class	T _{max} rating	Electronic release	SACE ordering code for breaker and release unit
		I _{sc}				
		kA	A	A	A	
3-phase U _n = 400 or 480 V						
02A7-4	S 203P-B/C/Z 10	20	N/A	N/A	N/A	N/A
03A4-4	S 203P-B/C/Z 10	20	N/A	N/A	N/A	N/A
04A1-4	S 203P-B/C/Z 10	20	N/A	N/A	N/A	N/A
05A7-4	S 203P-B/C/Z 10	20	N/A	N/A	N/A	N/A
07A3-4	S 203P-B/C/Z 10	20	N/A	N/A	N/A	N/A
09A5-4	S 203P-B/C/Z 10	20	N/A	N/A	N/A	N/A
12A7-4	S 203P-B/C/Z 16	20	N/A	N/A	N/A	N/A
018A-4	S 203P-B/C/Z 20	20	N/A	N/A	N/A	N/A
026A-4	S 203P-B/C/Z 25	20	N/A	N/A	N/A	N/A
033A-4	S 203P-B/C/Z 32	12	N/A	N/A	N/A	N/A
039A-4	S 203P-B/C/Z 40	12	N/A	N/A	N/A	N/A
046A-4	S 203P-B/C/Z 50	12	N/A	N/A	N/A	N/A
062A-4	S 803S-B/C 80	50	N/A	N/A	N/A	N/A
073A-4	S 803S-B/C 80	50	N/A	N/A	N/A	N/A
088A-4	S 803S-B/C 100	50	N/A	N/A	N/A	N/A
089A-4	S 803S-B/C 100	50	N/A	N/A	N/A	N/A
106A-4	S 803S-B/C 125	50	N/A	N/A	N/A	N/A
145A-4	XT4 L 250 Ekip LS/I In=250 3p F F	65	XT4	250	250	1SDA068555R1
169A-4	XT4 L 250 Ekip LS/I In=250 3p F F	65	XT4	250	250	1SDA068555R1
206A-4	T4 L 320 PR221DS-LS/I In=320 3p F F	65	T4	320	320	1SDA054141R1
246A-4	T5 L 400 PR221DS-LS/I In=400 3p F F	65	T5	400	400	1SDA054365R1
293A-4	T5 L 630 PR221DS-LS/I In=630 3p F F	65	T5	630	630	1SDA054420R1
363A-4	T5 L 630 PR221DS-LS/I In=630 3p F F	65	T5	630	630	1SDA054420R1
430A-4	T5 L 630 PR221DS-LS/I In=630 3p F F	65	T5	630	630	1SDA054420R1

1) Trip characteristic Z is recommended

Fuses (UL)

Fuses for branch circuit protection per NEC are listed below. ABB recommends fast acting class T or faster fuses in the USA. Obey local regulations.

ACS580-01-	Input current	Maximum current	Voltage rating	Bussmann type	UL class ¹⁾
	A	A	V		
3-phase $U_1 = 200 \dots 240$ V, P_n at $U_n = 208/230$ V, 60 Hz					
04A6-2	4.6	15	600	JJS-15	T
06A6-2	6.6	15	600	JJS-15	T
07A5-2	7.5	15	600	JJS-15	T
10A6-2	10.6	15	600	JJS-15	T
017A-2	16.7	30	600	JJS-30	T
024A-2	24.2	40	600	JJS-40	T
031A-2	30.8	40	600	JJS-40	T
046A-2	46.2	80	600	JJS-80	T
059A-2	59.4	80	600	JJS-80	T
075A-2	74.8	100	600	JJS-100	T
088A-2	88.0	150	600	JJS-150	T
114A-2	114	150	600	JJS-150	T
143A-2	143	200	600	JJS-200	T
169A-2	169	250	600	JJS-250	T
211A-2	211	300	600	JJS-300	T
273A-2	273	400	600	JJS-400	T
343A-2	343	500	600	JJS-500	T
396A-2	396	600	600	JJS-600	T
3-phase $U_1 = 440 \dots 480$ V, P_n at $U_n = 480$ V, 60 Hz					
02A1-4	2.1	15	600	JJS-15	T
03A0-4	3.0	15	600	JJS-15	T
03A5-4	3.5	15	600	JJS-15	T
04A8-4	4.8	15	600	JJS-15	T
06A0-4	6.0	15	600	JJS-15	T
07A6-4	7.6	15	600	JJS-15	T
012A-4	12.0	15	600	JJS-15	T
014A-4	14.0	30	600	JJS-30	T
023A-4	23.0	30	600	JJS-30	T
027A-4	27.0	40	600	JJS-40	T
034A-4	34.0	60	600	JJS-60	T
044A-4	44.0	60	600	JJS-60	T
052A-4	52	80	600	JJS-80	T
065A-4	62	90	600	JJS-90	T
077A-4	77	110	600	JJS-110	T

ACSS580-01-	Input current	Maximum current	Voltage rating	Bussmann type	UL class ¹⁾
	A	A	V		
078A-4	78	110	600	JJS-110	T
096A-4	106	150	600	JJS-150	T
124A-4	124	200	600	JJS-200	T
156A-4	156	225	600	JJS-225	T
180A-4	180	300	600	JJS-300	T
240A-4	240	350	600	JJS-350	T
260A-4	260	400	600	JJS-400	T
302A-4	302	500	600	JJS-500	T
361A-4 ²⁾	361	500	600	JJS-500	T
414A-4 ²⁾	414	600	600	JJS-600	T
3-phase $U_1 = 500 \dots 600$ V, P_n at $U_n = 575$ V, 60 Hz					
02A7-6	2.7	15	600	JJS-15	T
03A9-6	3.9	15	600	JJS-15	T
06A1-6	6.1	15	600	JJS-15	T
09A0-6	9.0	15	600	JJS-15	T
011A-6	11.0	15	600	JJS-15	T
017A-6	17.0	30	600	JJS-30	T
022A-6	22.0	40	600	JJS-40	T
027A-6	27.0	40	600	JJS-40	T
032A-6	32.0	40	600	JJS-40	T
041A-6	41.0	100	600	JJS-100	T
052A-6	52.0	100	600	JJS-100	T
062A-6	62.0	100	600	JJS-100	T
077A-6	77.0	100	600	JJS-100	T
099A-6	99.0	150	600	JJS-150	T
125A-6	125	200	600	JJS-200	T
144A-6	144	250	600	JJS-250	T
192A-6	192	300	600	JJS-300	T
242A-6	242	400	600	JJS-400	T
271A-6	271	400	600	JJS-400	T

1) Class J, CC, and CF fuses are also allowed at the same nominal current and voltage ratings

2) See note 8 below

1. Fuses are required as part of the installation, are not included in the base drive configuration and must be provided by others.
2. Fuses with a higher current rating than specified must not be used.

3. The UL listed fuses recommended by ABB are the required branch circuit protection per NEC. Circuit breakers listed in section *Circuit breakers (UL)* are also acceptable as branch circuit protection.
4. The recommended size or smaller UL listed 248 fast acting, time delay, or high speed fuses must be used to maintain the UL listing of the drive. Additional protection can be used. Refer to local codes and regulations.
5. A fuse of a different class can be used at the high fault rating where the I_{peak} and I^2t of the new fuse is not greater than that of the specified fuse.
6. UL listed 248 fast acting, time delay, or high speed fuses from other manufacturers can be used if they meet the same class and rating requirements specified in the rules above.
7. When installing a drive, always follow ABB installation instructions, NEC requirements and local codes.
8. Only 480 V R9 drives with serial numbers beginning 1204109256 when built in Finland and beginning 22106xxxxx when built in the U.S. may be protected with fuses other than Class T fuses.
9. Alternative fuses can be used if they meet certain characteristics. For acceptable fuses, see the manual supplement ([3AXD50000645015](#)).

Circuit breakers (UL)

These drives are suitable for use on a circuit capable of delivering not more than 65 kA symmetrical amperes (RMS) at 240 / 480 / 600 V maximum, when protected by appropriate circuit breakers in the tables below. Additional fuse protection is not required by UL when using circuit breakers herein. Circuit breakers are not required to be in the same enclosure as the drive.

Notes below the tables must be followed when using these breakers.

ACS580-01	Frame size	Input current	CB maximum current	CB voltage	Enclosure minimum volume	Drive volume	ABB circuit breaker
		A	A	V	in³	in³	65 kA @ 240 V
3-phase $U_1 = 200...240$ V, P_n at $U_n = 208/230$ V, 60 Hz							
04A6-2	R1	4.6	25	240	6480	506	XT2Naβ025#*****
06A6-2	R1	6.6	25	240	6480	506	XT2Naβ025#*****
07A5-2	R1	7.5	25	240	6480	506	XT2Naβ025#*****
10A6-2	R1	10.6	25	240	6480	560	XT2Naβ025#*****
017A-2	R1	16.7	25	240	6480	506	XT2Naβ025#*****
024A-2	R2	24.2	40	240	6480	684	XT2Naβ040#*****
031A-2	R2	30.8	40	240	6480	684	XT2Naβ040#*****
046A-2	R3	46.2	100	240	6480	1011	XT2Naβ100#*****

ACS580-01	Frame size	Input current	CB maximum current	CB voltage	Enclosure minimum volume	Drive volume	ABB circuit breaker
		A	A	V	in³	in³	65 kA @ 240 V
059A-2	R3	59.4	100	240	6480	1011	XT2Nαβ100#*****
075A-2	R4	74.8	100	240	6480	1669	XT2Nαβ100#*****
088A-2	R5	88.0	150	240	8100	2030	XT4Nαβ150#*****
114A-2	R5	114	150	240	8100	2030	XT4Nαβ150#*****
143A-2	R6	143	200	240	α	2880	XT4Nαβ200#*****
169A-2	R7	169	300	240	α	3369	XT5Nαβ30A#*****
211A-2	R7	211	300	240	α	3369	XT5Nαβ30A#*****
273A-2	R8	273	400	240	α	3858	XT5Nαβ40A#*****

α Enclosure minimum volume is not applicable

See notes 1-11 below

ACS580-01	Frame size	Input current	CB maximum current	CB voltage	Enclosure minimum volume	Drive volume	ABB circuit breaker	Maximum I ² t	Maximum I _{peak}
		A	A	V	in³	in³	65 kA @ 240 V	A²s	kA
3-phase U ₁ = 440...480 V, P _N at U _N = 480 V, 60 Hz									
02A1-4	R1	2.1	20	480	6480	506	XT2Hαβ020#*****	0.512×10 ⁶	23.2
03A0-4	R1	3.0	20	480	6480	506	XT2Hαβ020#*****	0.512×10 ⁶	23.2
03A5-4	R1	3.5	20	480	6480	506	XT2Hαβ020#*****	0.512×10 ⁶	23.2
04A8-4	R1	4.8	20	480	6480	560	XT2Hαβ020#*****	0.512×10 ⁶	23.2
07A6-4	R1	7.6	20	480	6480	506	XT2Hαβ020#*****	0.512×10 ⁶	23.2
012A-4	R1	12.0	20	480	6480	506	XT2Hαβ020#*****	0.512×10 ⁶	23.2
014A-4	R2	14.0	35	480	16200	684	XT2Hαβ035#*****	0.512×10 ⁶	23.2
023A-4	R2	23.0	35	480	16200	684	XT2Hαβ035#*****	0.512×10 ⁶	23.2
027A-4	R3	27.0	70	480	27720	1011	XT2Hαβ070#*****	0.512×10 ⁶	23.2
034A-4	R3	34.0	70	480	27720	1011	XT2Hαβ070#*****	0.512×10 ⁶	23.2
044A-4	R3	44.0	70	480	27720	1011	XT2Hαβ070#*****	0.512×10 ⁶	23.2
052A-4	R4	52	125	480	30240	1669	XT2Hαβ125#*****	0.512×10 ⁶	23.2
065A-4	R4	65	125	480	30240	1669	XT2Hαβ125#*****	0.512×10 ⁶	23.2
077A-4	R4	77	125	480	30240	1669	XT2Hαβ125#*****	0.512×10 ⁶	23.2
078A-4	R5	78	150	480	30240	2030	XT4Hαβ150#*****	0.98×10 ⁶	30
096A-4	R5	96	150	480	30240	2030	XT4Hαβ150#*****	0.98×10 ⁶	30
124A-4	R6	124	225	480	53705	2880	XT4Hαβ225#*****	0.98×10 ⁶	30
156A-4	R7	156	250	480	53703	3369	XT4Hαβ250#*****	0.98×10 ⁶	30
180A-4	R7	180	250	480	53703	3369	XT4Hαβ250#*****	0.98×10 ⁶	30

ACS580-01	Frame size	Input current	CB maximum current	CB voltage	Enclosure minimum volume	Drive volume	ABB circuit breaker	Maximum I^2t	Maximum I_{peak}
		A	A	V	in^3	in^3	65 kA @ 240 V	A^2s	kA
240A-4	R8	240	400	480	53703	3858	XT5Hαβ40A#*****	4.2×10^6	47.9
260A-4	R8	240	400	480	53703	3858	XT5Hαβ40A#*****	4.2×10^6	47.9
302A-4	R9	302	600	480	53703	5226	XT5Hαβ60B#*****	4.2×10^6	47.9
361A-4	R9	361	600	480	53703	5226	XT5Hαβ60B#*****	4.2×10^6	47.9
414A-4	R9	414	600	480	53703	5226	XT5Hαβ60B#*****	4.2×10^6	47.9

See notes 1-9 and 12-16 below

ACS580-01	Frame size	Input current	CB maximum current	CB voltage	Enclosure minimum volume	Drive volume	ABB circuit breaker	Maximum I^2t	Maximum I_{peak}
		A	A	V	in^3	in^3	65 kA @ 240 V	A^2s	kA
3-phase $U_1 = 500 \dots 600$ V, P_{η} at $U_{\eta} = 575$ V, 60 Hz									
02A7-6	R2	2.7	25	600	16200	684	XT4Vαβ025#*****	1.2×10^6	31.5
03A9-6	R2	3.9	25	600	16200	684	XT4Vαβ025#*****	1.2×10^6	31.5
06A1-6	R2	6.1	25	600	16200	684	XT4Vαβ025#*****	1.2×10^6	31.5
09A0-6	R2	9	25	600	16200	684	XT4Vαβ025#*****	1.2×10^6	31.5
011A-6	R2	11	25	600	16200	684	XT4Vαβ025#*****	1.2×10^6	31.5
017A-6	R2	17	25	600	16200	684	XT4Vαβ025#*****	1.2×10^6	31.5
022A-6	R3	22	50	600	16200	684	XT4Vαβ050#*****	1.2×10^6	31.5
027A-6	R3	27	50	600	16200	1011	XT4Vαβ050#*****	1.2×10^6	31.5
032A-6	R3	32	50	600	16200	1011	XT4Vαβ050#*****	1.2×10^6	31.5
041A-6	R5	41	125	600	16200	2030	XT4Vαβ125#*****	1.2×10^6	31.5
052A-6	R5	52	125	600	16200	2030	XT4Vαβ125#*****	1.2×10^6	31.5
062A-6	R5	62	125	600	16200	2030	XT4Vαβ125#*****	1.2×10^6	31.5
077A-6	R5	77	125	600	16200	2030	XT4Vαβ125#*****	1.2×10^6	31.5
099A-6	R7	99	200	600	18900	3369	XT4Vαβ200#*****	1.2×10^6	31.5
125A-6	R7	125	200	600	18900	3369	XT4Vαβ200#*****	1.2×10^6	31.5
144A-6	R7	144	250	600	32400	3858	XT4Vαβ200#*****	1.2×10^6	31.5
192A-6	R9	192	400	600	32400	5226	XT5Lαβ40A#*****	4.2×10^6	51.4
242A-6	R9	242	400	600	32400	5226	XT5Lαβ40A#*****	4.2×10^6	51.4
271A-6	R9	271	400	600	32400	5226	XT5Lαβ40A#*****	4.2×10^6	51.4

See notes 1-9, 12-13 and 17 below

Notes:

1. Drives that have an enclosure minimum volume listed must be mounted in an enclosure \geq enclosure minimum volume specified in the tables above.
 2. When multiple drives that have an enclosure minimum volume specified are installed in the same enclosure, minimum volume of the enclosure is determined by largest enclosure minimum volume of the drives to be placed in the enclosure, plus the volume(s) of each additional drive. i.e. for the 480V R6 and R3 drive select enclosure with the volume $\geq 53703+1011 = 54714 \text{ in}^3$.
 3. For UL Open Type, UL Type 1 or UL Type 12 drives that have a minimum enclosure volume indicated with ∞ , no minimum enclosure volume is required but the drive must be mounted inside an enclosure.
 4. If combining a drive with an enclosure minimum volume specified and others with an enclosure minimum volume indicated with ∞ , start with the largest specified enclosure minimum volume listed and add the drive volumes for the other drives.
 5. If you are only mounting drives with no enclosure minimum volume specified, you have no restrictions on the enclosure size, but follow air clearances specified in the drive HW manuals for sufficient ventilation around each drive.
 6. UL Open Type, UL Type 1 and UL Type 12 drives can be used inside of the enclosure. Use drive volume for all three types listed in the table when installing multiple drives in the enclosure.
 7. The ABB circuit breaker part number listed in the table is a base part number.
 - Symbol α represents 80% or 100% allowable continuous current. Options allowed are U, Q, C and D.
 - Symbol β represents the number of poles for the breaker. Options allowed are 3, and 4.
 - Symbol # represents trip units. Trip units allowed include A thru C, E thru L, P thru Z. If using Ekip breakers, set the overload current of the circuit breaker equal to or less than the value shown in the "CB Maximum Current" column in the tables above.
 - The digits indicated with an "*" represent accessories for the breakers and have no impact on the drive UL listing or performance or rating of the breaker.
 - For the ABB circuit breaker configurator refer to: https://lowvoltageconfigurator.tnb.com/configurator/#/config/tmax_xt
 8. Ratings in the tables are maximum for the given circuit breaker frame size. Breakers of the same frame size and interrupting rating with lower current ratings are also allowed.
 9. Using a circuit breaker with a lower KAIC rating is not allowed even if the available SC current is less than 65kA.
230V drives were tested with ABB inverse time circuit breakers rated at 65kA and 240V.
-

Notes 10 and 11 for 230V drives only:

10. Other manufacturers' inverse time circuit breakers can be used if they are UL 489 listed, they are 240V or higher, they have a 65kA or higher interrupting rating and they have the same or lower nominal current rating than the ABB specified circuit breaker.
11. Current limiting inverse time circuit breakers must not be used.
480V and 600V drives were tested with ABB current limiting inverse time circuit breakers rated at 65kA and 480V or 600V.

Notes 12 and 13 for 480V and 600V drives only:

12. When designing UL508A panels, Article SB 4.2.3 Exception No. 3 allows the use of other manufacturers' current limiting inverse time circuit breakers which have same voltage, current and interrupting rating, if I_{peak} and I^2t are the same or less than the ABB specified circuit breaker.
13. Non-current limiting inverse time circuit breakers must not be used.

Notes 14...16 for 480V drives only:

14. Enclosures for frames R1, R3, and R9 must have a solid bottom directly below the drive. i.e. fans, filters or louvers cannot be mounted directly below the drive but can be mounted in adjacent areas on the bottom of the enclosure.
15. Only 480V R8 frame drives with serial numbers after 1204301926 when built in Finland and after 2205002140 when built in the U.S. may be protected with circuit breakers listed in the tables above.
16. Only 480V R9 frame drives with serial numbers beginning 1204109256 when built in Finland and beginning 22106xxxxx when built in the U.S. may be protected with circuit breakers listed in the tables above.

Note 17 for 600V drives only:

17. Enclosures for frames R2, R3, R5 and R9 must have a solid bottom directly below the drive. i.e. fans, filters or louvers cannot be mounted directly below the drive but can be mounted in adjacent areas on the bottom of the enclosure.
18. Alternative circuit breakers can be used if they meet certain characteristics. For acceptable breakers see the manual supplement ([3AXD50000645015](#) [English]).

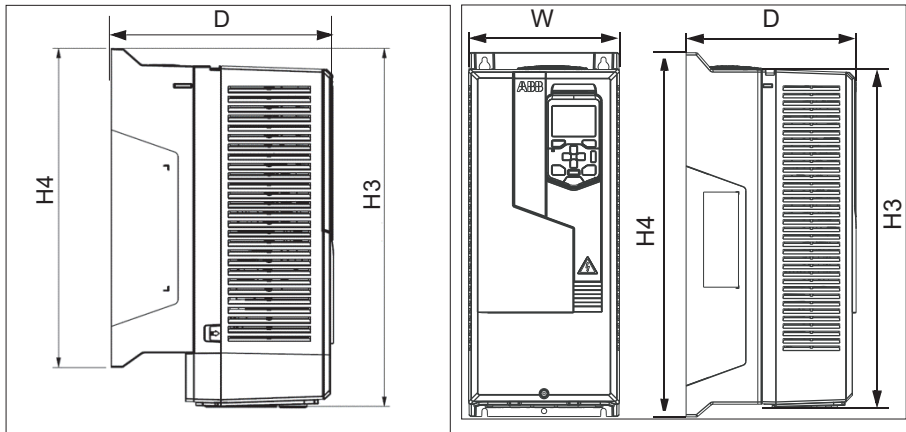
Dimensions, weights and free space requirements

Frame size	Dimensions and weights													
	IP21							UL Type 1						
	H1	H2	H3	H4	W	D	Weight	H1	H2	H3	H4	W	D	Weight
	mm	mm	mm	mm	mm	mm	kg	in	in	in	in	in	in	lb
R1	-	-	373	331	125	223	4.6	-	-	14.69	13.03	4.92	8.78	10.1
R2	-	-	473	432	125	229	6.6	-	-	18.62	17.01	4.92	9.00	14.6

Frame size	Dimensions and weights													
	IP21							UL Type 1						
	H1	H2	H3	H4	W	D	Weight	H1	H2	H3	H4	W	D	Weight
	mm	mm	mm	mm	mm	mm	kg	in	in	in	in	in	in	lb
R3	-*)	-*)	454	490	203	229	11.8	-*)	-*)	17.87	19.29	7.99	9.02	26.0
R4	-*)	-*)	600	636	203	257	19.0	-*)	-*)	23.62	25.04	7.99	10.12	41.9
R4 v2	-*)	-*)	601	636	203	257	20.0	-*)	-*)	23.66	25.04	7.99	10.12	44.1
R5	596	596	732	633	203	295	28.3	23.46	23.46	28.82	24.90	7.99	11.61	62.4
R6	548	549	727	589	252	369	42.4	21.57	21.63	28.62	23.20	9.92	14.53	93.5
R7	600	601	880	641	284	370	54	23.62	23.67	34.65	25.25	11.18	14.57	119.1
R8	680	677	965	721	300	393	69	26.77	26.66	37.99	28.39	11.81	15.47	152.1
R9	680	680	955	741	380	418	97	26.77	26.77	37.60	29.19	14.96	16.46	213.9

*) Frames with an integrated cable/conduit box

IP21 (UL Type 1) & IP55 (UL Type 12), R1...R2 IP21 (UL Type 1), R3...R4

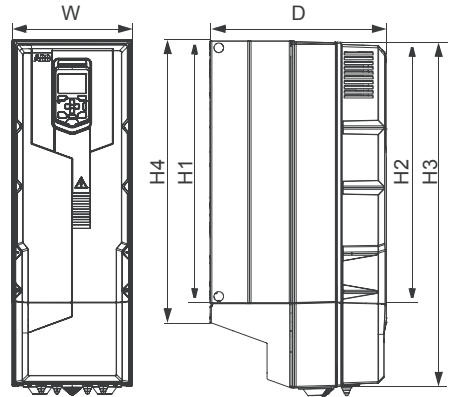


Symbols

IP21 (UL Type 1), R1...R2, R5...R9

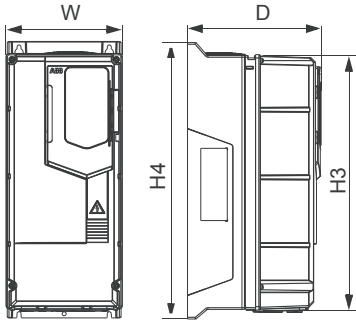
IP21 / UL Type 1

- H1** R5....R9: Height back without cable/conduit box
- H2** R5....R9: Height front without cable/conduit box
- H3** R3....R4: Height front, R1...R2, R5....R9: Height front with cable/conduit box
- H4** R3....R4: Height back, R1...R2, R5....R9: Height back with cable/conduit box
- W** Width
- D** Depth

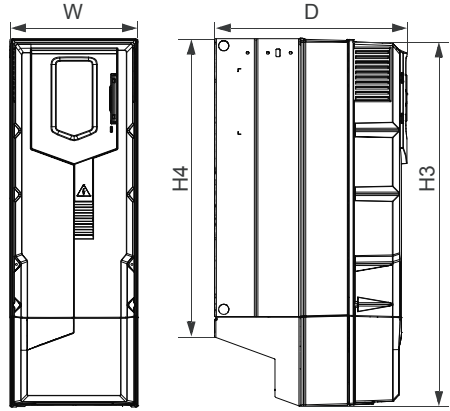


Frame size	Dimensions and weights												
	IP55					UL Type 12							
	H3	H4	W	D	Weight	H3	H4	H5	W	D	Weight	HH	HW
	mm	mm	mm	mm	kg	in	in	in	in	in	lb	in	in
R1	403	331	128	233	4.8	15.87	13.03	17.78	5.04	9.17	10.6	2.56	5.09
R2	503	432	128	239	6.8	17.95	17.01	21.49	5.04	9.41	15.0	2.56	5.10
R3	456	490	206	237	13.0	17.95	19.29	20.93	8.11	9.33	28.7	2.52	8.16
R4	600	636	203	265	20.0	23.62	25.04	27.03	7.99	10.43	44.1	2.83	8.59
R4 v2	601	636	203	265	21.0	23.66	25.04	27.05	7.99	10.43	46.3	2.83	8.59
R5	732	633	203	320	29.0	28.82	24.90	32.01	7.99	12.60	64.0	3.15	8.58
R6	727	589	252	380	43.0	28.62	23.20	34.81	9.92	14.96	94.8	6.10	11.46
R7	880	641	284	381	56.0	34.65	25.25	40.86	11.18	15.00	123.5	6.10	13.00
R8	965	721	300	452	77	37.99	28.39	44.23	11.81	17.80	169.8	6.10	13.80
R9	955	741	380	477	103	37.60	29.19	46.75	14.96	18.78	227.1	9.06	16.95

IP55 (UL Type 12)¹⁾, R3...R4



IP55 (UL Type 12)¹⁾, R1...R2, R5...R9

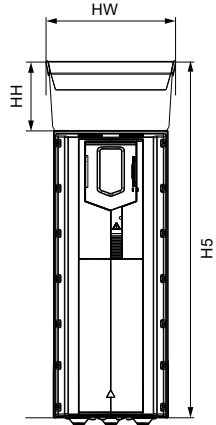
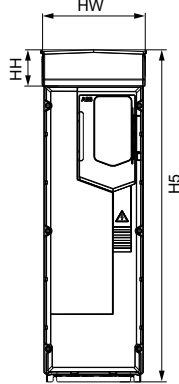
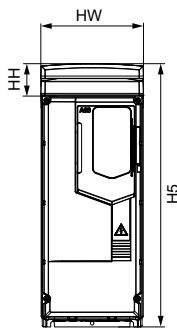
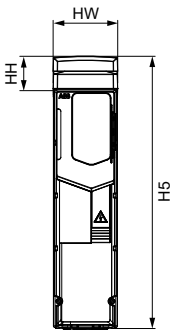


UL Type 12, R1...R3

UL Type 12, R1...R3

UL Type 12, R4...R5

UL Type 12, R6...R9



Symbols

H3 R3...R4: Height front, R1...R2)¹⁾ and R5...R9: Height front with cable/conduit box

H4 R3...R4: Height back, R1...R2)¹⁾ and R5...R9: Height back with cable/conduit box

W Width

D Depth

HH Hood height

HW Hood width

1) See H3 and H4 location for R1...R2 in the figure on page 266

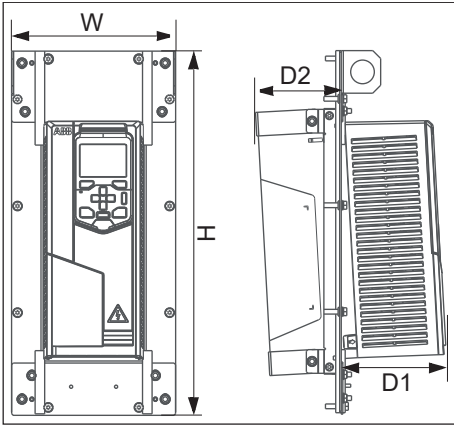
1) IP55 / UL Type 12 without hood

Frame size	Dimensions and weights with main switch and EMC C1 filter options (+F278, +F316, +E223), IP55									
	H3		H4		W		D		Weight	
	mm	in	mm	in	mm	in	mm	in	kg	lb
R1	403	18.87	331	13.03	128	5.04	255	10.03	5.4	11.8
R2	503	19.80	432	17.01	128	5.04	257	10.12	7.4	16.4
R3	733	28.86	519	20.43	207	8.15	258	10.16	15.0	33.1
R4	879	34.61	665	26.18	206	8.11	286	11.26	23.3	51.5
R5	1023	40.28	626	24.65	203	7.99	342	13.46	33.0	72.8

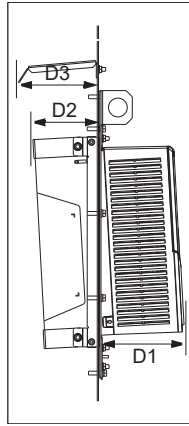
Frame size	Dimensions with flange option kit (+C135), IP21 (UL Type 1) & IP55 (UL Type 12)								UL Type 12 hood	
	H		W		D1		D2		D3	
	mm	in	mm	in	mm	in	mm	in	mm	in
R1	461	18.15	206	8.12	133	5.22	109	4.28	126	4.95
R2	551	21.69	206	8.12	130	5.13	114	4.51	126	4.95
R3	613	24.13	290	11.42	118	4.65	116	4.58	191	7.53
R4	776	30.55	290	11.42	120	4.74	137	5.41	191	7.53
R5	776	30.55	290	11.42	124	4.89	173	6.81	191	7.53
R6	672	26.46	374	14.72	194	7.63	170	6.67	191	7.53
R7	722	28.43	406	15.98	19	7.67	169	6.65	211	8.32
R8	814	32.01	433	17.46	202	7.95	184	7.22	209	8.22
R9	804	31.65	502	19.76	204	8.03	209	8.21	226	8.91

- H** Height with flange
- W** Width with flange
- D1** Depth of the drive outwards from the outer surface of the flange plate
- D2** Depth of the drive inwards from the outer surface of the flange plate
- D3** Depth of the hood inwards from the outer surface of the flange plate (UL Type 12 only)

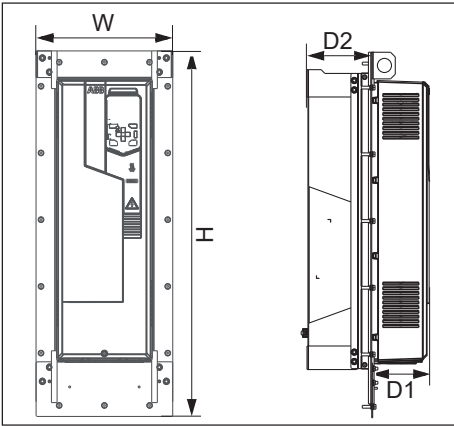
R1...R3 IP21 (UL Type 1)



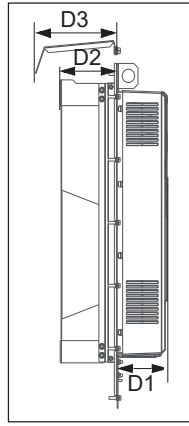
R1...R3 IP55 (UL Type 12)



R4...R9 IP21 (UL Type 1)



R4...R9 IP55 (UL Type 12)



Note:

1. For the actual degree of protection that can be achieved with flange for each frame size (on the back and front sides of the drive), see *Flange mounting kit installation supplement* (3AXD50000019100 [English]).
2. Regarding flange mounting:
 - The outside of the cabinet sets the limit for vertical positioning, since that is where the cooling is required
 - There are no limitations inside the cabinet; practically the outside positioning defines the distance between drives
 - The space inside the cabinet can be used as long as the following requirements are still met:
 - Heat loss dissipation inside the cabinet per the hardware manual
 - Sufficient space for the maintenance operations
 - Wire bending radius rules according to UL when planning routing for mains and motor cables.

Frame size	Free space, IP21 (UL Type 1)											
	Vertical mounting stand alone						Vertical mounting side by side					
	Above		Below		Beside		Above		Below ¹⁾		Between	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
R1	150	5.91	86	3.39	150	5.91	200	7.87	200	7.87	0	0
R2	150	5.91	86	3.39	150	5.91	200	7.87	200	7.87	0	0
R3	200	7.87	53	2.09	150	5.91	200	7.87	200	7.87	0	0
R4	53	2.09	200	7.87	150	5.91	200	7.87	200	7.87	0	0
R5	100	3.94	200	7.87	150	5.91	200	7.87	200	7.87	0	0
R6	155	6.10	300	11.8	150	5.91	200	7.87	300	11.8	0	0
R7	155	6.10	300	11.8	150	5.91	200	7.87	300	11.8	0	0
R8	155	6.10	300	11.8	150	5.91	200	7.87	300	11.8	0	0
R9	200	7.87	300	11.8	150	5.91	200	7.87	300	11.8	0	0

1) Free space below is always measured from the drive frame, not from the cable box.

Frame size	Free space, IP21 (UL Type 1) ¹⁾					
	Horizontal mounting					
	Above ²⁾		Below ^{2), 3)}		Between ²⁾	
	mm	in	mm	in	mm	in
R1	150	5.91	86	3.39	30/200	1.18/7.87

Frame size	Free space, IP21 (UL Type 1) ¹⁾					
	Horizontal mounting					
	Above ²⁾		Below ^{2), 3)}		Between ²⁾	
	mm	in	mm	in	mm	in
R2	150	5.91	86	3.39	30/200	1.18/7.87
R3	200	7.87	53	2.09	30/200	1.18/7.87
R4	30	1.18	200	7.87	30/200	1.18/7.87
R5	30	1.18	200	7.87	30/200	1.18/7.87

1) **Note:** Horizontal installation meets IP20 requirements only.

2) For definition, see the figure on page 56

3) Free space below is always measured from the drive frame, not from the cable box.

Frame size	Free space, IP55 (UL Type 12)											
	Vertical mounting stand alone						Vertical mounting side by side					
	Above		Below		Beside		Above		Below ¹⁾		Between	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
R1	150	5.91	86	3.39	150	5.91	200	7.87	200	7.87	0	0
R2	150	5.91	86	3.39	150	5.91	200	7.87	200	7.87	0	0
R3	200	7.87	53	2.09	150	5.91	200	7.87	200	7.87	0	0
R4	53	2.09	200	7.87	150	5.91	200	7.87	200	7.87	0	0
R5	100	3.94	200	7.87	150	5.91	200	7.87	200	7.87	0	0
R6	155	6.10	300	11.8	150	5.91	200	7.87	300	11.8	0	0
R7	155	6.10	300	11.8	150	5.91	200	7.87	300	11.8	0	0
R8	155	6.10	300	11.8	150	5.91	200	7.87	300	11.8	0	0
R9	200	7.87	300	11.8	150	5.91	200	7.87	300	11.8	0	0

1) Free space below is always measured from the drive frame, not from the cable box.

Frame size	Free space, IP55 (UL Type 12) ¹⁾					
	Horizontal mounting					
	Above ²⁾		Below ^{2), 2)}		Between ²⁾	
	mm	in	mm	in	mm	in
R1	150	5.91	86	3.39	30/200	1.18/7.87
R2	150	5.91	86	3.39	30/200	1.18/7.87
R3	200	7.87	53	2.09	30/200	1.18/7.87
R4	30	1.18	200	7.87	30/200	1.18/7.87
R5	30	1.18	200	7.87	30/200	1.18/7.87

1) **Note:** IP55/UL Type 12 drive mounted horizontally meets IP21/ UL Type 1 ratings.

2) Free space below is always measured from the drive frame, not from the cable box.

See the figures in section *Examining the installation site* (page 52).

Note: IP55 (UL Type 12) does not imply that the drive can be installed outside/outdoors. To install outside, contact your local ABB representative directly for specific instructions (3AXD10000425906). The warranty will be void if installed outdoors without using these special instructions.

Losses, cooling data and noise

The air flow direction is from bottom to top.

■ Cooling air flow, heat dissipation and noise for stand-alone drives

The table below specifies the heat dissipation in the main circuit at nominal load and in the control circuit with minimum load (I/O, options and panel not in use) and maximum load (all digital inputs and relays in the ON state, and the panel, fieldbus and fan in use). The total heat dissipation is the sum of the heat dissipation in the main and control circuits. Use the maximum heat dissipation when designing cabinet or electrical room cooling needs.

IEC

ACS580-01-	Typical heat dissipation ¹⁾		Air flow		Noise	Frame size
	W	BTU/h	m ³ /h	CFM	dB(A)	
3-phase $U_n = 230\text{ V}$						
04A7-2	51	174	43	25	59	R1
06A7-2	70	239	43	25	59	R1
07A6-2	80	273	43	25	59	R1
012A-2	142	485	43	25	59	R1
018A-2	228	778	43	25	59	R1
025A-2	253	863	101	59	64	R2
032A-2	358	1222	101	59	64	R2
047A-2	527	1798	179	105	76	R3
060A-2	775	2644	179	105	76	R3
089A-2	876	2989	139	82	63	R5
115A-2	1285	4385	139	82	63	R5
144A-2	1932	6592	435	256	67	R6
171A-2	2000	6824	450	265	67	R7
213A-2	2854	9738	450	265	67	R7
276A-2	3567	12171	550	324	65	R8
3-phase $U_n = 400\text{ or }480\text{ V}$						
02A7-4	42	143	43	25	59	R1
03A4-4	50	171	43	25	59	R1
04A1-4	59	201	43	25	59	R1
05A7-4	83	283	43	25	59	R1

ACS580-01-	Typical heat dissipation ¹⁾		Air flow		Noise	Frame size
	W	BTU/h	m ³ /h	CFM	dB(A)	
07A3-4	97	331	43	25	59	R1
09A5-4	135	461	43	25	59	R1
12A7-4	211	720	43	25	59	R1
018A-4	238	812	101	59	64	R2
026A-4	382	1303	101	59	64	R2
033A-4	486	1658	179	105	76	R3
039A-4	517	1764	179	105	76	R3
046A-4	667	2276	179	105	76	R3
062A-4	867	2958	134	79	69	R4
062A-4	803	2740	150	88	70	R4 v2
073A-4	1114	3801	134	79	69	R4
073A-4	882	3010	150	88	70	R4 v2
089A-4	1059	3613	159	94	70	R4 v2
088A-4	1139	3886	139	82	63	R5
106A-4	1290	4402	139	82	63	R5
145A-4	1960	6688	435	256	67	R6
169A-4	2021	6896	450	265	67	R7
206A-4	2785	9503	450	265	67	R7
246A-4	3126	10666	550	324	65	R8
293A-4	4066	13874	550	324	65	R8
363A-4	4834	16494	1150	677	68	R9
430A-4	6067	20701	1150	677	68	R9

¹⁾ Typical drive losses when it operates at 90% of the motor nominal frequency and 100% of the drive nominal output current.

UL (NEC)

ACS580-01-	Typical heat dissipation ¹⁾		Air flow		Noise	Frame size
	W	BTU/h	m ³ /h	CFM	dB(A)	
3-phase $U_1 = 200...240$ V, P_n at $U_n = 208/230$ V, 60 Hz						
04A6-2	50	171	43	25	59	R1
06A6-2	69	235	43	25	59	R1
07A5-2	79	270	43	25	59	R1
10A6-2	120	409	43	25	59	R1
017A-2	203	693	43	25	59	R1
024A-2	247	843	101	59	64	R2
031A-2	348	1187	101	59	64	R2
046A-2	518	1767	179	105	76	R3
059A-2	762	2600	179	105	76	R3

ACS580-01-	Typical heat dissipation 1)		Air flow		Noise	Frame size
	W	BTU/h	m ³ /h	CFM	dB(A)	
075A-2	809	2760	288	170	69	R4
088A-2	861	2938	139	82	63	R5
114A-2	1268	4327	139	82	63	R5
143A-2	1916	6538	435	256	67	R6
169A-2	1965	6705	450	265	67	R7
211A-2	2809	9585	450	265	67	R7
273A-2	3518	12004	550	324	65	R8
343A-2	2547	8691	1150	677	68	R9
396A-2	3060	10441	1150	677	68	R9
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz						
02A1-4	37	126	43	25	59	R1
03A0-4	47	160	43	25	59	R1
03A5-4	52	177	43	25	59	R1
04A8-4	71	242	43	25	59	R1
07A6-4	103	351	43	25	59	R1
012A-4	200	682	43	25	59	R1
018A-4	238	812	101	59	64	R2
023A-4	342	1167	101	59	64	R2
027A-4	386	1317	179	105	76	R3
034A-4	446	1522	179	105	76	R3
044A-4	656	2238	179	105	76	R3
052A-4	671	2290	134	79	69	R4
052A-4	640	2184	150	88	70	R4 v2
065A-4	719	2453	134	79	69	R4
065A-4	760	2593	150	88	70	R4 v2
077A-4	1047	3573	159	94	70	R4 v2
078A-4	941	3211	139	82	63	R5
096A-4	1127	3845	139	82	63	R5
124A-4	1563	5333	435	256	67	R6
156A-4	1815	6193	450	265	67	R7
180A-4	2285	7797	450	265	67	R7
240A-4	3039	10369	550	324	65	R8
302A-4	3253	11100	N/A	N/A	N/A	R9
361A-4	4836	16501	1150	677	68	R9
414A-4	5691	19418	1150	677	68	R9
3-phase $U_1 = 525...600$ V, P_n at $U_n = 575$ V, 60 Hz						
02A7-6	66	225	101	59	64	R2
03A9-6	84	287	101	59	64	R2

ACS580-01-	Typical heat dissipation ¹⁾		Air flow		Noise	Frame size
	W	BTU/h	m ³ /h	CFM	dB(A)	
06A1-6	133	454	101	59	64	R2
09A0-6	174	594	101	59	64	R2
011A-6	228	778	101	59	64	R2
017A-6	322	1099	101	59	64	R2
022A-6	430	1467	179	105	75	R3
027A-6	524	1788	179	105	75	R3
032A-6	619	2112	179	105	75	R3
041A-6	835	2849	139	82	63	R5
052A-6	1024	3494	139	82	63	R5
062A-6	1240	4231	139	82	63	R5
077A-6	1510	5152	139	82	63	R5
099A-6	2061	7032	450	265	67	R7
125A-6	2466	8414	450	265	67	R7
144A-6	3006	10257	550	324	65	R8
192A-6	4086	13942	1150	677	68	R9
242A-6	4896	16706	1150	677	68	R9
271A-6	4896	16706	1150	677	68	R9

¹⁾ Typical drive losses when it operates at 90% of the motor nominal frequency and 100% of the drive nominal output current.

■ **Cooling air flow and heat dissipation for flange mounting (option +C135)**

Flange mounting kit is ordered separately in North America, not with a plus code.

IEC

ACS580-01-	Heat dissipation (+C135)		Air flow (+C135)				Frame size
	Heatsink	Front	Heatsink		Front		
	W	W	m ³ /h	CFM	m ³ /h	CFM	
3-phase $U_n = 400$ or 480 V							
02A7-4	20	23	TBA	TBA	TBA	TBA	R1
03A4-4	28	23	TBA	TBA	TBA	TBA	R1
04A1-4	36	23	TBA	TBA	TBA	TBA	R1
05A7-4	60	23	TBA	TBA	TBA	TBA	R1
07A3-4	72	24	TBA	TBA	TBA	TBA	R1
09A5-4	109	25	TBA	TBA	TBA	TBA	R1
12A7-4	181	28	TBA	TBA	TBA	TBA	R1
018A-4	192	43	TBA	TBA	TBA	TBA	R2
026A-4	322	54	TBA	TBA	TBA	TBA	R2

ACS580-01-	Heat dissipation (+C135)		Air flow (+C135)				Frame size
	Heatsink	Front	Heatsink		Front		
	W	W	m ³ /h	CFM	m ³ /h	CFM	
033A-4	418	71	TBA	TBA	TBA	TBA	R3
039A-4	439	82	TBA	TBA	TBA	TBA	R3
046A-4	578	92	TBA	TBA	TBA	TBA	R3
062A-4	729	127	TBA	TBA	TBA	TBA	R4
062A-4	686	105	TBA	TBA	TBA	TBA	R4 v2
073A-4	947	151	TBA	TBA	TBA	TBA	R4
073A-4	752	118	TBA	TBA	TBA	TBA	R4 v2
089A-4	887	151	TBA	TBA	TBA	TBA	R4 v2
088A-4	977	141	TBA	TBA	TBA	TBA	R5
106A-4	1099	165	TBA	TBA	TBA	TBA	R5
145A-4	1733	188	435	256	52	31	R6
169A-4	1758	223	450	265	75	44	R7
206A-4	2464	266	450	265	75	44	R7
246A-4	2743	326	550	324	120	71	R8
293A-4	3601	391	550	324	120	71	R8
363A-4	4220	524	1150	677	170	100	R9
430A-4	5330	623	1150	677	170	100	R9

UL (NEC)

ACS580-01-	Heat dissipation (with flange kit)		Air flow (with flange kit)				Frame size
	Heatsink	Front	Heatsink		Front		
	W	W	m ³ /h	CFM	m ³ /h	CFM	
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz							
02A1-4	20	23	TBA	TBA	TBA	TBA	R1
03A0-4	28	23	TBA	TBA	TBA	TBA	R1
03A5-4	36	23	TBA	TBA	TBA	TBA	R1
04A8-4	60	23	TBA	TBA	TBA	TBA	R1
06A0-4	72	24	TBA	TBA	TBA	TBA	R1
07A6-4	109	25	TBA	TBA	TBA	TBA	R1
012A-4	181	28	TBA	TBA	TBA	TBA	R1
014A-4	192	43	TBA	TBA	TBA	TBA	R2
023A-4	322	54	TBA	TBA	TBA	TBA	R2
027A-4	418	71	TBA	TBA	TBA	TBA	R3
034A-4	439	82	TBA	TBA	TBA	TBA	R3
044A-4	578	92	TBA	TBA	TBA	TBA	R3

ACSS580-01-	Heat dissipation (with flange kit)		Air flow (with flange kit)				Frame size
	Heatsink	Front	Heatsink		Front		
	W	W	m ³ /h	CFM	m ³ /h	CFM	
052A-4	729	127	TBA	TBA	TBA	TBA	R4
052A-4	686	105	TBA	TBA	TBA	TBA	R4 v2
065A-4	947	151	TBA	TBA	TBA	TBA	R4
065A-4	752	118	TBA	TBA	TBA	TBA	R4 v2
077A-4	887	151	TBA	TBA	TBA	TBA	R4 v2
078A-4	977	141	TBA	TBA	TBA	TBA	R5
096A-4	1099	165	TBA	TBA	TBA	TBA	R5
124A-4	1733	188	435	256	52	31	R6
156A-4	1758	223	450	265	75	44	R7
180A-4	2464	266	450	265	75	44	R7
240A-4	2743	326	550	324	120	71	R8
260A-4	3601	391	550	324	120	71	R8
302A-4	2849	340	TBA	TBA	TBA	TBA	R9
361A-4	4220	524	1150	677	170	100	R9
414A-4	5330	623	1150	677	170	100	R9

Terminal and entry data for the power cables

■ IEC

Input, motor, resistor and DC cable entries, maximum wire sizes (per phase) and terminal screw sizes and tightening torques (*T*) are given below.

Frame size	Cable entries		L1, L2, L3, T1/U, T2/V, T3/W terminals			Grounding terminals	
	Per cable type	∅ ¹⁾	Min wire size (solid/stranded) ²⁾	Max wire size (solid/stranded)	<i>T</i>	Max wire size	<i>T</i>
		pcs					
3-phase $U_n = 230\text{ V}$							
R1	1	30	0.2/0.2	6/4	1.0	16/16	1.5
R2	1	30	0.5/0.5	16/16	1.5	16/16	1.5
R3	1	30	0.5/0.5	35/25	3.5	35/35	1.5
R5	1	45	6	70	5.6	-	2.2
R6	1	45	25	150	30	180	9.8
R7	1	54	95	240	40	180	9.8
R8	2	45	2×50	2×150	40	180	9.8
3-phase $U_n = 400\text{ or }480\text{ V}$							

Frame size	Cable entries		L1, L2, L3, T1/U, T2/V, T3/W terminals			Grounding terminals	
	Per cable type	∅ ¹⁾	Min wire size (solid/stranded) ²⁾	Max wire size (solid/stranded)	T	Max wire size	T
	pcs	mm	mm ²	mm ²	N·m	mm ²	N·m
R1	1	30	0.20/0.25	6/4	1.0	16/16	1.5
R2	1	30	0.5/0.5	16/16	1.5	16/16	1.5
R3	1	30	0.5/0.5	35/25	3.5	35/35	1.5
R4	1	45	0.5/0.5	50	4.0	35/35	2.9
R4 v2	1	45	1.5/1.5	70	5.5	35/35	2.9
R5	1	45	6	70	5.6	35/35 ³⁾	2.2
R6	1	45	25	150	30	185 ³⁾	9.8
R7	1	54	95	240	40	185 ³⁾	9.8
R8	2	45	2×50	2×150	40	2×185 ³⁾	9.8
R9	2	54	2×95	2×240	70	2×185 ³⁾	9.8

1) Maximum cable diameter accepted. For the entry plate hole diameters, see chapter *Dimension drawings* (page 309).

2) **Note:** Minimum wire size does not necessarily have enough current capability for full load. Make sure the installation complies with local laws and regulations.

3) **Note:** Either cable lug (R5, see page 133) or clamp (R6...R9, see page 136) is used for grounding.

Note: For the tightening torques of the grounding terminals, see sections *Connection procedure, frames R1...R4* (page 123), *Connection procedure, frame R5* (page 129) and *Connection procedure, frames R6...R9* (page 134).

Frame size	Cable entries		R+, R-, UDC+ and UDC- terminals			
	Per cable type	∅ ¹⁾	Min wire size (solid/stranded) ²⁾	Max wire size (solid/stranded)	T (Wire screw)	
	pcs	mm	mm ²	mm ²	ScrewBot	N·m
3-phase $U_n = 230$ V						
R1	1	23	0.2/0.2	6/4	3)	10
R2	1	23	0.5/0.5	16/16	3)	1.5
R3	1	30	0.5/0.5	35/35	3)	3.5
R5	1	39	6	70	M5	5.6
R6	1	45	25	150	M8	30
R7	1	54	95	240	M10	30
R8	2	45	2×50	2×150	M10	40
3-phase $U_n = 400$ or 480 V						
R1	1	23	0.20/0.25	6/4	3)	1.0

Frame size	Cable entries		R+, R-, UDC+ and UDC- terminals			
	Per cable type	∅ ¹⁾	Min wire size (solid/stranded) ²⁾	Max wire size (solid/stranded)	T (Wire screw)	
	pcs	mm	mm ²	mm ²	ScrewBot	N·m
R2	1	23	0.5/0.5	16/16	3)	1.5
R3	1	23	0.5/0.5	35/25	3)	3.5
R4	1	39	0.5/0.5	50	3)	4.0
R4 v2	1	39	1.5/1.5	70	3)	5.5
R5	1	39	6	70	M5	5.6
R6	1	45	25	150	M8	30
R7	1	54	95	240	M10	30
R8	2	45	2×50	2×150	M10	40
R9	2	54	2×95	2×240	M12	70

- 1) Maximum cable diameter accepted. For the entry plate hole diameters, see chapter *Dimension drawings (page 309)*.
- 2) **Note:** Minimum wire size does not necessarily have enough current capability for full load. Make sure the installation complies with local laws and regulations.
- 3) Either cable lug (R5) or clamp (R6...R9) is used for grounding.

Frame size	Screwdrivers for the terminals of the main circuit
R1	Combo: Slot 4 mm and PH1
R2	Combo: Slot 4.5 mm and PH2
R3, R4, R4 v2	PH2

■ UL (NEC)

Input, motor, resistor and DC cable entries, maximum wire sizes (per phase) and terminal screw sizes and tightening torques (*T*) are given below.

Frame size	Cable entries		L1, L2, L3, T1/U, T2/V, T3/W terminals			Grounding terminals		
	Per cable type	∅ ¹⁾	Wire range (stranded/solid ²⁾		<i>T</i>	Wire range (stranded/solid)		<i>T</i>
			Min	Max		Min	Max	
	pcs	in	AWG	AWG	lbf·ft	AWG	AWG	lbf·ft
3-phase $U_1 = 200...240$ V, P_n at $U_n = 208/230$ V, 60 Hz								
R1	1	1.18	24	10	0.7	18	6	1.1
R2	1	1.18	20	6	1.1	18	6	1.1
R3	1	1.18	20	2	2.6	18	2	1.1
R5	1	1.77	10	2/0	4.1	3)	3)	1.6
R6	1	1.77	4	300 MCM	22.1	3)	350 MCM	1.6

Frame size	Cable entries		L1, L2, L3, T1/U, T2/V, T3/W terminals			Grounding terminals		
	Per cable type	∅ ¹⁾	Wire range (stranded/solid ²⁾)		T	Wire range (stranded/solid)		T
			Min	Max		Min	Max	
	pcs	in	AWG	AWG	lbf-ft	AWG	AWG	lbf-ft
R7	1	2.13	3/0	500 MCM	29.5	³⁾	350 MCM	1.1
R8	2	1.77	2×1/0	2×300 MCM	29.5	³⁾	2×350 MCM	1.1
R9	2	2.13	2×3/0	2×500 MCM	51.6	³⁾	2×350 MCM	7.2
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz								
R1	1	1.18	24	10	0.7	18	6	1.1
R2	1	1.18	20	6	1.1	18	6	1.1
R3	1	1.18	20	2	2.6	24	2	1.1
R4	1	1.77	20	1	3.0	12	2	2.1
R5	1	1.77	10	2/0	4.1	³⁾	³⁾	1.6
R6	1	1.77	4	300 MCM	22.1	³⁾	350 MCM	7.2
R7	1	2.13	3/0	500 MCM	29.5	³⁾	350 MCM	7.2
R8	2	1.77	2×1/0	2×300 MCM	29.5	³⁾	2×350 MCM	7.2
R9	2	2.13	2×3/0	2×500 MCM	51.6	³⁾	2×350 MCM	7.2
3-phase $U_1 = 525...600$ V, P_n at $U_n = 575$ V, 60 Hz								
R2	1	1.18	20	6	1.1	18	6	1.1
R3	1	1.18	20	2	2.6	18	6	1.1
R5	1	1.77	10	2/0	4.1	³⁾	³⁾	1.6
R7	1	2.13	3/0	500 MCM	29.5	³⁾	350 MCM	7.2
R8	2	1.77	2×1/0	2×300 MCM	29.5	³⁾	2×350 MCM	7.2
R9	2	2.13	2×3/0	2×500 MCM	51.6	³⁾	2×350 MCM	7.2

1) Maximum cable diameter accepted. For the entry plate hole diameters, see chapter *Dimension drawings* (page 309).

2) **Note:** Minimum wire size does not necessarily have enough current capability for full load. Make sure the installation complies with local laws and regulations.

3) Either cable lug, not provided (R5) or cable clamp (R6...R9) is used for grounding.

Note: For the tightening torques of the grounding terminals, see sections *Connection procedure, frames R1...R4* (page 174), *Connection procedure, frame R5* (page 178) and *Connection procedure, frames R6...R9* (page 182).

Frame size	Cable entries		R+, R-, UDC+ and UDC- terminals			
	Per cable type	ø ¹⁾	Wire range size (stranded/solid) ²⁾		T	
			Min	Max	ScrewBot	lbf-ft
	pcs	in	AWG	AWG		
3-phase $U_1 = 200...240$ V, P_n at $U_n = 208/230$ V, 60 Hz						
R1	1	0.91	24	10	3)	0.7
R2	1	0.91	20	6	3)	1.1
R3	1	1.18	20	2	3)	2.6
R4	1	1.54	50	1	3)	3.0
R5	1	1.54	10	2/10	M5	4.1
R6	1	1.77	4	300 MCM	M8	22.1
R7	1	2.13	3/10	500 MCM	M10	29.5
R8	2	1.77	2×1/0	2×300 MCM	M10	29.5
R9	2	2.13	2×3/0	2×500 MCM	M12	51.6
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz						
R1	1	0.91	24	10	3)	0.7
R2	1	0.91	20	6	3)	1.1
R3	1	0.91	20	2	3)	2.6
R4	1	1.54	50	1	3)	3.0
R5	1	1.54	10	2/10	M5	4.1
R6	1	1.77	4	300 MCM	M8	22.1
R7	1	2.13	3/0	500 MCM	M10	29.5
R8	2	1.77	2×1/0	2×300 MCM	M10	29.5
R9	2	2.13	2×3/0	2×500 MCM	M12	51.6
3-phase $U_1 = 525...600$ V, P_n at $U_n = 575$ V, 60 Hz						
R2	1	0.91	20	6	3)	1.1
R3	1	1.18	20	2	3)	2.6
R5	1	1.54	10	2/0	M5	4.1
R7	1	2.13	3/0	500 MCM	M10	29.5
R8	2	1.77	2×1/0	2×300 MCM	M10	29.5
R9	2	2.13	2×3/0	2×500 MCM	-	51.6

- 1) Maximum cable diameter accepted. For the entry plate hole diameters, see chapter *Dimension drawings (page 309)*.
- 2) **Note:** Minimum wire size does not necessarily have enough current capability for full load. Make sure the installation complies with local laws and regulations.
- 3) See the table below

Frame size	Screwdrivers for the terminals of the main circuit
R1	Combo: Slot 4 mm and PH1

Frame size	Screwdrivers for the terminals of the main circuit
R2	Combo: Slot 4.5 mm and PH2
R3, R4	PH2

Power cables

■ Typical power cable sizes, IEC

The table below gives copper cable types with concentric copper shield for the drives with nominal current. The value separated by the plus sign means the diameter of the PE conductor.

See page 278 for the cable entry sizes allowed for the selected drive frame size.

ACS580-01-	Frame size	Cu cable type ¹⁾	Al cable type ^{1), 2)}
		mm ²	mm ²
3-phase $U_n = 230\text{ V}$			
04A7-2	R1	3×1.5 + 1.5	-
06A7-2	R1	3×1.5 + 1.5	-
07A6-2	R1	3×1.5 + 1.5	-
012A-2	R1	3×1.5 + 1.5	-
018A-2	R1	3×2.5 + 2.5	-
025A-2	R2	3×4.0 + 4.0	-
032A-2	R2	3×6.0 + 6.0	-
047A-2	R3	3×10 + 10	-
060A-2	R3	3×16 + 16	-
089A-2	R5	3×35 + 16	3×50 + 25
115A-2	R5	3×50 + 25	3×70 + 35
144A-2	R6	3×70 + 35	3×120 + 70
171A-2	R7	3×95 + 50	3×150 + 70
213A-2	R7	3×120 + 70	3×240 + 120
276A-2	R8	2×(3×70 + 35)	2×(3×95 + 50)
3-phase $U_n = 400\text{ V}$			
02A7-4	R1	3×1.5 + 1.5	-
03A4-4	R1	3×1.5 + 1.5	-
04A1-4	R1	3×1.5 + 1.5	-
05A7-4	R1	3×1.5 + 1.5	-
07A3-4	R1	3×1.5 + 1.5	-
09A5-4	R1	3×2.5 + 2.5	-
12A7-4	R1	3×2.5 + 2.5	-
018A-4	R2	3×2.5 + 2.5	-
026A-4	R2	3×6 + 6	-

ACS580-01-	Frame size	Cu cable type ¹⁾	Al cable type ^{1), 2)}
		mm ²	mm ²
033A-4	R3	3×10 + 10	-
039A-4	R3	3×10 + 10	-
046A-4	R3	3×10 + 10	-
062A-4	R4	3×25 + 16	-
073A-4	R4	3×35 + 16	-
089A-4	R4 v2	3×50 + 25	-
088A-4	R5	3×50 + 25	-
106A-4	R5	3×70 + 35	-
145A-4	R6	3×95 + 50	-
169A-4	R7	3×120 + 70	-
206A-4	R7	3×150 + 70	-
246A-4	R8	2×(3×70+35)	-
293A-4	R8	2×(3×95+50)	-
363A-4	R9	2×(3×120+70)	-
430A-4	R9	2×(3×150+70)	-

1) The cable sizing is based on max. 6 cables laid on a cable ladder side by side, ambient temperature 30 °C, PVC insulation, surface temperature 70 °C (EN 60204-1 and IEC 60364- 5-52/2001). For other conditions, size the cables according to local safety regulations, appropriate input voltage and the load current of the drive. See page 278 for the accepted cable sizes of the drive.

2) Aluminum cables can be used with $U_n = 230$ V frames R5...R8 only.

Temperature: For IEC, select a cable rated for at least 70 °C maximum permissible temperature of conductor in continuous use. For North America, power cables must be rated for 90 °C (194 °F) or higher.

Note: For drives with option +B056 (IP55, UL Type 12), select a cable rated for at least 90 °C (194 °F) maximum permissible temperature of conductor in continuous use.

Voltage: 600 V AC cable is accepted for up to 500 V AC.

Terminal and entry data for the control cables

■ IEC

Control cable entries, wire sizes and tightening torques (T) are given below.

Frame size	Cable entries		Control cable entries and terminal sizes			
	Holes	Max cable size	+24V, DCOM, DGND, EXT. 24V terminals		DI, AI/O, AGND, RO, STO terminals	
			Wire size	T	Wire size	T
	pcs	mm	mm ²	N·m	mm ²	N·m
3-phase $U_n = 230$ V						
R1	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6

Frame size	Cable entries		Control cable entries and terminal sizes			
	Holes	Max cable size	+24V, DCOM, DGND, EXT. 24V terminals		DI, AI/O, AGND, RO, STO terminals	
			Wire size	T	Wire size	T
	pcs	mm	mm ²	N·m	mm ²	N·m
R2	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R3	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R5	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R6	4	17	0.14...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R7	4	17	0.14...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R8	4	17	0.14...2.5	0.5...0.6	0.14...1.5	0.5...0.6
3-phase $U_n = 400$ or 480 V						
R1	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R2	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R3	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R4	4	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R5	3	17	0.2...2.5	0.5...0.6	0.14...1.5	0.5...0.6
R6	4	17	0.14...2.5	0.5...0.6	0.14...2.5	0.5...0.6
R7	4	17	0.14...2.5	0.5...0.6	0.14...2.5	0.5...0.6
R8	4	17	0.14...2.5	0.5...0.6	0.14...2.5	0.5...0.6
R9	4	17	0.14...2.5	0.5...0.6	0.14...2.5	0.5...0.6

■ **UL (NEC)**

Control cable entries, wire sizes and tightening torques (T) are given below.

Frame size	Cable entries		Control cable entries and terminal sizes			
	Holes	Max cable size	+24V, DCOM, DGND, EXT. 24V terminals		DI, AI/O, AGND, RO, STO terminals	
			Wire size	T	Wire size	T
	pcs	in	AWG	lbf·ft	AWG	lbf·ft
3-phase $U_1 = 200...240$ V, P_n at $U_n = 208/230$ V, 60 Hz						
R1	3	0.67	24...14	0.4	26...16	0.4
R2	3	0.67	24...14	0.4	26...16	0.4
R3	3	0.67	24...14	0.4	26...16	0.4
R4	4	0.67	24...14	0.4	26...16	0.4
R5	3	0.67	24...14	0.4	26...16	0.4
R6	4	0.67	26...14	0.4	26...16	0.4
R7	4	0.67	26...14	0.4	26...16	0.4
R8	4	0.67	26...14	0.4	26...16	0.4
R9	4	0.67	26...14	0.4	26...14	0.4

Frame size	Cable entries		Control cable entries and terminal sizes			
	Holes	Max cable size	+24V, DCOM, DGND, EXT. 24V terminals		DI, AI/O, AGND, RO, STO terminals	
			Wire size	T	Wire size	T
	pcs	in	AWG	lbf-ft	AWG	lbf-ft
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V, 60 Hz						
R1	3	0.67	24...14	0.4	26...16	0.4
R2	3	0.67	24...14	0.4	26...16	0.4
R3	3	0.67	24...14	0.4	26...16	0.4
R4	4	0.67	24...14	0.4	26...16	0.4
R5	3	0.67	24...14	0.4	26...16	0.4
R6	4	0.67	26...14	0.4	26...14	0.4
R7	4	0.67	26...14	0.4	26...14	0.4
R8	4	0.67	26...14	0.4	26...14	0.4
R9	4	0.67	26...14	0.4	26...14	0.4
3-phase $U_1 = 525...600$ V, P_n at $U_n = 575$ V, 60 Hz						
R2	3	0.67	24...14	0.4	26...16	0.4
R3	3	0.67	24...14	0.4	26...16	0.4
R5	3	0.67	24...14	0.4	26...16	0.4
R7	4	0.67	26...14	0.4	26...16	0.4
R8	4	0.67	26...14	0.4	26...16	0.4
R9	4	0.67	26...14	0.4	26...16	0.4

Electrical power network specification

Voltage (U_1)

- ACS580-01-xxxx-2 drives: Input voltage range 3~ 208...240 V AC +10%... -15%.
IEC: This is indicated in the type designation label as typical input voltage levels 3~ 230 V AC.
North America: This is indicated in the type designation label as typical input voltage levels 1~ 208/230 V AC and 3~ 208/230 V AC.
- ACS580-01-xxxx-4 drives: Input voltage range 3~ 380...480 V AC +10%...-15%.
 This is indicated in the type designation label as typical input voltage levels 3~ 400/480 V AC.
- ACS580-01-xxxx-6 drives: Input voltage range 3~ 525...600 V AC +10%...-15%.
 This is indicated in the type designation label as typical input voltage level 3~ 600 V AC.

Network type	<p>Public low voltage networks. Symmetrically grounded TN-S system, IT (ungrounded), corner-grounded delta, midpoint-grounded delta and TT systems, see sections:</p> <p><u>IEC</u>: <i>When to disconnect EMC filter or ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems (page 116) and Guidelines for installing the drive to a TT system (page 117).</i></p> <p><u>North America</u>: <i>When to connect EMC filter or disconnect ground-to-phase varistor: TN-S, IT, corner-grounded delta and midpoint-grounded delta systems (page 166) and Guidelines for installing the drive to a TT system (page 168).</i></p> <p>Note: Frames R4 and R5 cannot be used in corner-grounded or midpoint-grounded delta systems.</p>
Rated conditional short-circuit current (IEC 61800-5-1)	65 kA when protected by fuses given in the fuse tables
Short-circuit current protection (UL 61800-5-1)	<p>US and Canada: The drive is suitable for use on a circuit capable of delivering not more than 100 kA symmetrical amperes (rms) at 480 V maximum when protected by fuses given in the fuse table.</p> <p>US and Canada: The drive is suitable for use on a circuit capable of delivering not more than 65 kA symmetrical amperes (RMS) maximum when protected by circuit breakers given in the circuit breaker table.</p>
Frequency (f_1)	47 to 63 Hz. This is indicated in the type designation label as typical input frequency level f_1 (50/60 Hz).
Imbalance	Max. \pm 3% of nominal phase to phase input voltage
Fundamental power factor ($\cos \phi_1$)	0.98 (at nominal load)

Minimum short-circuit power (IEC/EN 61000-3-12)

The minimum short-circuit power S_{sc} given for each drive type for the R_{sc} (transformer short circuit ratio) value of 350.

ACS580-01	Input rating	Min. short circuit power		Frame size
		400 V	480 V	
	I_1	Ssc	Ssc	
	A	MVA	MVA	
3-phase $U_n = 400\text{ V}$ and 480 V, IEC ratings				
02A7-4	2.6	0.6	0.6	R1
03A4-4	3.3	0.8	0.9	R1
04A1-4	4.0	1.0	1.0	R1
05A7-4	5.6	1.4	1.4	R1
07A3-4	7.2	1.8	1.8	R1
09A5-4	9.4	2.3	2.2	R1
12A7-4	12.6	3.1	3.5	R1
018A-4	17.0	4.1	4.1	R2
026A-4	25.0	6.1	6.7	R2
033A-4	32.0	7.8	7.9	R3
039A-4	38.0	9.2	9.9	R3
046A-4	45.0	10.9	12.8	R3
062A-4	62	15.0	15.1	R4
073A-4	73	17.7	18.9	R4
089A-4	89	21.6	22.4	R4 v2
088A-4	88	21.3	22.4	R5
106A-4	106	25.7	27.9	R5
145A-4	145	35.2	36.1	R6
169A-4	169	41.0	45.4	R7
206A-4	206	50.0	52.4	R7
246A-4	246	59.7	69.8	R8
293A-4	293	71.1	75.7	R8
363A-4	363	88.0	105.1	R9
430A-4	430	104.3	120.5	R9

Motor connection data**Motor types**

Asynchronous AC induction motors, permanent magnet motors and synchronous reluctance motors

Short-circuit current protection (IEC/EN 61800-5-1)

The drive provides solid state short circuit protection for the motor connection per IEC/EN 61800-5-1 and UL 61800-5-1.

Frequency (f_2)

0...500 Hz. This is indicated in the type designation label as output frequency level f_1 (0...500 Hz).

Frequency resolution 0.01 Hz
Current See section *Ratings (page 231)*.
Switching frequency 2 kHz, 4 kHz (default), 8 kHz, 12 kHz

Maximum recommended motor cable length **Operational functionality and motor cable length**

The drive is designed to operate with optimum performance with the following maximum motor cable lengths.

Note: Conducted and radiated emissions of these motor cable lengths do not comply with EMC requirements.

Frame size	Maximum motor cable length, 4 kHz			
	Scalar control		Vector control	
	m	ft	m	ft
Standard drive, without external options				
R1	100	330	100	330
R2*	200	660	200	660
R3*	300	990	300	990
R4	300	990	300	990
R5	300	990	300	990
R6	300	990	300	990
R7	300	990	300	990
R8	300	990	300	990
R9	300	990	300	990

*For 600 V drives the maximum motor cable length is 100 m (330 ft) for frame R2 and 200 m (660 ft) for frame R3.

Note:

1. In multimotor systems, the calculated sum of all motor cable lengths must not exceed the maximum motor cable length given in the table.
2. Longer motor cables cause a motor voltage decrease which limits the available motor power. The decrease depends on the motor cable length and characteristics. Contact your local ABB representative for more information.
3. When using longer motor cables than 50 m (165 ft), 8 and 12 kHz switching frequencies are not allowed. With motor cable length over 100 m, disconnect EMC DC screw if applicable.
4. Acceptable motor cable length for motor manufactures may be different. Check with specific motor manufacturer for maximum allowable distance.

EMC compatibility and motor cable length

To comply with the European EMC Directive (standard EN 61800-3), use the following maximum motor cable lengths at 4 kHz switching frequency. See the table below.

Frame size	Maximum motor cable length, 4 kHz	
	m	ft
EMC limits for Category C2¹⁾ Standard drive with an internal EMC filter. See notes 1, 2 and 3.		
R1	100	330
R2	100	330
R3	100	330
R4	100	330
R5	100	330
R6	150	492
R7	150	492
R8	150	492
R9	150	492
EMC limits for Category C3¹⁾ Standard drive with an internal EMC filter. See notes 3 and 4.		
R1	150	492
R2	150	492
R3	150	492
R4	150	492
R5	150	492
R6	150	492
R7	150	492
R8	150	492
R9	150	492

¹⁾ See the terms in section *Definitions* (page 304)

Note:

1. Radiated and conducted emissions are according to category C2 with an internal EMC filter. The internal EMC filter must be connected.
2. Categories C1 and C2 meet requirements for connecting equipment to the public low-voltage networks.
3. Not applicable to 600 V ratings.
4. Radiated and conducted emissions are according to category C3 with an internal EMC filter. The internal EMC filter must be connected.

Brake resistor connection data for frames R1...R3

Short-circuit protection (IEC/EN 61800-5-1, IEC 61439-1) The brake resistor output is conditionally short-circuit proof by IEC/EN 61800-5-1. Rated conditional short-circuit current as defined in IEC 61439-1.

Control connection data

External power supply Maximum power:
 Frames R1...R5: 25 W, 1.04 A at 24 V AC/DC $\pm 10\%$ with an option module
 Frames R6...R9: 36 W, 1.50 A at 24 V AC/DC $\pm 10\%$ as standard
 Supplied from an external power supply through option module CMOD-01 or CMOD-02 with frames R1...R5. With frames R6...R9 no options are needed.
 Terminal size:
 Frames R1...R5: $0.2 \dots 2.5 \text{ mm}^2$ (24...14 AWG)
 Frames R6...R9: $0.14 \dots 2.5 \text{ mm}^2$ (26...14 AWG)

+24 V DC output (Term. 10) Total load capacity of this outputs is 6.0 W (250 mA / 24 V) minus the power taken by the option modules installed on the board.
 Terminal size:
 Frames R1...R5: $0.2 \dots 2.5 \text{ mm}^2$ (24...14 AWG)
 Frames R6...R9: $0.14 \dots 2.5 \text{ mm}^2$ (26...14 AWG)

Digital inputs DI1...DI6
(Term. 13...18)

Input type: NPN/PNP
Terminal size:
Frames R1...R5: 0.14...1.5 mm² (26...16 AWG)
Frames R6...R9: 0.14...2.5 mm² (26...14 AWG)
DI1...DI4 (Term.13...16)
12/24 V DC logic levels: "0" < 4 V, "1" > 8 V,
10...24 V AC
 R_{in} : 3 kohm
Hardware filtering: 0.04 ms, digital filtering: 2 ms sampling
DI5 (Term.17)
Can be used as a digital or frequency input.
12/24 V DC logic levels: "0" < 4 V, "1" > 8 V,
10...24 V AC
 R_{in} : 3 kohm
Max. frequency 16 kHz
Symmetrical signal (duty cycle D = 0.50)
DI6 (Term. 18)
Can be used as a digital or PTC input.
Digital input mode
12/24 V DC logic levels: "0" < 3 V, "1" > 8 V
 R_{in} : 3 kohm
Hardware filtering: 0.04 ms, digital filtering: 2 ms sampling

Note: DI6 is not supported in the NPN configuration. PTC mode – PTC thermistor can be connected between DI6 and +24 V DC: < 1.5 kohm = '1' (low temperature), > 4 kohm = '0' (high temperature), open circuit = '0' (high temperature).

DI6 is not a reinforced/double insulated input. Connecting the motor PTC sensor to this input requires usage of a reinforced/double insulated PTC sensor inside the motor.

Relay outputs RO1...RO3
(Term. 19...27)

250 V AC / 30 V DC, 2 A
Terminal size:
Frames R1...R5: 0.14...1.5 mm²
Frames R6...R9: 0.14...2.5 mm²
See sections **Isolation areas, R1...R5 (page 294)** and **Isolation areas, R6...R9 (page 295)**.

Analog inputs AI1 and AI2
(Term. 2 and 5)

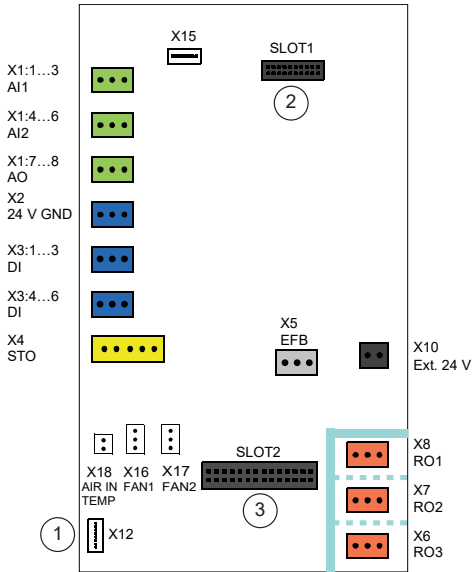
Current/voltage input mode selected with a parameter.
Current input: 0(4)...20 mA, R_{in} : 100 ohm
Voltage input: 0(2)...10 V, R_{in} : > 200 kohm
Terminal size:
Frames R1...R5: 0.14...1.5 mm²
Frames R6...R9: 0.14...2.5 mm²
Inaccuracy: typical ±1%, max. ±1.5% of full scale



Analog outputs AO1 and AO2
(Term. 7 and 8)

Current/voltage input mode selected with a parameter.
Current output: 0...20 mA, R_{load} : < 500 ohm
Voltage output: 0...10 V, R_{load} : > 100 kohm (AO1 only)
Terminal size:
Frames R1...R5: 0.14...1.5 mm²
Frames R6...R9: 0.14...2.5 mm²
Inaccuracy: ±1% of full scale (in voltage and current modes)

Reference voltage output for analog inputs +10V DC (Term. 4)	Max. 20 mA output Inaccuracy: $\pm 1\%$
Embedded fieldbus (Term. 29...31)	Connector pitch 5 mm, wire size 2.5 mm ² Physical layer: EIA-485 Cable type: Shielded twisted pair cable with twisted pair for data and a wire or pair for signal ground, nominal impedance 100...165 ohms, for example Belden 9842 Baud rate: 4.8...115.2 kbit/s Termination by switch
Safe torque off (STO) inputs IN1 and IN2 (Term. 37 and 38)	24 V DC logic levels: "0" < 5 V, "1" > 13 V R_{in} : 2.47 kohm Terminal size: Frames R1...R5: 0.14...1.5 mm ² Frames R6...R9: 0.14...2.5 mm ²
STO cable	Maximum cable length 300 m (984 ft) between activation switch (K) and drive control unit, see sections Wiring (page 349) and Safety data (page 362) .
Control panel - drive and drive-drive connection	EIA-485, male RJ-45 connector, unshielded or shielded twisted pair cable, type CAT 5e or better, max. total cable length of the panel bus 100 m (in single or multiple cables)
Control panel - PC connection	USB Type Mini-B, max. cable length 3 m

Isolation areas, R6...R9



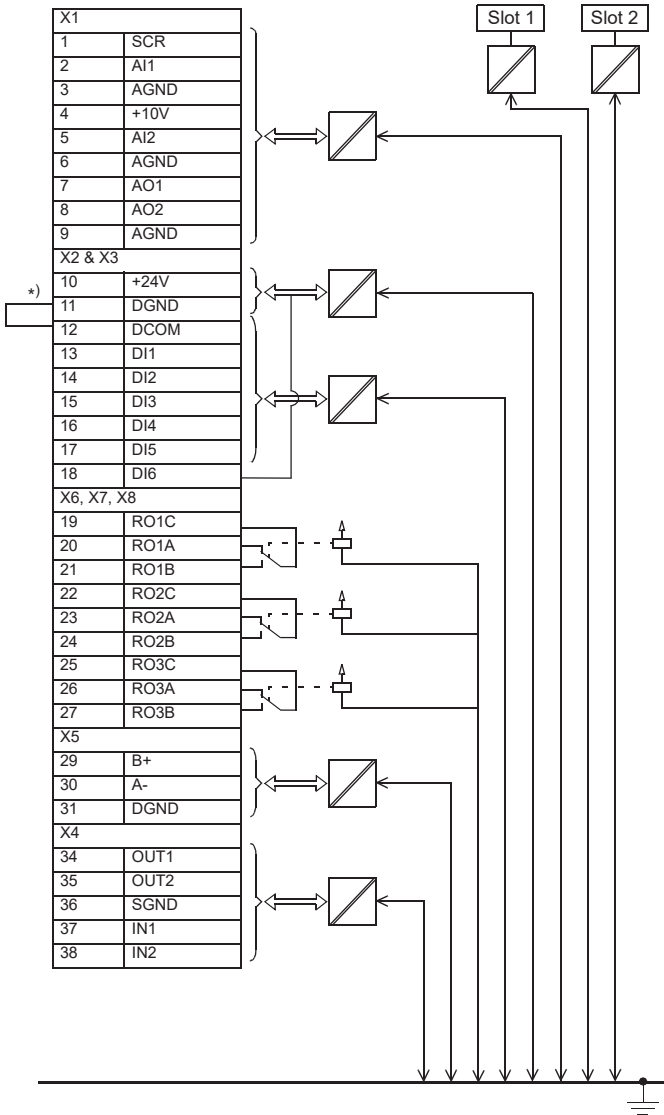
Symbol	Description
1	Power unit connection
2	I/O extension
	Reinforced insulation (IEC/EN 61800-5-1:2007)
	Functional insulation (IEC/EN 61800-5-1:2007)

The terminals on the control unit fulfill the Protective Extra Low Voltage (PELV) requirements (EN 50178): There is reinforced insulation between the user terminals which only accept ELV voltages and terminals that accept higher voltages (relay outputs).

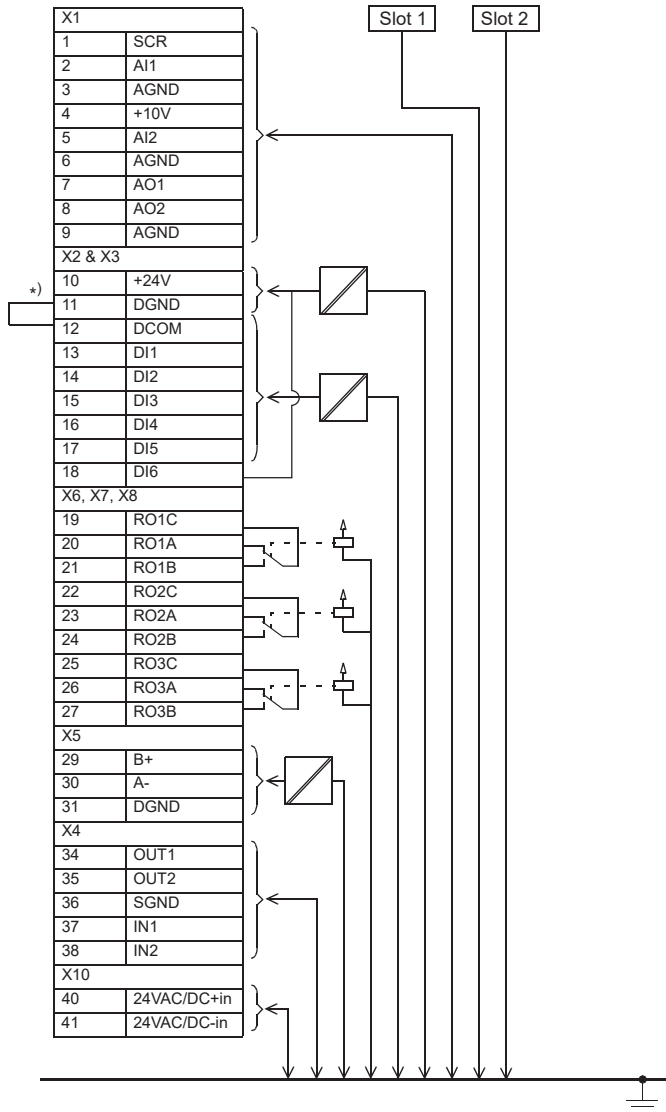
Note: There is functional insulation between the individual relay outputs.

Note: There is reinforced insulation on the power unit.

Grounding of frames R1...R5



Grounding of frames R6...R9



Auxiliary circuit power consumption

Maximum external power supply:
Frames R1...R5: 25 W, 1.04 A at 24 V AC/DC (with option modules CMOD-01, CMOD-02)
Frames R6...R9: 36 W, 1.50 A at 24 V AC/DC (as standard, terminals 40...41)

Efficiency

Approximately 98% at nominal power level. The efficiency is not calculated according to IEC 61800-9-2.

Energy efficiency data (ecodesign)

Energy efficiency data according to IEC-61800-9-2 is available from the ecodesign tool (<https://ecodesign.drivesmotors.abb.com>).



Protection classes for module

Degrees of protection (IEC/EN 60529)	IP21 (standard) IP20 (option +P940, +P944) IP55 (option +B056)
Enclosure types (UL 50/50E)	UL Type 1 UL Open Type(option +P940, +P944) UL Type 12 (option +B056)
Overvoltage category (IEC/EN 60664-1)	III
Protective class (IEC/EN 61800-5-1)	I

Materials

Drive enclosure	<ul style="list-style-type: none"> • PC/ABS 3 mm, PC+GF10 3mm, color NCS 1502-Y (RAL 9002 / PMS 1C Cool Grey), RAL 9002 and PMS 425 C. • hot-dip zinc coated steel sheet 1.5...2.5 mm, thickness of coating 100 micrometers, color NCS 1502-Y
Package	Plywood, cardboard and molded pulp. Foam cushions PE, PP-E, bands PP.
Disposal	<p>The main parts of the drive can be recycled to preserve natural resources and energy. Product parts and materials should be dismantled and separated.</p> <p>Generally all metals, such as steel, aluminum, copper and its alloys, and precious metals can be recycled as material. Plastics, rubber, cardboard and other packaging material can be used in energy recovery. Printed circuit boards and large electrolytic capacitors need selective treatment according to IEC 62635 guidelines. To aid recycling, plastic parts are marked with an appropriate identification code. Contact your local ABB distributor for further information on environmental aspects and recycling instructions for professional recyclers. End of life treatment must follow international and local regulations.</p>

Applicable standards

The drive complies with the following standards. The compliance with the European Low Voltage Directive is verified according to standard EN 61800-5-1.

EN 60204-1:2018,
EN 60204-1:2006 +
AC:2010

Safety of machinery. Electrical equipment of machines. Part 1: General requirements. Provisions for compliance:

The final assembler of the machine is responsible for installing

- emergency-stop device
- supply disconnecting device.

IEC 60146-1-1:2009
EN 60146-1-1:2010
IEC 60529:1989 +
AMD1:1999 + AMD2: 2013,
EN 60529:1991 + A1:2000
+ A2: 2013

Semiconductor converters - General requirements and line commutated converters - Part 1-1: Specification of basic requirements

Degrees of protection provided by enclosures (IP code)

IEC 61000-3-2:2018,
EN 61000-3-2:2014
EN 61000-3-12:2011

Electromagnetic compatibility (EMC) – Limits for harmonic current emissions (input current > 16 A per phase)

Electromagnetic compatibility (EMC) – Limits for harmonic currents produced by equipment connected to public low-voltage systems with input current input current > 16 A and < 75 A per phase

This drive complies with the standard provided that the short-circuit power S_{sc} is greater than or equal to the minimum short-circuit power given for the drive (listed for each drive type on page 302) at the interface point between the user's supply and the public system. It is the responsibility of the installer or user of the drive to ensure, by consultation with the distribution network operator if necessary, that the drive is connected only to a supply with a short-circuit power S_{sc} greater than or equal to the minimum short-circuit power given for the drive.

IEC/EN 61800-3:2017	<i>Adjustable speed electrical power drive systems. Part 3: EMC requirements and specific test methods</i>
IEC/EN 61800-5-1:2007	<i>Adjustable speed electrical power drive systems. Part 5-1: Safety requirements – electrical, thermal and energy</i>
IEC/EN 61800-9-2:2017	<i>Adjustable speed electrical power drive systems. Part 9-2: Ecodesign for power drive systems, motor starters, power electronics and their driven applications – Energy efficiency indicators for power drive systems and motor starters</i>
IEC 60664-1:2007	<i>Insulation coordination for equipment within low-voltage systems. Part 1: Principles, requirements and tests.</i>
UL 61800-5-1: 1st edition	<i>Standard for Safety, Adjustable Speed Electrical Power Drive Systems – Part 5-1: Safety Requirements – Electrical, Thermal and Energy</i>
CSA C22.2 No. 274-17	<i>Adjustable speed drives</i>

Note: US variants 343A-2 and 396A-2 have not been verified to comply with CSA, CE or IEC directives or any standard other than UL 61800-5-1: 1st edition.

Ambient conditions

Environmental limits for the drive are given below. The drive is to be used in a heated, indoor, controlled environment. All printed circuit boards are conformal coated.

	Operation installed for stationary use	Storage in the package	Transportation in the package
Installation site altitude	<ul style="list-style-type: none"> • 0...4000 m (13123 ft) above sea level ¹⁾ • 0...2000 m (6561 ft) above sea level ²⁾ Output derated above 1000 m (3281 ft), see section <i>Altitude derating (page 245)</i> .	-	-
Air temperature	-15...+50 °C (5...122 °F). 0...-15 °C (32...5 °F): No frost allowed. See section <i>Ratings (page 231)</i> .	-40...+70 °C (-40...+158 °F)	-40...+70 °C (-40...+158 °F)
Relative humidity	5...95%	Max. 95%	Max. 95%
No condensation allowed. Maximum allowed relative humidity is 60% in the presence of corrosive gases.			









Contamination levels (IEC 60721-3-x)	IEC 60721-3-3: 2002: Classification of environmental conditions - Part 3-3: Classification of groups of environmental parameters and their severities - Stationary use of weather protected locations	IEC 60721-3-1: 1997	IEC 60721-3-2: 1997															
Chemical gases	Class 3C2	Class 1C2	Class 2C2															
Solid particles	Class 3S2. No conductive dust allowed.	Class 1S3 (packing must support this, otherwise 1S2)	Class 2S2															
Pollution degree (IEC/EN 60664-1)	Pollution degree 2	-	-															
Atmospheric pressure	70...106 kPa 0.7...1.05 atmospheres	70...106 kPa 0.7...1.05 atmospheres	60...106 kPa 0.6...1.05 atmospheres															
Vibration (IEC 60068-2)	Max. 1 mm (0.04 in) (5...13.2 Hz), max. 7 m/s ² (23 ft/s ²) (13.2...100 Hz) sinusoidal	-	-															
Vibration (ISTA)	-	R1...R4 (ISTA 1A): Displacement, 25 mm peak to peak, 14200 vibratory impacts R5...R9 (ISTA 3E): Random, overall Grms level of 0.52																
Shock/Drop (ISTA)	Not allowed	R1...R4 (ISTA 1A): Drop, 6 faces, 3 edges and 1 corner <table border="1" data-bbox="632 981 1036 1145"> <thead> <tr> <th>Weight range</th> <th>mm</th> <th>in</th> </tr> </thead> <tbody> <tr> <td>0...10 kg (0...22 lb)</td> <td>760</td> <td>29.9</td> </tr> <tr> <td>10...19 kg (22...42 lb)</td> <td>610</td> <td>24.0</td> </tr> <tr> <td>19...28 kg (42...62 lb)</td> <td>460</td> <td>18.1</td> </tr> <tr> <td>28...41 kg (62...90 lb)</td> <td>340</td> <td>13.4</td> </tr> </tbody> </table> R5...R9 (ISTA 3E): Shock, incline impact: 1.1 m/s (3.61 ft/s) Shock, rotational edge drop: 200 mm (7.9 in)		Weight range	mm	in	0...10 kg (0...22 lb)	760	29.9	10...19 kg (22...42 lb)	610	24.0	19...28 kg (42...62 lb)	460	18.1	28...41 kg (62...90 lb)	340	13.4
Weight range	mm	in																
0...10 kg (0...22 lb)	760	29.9																
10...19 kg (22...42 lb)	610	24.0																
19...28 kg (42...62 lb)	460	18.1																
28...41 kg (62...90 lb)	340	13.4																



- 1) For symmetrically grounded TN-S systems, TT systems, and ungrounded or symmetrically high-resistance grounded IT systems. See also section *Limiting relay output maximum voltages at high installation altitudes (page 110)*.
- 2) For corner-grounded delta systems, midpoint-grounded delta systems and corner-grounded (via high resistance) IT systems.

Note: There are special considerations in corner-grounded installations above 2000 m. Contact your local ABB representative for further information.

Markings

These markings are attached to the drive:

	<p>CE mark Product complies with the applicable European Union legislation. For fulfilling the EMC requirements, see the additional information concerning the drive EMC compliance (IEC/EN 61800-3).</p>
	<p>TÜV Safety Approved mark (functional safety) Product contains Safe Torque Off and possibly other (optional) safety functions which are certified by TÜV according to the relevant functional safety standards. Applicable to drives and inverters; not applicable to supply, brake or DC/DC converter units or modules.</p>
	<p>UL Listed mark for USA and Canada Product has been tested and evaluated against the relevant North American standards by the Underwriters Laboratories. Valid with rated voltages up to 600 V.</p>
	<p>CSA certification mark for USA and Canada Product has been tested and evaluated against the relevant North American standards by the CSA Group. Valid with rated voltages up to 600 V.</p>
	<p>EAC (Eurasian Conformity) mark Product complies with the technical regulations of the Eurasian Customs Union. EAC mark is required in Russia, Belarus and Kazakhstan.</p>
	<p>Electronic Information Products (EIP) symbol including an Environment Friendly Use Period (EFUP) Product is compliant with the People's Republic of China Electronic Industry Standard (SJ/T 11364-2014) about hazardous substances. The EFUP is 20 years.</p>
	<p>UKCA (UK Conformity Assessed) mark Product complies with the applicable United Kingdom's legislation (Statutory Instruments). Marking is required for products being placed on the market in Great Britain (England, Wales and Scotland).</p>
	<p>KC mark Product complies with Korea's product safety requirements for electrical and electronic equipment and components that utilize power from 50...1000 V AC.</p>

	<p>RCM mark Product complies with Australian and New Zealand requirements specific to EMC, telecommunications and electrical safety. For fulfilling the EMC requirements, see the additional information concerning the drive EMC compliance (IEC/EN 61800-3).</p>
	<p>WEEE mark At the end of life the product should enter the recycling system at an appropriate collection point and not placed in the normal waste stream.</p>

Note: The ACS580-01 230 V 3-phase R9 drives have NOT been verified to comply with CSA, CE or IEC directives or any other world standards outside of North America.

CE marking

A CE mark is attached to the drive to verify that the drive follows the provisions of the European Low Voltage, EMC and RoHS Directives. The CE marking also verifies that the drive, in regard to its safety functions (such as Safe torque off), conforms with the Machinery Directive as a safety component.

■ Compliance with the European Low Voltage Directive

The compliance with the European Low Voltage Directive has been verified according to standard EN 61800-5-1:2007. The declaration of conformity (3AXD10000302784) is available on the Internet. See section *Document library on the Internet* on the inside of the back cover.

■ Compliance with the European EMC Directive

The EMC Directive defines the requirements for immunity and emissions of electrical equipment used within the European Union. The EMC product standard (EN 61800-3:2004 + A1:2012) covers requirements stated for drives. See section [Compliance with the EN 61800-3:2004 + A1:2012](#) below. The declaration of conformity (3AXD10000302784) is available on the Internet. See section *Document library on the Internet* on the inside of the back cover.

■ Compliance with the European ROHS II Directive 2011/65/EU

The RoHS II Directive defines the restriction of the use of certain hazardous substances in electrical and electronic equipment. The declaration of conformity (3AXD10000302784) is available on the Internet. See section *Document library on the Internet* on the inside of the back cover.

■ Compliance with the European WEEE Directive 2002/96/EC

The WEEE Directive defines the regulated disposal and recycling of electric and electrical equipment.

■ Compliance with the European Machinery Directive 2006/42/EC 2nd Edition – June 2010

The drive is a machinery component that can be integrated into a wide range of machinery categories as specified in European Commission's *Guide to application of the Machinery Directive 2006/42/EC 2nd Edition – June 2010*. See chapter [The Safe torque off function \(page 347\)](#).

Validating the operation of the Safe torque off function

See chapter [The Safe torque off function \(page 347\)](#).

Compliance with the EN 61800-3:2004 + A1:2012

■ Definitions

EMC stands for Electromagnetic Compatibility. It is the ability of electrical/electronic equipment to operate without problems within an electromagnetic environment. Likewise, the equipment must not disturb or interfere with any other product or system within its locality.

First environment includes establishments connected to a low-voltage network which supplies buildings used for domestic purposes.

Second environment includes establishments connected to a network not supplying domestic premises.

Drive of category C1: drive of rated voltage less than 1000 V and intended for use in the first environment.

Drive of category C2: drive of rated voltage less than 1000 V and intended to be installed and started up only by a professional when used in the first environment.

Note: A professional is a person or organization having necessary skills in installing and/or starting up power drive systems, including their EMC aspects.

Drive of category C3: drive of rated voltage less than 1000 V and intended for use in the second environment and not intended for use in the first environment.

Drive of category C4: drive of rated voltage equal to or above 1000 V, or rated current equal to or above 400 A, or intended for use in complex systems in the second environment.

■ Category C1

The emission limits are complied with the following provisions:

1. The optional EMC C1 filter is selected according to the documentation and installed as specified in the EMC C1 filter manual. See *Main switch and EMC C1 filter options (+F278, +F316, +E223) installation supplement for ACS580-01, ACH580-01 and ACQ580-01 frames R1 to R5 (3AXD50000155132 [Multilingual])*.
-

Only available for IP55 (+B056) frames R1...R5, up to 55 kW.

2. The motor and control cables are selected as specified in this manual.
3. The drive is installed according to the instructions given in this manual.
4. The maximum motor cable length with 2 kHz switching frequency is 10 m.



WARNING!

In a domestic environment, this product may cause radio interference, in which case supplementary mitigation measures may be required.

■ **Category C2**

The emission limits are complied with the following provisions:

1. The motor and control cables are selected as specified in this manual.
2. The drive is installed according to the instructions given in this manual.
3. For the maximum motor cable length with 4 kHz switching frequency, see *Maximum recommended motor cable length (page 289)*.



WARNING!

The drive may cause radio interference if used in residential or domestic environment. The user is required to take measures to prevent interference, in association to the requirements for the CE compliance listed above, if necessary.

Note: Do not install a drive with the EMC filter connected to a system that the filter is not suitable for. This can cause danger, or damage the drive.

Note: Do not install the drive with the ground-to-phase varistor connected to a system that the varistor is not suitable for. If you do, the varistor circuit can be damaged.

If you install the drive to any other system than symmetrically grounded TN-S system, you may need to disconnect the EMC filter or the ground-to-phase varistor. See sections:

IEC: *Grounding system compatibility check (page 115)*

North America: *Grounding system compatibility check (page 166)*

■ **Category C3**

The drive complies with the standard with the following provisions:

1. The motor and control cables are selected as specified in this manual.
2. The drive is installed according to the instructions given in this manual.
3. For the maximum motor cable length with 4 kHz switching frequency, see page *Maximum recommended motor cable length (page 289)*



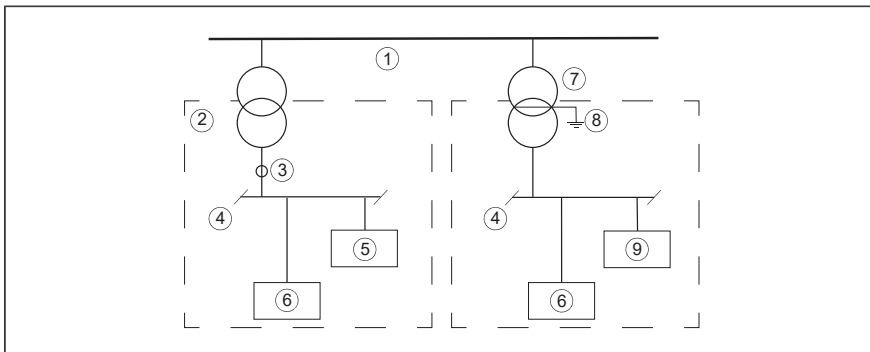
WARNING!

A drive of category C3 is not intended to be used on a low-voltage public network which supplies domestic premises. Radio frequency interference is expected if the drive is used on such a network.

■ **Category C4**

The drive complies with the C4 category with these provisions:

1. It is ensured that no excessive emission is propagated to neighboring low-voltage networks. In some cases, the natural suppression in transformers and cables is sufficient. If in doubt, the supply transformer with static screening between the primary and secondary windings can be used.



1	Medium voltage network	6	Equipment
2	Neighboring network	7	Supply transformer
3	Point of measurement	8	Static screen
4	Low voltage	9	Drive
5	Equipment (victim)	-	-

2. An EMC plan for preventing disturbances is drawn up for the installation. A template is available in *Technical guide No. 3 EMC compliant installation and configuration for a power drive system* ([3AFE61348280](https://www.afe.com/3AFE61348280) (English)).
3. The motor and control cables are selected, and routed according to the electrical planning guidelines of the drive. The EMC recommendations are obeyed.
4. The drive is installed according to its installation instructions. The EMC recommendations are obeyed.

**WARNING!**

A drive of category C4 is not intended to be used on a low-voltage public network which supplies domestic premises. Radio frequency interference is expected if the drive is used on such a network.

UL checklist

**WARNING!**

Operation of this drive requires detailed installation and operation instructions provided in the hardware and software manuals. The manuals are provided in electronic format in the drive package or on the Internet. Keep the manuals with the drive at all times. Hard copies of the manuals can be ordered through the manufacturer.

- Make sure that the drive type designation label includes the applicable marking.
- **DANGER - Risk of electric shock.** After disconnecting the input power, always wait for 5 minutes to let the intermediate circuit capacitors discharge before you start working on the drive, motor or motor cable.
- The drive is to be used in a heated, indoor controlled environment. The drive must be installed in clean air according to the enclosure classification. Cooling air must be clean, free from corrosive materials and electrically conductive dust.
- The maximum surrounding air temperature is 40 °C at rated output current. The output current is derated for 40...50 °C.

Note: For cabinet-built drives, the maximum surrounding air temperature is 40 °C (104 °F).

- The drive is suitable for use in a circuit capable of delivering not more than 100 kA rms symmetrical amperes, 600 V maximum when protected by the UL fuses given elsewhere in this chapter.
- The drive is suitable for use in a circuit capable of delivering not more than 65 kA rms symmetrical amperes, 600 V maximum when protected by the UL circuit breakers given elsewhere in this chapter.
- The cables located within the motor circuit must be rated for at least 75 °C in UL-compliant installations.
- The input cable must be protected with fuses or circuit breakers. These protective devices provide branch circuit protection in accordance with the national regulations (National Electrical Code (NEC) or Canadian Electrical Code). Obey also any other applicable local or provincial codes.

Suitable UL fuses are listed in section *Fuses (UL) (page 259)* and circuit breakers in section *Circuit breakers (IEC) (page 257)*.



WARNING!

The opening of the branch-circuit protective device may be an indication that a fault current has been interrupted. To reduce the risk of fire or electric shock, current-carrying parts and other components of the device should be examined and replaced if damaged.

- The drive provides motor overload protection. For adjustments, see the firmware manual.
- The drive overvoltage category according to IEC 60664-1 is III
- To maintain the environment integrity of the enclosure, replace the cable grommets with field-installed industrial conduit hubs or closure plates required by the enclosure type (or better).

Disclaimers

■ Generic disclaimer

The manufacturer shall have no obligation with respect to any product which (i) has been improperly repaired or altered; (ii) has been subjected to misuse, negligence or accident; (iii) has been used in a manner contrary to the manufacturer's instructions; or (iv) has failed as a result of ordinary wear and tear.

■ Cybersecurity disclaimer

This product can be connected to and to communicate information and data via a network interface. The HTTP protocol, which is used between the commissioning tool (Drive Composer) and the product, is an unsecured protocol. For independent and continuous operation of product such connection via network to commissioning tool is not necessary. However it is Customer's sole responsibility to provide and continuously ensure a secure connection between the product and Customer network or any other network (as the case may be). Customer shall establish and maintain any appropriate measures (such as but not limited to the installation of firewalls, prevention of physical access, application of authentication measures, encryption of data, installation of anti-virus programs, etc) to protect the product, the network, its system and the interface against any kind of security breaches, unauthorized access, interference, intrusion, leakage and/or theft of data or information.

Notwithstanding any other provision to the contrary and regardless whether the contract is terminated or not, ABB and its affiliates are under no circumstances liable for damages and/or losses related to such security breaches, any unauthorized access, interference, intrusion, leakage and/or theft of data or information.

11

Dimension drawings

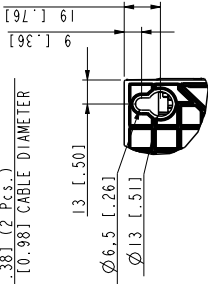
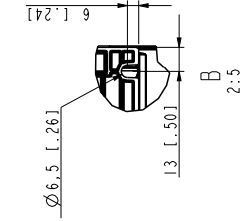
Contents of this chapter

This chapter shows the dimension drawings of the ACS580-01.

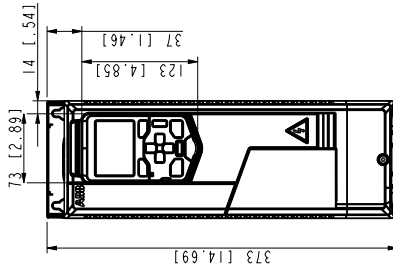
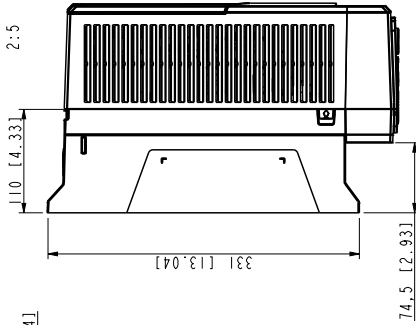
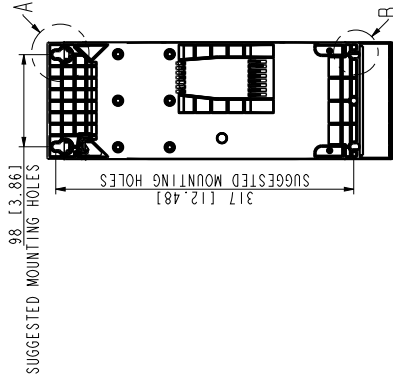
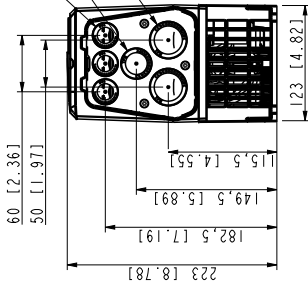
Note: The dimensions are given in millimeters and [inches].

Frame R1, IP21 (UL Type 1)

IP21



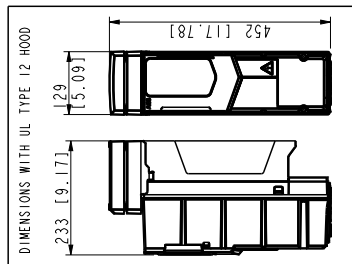
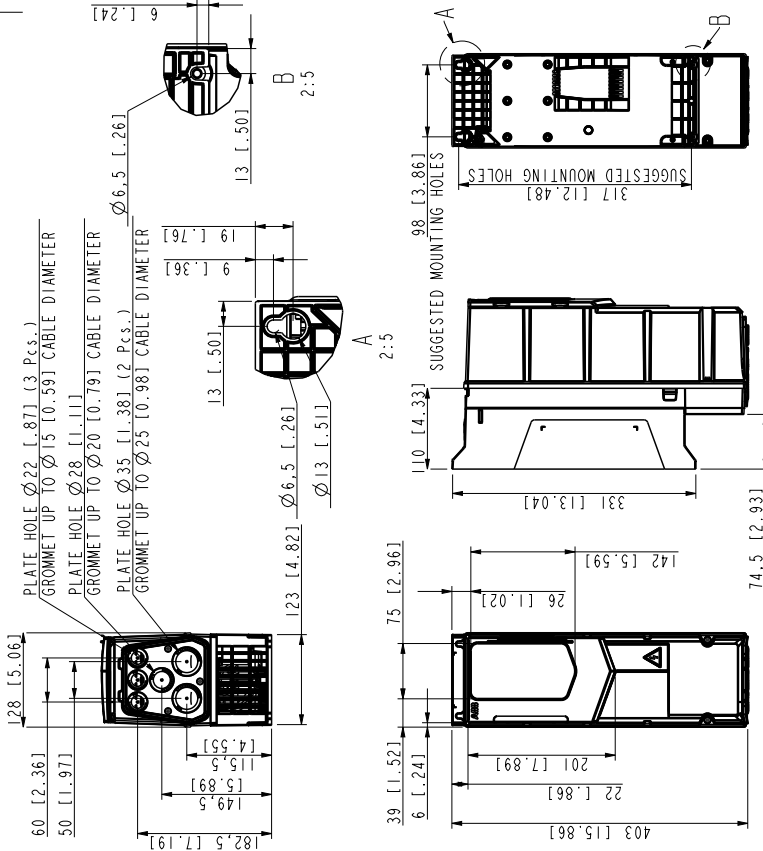
- PLATE HOLE $\varnothing 22$ [1.87] (3 Pcs.)
- GROMMET UP TO $\varnothing 15$ [0.59] CABLE DIAMETER
- PLATE HOLE $\varnothing 28$ [1.11]
- GROMMET UP TO $\varnothing 20$ [0.79] CABLE DIAMETER
- PLATE HOLE $\varnothing 35$ [1.38] (2 Pcs.)
- GROMMET UP TO $\varnothing 25$ [0.98] CABLE DIAMETER



3AXD10000601652

Frame R1, IP55 (UL Type 12)

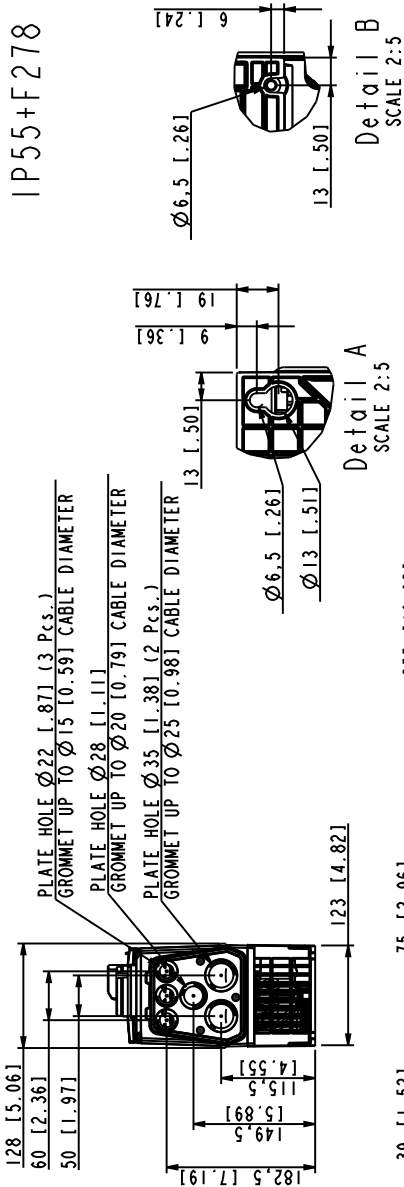
IP55



3AXD10000601699

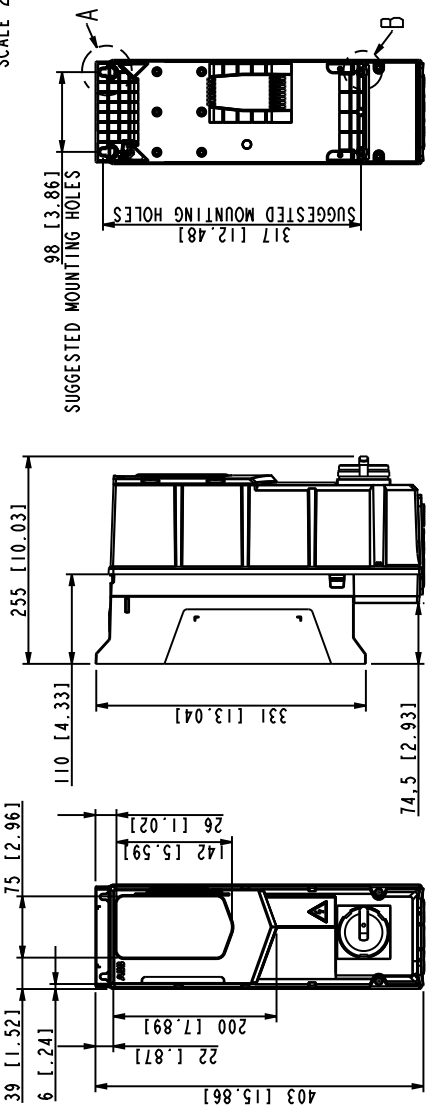
Frame R1, IP55+F278 (UL Type 12)

IP55+F278

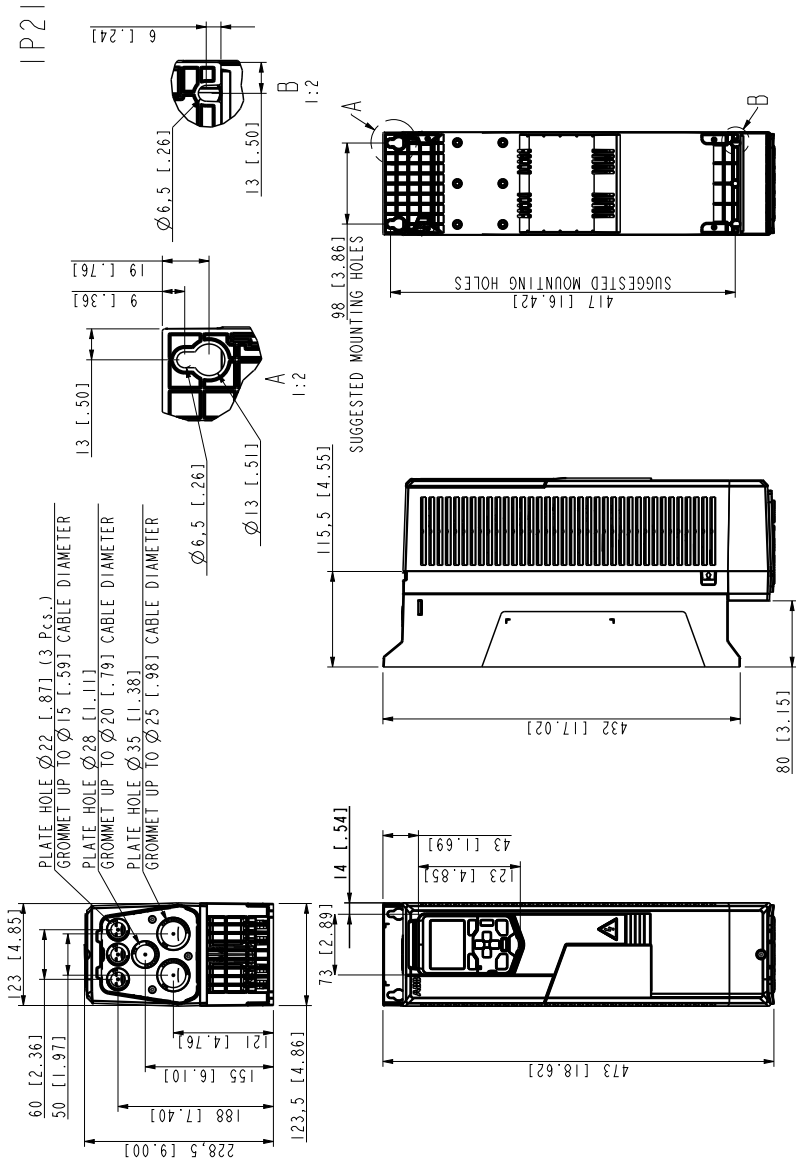


Detail B
SCALE 2:5

Detail A
SCALE 2:5

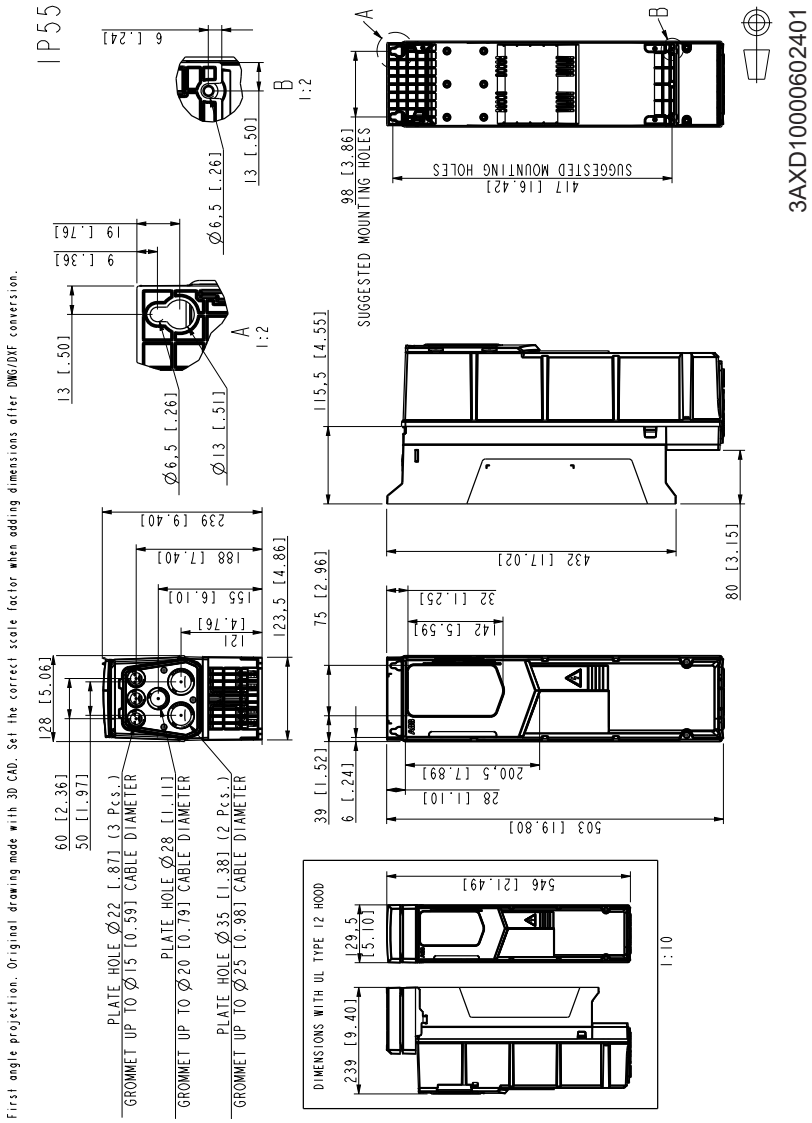


Frame R2, IP21 (UL Type 1)

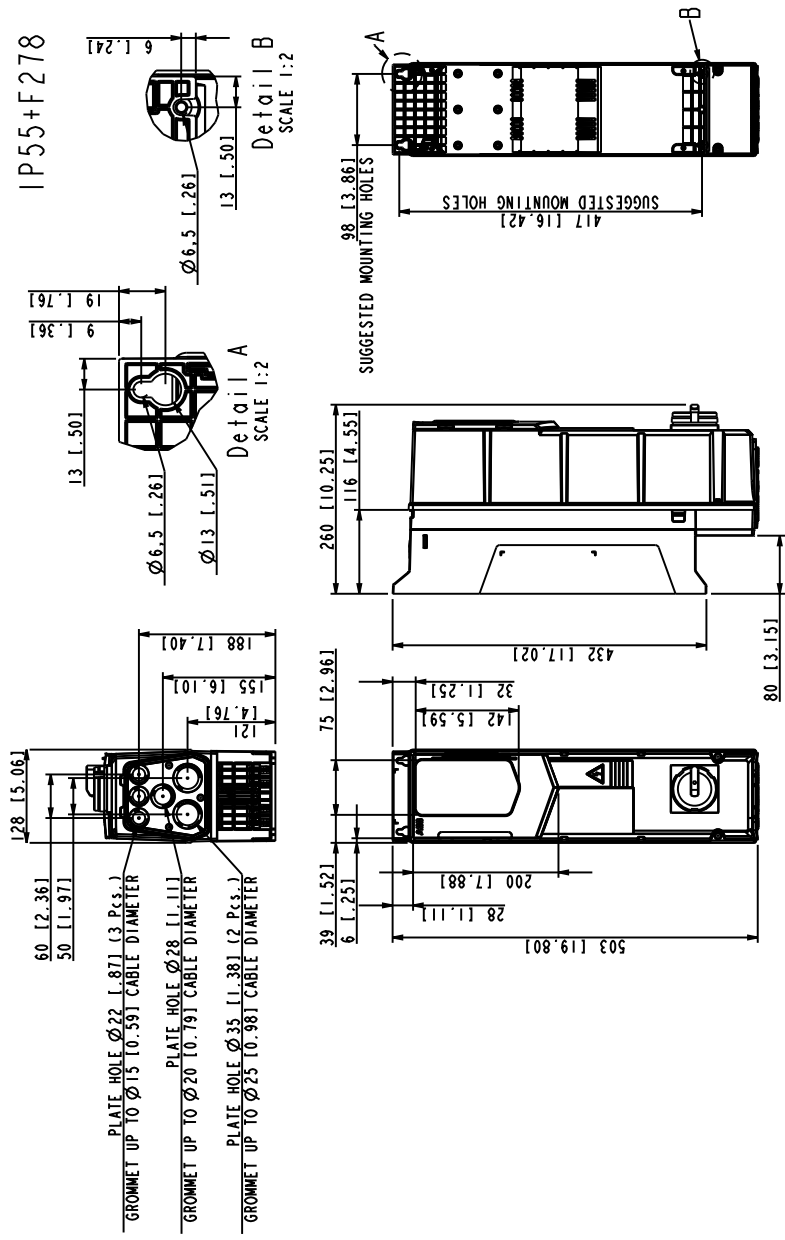


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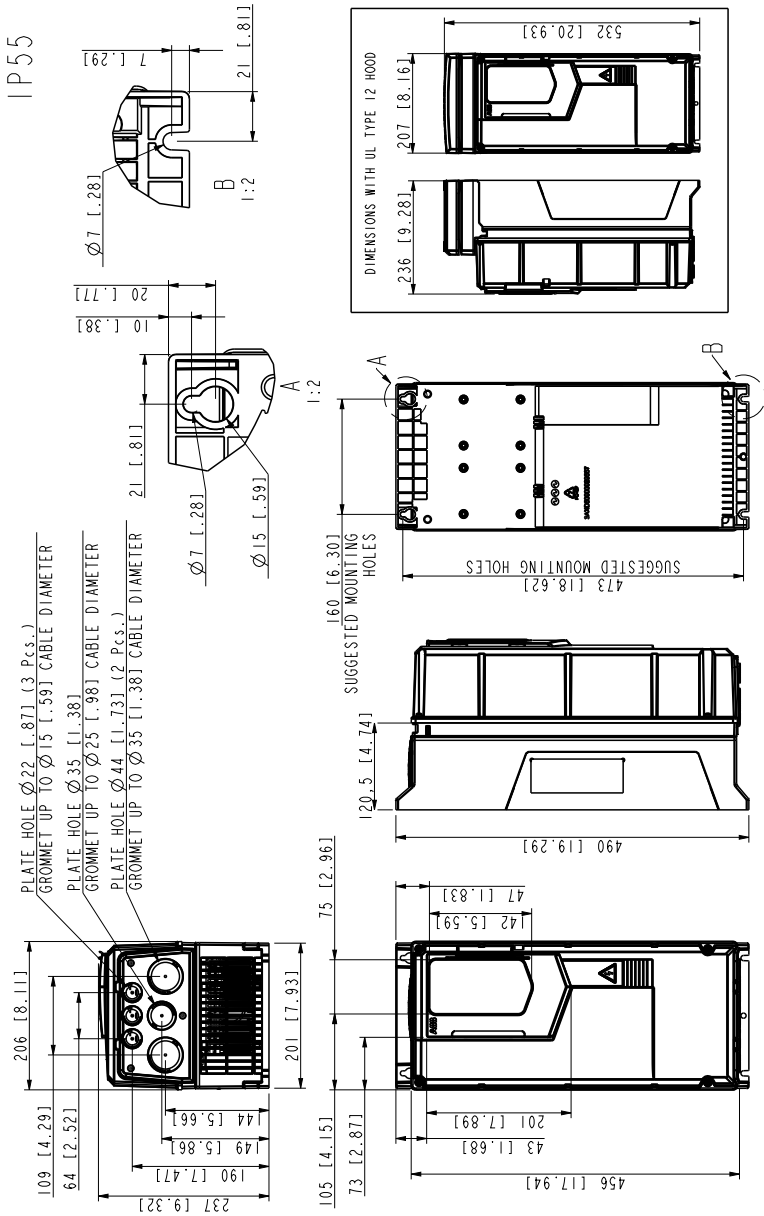
Frame R2, IP55 (UL Type 12)



Frame R2, IP55+F278 (UL Type 12)



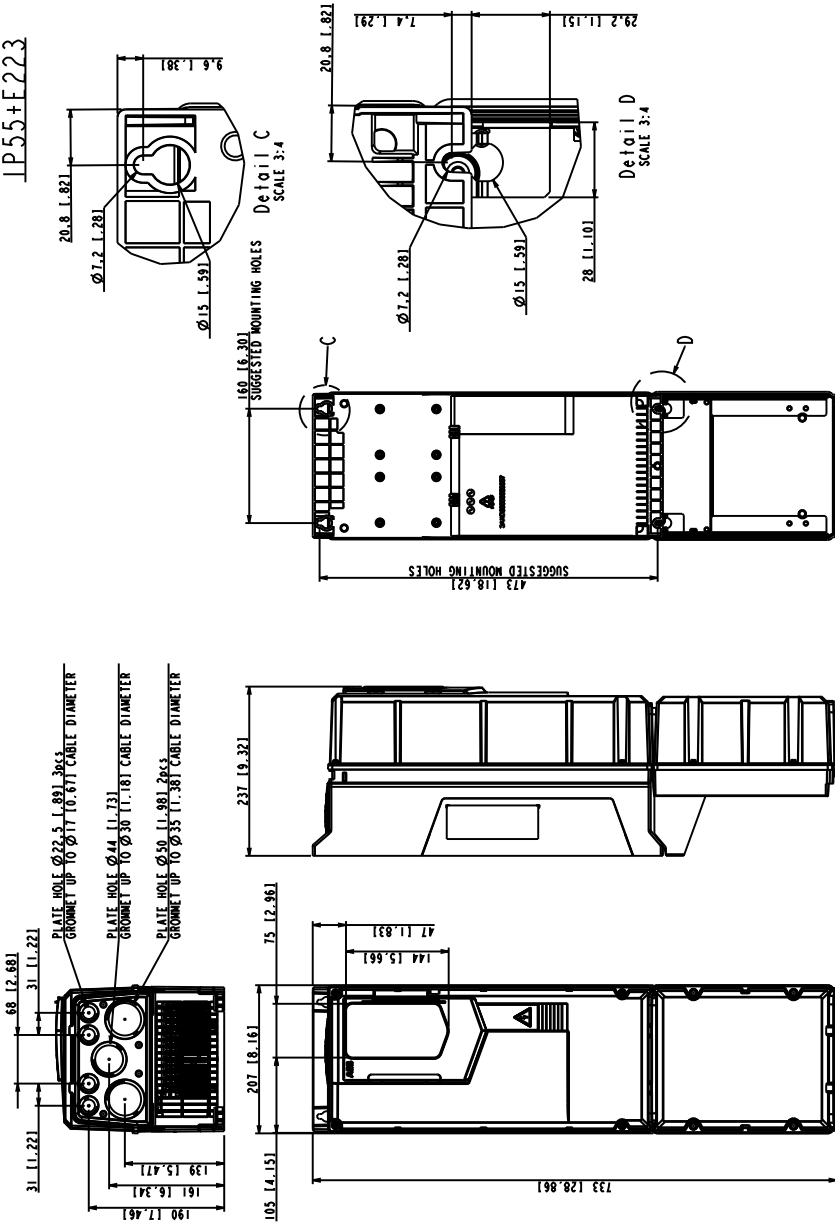
Frame R3, IP55 (UL Type 12)



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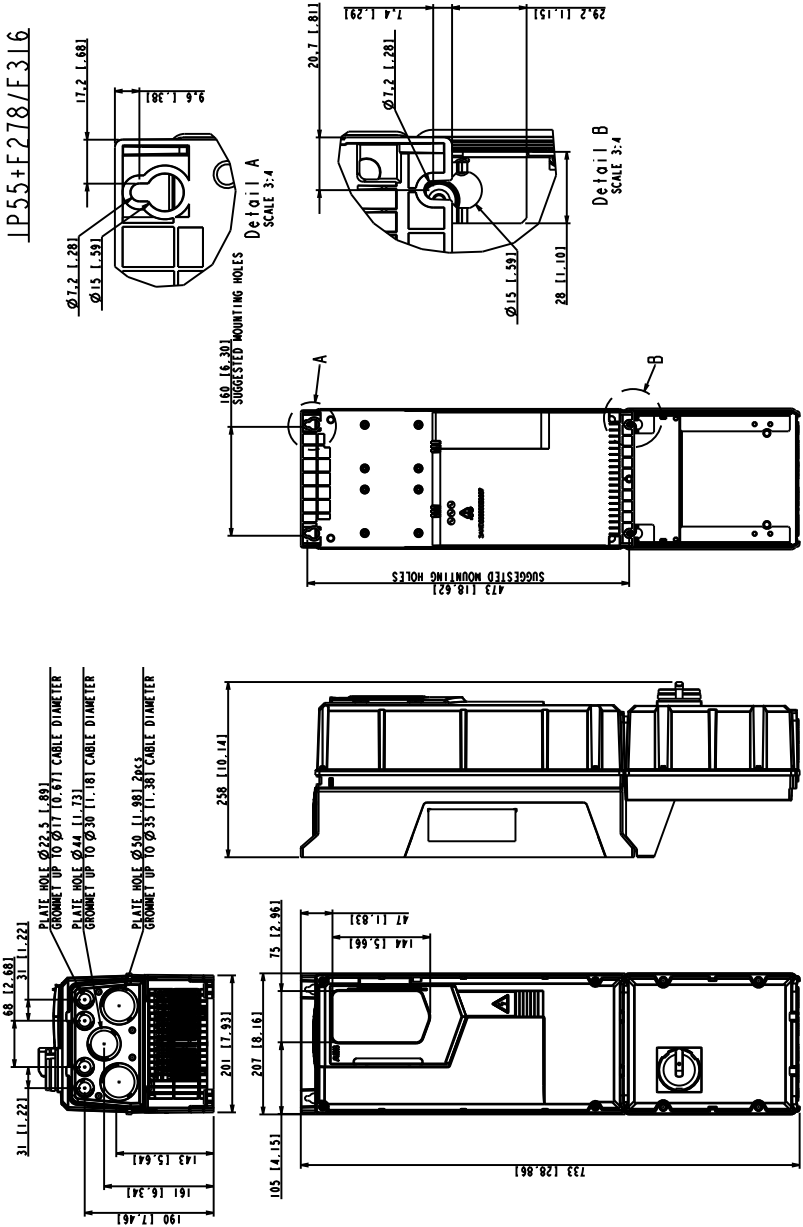
Frame R3, IP55+E223 (UL Type 12)

IP55+E223

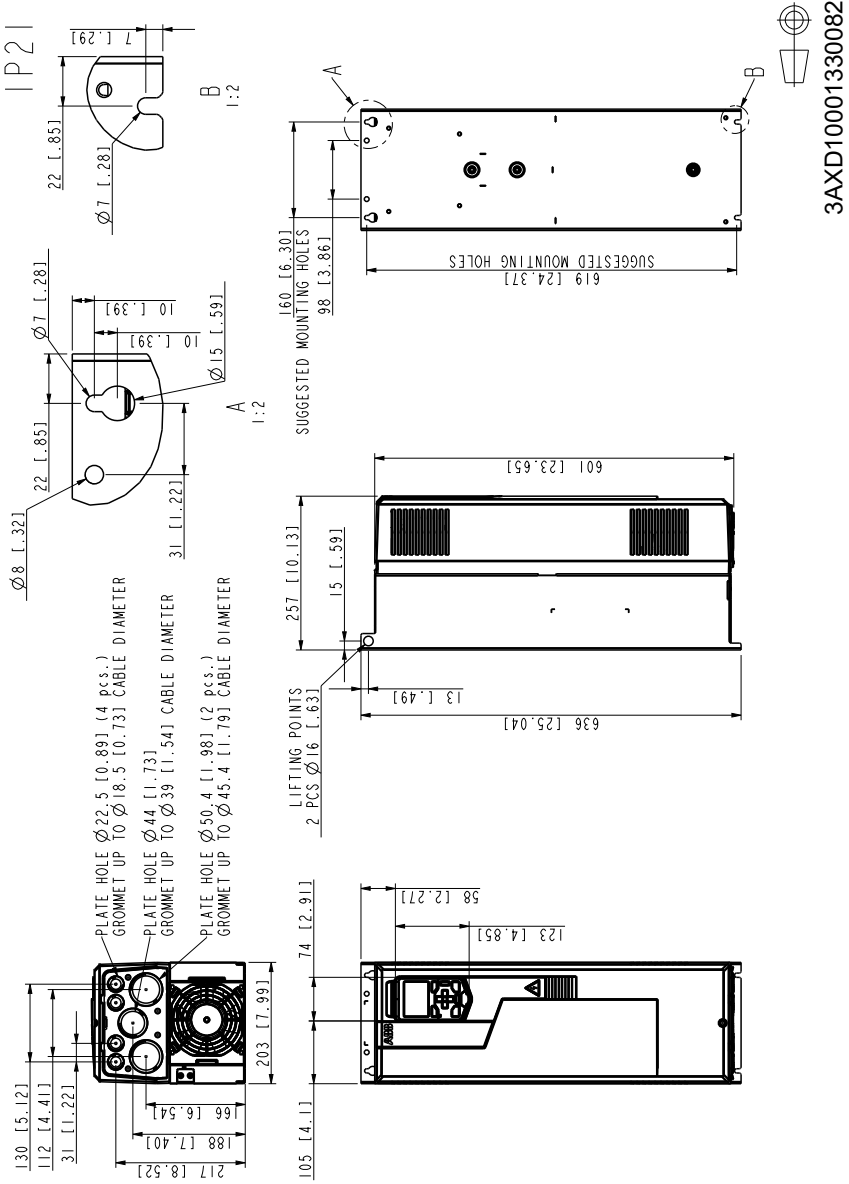


Frame R3, IP55+F278/F316 (UL Type 12)

IP55+F278/F316

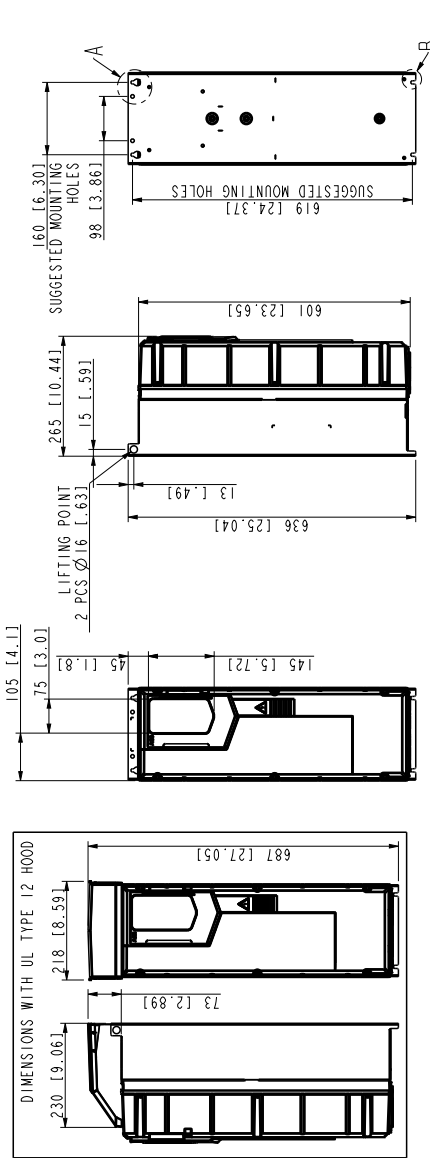
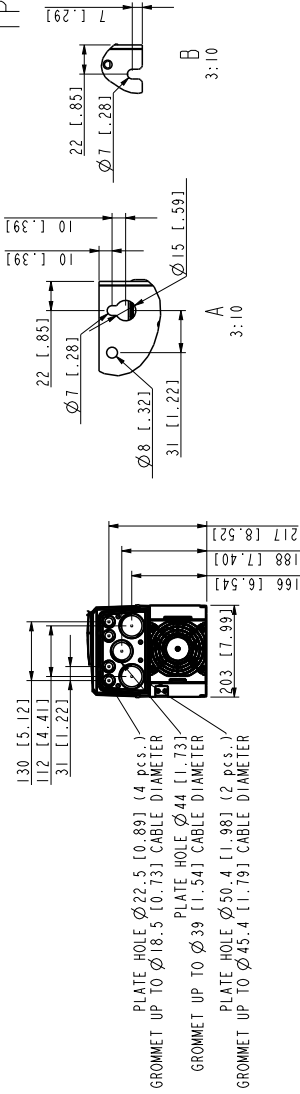


Frame R4, IP21 (UL Type 1)



Frame R4, IP55 (UL Type 12)

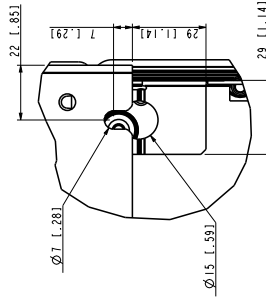
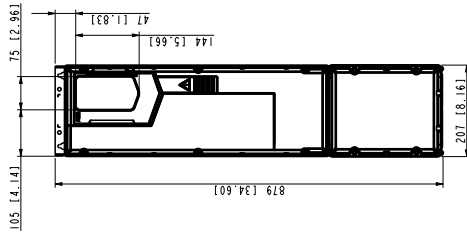
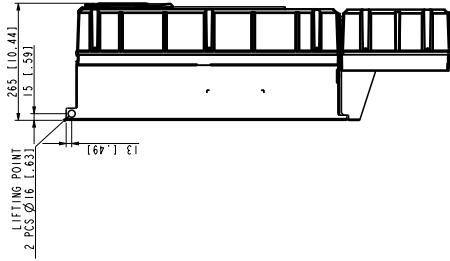
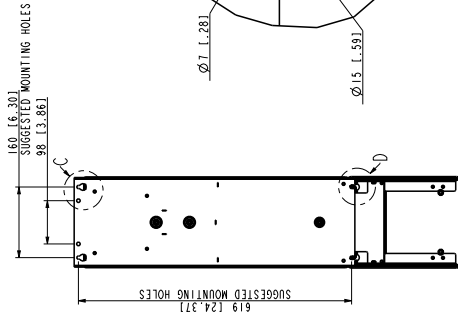
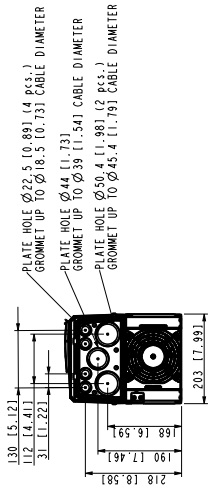
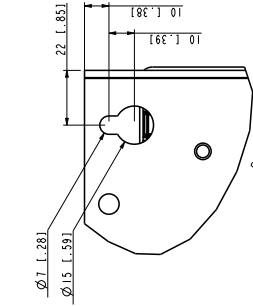
IP55



3AXD10001330271

Frame R4, IP55+E223 (UL Type 12)

IP55+E223



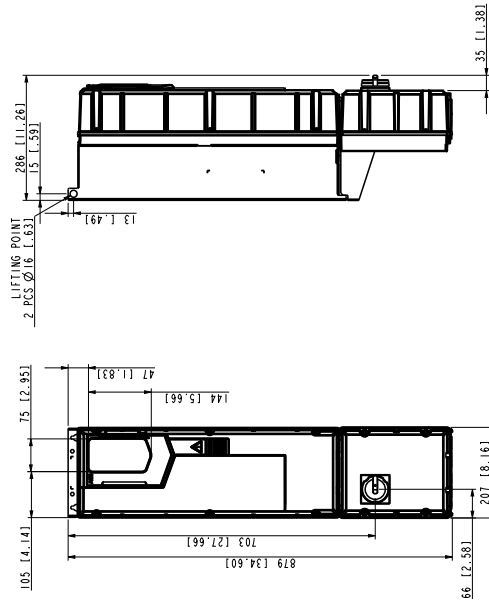
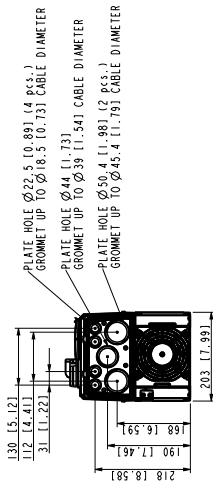
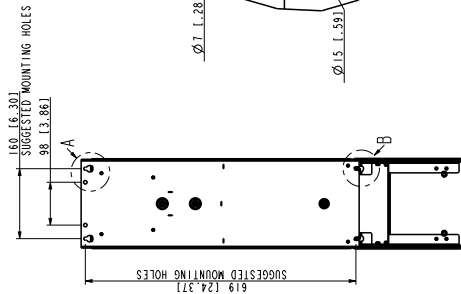
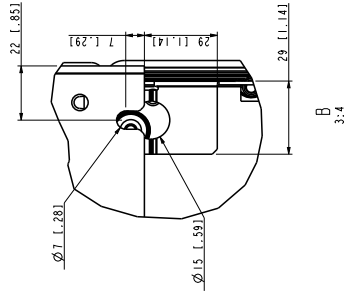
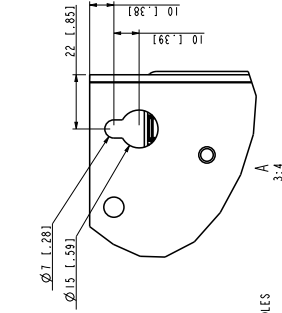
D
3:4



3AXD10001373680

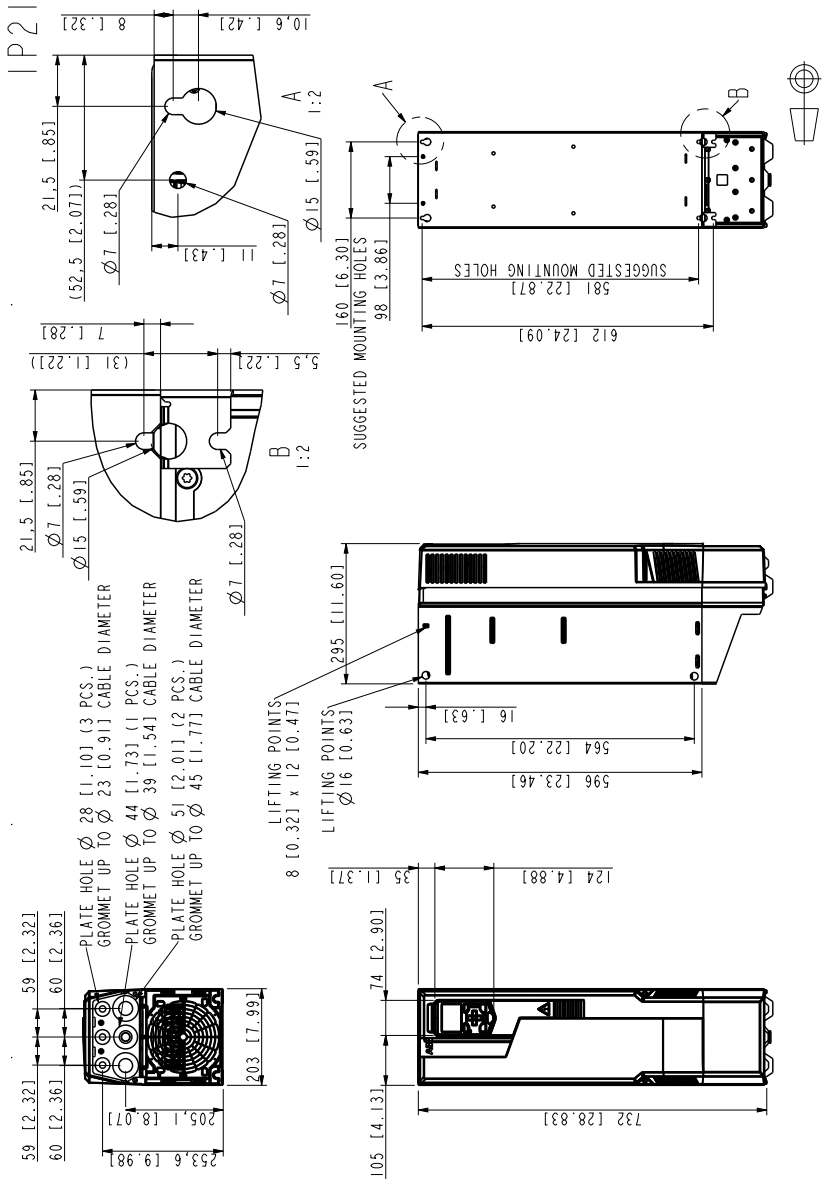
Frame R4, IP55+F278/F316 (UL Type 12)

IP55+F278/F316



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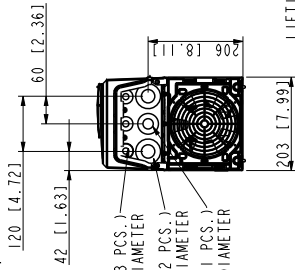
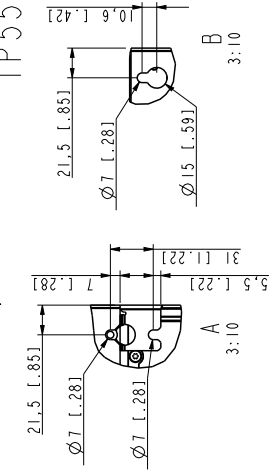
Frame R5, IP21 (UL Type 1)



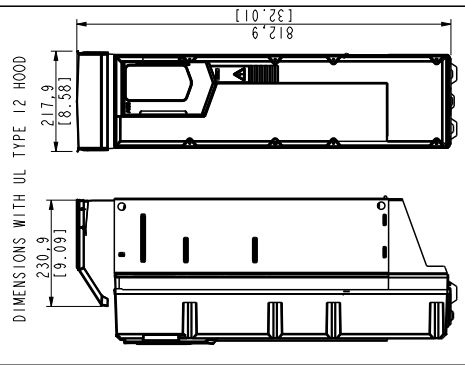
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Frame R5, IP55 (UL Type 12)

IP55

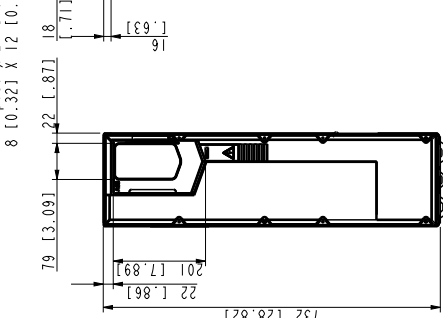
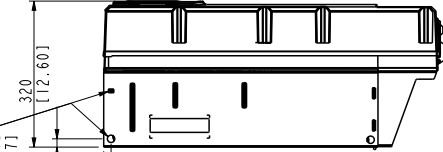
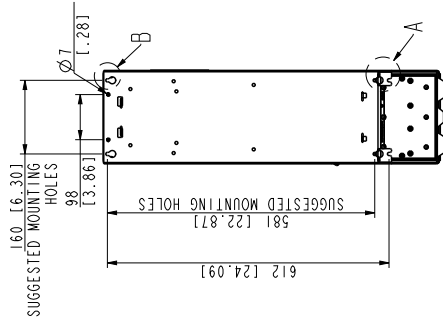


- PLATE HOLE \varnothing 28 [1.11] (3 PCS.)
- GROMMET UP TO \varnothing 23 [0.91] CABLE DIAMETER
- PLATE HOLE \varnothing 51 [2.01] (2 PCS.)
- GROMMET UP TO \varnothing 45 [1.77] CABLE DIAMETER
- PLATE HOLE \varnothing 44 [1.73] (1 PCS.)
- GROMMET UP TO \varnothing 39 [1.54] CABLE DIAMETER



LIFTING POINTS

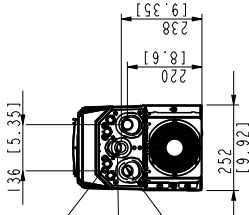
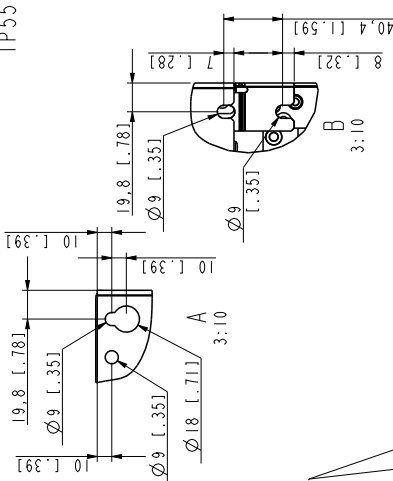
- 4PCS. \varnothing 20 [0.79]
- 8 10.32 [0.41] X 12 [0.47]



3AXD1000386017

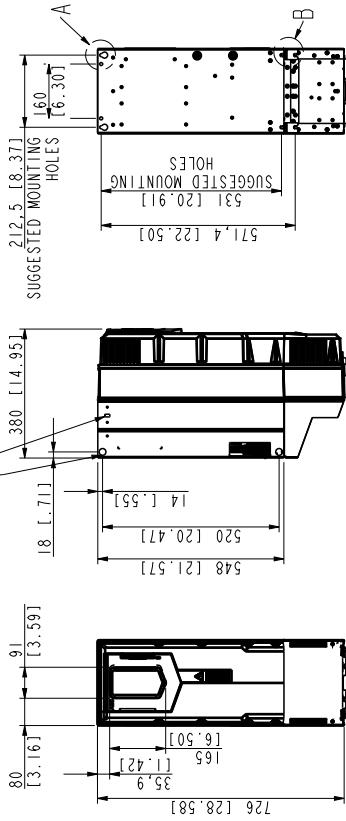
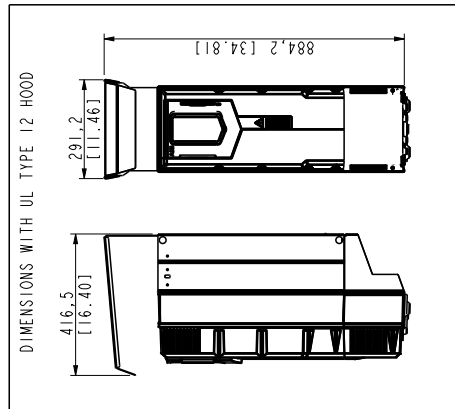
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IP55



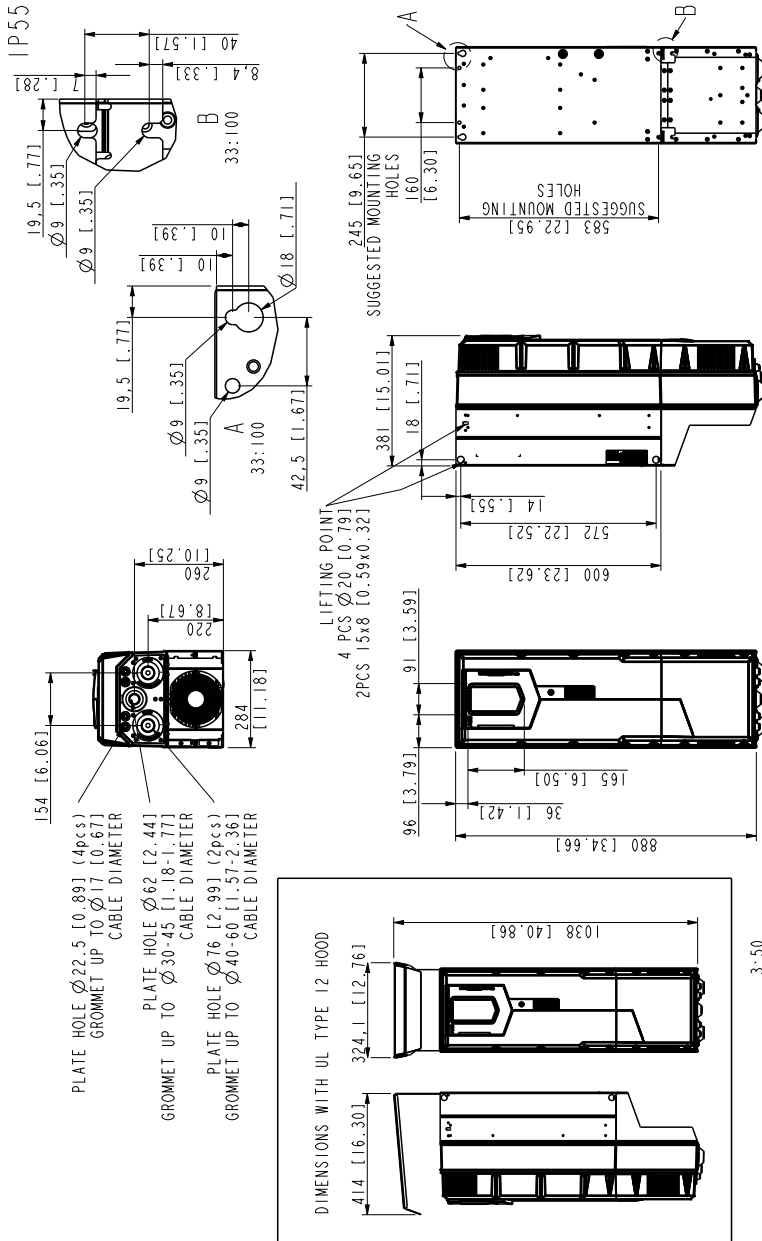
- PLATE HOLE $\varnothing 22.5$ [0.89] (4PCS) GROMMET UP TO $\varnothing 17$ [0.67] CABLE DIAMETER
- PLATE HOLE $\varnothing 50$ [1.97] GROMMET FOR $\varnothing 26-35$ [1.02-1.38] CABLE DIAMETER
- PLATE HOLE $\varnothing 62$ [2.44] GROMMET FOR $\varnothing 30-45$ [1.18-1.77] CABLE DIAMETER

LIFTING POINT
4 PCS $\varnothing 20$ [0.79]
2 PCS 15x8 [0.59x0.32]



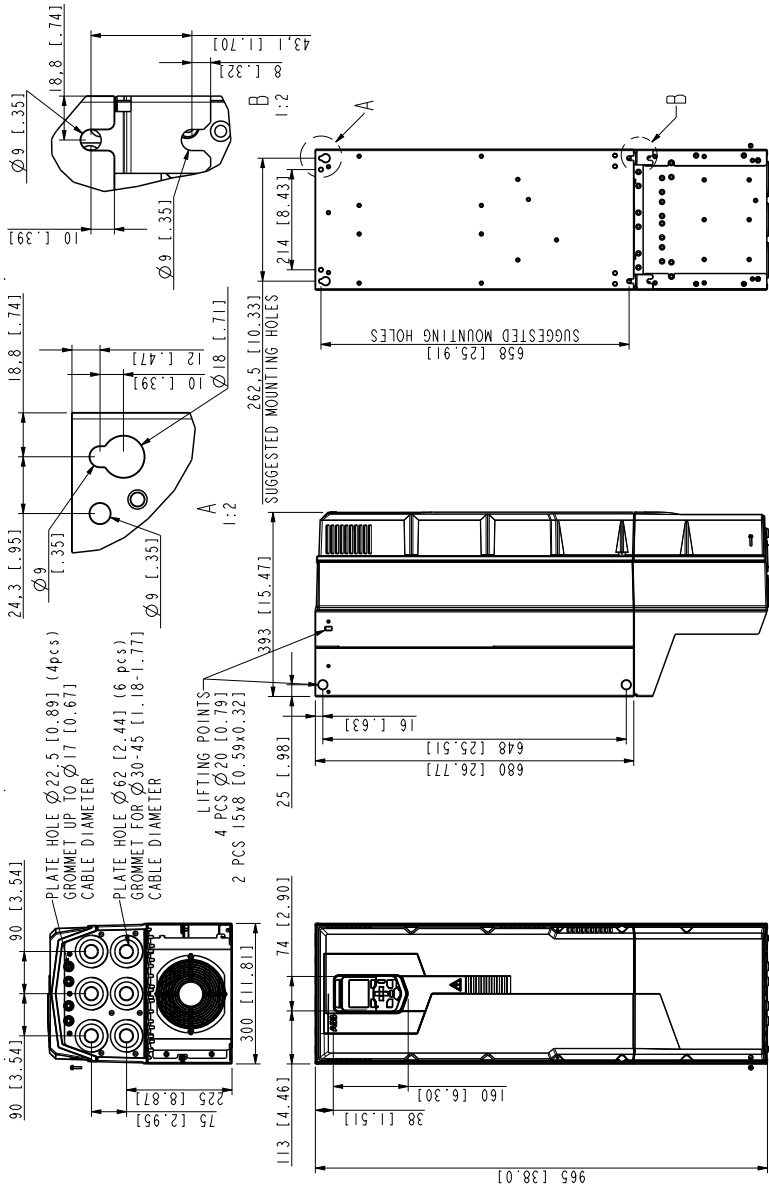
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Frame R7, IP55 (UL Type 12)



3AXD10000330932

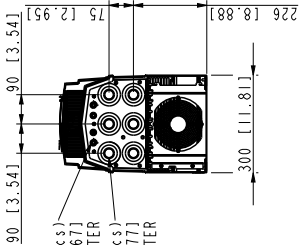
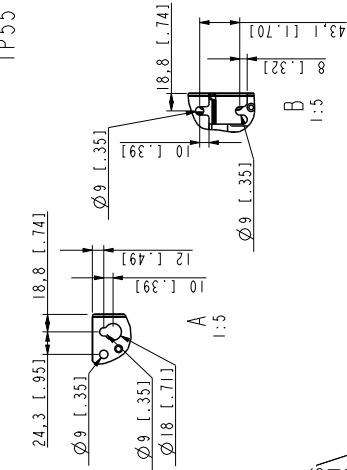
Frame R8, IP21 (UL Type 1)



3AXD10000287670

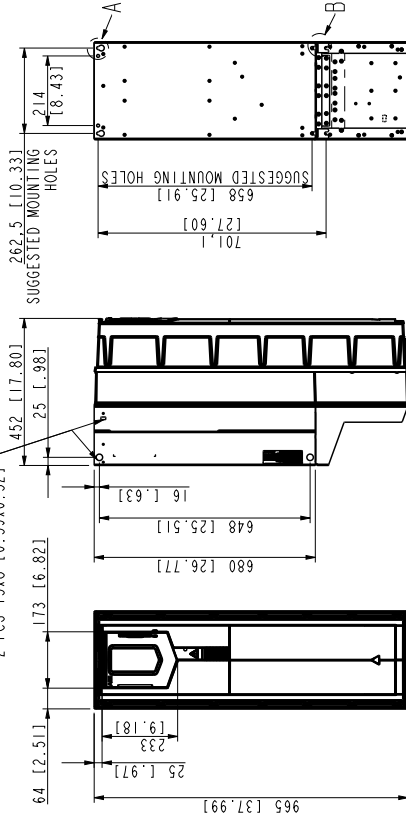
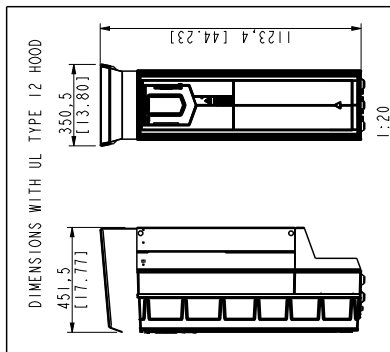
Frame R8, IP55 (UL Type 12)

IP55



- PLATE HOLE $\varnothing 22.5$ [0.89"] (4pcs) GROMMET UP TO $\varnothing 17$ [0.67] CABLE DIAMETER
- PLATE HOLE $\varnothing 62$ [2.44] (6pcs) GROMMET FOR $\varnothing 30-45$ [1.18-1.77] CABLE DIAMETER

LIFTING POINTS
4 PCS $\varnothing 20$ [0.79]
2 PCS 15×8 [0.59 x 0.32]



3AXD10000332446

12

Resistor braking

Contents of this chapter

This chapter describes how to select, protect and wire brake choppers and resistors. The chapter also contains technical data.

Operation principle and hardware description

The brake chopper handles the energy generated by a decelerating motor. The chopper connects the brake resistor to the intermediate DC circuit whenever the voltage in the circuit exceeds the limit defined by the control program. Energy consumption by the resistor losses lowers the voltage until the resistor can be disconnected.

For frame R1...R3 internal brake choppers and resistors, see below. For R4...R9 external brake choppers and resistors, see [Resistor braking, frames R4...R9 \(page 343\)](#).

Resistor braking, frames R1...R3

■ Planning the braking system

Selecting the brake resistor

Frames R1...R3 have a built-in brake chopper as standard equipment. The brake resistor is selected using the table and equations presented in this section.

1. Determine the required maximum braking power P_{Rmax} for the application. P_{Rmax} must be smaller than P_{BRmax} given in the table on page 338 for the used drive type.
 2. Calculate resistance R with Equation 1.
 3. Calculate energy E_{Rpulse} with Equation 2.
-

4. Select the resistor so that the following conditions are met:

- The rated power of the resistor must be greater than or equal to P_{Rmax} .
- Resistance R must be between R_{min} and R_{max} given in the table for the used drive type.
- The resistor must be able to dissipate energy E_{Rpulse} during the braking cycle T .

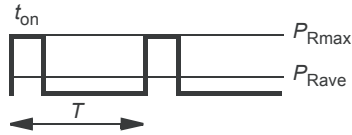
Equations for selecting the resistor:

Eq. 1. $U_N = 400V : R = \frac{450000}{P_{Rmax}}$

$U_N = 480V : R = \frac{615000}{P_{Rmax}}$

Eq. 2. $E_{Rpulse} = P_{Rmax} \cdot t_{on}$

Eq. 3. $P_{Rave} = P_{Rmax} \cdot \frac{t_{on}}{T}$



For conversion, use 1 hp = 746 W.

where

R = calculated brake resistor value (ohm). Make sure that: $R_{min} < R < R_{max}$.

P_{Rmax} = maximum power during the braking cycle (W)

P_{Rave} = average power during the braking cycle (W)

E_{Rpulse} = energy conducted into the resistor during a single braking pulse (J)

t_{on} = length of the braking pulse (s)

T = length of the braking cycle (s).

The tables below show reference resistor types for the maximum braking power.

IEC

ACS580-01-	R_{min}	R_{max}	P_{BRmax}	Reference resistor types
	ohm	ohm	kW	
3-phase $U_n = 230 V$				
04A7-2	25	205	0.7	Danotherm CBR-V 330 D T 406 78R UL
06A7-2	25	130	1.1	Danotherm CBR-V 330 D T 406 78R UL
07A6-2	25	95	1.5	Danotherm CBR-V 560 D HT 406 39R UL
012A-2	25	48	3.0	Danotherm CBR-V 560 D HT 406 39R UL
018A-2	25	35	4.1	-
024A-2	14	26	5.4	Danotherm CBT-H 560 D HT 406 19R
032A-2	14	19	7.4	Danotherm CBT-H 760 D HT 406 16R
047A-2	6.0	13	11	SAFUR90F575
060A-2	6.0	9.0	16	SAFUR90F575
3-phase $U_n = 400$ or $480 V$				
02A7-4	52	864	0.6	Danotherm CBH 360 C T 406 210R

ACS580-01-	R_{min}	R_{max}	P_{BRmax}	Reference resistor types
	ohm	ohm	kW	
03A4-4	52	582	0.9	Danotherm CBH 360 C T 406 210R
04A1-4	52	392	1.4	Danotherm CBH 360 C T 406 210R
05A7-4	52	279	2.0	Danotherm CBH 360 C T 406 210R
07A3-4	52	191	2.9	Danotherm CBR-V 330 D T 406 78R UL
09A5-4	52	140	3.9	Danotherm CBR-V 330 D T 406 78R UL
12A7-4	52	104	5.3	Danotherm CBR-V 330 D T 406 78R UL
018A-4	31	75	7.3	Danotherm CBR-V 560 D HT 406 39R UL
026A-4	22	52	10	Danotherm CBR-V 560 D HT 406 39R UL
033A-4	16	37	15	Danotherm CBT-H 560 D HT 406 19R
039A-4	10	27	20	Danotherm CBT-H 760 D HT 406 16R
046A-4	10	22	25	Danotherm CBT-H 760 D HT 406 16R

UL (NEC)

ACS580-01-	R_{min}	R_{max}	P_{BRmax}		Reference resistor types
	ohm	ohm	kW	hp	
3-phase $U_1 = 208...240$ V, P_n at $U_n = 208/230$ V					
04A6-2	25	205	0.7	0.9	Danotherm CBR-V 330 D T 406 78R UL
06A6-2	25	130	1.1	1.5	Danotherm CBR-V 330 D T 406 78R UL
07A5-2	25	95	1.5	2.0	Danotherm CBR-V 560 D HT 406 39R UL
10A6-2	25	65	2.2	2.9	Danotherm CBR-V 560 D HT 406 39R UL
017A-2	25	35	4.0	5.4	TBD
024A-2	14	26	5.4	7.2	Danotherm CBT-H 560 D HT 406 19R
031A-2	14	19	7.4	9.9	Danotherm CBT-H 560 D HT 406 16R
046A-2	7	13	11	14.7	SAFUR90F575
059A-2	7	9	16	21.4	SAFUR90F575
3-phase $U_1 = 440...480$ V, P_n at $U_n = 480$ V					
02A1-4	52	864	0.6	0.8	Danotherm CBH 360 C T 406 210R
03A0-4	52	582	0.9	1.2	Danotherm CBH 360 C T 406 210R
03A5-4	52	392	1.4	1.9	Danotherm CBH 360 C T 406 210R
04A8-4	52	279	2.0	2.7	Danotherm CBH 360 C T 406 210R
06A0-4	52	191	2.9	3.9	Danotherm CBR-V 330 D T 406 78R UL
07A6-4	52	140	3.9	5.2	Danotherm CBR-V 330 D T 406 78R UL
012A-4	52	104	5.3	7.1	Danotherm CBR-V 330 D T 406 78R UL
014A-4	31	75	7.3	9.8	Danotherm CBR-V 560 D HT 406 39R UL
023A-4	22	52	10	13.6	Danotherm CBR-V 560 D HT 406 39R UL
027A-4	16	37	15	20.1	Danotherm CBT-H 560 D HT 406 19R
034A-4	10	27	20	26.8	Danotherm CBT-H 760 D HT 406 16R
044A-4	10	22	25	33.5	Danotherm CBT-H 760 D HT 406 16R

ACS580-01-	R_{min}	R_{max}	P_{BRmax}		Reference resistor types
	ohm	ohm	kW	hp	
3-phase $U_1 = 525...600$ V, P_n at $U_n = 575$ V					
02A7-6	60	600	1.5	2.09	Danotherm CBR-V 330 D T 406 78R UL
03A9-6	60	450	2.2	2.7	Danotherm CBR-V 330 D T 406 78R UL
06A1-6	60	225	4.0	5.4	Danotherm CBR-V 330 D T 406 78R UL
09A0-6	60	165	5.4	7.2	Danotherm CBR-V 330 D T 406 78R UL
011A-6	60	120	7.4	9.9	Danotherm CBR-V 330 D T 406 78R UL
017A-6	60	82	11	14.7	Danotherm CBR-V 330 D T 406 78R UL
022A-6	25	56	16	21.4	Danotherm CBR-V 560 D HT 406 39R UL
027A-6	25	43	21	28.2	Danotherm CBR-V 560 D HT 406 39R UL
032A-6	25	35	26	34.9	TBD

Symbols

- R_{min} = minimum allowed brake resistor that can be connected to the brake chopper
- R_{max} = maximum allowed brake resistor that allows P_{BRmax}
- P_{BRmax} = maximum braking capacity of the drive, must exceed the desired braking power.



WARNING!

Do not use a brake resistor with a resistance below the minimum value specified for the particular drive. The drive and the internal chopper are not able to handle the overcurrent caused by the low resistance.

Selecting and routing the brake resistor cables

Use a shielded cable with the conductor size specified in section Terminal and entry data for the power cables on page [Terminal and entry data for the power cables \(page 278\)](#).

Minimizing electromagnetic interference

Follow these rules in order to minimize electromagnetic interference caused by the rapid current changes in the resistor cables:

- Install the cables away from other cable routes.
- Avoid long parallel runs with other cables. The minimum parallel cabling separation distance should be 0.3 meters.
- Cross the other cables at right angles.
- Keep the cable as short as possible in order to minimize the radiated emissions and stress on chopper IGBTs. The longer the cable the higher the radiated emissions, inductive load and voltage peaks over the IGBT semiconductors of the brake chopper.

Note: ABB has not verified that the EMC requirements are fulfilled with external user-defined brake resistors and cabling. The EMC compliance of the complete installation must be considered by the customer.

Maximum cable length

The maximum length of the resistor cable(s) is 10 m (33 ft).

Placing the brake resistor

Install the resistors outside the drive in a place where they will cool.

Arrange the cooling of the resistor in a way that:

- no danger of overheating is caused to the resistor or nearby materials
- the temperature of the room the resistor is located in does not exceed the allowed maximum.

Supply the resistor with cooling air/water according to the resistor manufacturer's instructions.



WARNING!

The materials near the brake resistor must be non-flammable. The surface temperature of the resistor is high. Air flowing from the resistor is of hundreds of degrees Celsius. If the exhaust vents are connected to a ventilation system, make sure that the material withstands high temperatures. Protect the resistor against contact.

Protecting the system in brake circuit fault situations

Protecting the system in cable and brake resistor short-circuit situations

The drive input fuses will also protect the resistor cable when it is identical with the input power cable.

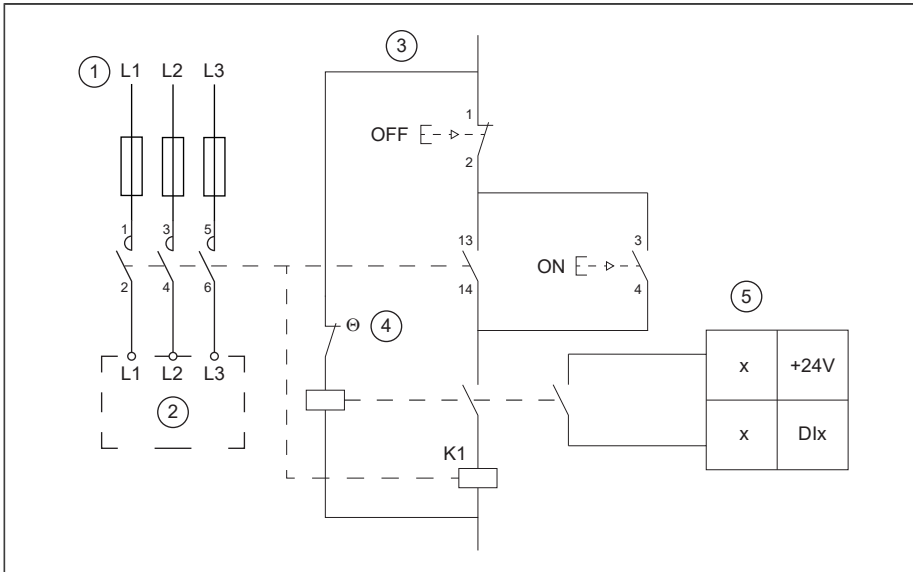
Protecting the system against thermal overload

The drive has a brake thermal model which protects the brake resistor against overload. ABB recommends to enable the thermal model at start up.

ABB recommends to equip the drive with a main contactor for safety reasons even when you have enabled the resistor thermal model. Wire the contactor so that it opens in case the resistor overheats. This is essential for safety since the drive will not otherwise be able to interrupt the main supply if the chopper remains conductive in a fault situation. An example wiring diagram is shown below. ABB recommends that you use resistors equipped with a thermal switch (1) inside the resistor assembly. The switch indicates overtemperature.

342 Resistor braking

ABB recommends that you also wire the thermal switch to a digital input of the drive, and configure the input to cause a fault trip at resistor overtemperature indication.



1	Drive input power connection with a main contactor
2	Drive
3	Main contactor control circuit
4	Brake resistor thermal switch
5	Digital input. Monitors the brake resistor thermal switch.

■ Mechanical installation

All brake resistors must be installed outside the drive. Follow the resistor manufacturer's instructions.

■ Electrical installation

Checking the insulation of the assembly

Follow the instructions given in section [Brake resistor assembly for R1...R3 \(page 115\)](#) or [Brake resistor assembly for R1...R3 \(page 165\)](#) (North America).

Connection diagram

See section [Connection diagram \(page 122\)](#) (IEC) or [Connection diagram \(page 172\)](#) (North America).

Connection procedure

See section [Grounding shelf \(page 127\)](#).

Connect the thermal switch of the brake resistor as described in *Protecting the system against thermal overload* (page 341).

■ Start-up

Start-up

Note: New brake resistors may be coated with storage grease. As the brake chopper operates for the first time, the grease burns off and may produce some smoke. Make sure there is sufficient ventilation.

Set the following parameters (HVAC control program):

- Disable the overvoltage control of the drive by parameter *30.30 Overvoltage control*.
- Set parameter *31.01 External event 1 source* to point to the digital input where the thermal switch of the brake resistor is wired.
- Set parameter *31.02 External event 1 type* to Fault.
- Enable the brake chopper by parameter *43.06 Brake chopper enable*. If Enabled with thermal model is selected, set also the brake resistor overload protection parameters *43.08* and *43.09* according to the application.
- Check the resistance value of parameter *43.10 Brake resistance*.

With these parameter settings, the drive stops by coasting on brake resistor overtemperature.



WARNING!

If the drive is equipped with a brake chopper but the chopper is not enabled by the parameter setting, the internal thermal protection of the drive against resistor overheating is not in use. In this case, the brake resistor must be disconnected.

Resistor braking, frames R4...R9

■ Planning the braking system

Frames R4...R9 need external brake choppers and resistors. The table below lists suitable choppers and resistors.

For more information, see *NBRA-6xx Braking Choppers Installation and start-up guide* (3AFY58920541 [English]) and *ACS-BRK Brake Units Installation and start-up guide* (3AFY61514309 [English]).

IEC

ACS580-01-	Brake chopper	R _{min}	R _{max}	P _{BRmax}	Reference resistor types ¹⁾
		ohm	ohm	kW	
3-phase U _n = 230 V					

344 Resistor braking

ACS580-01-	Brake chopper	R _{min}	R _{max}	P _{BRmax}	Reference resistor types ¹⁾
		ohm	ohm	kW	
076A-2	NBRA-658	-	-	-	-
089A-2	NBRA-658	2.0	5.6	26	SAFUR125F500
115A-2	NBRA-658	2.0	4.7	31	SAFUR125F500
144A-2	NBRA-658	2.0	3.4	43	SAFUR125F500
171A-2	NBRA-658	1.3	2.8	53	SAFUR125F500
213A-2	NBRA-658	1.3	2.3	64	2xSAFUR210F575
276A-2	NBRA-658	0.9	1.9	78	2xSAFUR210F575
3-phase U_n = 400 or 480 V (380...415 V, 440...480 V)					
062A-4	ACS-BRK-D	7.8	18.1	30	Built in with the brake chopper
073A-4	ACS-BRK-D	7.8	13.1	42	Built in with the brake chopper
088A-4	ACS-BRK-D	7.8	10.7	51	Built in with the brake chopper
106A-4	NBRA-658	1.3	8.7	63	SAFUR125F500
145A-4	NBRA-658	1.3	7.1	77	SAFUR125F500
169A-4	NBRA-658	1.3	5.2	105	SAFUR200F500
206A-4	NBRA-658	1.3	4.3	126	SAFUR200F500
246A-4	NBRA-658	1.3	3.5	156	2xSAFUR125F500
293A-4	NBRA-658	1.3	2.9	187	2xSAFUR210F575
363A-4	NBRA-659	0.7	2.4	227	2xSAFUR200F500
430A-4	NBRA-659	0.7	1.9	284	2xSAFUR200F500

1) Other resistors can be used if they meet the minimum resistance value and required power values.

UL (NEC)

ACS580-01-	R _{min}	R _{max}	P _{BRmax}	Reference resistor types
	ohm	ohm	kW	
3-phase U₁ = 208...240 V, P_n at U_n = 208/230 V				
075A-2	2.6	7	210	SAFUR125F500
088A-2	2	5.6	26	SAFUR125F500
114A-2	2	4.7	31	SAFUR125F500
143A-2	2	3.4	43	SAFUR200F500
169A-2	1.3	2.8	53	SAFUR200F500
211A-2	1.3	2.3	64	2xSAFUR210F575
273A-2	0.9	1.9	78	2xSAFUR210F575
343A-2	0.65	1.8	106	2x(2xSAFUR210F575)
396A-2	0.65	1.1	133	2x(2xSAFUR210F575)
3-phase U₁ = 440...480 V, P_n at U_n = 480 V				
052A-4	7.8	18.1	30	Built in with the brake chopper
065A-4	7.8	13.1	42	Built in with the brake chopper
077A-4	-	-	-	-

ACS580-01-	R_{min}	R_{max}	P_{BRmax}	Reference resistor types
	ohm	ohm	kW	
078A-4	7.8	10.7	51	Built in with the brake chopper
096A-4	1.3	8.7	63	SAFUR125F500
124A-4	1.3	7.1	77	SAFUR125F500
156A-4	1.3	5.2	105	SAFUR200F500
180A-4	1.3	4.3	126	SAFUR200F500
240A-4	1.3	3.5	156	2xSAFUR125F500
260A-4	1.3	2.9	187	2xSAFUR210F575
302A-4	-	-	-	-
361A-4	0.7	2.4	227	2xSAFUR200F500
414A-4	0.7	1.9	284	2xSAFUR200F500
3-phase $U_1 = 525...600$ V, P_n at $U_n = 575$ V				
041A-6	6.5	30	31	SAFUR90F575
052A-6	6.5	21	43	SAFUR90F575
062A-6	6.5	17	53	SAFUR90F575
077A-6	6.5	14	64	SAFUR90F575
099A-6	4.3	11.5	78	SAFUR80F500
125A-6	4.3	8.5	107	SAFUR80F500
144A-6	3.2	7	128	SAFUR80F500
192A-6	2.2	5.8	157	SAFUR125F500
242A-6	2.2	4.8	188	2xSAFUR200F500
271A-6	2.2	4	228	2xSAFUR200F500

Symbols

R_{min} = minimum allowed brake resistor that can be connected to the brake chopper

R_{max} = maximum allowed brake resistor that allows P_{BRmax}

P_{BRmax} = maximum braking capacity of the drive, must exceed the desired braking power.



WARNING!

Do not use a brake resistor with a resistance below the minimum value specified for the particular drive. The drive and the internal chopper are not able to handle the overcurrent caused by the low resistance.

■ Parameter settings for external braking chopper and resistor

Disable the overvoltage control of the drive with parameter 30.30 Overvoltage control.

Disable parameter 43.06 Braking chopper function as parameter group 43 Brake chopper is used for internal braking chopper and resistor only.

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The Safe torque off function

Contents of this chapter

This chapter describes the Safe torque off (STO) function of the drive and gives instructions for its use.

Description

The Safe torque off function can be used, for example, as the final actuator device of safety circuits that stop the drive in case of danger (such as an emergency stop circuit). Another typical application is a prevention of unexpected start-up function that enables short-time maintenance operations like cleaning or work on non-electrical parts of the machinery without switching off the power supply to the drive.

When activated, the Safe torque off function disables the control voltage for the power semiconductors of the drive output stage (A, see the diagrams below), thus preventing the drive from generating the torque required to rotate the motor. If the motor is running when Safe torque off is activated, it coasts to a stop.

The Safe torque off function has a redundant architecture, that is, both channels must be used in the safety function implementation. The safety data given in this manual is calculated for redundant use, and does not apply if both channels are not used.

The Safe torque off function complies with these standards:

Standard	Name
IEC 60204-1:2016 EN 60204-1:2018	<i>Safety of machinery – Electrical equipment of machines – Part 1: General requirements</i>

Standard	Name
IEC 61000-6-7:2014	<i>Electromagnetic compatibility (EMC) – Part 6-7: Generic standards – Immunity requirements for equipment intended to perform functions in a safety-related system (functional safety) in industrial locations</i>
IEC 61326-3-1:2017	<i>Electrical equipment for measurement, control and laboratory use – EMC requirements – Part 3-1: Immunity requirements for safety-related systems and for equipment intended to perform safety-related functions (functional safety) – General industrial applications</i>
IEC 61508-1:2010	<i>Functional safety of electrical/electronic/programmable electronic safety-related systems – Part 1: General requirements</i>
IEC 61508-2:2010	<i>Functional safety of electrical/electronic/programmable electronic safety-related systems – Part 2: Requirements for electrical/electronic/programmable electronic safety-related systems</i>
IEC 61511-1:2017	<i>Functional safety – Safety instrumented systems for the process industry sector</i>
IEC 61800-5-2:2016 EN 61800-5-2:2007	<i>Adjustable speed electrical power drive systems – Part 5-2: Safety requirements – Functional</i>
IEC 62061:2021 EN 62061:2005 + AC:2010 + A1:2013 + A2:2015	<i>Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems</i>
EN ISO 13849-1:2015	<i>Safety of machinery – Safety-related parts of control systems – Part 1: General principles for design</i>
EN ISO 13849-2:2012	<i>Safety of machinery – Safety-related parts of control systems – Part 2: Validation</i>

The function also corresponds to Prevention of unexpected start-up as specified by EN ISO 14118:2018 (ISO 14118:2017), and Uncontrolled stop (stop category 0) as specified in EN/IEC 60204-1.

■ **Compliance with the European Machinery Directive and the UK Supply of Machinery (Safety) Regulations**

See the technical data.

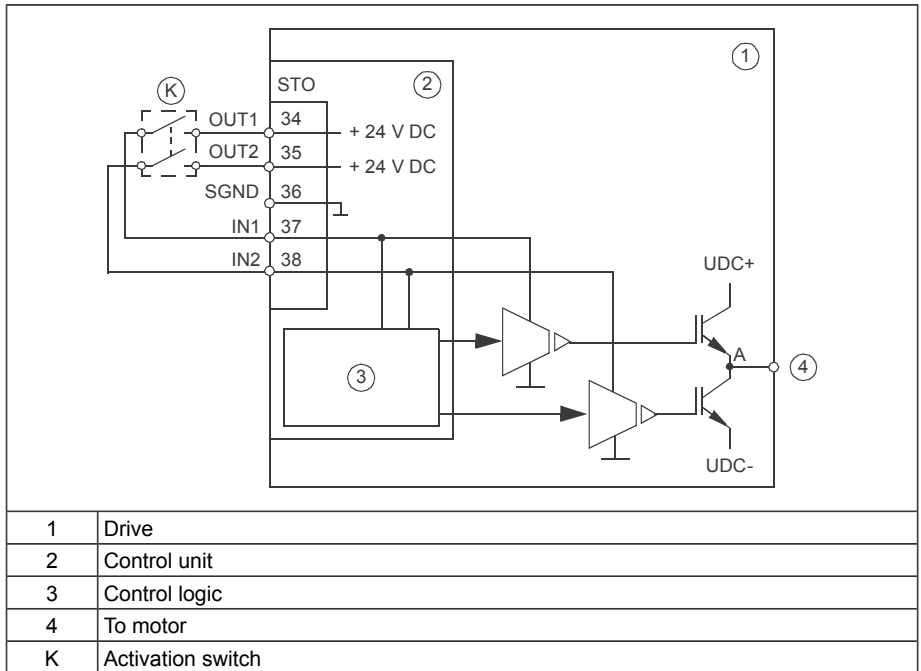
The Declarations of conformity are shown at the end of this chapter.

Wiring

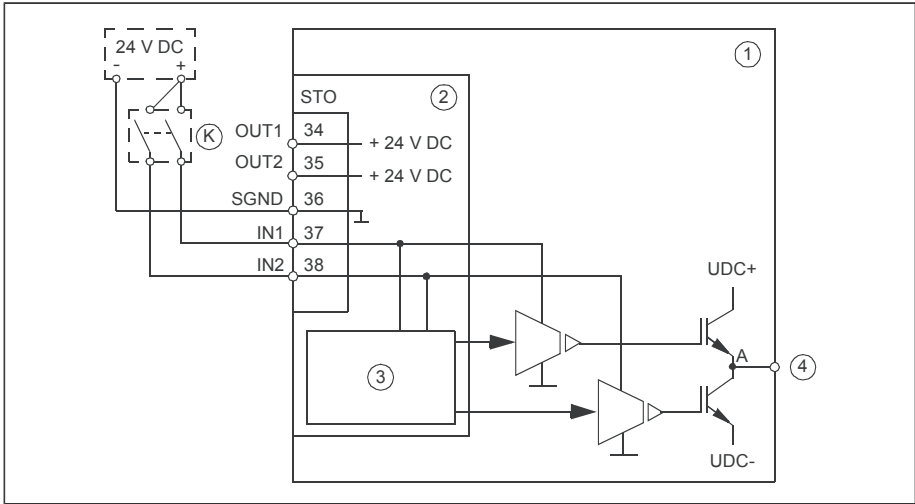
For the electrical specifications of the STO connection, see the technical data of the control unit.

■ Connection principle

Single ACS580-01 drive, internal power supply



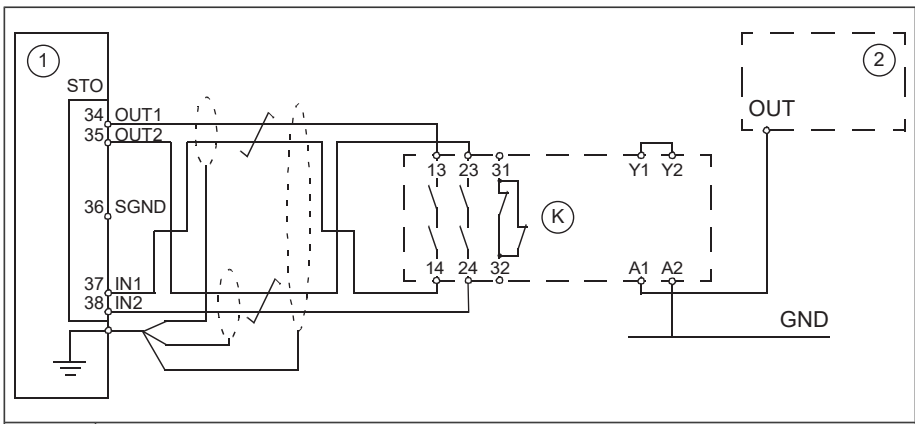
Single ACS580-01 drive, external power supply



1	Drive
2	Control unit
3	Control logic
4	To motor
K	Activation switch

■ **Wiring examples**

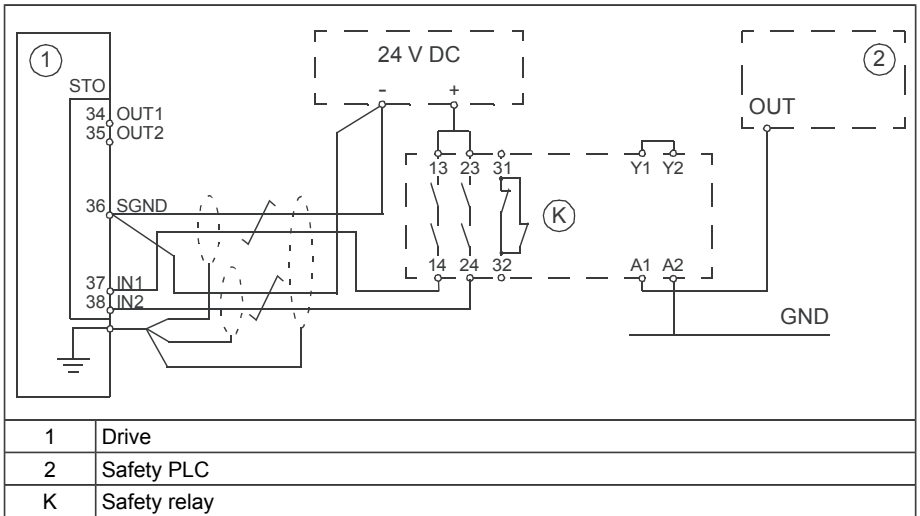
Single ACS580-01 drive, internal power supply



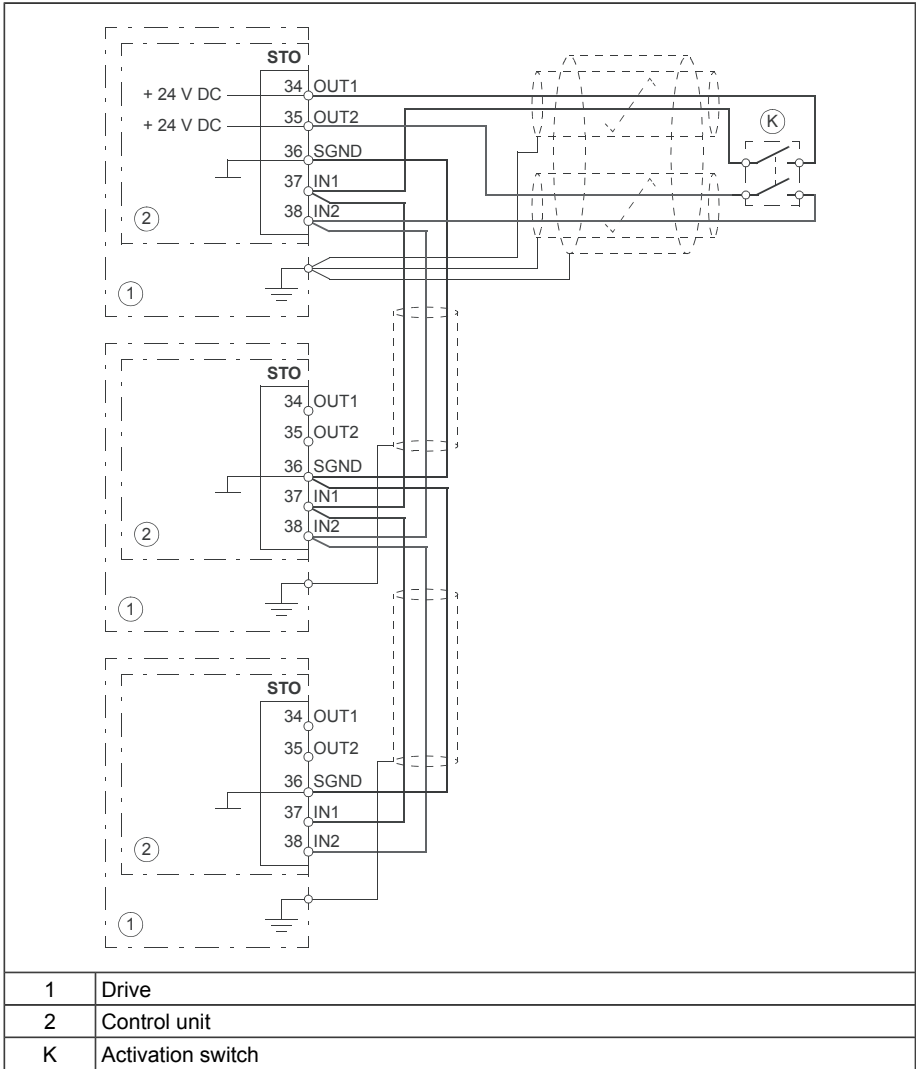
1	Drive
2	Safety PLC

K	Safety relay
---	--------------

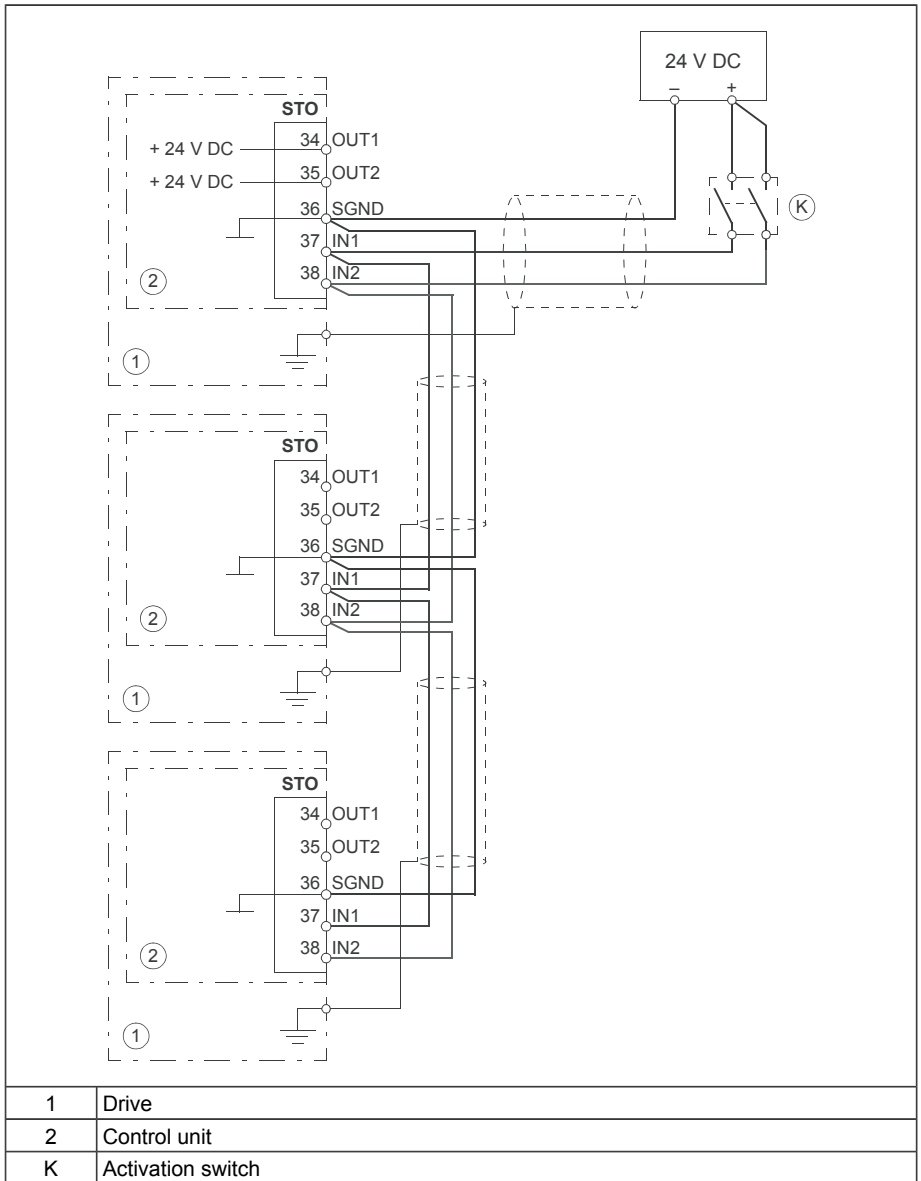
Single ACS580-01 drive, external power supply



Multiple ACS580-01 drives, internal power supply



Multiple ACS580-01 drives, external power supply



■ **Activation switch**

In the wiring diagrams, the activation switch has the designation [K]. This represents a component such as a manually operated switch, an emergency stop push button switch, or the contacts of a safety relay or safety PLC.

- In case a manually operated activation switch is used, the switch must be of a type that can be locked out to the open position.
- The contacts of the switch or relay must open/close within 200 ms of each other.
- A CPTC-02 thermistor protection module can also be used. For more information, see the module documentation.

■ **Cable types and lengths**

- Double-shielded twisted-pair cable is recommended.
- Maximum cable lengths:
 - 300 m (1000 ft) between activation switch [K] and drive control unit
 - 60 m (200 ft) between multiple drives
 - 60 m (200 ft) between external power supply and first control unit

Note: A short-circuit in the wiring between the switch and an STO terminal causes a dangerous fault. Therefore, it is recommended to use a safety relay (including wiring diagnostics) or a wiring method (shield grounding, channel separation) which reduces or eliminates the risk caused by the short-circuit.

Note: The voltage at the STO input terminals of the drive must be at least 13 V DC to be interpreted as “1”.

The pulse tolerance of the input channels is 1 ms.

■ **Grounding of protective shields**

- Ground the shield in the cabling between the activation switch and the control unit at the control unit only.
 - Ground the shield in the cabling between two control units at one control unit only.
-

Operation principle

1. The Safe torque off activates (the activation switch is opened, or safety relay contacts open).
 2. The STO inputs of the drive control unit de-energize.
 3. The control unit cuts off the control voltage from the output IGBTs.
 4. The control program generates an indication as defined by parameter 31.22 (see the firmware manual of the drive).
The parameter selects which indications are given when one or both STO signals are switched off or lost. The indications also depend on whether the drive is running or stopped when this occurs.
Note: This parameter does not affect the operation of the STO function itself. The STO function will operate regardless of the setting of this parameter: a running drive will stop upon removal of one or both STO signals, and will not start until both STO signals are restored and all faults reset.
Note: The loss of only one STO signal always generates a fault as it is interpreted as a malfunction of STO hardware or wiring.
 5. The motor coasts to a stop (if running). The drive cannot restart while the activation switch or safety relay contacts are open. After the contacts close, a reset may be needed (depending on the setting of parameter 31.22). A new start command is required to start the drive.
-

Start-up including validation test

To ensure the safe operation of a safety function, validation is required. The final assembler of the machine must validate the function by performing a validation test. The test must be performed

- at initial start-up of the safety function
- after any changes related to the safety function (circuit boards, wiring, components, settings, etc.)
- after any maintenance work related to the safety function
- at the proof test of the safety function
- after a drive firmware update.

■ Competence

The validation test of the safety function must be carried out by a competent person with adequate expertise and knowledge of the safety function as well as functional safety, as required by IEC 61508-1 clause 6. The test procedures and report must be documented and signed by this person.


■ Validation test reports

Signed validation test reports must be stored in the logbook of the machine. The report shall include documentation of start-up activities and test results, references to failure reports and resolution of failures. Any new validation tests performed due to changes or maintenance shall be logged into the logbook.

■ Validation test procedure

After wiring the Safe torque off function, validate its operation as follows.

Note: If a CPTC-02 module is installed, refer to its documentation.

Action	<input checked="" type="checkbox"/>
 WARNING! Obey the safety instructions. If you ignore them, injury or death, or damage to the equipment can occur.	<input type="checkbox"/>
Make sure that the drive can be run and stopped freely during start-up.	<input type="checkbox"/>
Stop the drive (if running), switch the input power off and isolate the drive from the power line using a disconnecter.	<input type="checkbox"/>
Check the STO circuit connections against the wiring diagram.	<input type="checkbox"/>
Close the disconnecter and switch the power on.	<input type="checkbox"/>

Action	<input checked="" type="checkbox"/>
<p>Test the operation of the STO function when the motor is stopped.</p> <ul style="list-style-type: none"> • Give a stop command for the drive (if running) and wait until the motor shaft is at a standstill. <p>Make sure that the drive operates as follows:</p> <ul style="list-style-type: none"> • Open the STO circuit. The drive generates an indication if one is defined for the 'stopped' state in parameter 31.22 (see the firmware manual). • Give a start command to verify that the STO function blocks the drive's operation. The drive generates a warning. The motor should not start. • Close the STO circuit. • Reset any active faults. Restart the drive and check that the motor runs normally. 	<input type="checkbox"/>
<p>Test the operation of the STO function when the motor is running.</p> <ul style="list-style-type: none"> • Start the drive and make sure the motor is running. • Open the STO circuit. The motor should stop. The drive generates an indication if one is defined for the 'running' state in parameter 31.22 (see the firmware manual). • Reset any active faults and try to start the drive. • Make sure that the motor stays at a standstill and the drive operates as described above in testing the operation when the motor is stopped. • Close the STO circuit. • Reset any active faults. Restart the drive and check that the motor runs normally. 	<input type="checkbox"/>
<p>Test the operation of the failure detection of the drive. The motor can be stopped or running.</p> <ul style="list-style-type: none"> • Open the 1st channel of the STO circuit. If the motor was running, it should coast to a stop. The drive generates a <i>FA81 Safe Torque Off 1 loss</i> fault indication (see the firmware manual). • Give a start command to verify that the STO function blocks the drive's operation. The motor should not start. • Close the STO circuit. • Reset any active faults. Restart the drive and check that the motor runs normally. • Open the 2nd channel of the STO circuit. If the motor was running, it should coast to a stop. The drive generates a <i>FA82 Safe Torque Off 2 loss</i> fault indication (see the firmware manual). • Give a start command to verify that the STO function blocks the drive's operation. The motor should not start. • Close the STO circuit. • Reset any active faults. Restart the drive and check that the motor runs normally. 	<input type="checkbox"/>
<p>Document and sign the validation test report which verifies that the safety function is safe and accepted for operation.</p>	<input type="checkbox"/>

Use

1. Open the activation switch, or activate the safety functionality that is wired to the STO connection.
2. The STO inputs on the drive control unit de-energize, and the control unit cuts off the control voltage from the output IGBTs.
3. The control program generates an indication as defined by parameter 31.22 (see the firmware manual of the drive).
4. The motor coasts to a stop (if running). The drive will not restart while the activation switch or safety relay contacts are open.
5. Deactivate the STO by closing the activation switch, or resetting the safety functionality that is wired to the STO connection.
6. Reset any faults before restarting.



WARNING!

The Safe torque off function does not disconnect the voltage of the main and auxiliary circuits from the drive. Therefore maintenance work on electrical parts of the drive or the motor can only be carried out after isolating the drive from the supply and all other voltage sources.



WARNING!

The drive cannot detect or memorize any changes in the STO circuitry when the drive control unit is not powered. If both STO circuits are closed and a level-type start signal is active when the power is restored, it is possible that the drive starts without a fresh start command. Take this into account in the risk assessment of the system.

This is also valid when the drive is only powered by a CMOD-xx multifunction extension module.



WARNING!

(With permanent magnet or synchronous reluctance [SynRM] motors only)

In case of a multiple IGBT power semiconductor failure, the drive can produce an alignment torque which maximally rotates the motor shaft by $180/p$ degrees (with permanent magnet motors) or $180/2p$ degrees (with synchronous reluctance [SynRM] motors) regardless of the activation of the Safe torque off function. p denotes the number of pole pairs.

Notes:

- If a running drive is stopped by using the Safe torque off function, the drive will cut off the motor supply voltage and the motor will coast to a stop. If this causes danger
-

or is not otherwise acceptable, stop the drive and machinery using the appropriate stop mode before activating the Safe torque off function.

- The Safe torque off function overrides all other functions of the drive.
 - The Safe torque off function is ineffective against deliberate sabotage or misuse.
 - The Safe torque off function has been designed to reduce the recognized hazardous conditions. In spite of this, it is not always possible to eliminate all potential hazards. The assembler of the machine must inform the final user about the residual risks.
-

Maintenance

After the operation of the circuit is validated at start-up, the STO function shall be maintained by periodic proof testing. In high demand mode of operation, the maximum proof test interval is 20 years. In low demand mode of operation, the maximum proof test interval is 5 or 2 years; see section *Safety data (page 362)*. It is assumed that all dangerous failures of the STO circuit are detected by the proof test. To perform the proof test, do the *Validation test procedure (page 356)*.

Note: See also the Recommendation of Use CNB/M/11.050 (published by the European co-ordination of Notified Bodies) concerning dual-channel safety-related systems with electromechanical outputs:

- When the safety integrity requirement for the safety function is SIL 3 or PL e (cat. 3 or 4), the proof test for the function must be performed at least every month.
- When the safety integrity requirement for the safety function is SIL 2 (HFT = 1) or PL d (cat. 3), the proof test for the function must be performed at least every 12 months.

The STO function of the drive does not contain any electromechanical components.

In addition to proof testing, it is a good practice to check the operation of the function when other maintenance procedures are carried out on the machinery.

Include the Safe torque off operation test described above in the routine maintenance program of the machinery that the drive runs.

If any wiring or component change is needed after start-up, or the parameters are restored, do the test given in section *Validation test procedure (page 356)*.

Use only spare parts approved by ABB.

Record all maintenance and proof test activities in the machine logbook.

■ Competence

The maintenance and proof test activities of the safety function must be carried out by a competent person with adequate expertise and knowledge of the safety function as well as functional safety, as required by IEC 61508-1 clause 6.

Fault tracing

The indications given during the normal operation of the Safe torque off function are selected by drive control program parameter 31.22.

The diagnostics of the Safe torque off function cross-compare the status of the two STO channels. In case the channels are not in the same state, a fault reaction function is performed and the drive trips on an "STO hardware failure" fault. An attempt to use the STO in a non-redundant manner, for example activating only one channel, will trigger the same reaction.

See the firmware manual of the drive control program for the indications generated by the drive, and for details on directing fault and warning indications to an output on the control unit for external diagnostics.

Any failures of the Safe torque off function must be reported to ABB.

Safety data

The safety data for the Safe torque off function is given below.

Note: The safety data is calculated for redundant use, and does not apply if both STO channels are not used.

Frame size	SIL	PL	SFF (%)	PFH ($T_1 = 20$ a) (1/h)	PFD _{avg} ($T_1 = 2$ a)	PFD _{avg} ($T_1 = 5$ a)	MTTF _D (a)	DC (%)	Cat.	SC	HFT	CCF	T _M (a)
$U_N = 230$ V													
R1	3	e	>99	2.79E-09	2.34E-05	5.83E-05	2755	≥90	3	3	1	80	20
R2	3	e	>99	2.79E-09	2.34E-05	5.83E-05	2756	≥90	3	3	1	80	20
R3	3	e	>99	2.59E-09	2.28E-05	5.72E-05	2856	≥90	3	3	1	80	20
R4	3	e	>99	2.59E-09	2.28E-05	5.67E-05	2870	≥90	3	3	1	80	20
R5	3	e	>99	3.94E-09	2.28E-05	5.69E-05	2856	≥90	3	3	1	80	20
R6 R7 R8	3	e	>99	3.92E-09	3.44E-05	8.59E-05	9380	≥90	3	3	1	80	20
$U_N = 400$ V													
R1 R2	3	e	>99	2.55E-09	2.24E-05	5.59E-05	2918	≥90	3	3	1	80	20
R3	3	e	>99	2.62E-09	2.31E-05	5.75E-05	2823	≥90	3	3	1	80	20
R4 R4 v2	3	e	>99	2.59E-09	2.28E-05	5.67E-05	2870	≥90	3	3	1	80	20
R5	3	e	>99	2.59E-09	2.28E-05	5.68E-05	2868	≥90	3	3	1	80	20
R6 R7	3	e	>99	3.92E-09	3.44E-05	8.59E-05	9380	≥90	3	3	1	80	20
R8 R9	3	e	>99	4.22E-09	3.69E-05	9.24E-05	8792	≥90	3	3	1	80	20
$U_N = 600$ V													
R2	3	e	>99	2.67E-09	2.24E-05	5.57E-05	2920	≥90	3	3	1	80	20
R3	3	e	>99	2.61E-09	2.30E-05	5.72E-05	2840	≥90	3	3	1	80	20
R5	3	e	>99	2.59E-09	2.28E-05	5.69E-05	2856	≥90	3	3	1	80	20
R7 R8 R9	3	e	>99	4.25E-09	3.72E-05	9.29E-05	6443	≥90	3	3	1	80	20
3AXD10000776787 A, 3AXD10000015777 P													

- The following temperature profile is used in safety value calculations:
 - 670 on/off cycles per year with $\Delta T = 71.66$ °C
 - 1340 on/off cycles per year with $\Delta T = 61.66$ °C
 - 30 on/off cycles per year with $\Delta T = 10.0$ °C

- 32 °C board temperature at 2.0% of time
- 60 °C board temperature at 1.5% of time
- 85 °C board temperature at 2.3% of time.
- The STO is a type A safety component as defined in IEC 61508-2.
- Relevant failure modes:
 - The STO trips spuriously (safe failure)
 - The STO does not activate when requested
 - A fault exclusion on the failure mode “short circuit on printed circuit board” has been made (EN 13849-2, table D.5). The analysis is based on an assumption that one failure occurs at one time. No accumulated failures have been analyzed.
- STO response times:
 - STO reaction time (shortest detectable break): 1 ms
 - STO response time: 2 ms (typical), 5 ms (maximum)
 - Fault detection time: Channels in different states for longer than 200 ms
 - Fault reaction time: Fault detection time + 10 ms
- Indication delays:
 - STO fault indication (parameter 31.22) delay: < 500 ms
 - STO warning indication (parameter 31.22) delay: < 1000 ms

■ Terms and abbreviations

Term or abbreviation	Reference	Description
Cat.	EN ISO 13849-1	Classification of the safety-related parts of a control system in respect of their resistance to faults and their subsequent behavior in the fault condition, and which is achieved by the structural arrangement of the parts, fault detection and/or by their reliability. The categories are: B, 1, 2, 3 and 4.
CCF	EN ISO 13849-1	Common cause failure (%)
DC	EN ISO 13849-1	Diagnostic coverage
HFT	IEC 61508	Hardware fault tolerance
MTTF _D	EN ISO 13849-1	Mean time to dangerous failure: (Total number of life units) / (Number of dangerous, undetected failures) during a particular measurement interval under stated conditions

Term or abbreviation	Reference	Description
PFD _{avg}	IEC 61508	Average probability of dangerous failure on demand, that is, mean unavailability of a safety-related system to perform the specified safety function when a demand occurs
PFH	IEC 61508	Average frequency of dangerous failures per hour, that is, average frequency of a dangerous failure of a safety related system to perform the specified safety function over a given period of time
PL	EN ISO 13849-1	Performance level. Levels a...e correspond to SIL
Proof test	IEC 61508, IEC 62061	Periodic test performed to detect failures in a safety-related system so that, if necessary, a repair can restore the system to an "as new" condition or as close as practical to this condition
SC	IEC 61508	Systematic capability
SFF	IEC 61508	Safe failure fraction (%)
SIL	IEC 61508	Safety integrity level (1...3)
STO	IEC/EN 61800-5-2	Safe torque off
T_1	IEC 61508-6	Proof test interval. T_1 is a parameter used to define the probabilistic failure rate (PFH or PFD) for the safety function or subsystem. Performing a proof test at a maximum interval of T_1 is required to keep the SIL capability valid. The same interval must be followed to keep the PL capability (EN ISO 13849) valid. See also section Maintenance.
T_M	EN ISO 13849-1	Mission time: the period of time covering the intended use of the safety function/device. After the mission time elapses, the safety device must be replaced. Note that any T_M values given cannot be regarded as a guarantee or warranty.

■ TÜV certificate

The TÜV certificate is available on the Internet at www.abb.com/drives/documents.

■ **Declarations of conformity**



EU Declaration of Conformity

Machinery Directive 2006/42/EC

We

Manufacturer:
Address:
Phone:

ABB Oy
Hiomotie 13, 00380 Helsinki, Finland.
+358 10 22 11

declare under our sole responsibility that the following product:

Frequency converter

ACS580-01

with regard to the safety functions

- Safe Torque Off
- Safe stop 1 (SSI-t, with FSPS-21 PROFIsafe module, +Q986)

is in conformity with all the relevant safety component requirements of EU Machinery Directive 2006/42/EC, when the listed safety function is used for safety component functionality.

The following harmonized standards have been applied:

EN 61800-5-2:2007

Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems

EN 62061:2005

+ AC:2010 + A1:2013 + A2:2015

EN ISO 13849-1:2015

Safety of machinery – Safety-related parts of control systems. Part 1: General requirements

EN ISO 13849-2:2012

Safety of machinery – Safety-related parts of the control systems. Part 2: Validation

EN 60204-1:2018

Safety of machinery – Electrical equipment of machines – Part 1: General requirements

The following other standards have been applied:

IEC 61508:2010, parts 1-2

Functional safety of electrical / electronic / programmable electronic safety-related systems

IEC 61800-5-2:2016

Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional

The product(s) referred in this Declaration of conformity fulfil(s) the relevant provisions of other European Union Directives which are notified in Single EU Declaration of conformity 3AXD10000497690.

Person authorized to compile the technical file:

Name and address: Jussi Vesti, Hiomotie 13, 00380 Helsinki, Finland.

Helsinki, March 30, 2021

Signed for and on behalf of:

Tuomo Tarula
Local Division Manager, ABB Oy

Harri Mustonen
Product Unit Manager, ABB Oy

Document number 3AXD10000302783



Declaration of Conformity

Supply of Machinery (Safety) Regulations 2008

We
Manufacturer: ABB Oy
Address: Hiomotie 13, 00380 Helsinki, Finland.
Phone: +358 10 22 11

declare under our sole responsibility that the following product:

Frequency converter
ACS580-01

with regard to the safety functions

- Safe Torque Off
- Safe stop 1 (SS1-t, with FSPS-21 PROFIsafe module, +Q986)

is in conformity with all the relevant safety component requirements of the Supply of Machinery (Safety) Regulations 2008, when the listed safety function is used for safety component functionality.

The following harmonized standards have been applied:
EN 61800-5-2:2007

Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional
Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems

EN 62061:2005
+ AC:2010 + A1:2013 + A2:2015

Safety of machinery – Safety-related parts of control systems. Part 1: General requirements
Safety of machinery – Safety-related parts of the control systems. Part 2: Validation
Safety of machinery – Electrical equipment of machines – Part 1: General requirements

EN ISO 13849-1:2015

EN ISO 13849-2:2012

EN 60204-1:2018

The following other standards have been applied:
IEC 61508:2010, parts 1-2

Functional safety of electrical / electronic / programmable electronic safety-related systems
Adjustable speed electrical power drive systems – Part 5-2: Safety requirements - Functional

IEC 61800-5-2:2016

The product(s) referred in this declaration of conformity fulfill(s) the relevant provisions of other UK statutory requirements, which are notified in a single declaration of conformity 3AXD10001325742.

Person authorized to compile the technical file:

Name and address: Jussi Vesti, Hiomotie 13, 00380 Helsinki, Finland.

Helsinki, March 30, 2021
Signed for and on behalf of:

Tuomo Tarula
Local Division Manager, ABB Oy

Harri Mustonen
Product Unit Manager, ABB Oy

Document number 3AXD10001325534

14

Optional I/O extension and adapter modules

Contents of this chapter

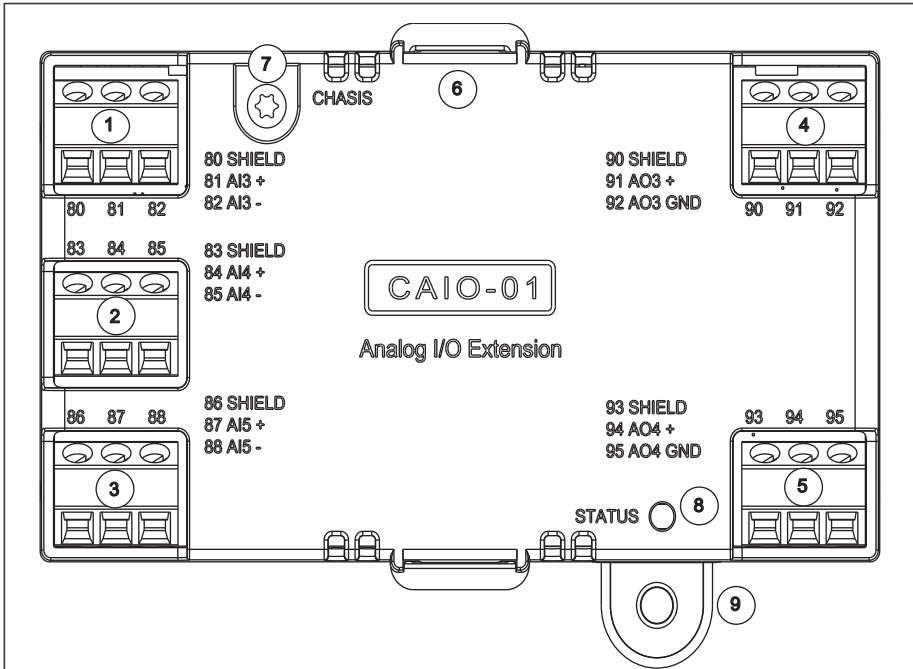
This chapter describes how to install and start up the optional CAIO-01, CHDI-01, CMOD-01 and CMOD-02 IO multifunction extension modules and CBAI-01 adapter module. The chapter also contains diagnostics and technical data.

CAIO-01 bipolar analog I/O adapter module

■ Product overview

The CAIO-01 bipolar analog I/O module expands the inputs and outputs of the drive control unit. It has three bipolar current/voltage inputs and two unipolar current/voltage outputs. The inputs can handle positive and negative signals. The way the drive interprets the negative range of the inputs depends on the parameter settings of the drive. The voltage/current selection of the inputs is done with a parameter.

■ Layout



1, 2, 3	Analog inputs		4, 5	Analog outputs	
80	SHIELD	Cable shield connection	90	SHIELD	Cable shield connection
81	AI3+	Analog input 3 positive signal	91	AO3	Analog output 3 signal
82	AI3-	Analog input 3 negative signal	92	AGND	Analog ground potential
83	SHIELD	Cable shield connection	93	SHIELD	Cable shield connection
84	AI4+	Analog input 4 positive signal	94	AO4	Analog output 4 signal
85	AI4-	Analog input 4 negative signal	95	AGND	Analog ground potential
86	SHIELD	Cable shield connection			
87	AI5+	Analog input 5 positive signal			
88	AI5-	Analog input 5 negative signal			
6	Control unit slot interface				
7	Grounding hole				
8	Diagnostic LED				
9	Mounting hole				

■ Mechanical installation

Necessary tools

- Screwdriver and a set of suitable bits.

Unpacking and examining the delivery

1. Open the option package. Make sure that the package contains:
 - the option module
 - a mounting screw.
2. Make sure that there are no signs of damage.

Installing the module

See section [Installing option modules \(page 153\)](#).

■ Electrical installation



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

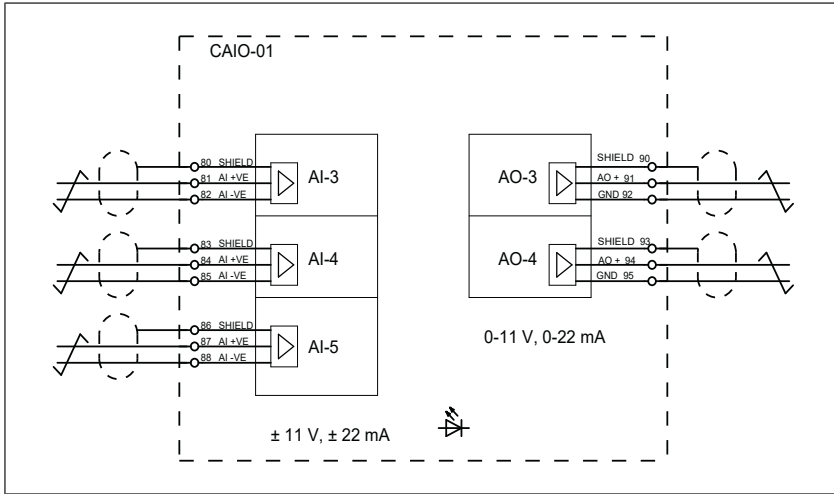
Stop the drive and do the steps in section [Electrical safety precautions \(page 22\)](#) before you start the work.

Necessary tools

- Screwdriver and a set of suitable bits.

Wiring

Connect the external cables to the applicable module terminals. Ground the outer shield of the cables to the SHIELD terminal.



■ **Start-up**

Setting the parameters

1. Power up the drive.
2. If no warning is shown,
 - make sure that the value of both parameters *15.01 Extension module type* and *15.02 Detected extension module* is CAIO-01.

If warning *A7AB Extension I/O configuration failure* is shown,

- make sure that the value of *15.02* is CAIO-01.
- set the value of parameter *15.01* to CAIO-01.

You can now see the parameters of the extension module in group *15 I/O extension module*.

3. Set the parameters of analog inputs AI3, AI4, AI5 or analog outputs AO3 or AO4 to applicable values, see the firmware manual.

Example: To connect supervision 1 to AI3 of the extension module:

- Select the mode of the supervision function (*32.05 Supervision function 1*).
- Set limits for the supervision function (*32.09 Supervision 1 low* and *32.10 Supervision 1 high*).
- Select the supervision action (*32.06 Supervision 1 action*).
- Connect *32.07 Supervision 1 signal* to *15.52 AI3 scaled value*.

■ Diagnostics

LEDs

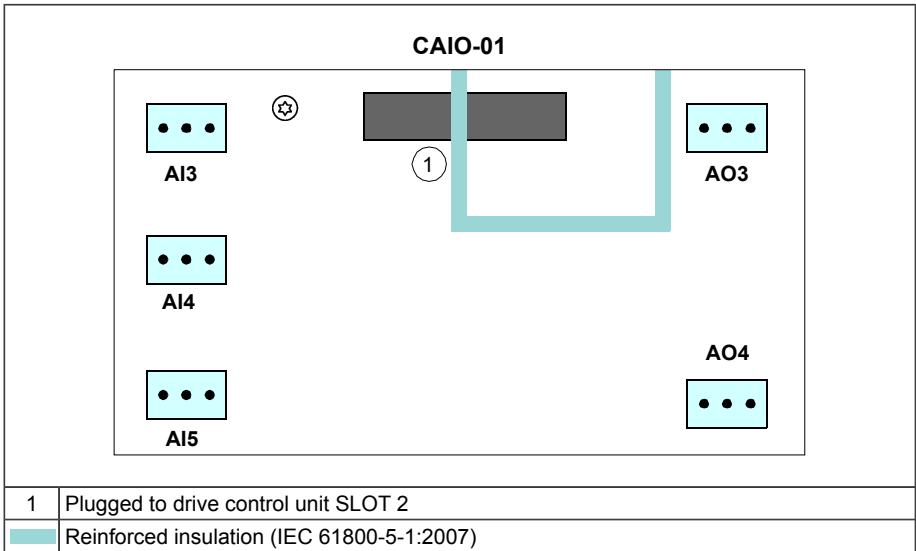
The adapter module has one diagnostic LED.

Color	Description
Green	The adapter module is powered up.
Red	There is no communication with the drive control unit or the adapter module has detected an error.

■ **Technical data**

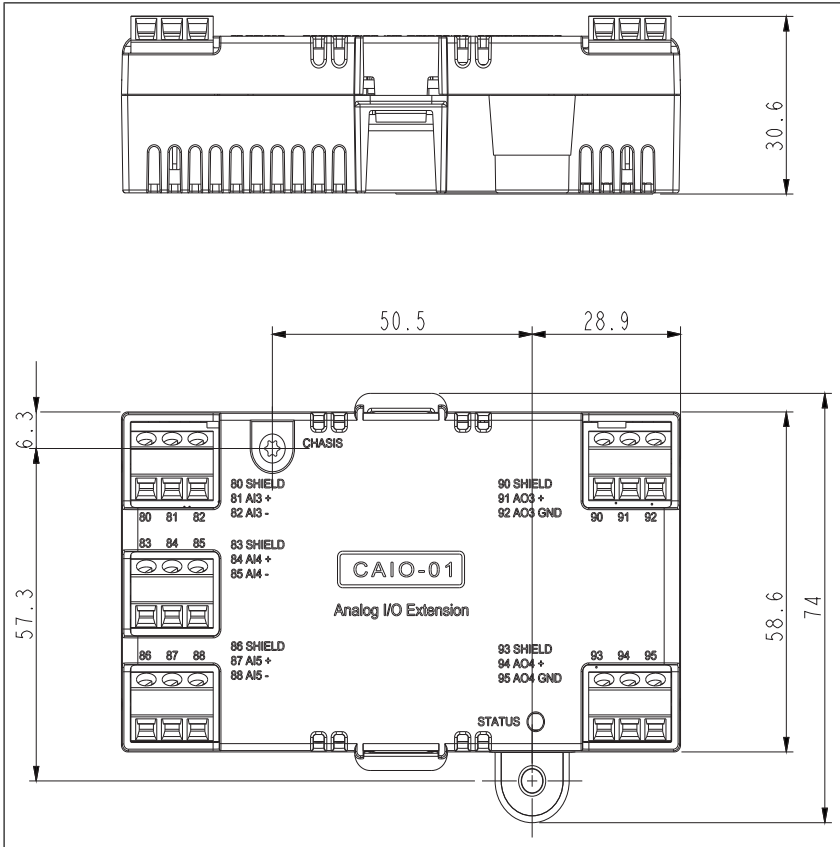
Installation	Into slot 2 of drive control unit
Degree of protection	IP20 / UL Type 1
Ambient conditions	See the drive technical data.
Package	Cardboard
Analog inputs (80..82, 83..85, 86..88)	
Maximum wire size	1.5 mm ²
Input voltage (AI+ and AI-)	-11 V ... +11 V
Input current (AI+ and AI-)	-22 mA ... +22 mA
Input resistance	>200 kohm (voltage mode), 100 ohm (current mode)
Optional cable shield connections	
Analog outputs (90..92, 93..95)	
Maximum wire size	1.5 mm ²
Output voltage (AO+ and AO-)	0 V ... +11 V
Output current (AO+ and AO-)	0 mA ... +22 mA
Output resistance	< 20 ohm
Recommended load	>10 kohm
Inaccuracy	± 1% Typical, ± 1.5% Max of full-scale value
Optional cable shield connections	

Isolation areas



■ Dimension drawings

The dimensions are in millimeters.

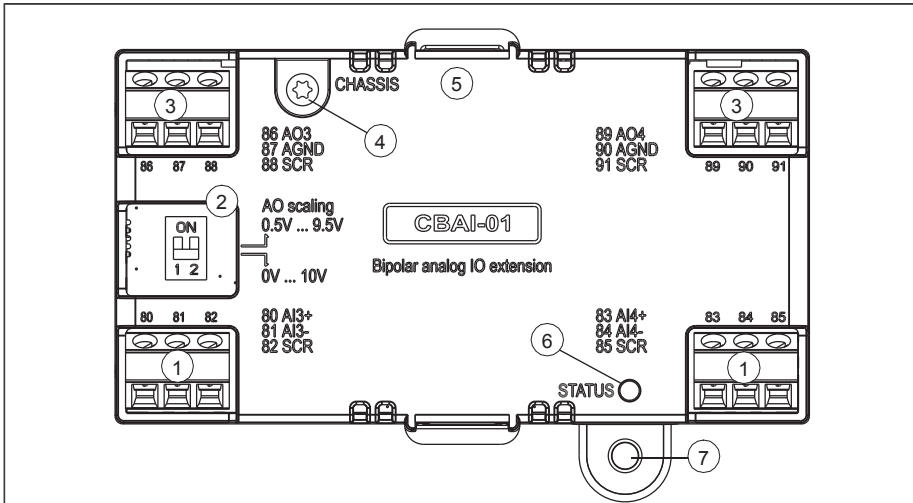


CBAI-01 bipolar analog IO adapter module

Product overview

The CBAI-01 includes two bipolar analog inputs, two unipolar analog outputs, and a switch which can be used to select scaling of the analog output level. The module converts the bipolar analog inputs (-10...+10 V) to respective unipolar analog inputs 0...+10 V which can be connected to the drive control unit. It offers no additional inputs.

Layout



Analog inputs (1)			Analog outputs (3)		
80	AI3+	Analog input 3 positive signal	86	AO3	Analog output 3 signal
81	AI3-	Analog input 3 negative signal	87	AGND	Analog ground potential
82	SCR	Cable shield connection	88	SCR	Cable shield connection
83	AI4+	Analog input 4 positive signal	89	AO4	Analog output 4 signal
84	AI4-	Analog input 4 negative signal	90	AGND	Analog ground potential
85	SCR	Cable shield connection	91	SCR	Cable shield connection
2	Analog output scale switch (2)		4	Grounding hole	
5	Control unit SLOT 2 interface		6	Diagnostic LED	
7	Grounding hole		-		

■ Mechanical installation

Necessary tools

- Screwdriver and a set of suitable bits.

Unpacking and examining the delivery

1. Open the option package. Make sure that the package contains:
 - the option module
 - a mounting screw.
2. Make sure that there are no signs of damage.

Installing the module

See section [Installing option modules \(page 153\)](#).

■ Electrical installation



WARNING!

Obey the instructions in chapter [Safety instructions \(page 19\)](#). If you ignore them, injury or death, or damage to the equipment can occur. If you are not a qualified electrician, do not do electrical work.

Make sure that the drive is disconnected from the input power during installation. If the drive is already connected to the input power, wait for 5 minutes after disconnecting the input power.

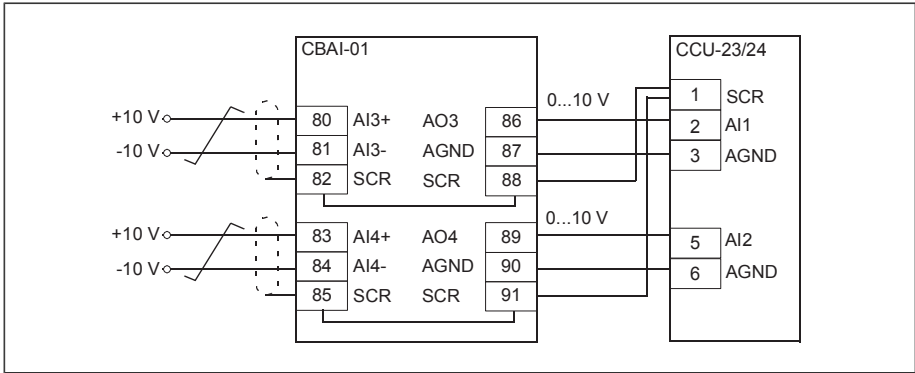
Necessary tools

- Screwdriver and a set of suitable bits.

Wiring

Connect the external control cables to the applicable module terminals. Ground the outer shield of the cables 360 degrees under a grounding clamp on the grounding shelf of the control cables and the pair cable shield to the SCR terminal of CBAI-01.

Connection diagram:



■ **Start-up**

Setting the parameters

1. Power up the drive.
2. Verify that the diagnostic LED is on.

Parameter setting example for AI1

This example shows how to set the control unit parameters for a bipolar speed reference ranging from -50 Hz to 50 Hz, with detection of a wire break between the adapter module and the control unit of the drive.

Parameter	Setting	Default
12.17 AI1 min	0.5 V	4.000 mA or 0.000 V
12.18 AI1 max	9.5 V	20.000 mA or 10.000 V
12.19 AI1 scaled at AI1 min	-50	0.000
12.20 AI1 scaled at AI1 max	50	50
32.05 Supervision 1 function	Low	Disabled
32.06 Supervision 1 action	Fault	No action
32.07 Supervision 1 signal	AI1	Frequency
32.09 Supervision 1 low	0.4	0.00

■ **Diagnostics**

LEDs

The adapter module has one diagnostic LED.

Color	Description
Green	The adapter module is powered up.

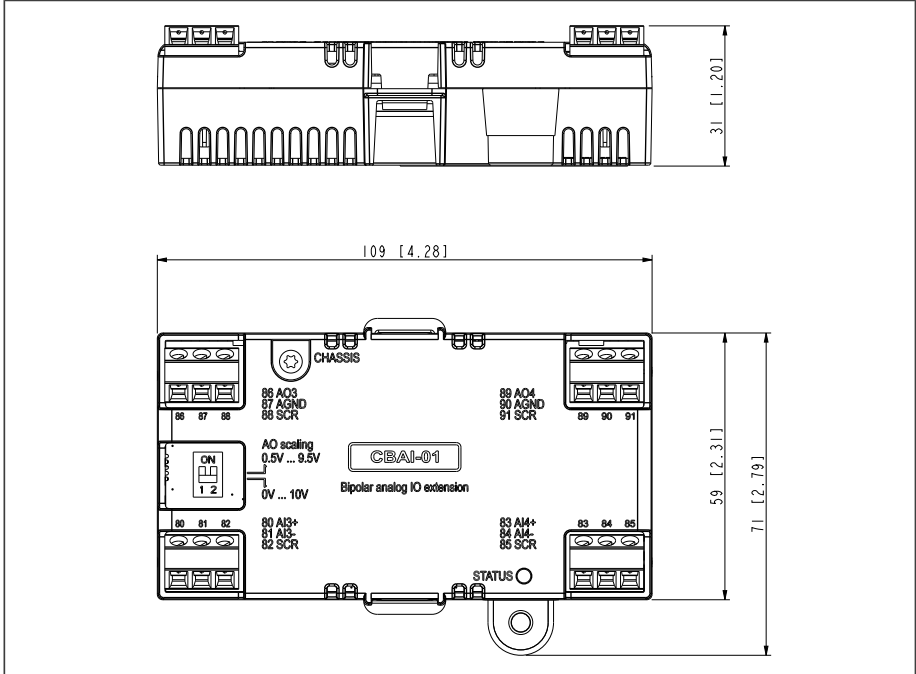
■ **Technical data**

Installation	Into SLOT 2 on the drive control unit
Degree of protection	IP20
Ambient conditions	See the drive technical data.
Package	Cardboard
Analog inputs (80...82, 83...85)	
Maximum wire size	1.5 mm ²
Input voltage (AI+ and AI-)	-10 V ... +10 V
Input resistance	> 200 kohm
Optional cable shield connection	
Analog outputs (86...88, 89...91)	
Maximum wire size	1.5 mm ²
Output voltage (AO+ and AGND)	0 V ... +10 V
Output resistance	< 20 ohm
Recommended load	> 10 kohm
Inaccuracy	typical ±1%, max. ±1.5% of full scale
Optional cable shield connection	
Analog output scale switch	
ON state	0.5 V ... 9.5 V range in use
OFF state	0 V ... 10 V range in use
Isolation areas	
<p style="text-align: center;">CBAI-01</p>	
1	Plugged to drive control unit SLOT2
2	Switch
	Reinforced insulation (IEC 61800-5-1:2007)

.....	Functional insulation (IEC 61800-5-1:2007)
-------	--

■ **Dimension drawing**

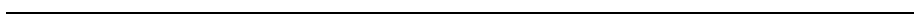
The dimensions are in millimeters and [inches].



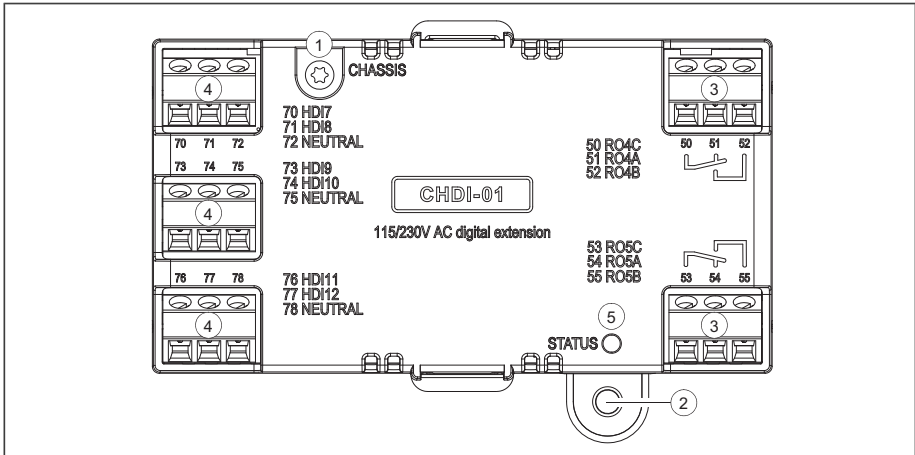
CHDI-01 115/230 V digital input extension module

■ **Product overview**

The CHDI-01 115/230 V digital input extension module expands the inputs of the drive control unit. It has six high voltage inputs and two relay outputs.



■ Layout and connection examples



4		3-pin terminal blocks for 115/230 V inputs	3		Relay outputs
70	HDI7	115/230 V input 1	50	RO4C	Common, C
71	HDI8	115/230 V input 2	51	RO4B	Normally closed, NC
72	NEUTRAL ¹⁾	Neutral point	52	RO4A	Normally open, NO
73	HDI9	115/230 V input 3	53	RO5C	Common, C
74	HDI10	115/230 V input 4	54	RO5B	Normally closed, NC
75	NEUTRAL ¹⁾	Neutral point	55	RO5A	Normally open, NO
76	HDI11	115/230 V input 5	1 Grounding screw		
77	HDI12	115/230 V input 5	2 Hole for mounting screw		
78	NEUTRAL ¹⁾	Neutral point	5 Diagnostic LED. Green = The extension module is powered up.		
¹⁾ Neutral points 72, 75 and 78 are connected.					

■ Mechanical installation

Necessary tools

- Screwdriver and a set of suitable bits.

Unpacking and examining the delivery

1. Open the option package. Make sure that the package contains:
 - the option module
 - a mounting screw.
2. Make sure that there are no signs of damage.

Installing the module

See section [Installing option modules \(page 153\)](#).

■ Electrical installation



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

Stop the drive and do the steps in section [Electrical safety precautions \(page 22\)](#) before you start the work.

Necessary tools

- Screwdriver and a set of suitable bits.

Wiring

Connect the external control cables to the applicable module terminals. Ground the outer shield of the cables 360 degrees under a grounding clamp on the grounding shelf of the control cables.

■ Start-up

Setting the parameters

1. Power up the drive.
 2. If no warning is shown,
 - make sure that the value of both parameters *15.01 Extension module type* and *15.02 Detected extension module* is CHDI-01.
- If warning the *A7AB Extension I/O configuration failure* is shown,
- make sure that the value of parameter *15.02* is CHDI-01.
-

- set parameter 15.01 value to CHDI-01.

You can now see the parameters of the extension module in parameter group 15 *I/O extension module*.

3. Set the parameters of the extension module to applicable values.

Parameter setting example for relay output

This example shows how make the relay output RO4 of the extension module indicate the reverse direction of rotation of the motor with a one-second delay.

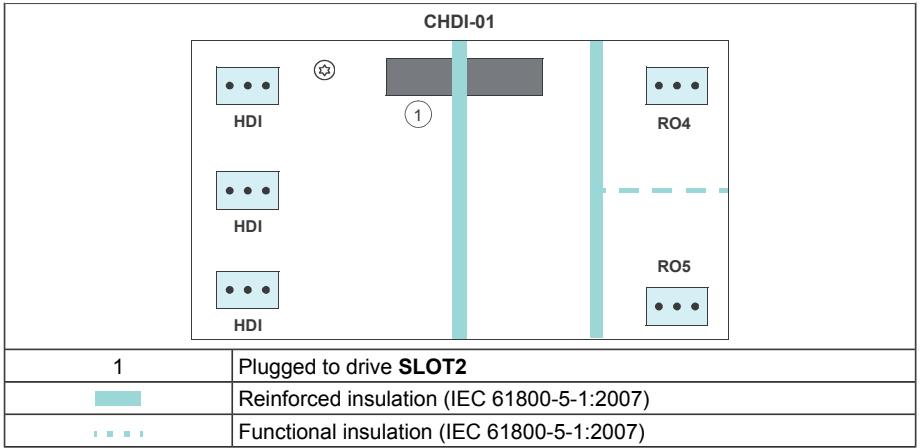
Parameter	Setting
15.07 RO4 source	Reverse
15.08 RO4 ON delay	1 s
15.09 RO4 OFF delay	1 s

■ **Fault and warning messages**

Warning A7AB *Extension I/O configuration failure*.

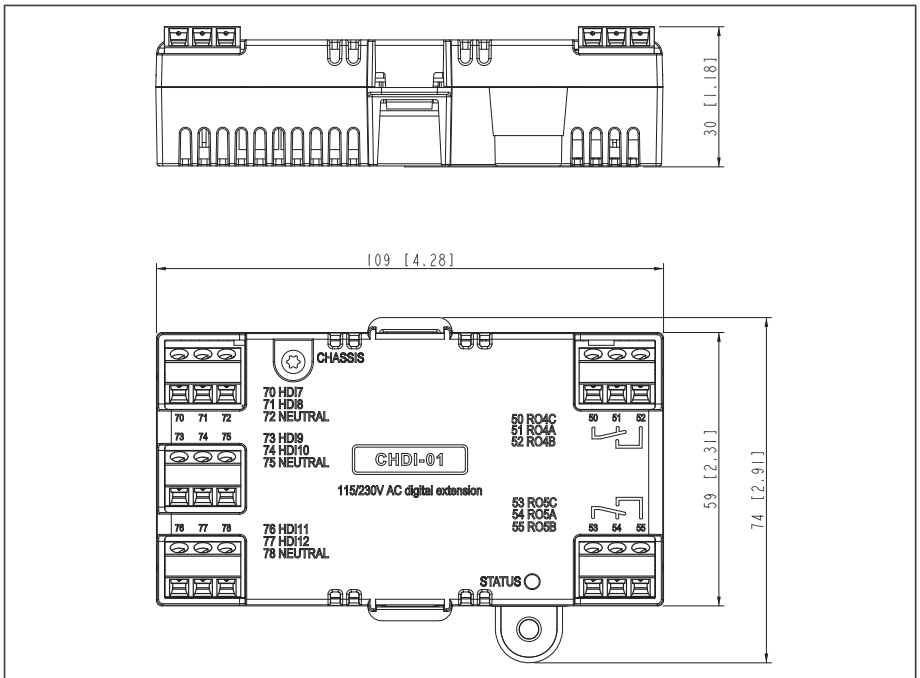
■ **Technical data**

Installation	Into an option slot on the drive control unit
Degree of protection	IP20 / UL Type 1
Ambient conditions	See the drive technical data.
Package	Cardboard
Relay outputs (50...52, 53...55)	
Maximum wire size	1.5 mm ²
Minimum contact rating	12 V / 10 mA
Maximum contact rating	250 V AC / 30 V DC / 2 A
Maximum breaking capacity	1500 VA
115/230 V inputs (70...78)	
Maximum wire size	1.5 mm ²
Input voltage	115 to 230 V AC ±10%
Maximum current leakage in digital off state	2 mA
Isolation areas	



■ Dimension drawing

The dimensions are in millimeters and [inches].



CMOD-01 multifunction extension module (external 24 V AC/DC and digital I/O)

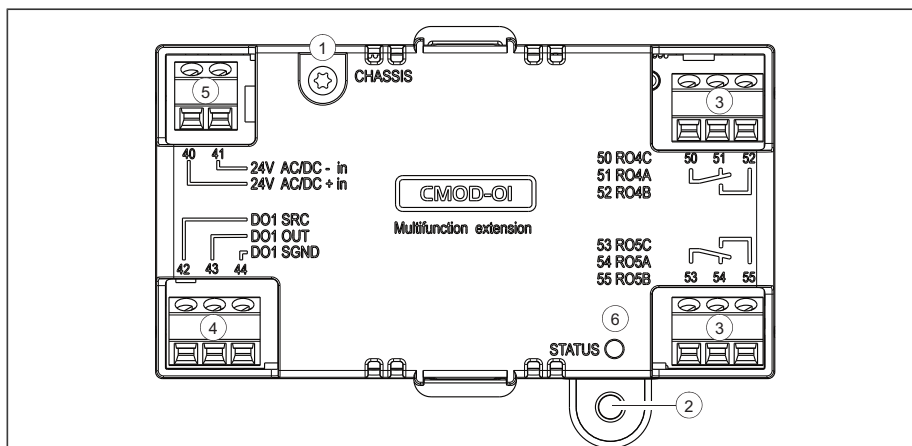
■ Product overview

The CMOD-01 multifunction extension module (external 24 V AC/DC and digital I/O) expands the outputs of the drive control unit. It has two relay outputs and one transistor output, which can function as a digital or frequency output.

In addition, the extension module has an external power supply interface, which can be used to power up the drive control unit in case the drive power supply is not on. If you do not need the back-up power supply, you do not have to connect it because the module is powered from the drive control unit by default.

Note: With CCU-24 control unit, a CMOD-01 module is not necessary for external 24 V AC/DC supply connection. The external supply is connected directly to terminals 40 and 41 on the control unit.

■ Layout and example connections



1	Grounding screw	6	Diagnostic LED
2	Hole for mounting screw		
5	2-pin terminal block for external power supply	3	3-pin terminal blocks for relay outputs
40	24 V AC/DC + in	50	RO4C Common, C
41	24V AC/DC - in	51	RO4A
		52	RO4B

41	24 V AC/DC - in	External 24 V (AC/DC) input	51	RO4A	Normally closed, NC
4	3-pin terminal block for for transistor output		52	RO4B	Normally open, NO
<p>1)</p> <p>2)</p>					
42	DO1 SRC	Source input	53	RO5C	Common, C
43	DO1 OUT	Digital or frequency output	54	RO5A	Normally closed, NC
44	DO1 SGND	Ground (earth) potential	55	RO5B	Normally open, NO

1) Digital output connection example

2) An externally supplied frequency indicator which provides, for example:

- a 40 mA / 12 V DC power supply for the sensor circuit (CMOD frequency output)
- suitable voltage pulse input (10 Hz ... 16 kHz).

■ Mechanical installation

Necessary tools

- Screwdriver and a set of suitable bits.

Unpacking and examining the delivery

1. Open the option package. Make sure that the package contains:
 - the option module
 - a mounting screw.
2. Make sure that there are no signs of damage.

Installing the module

See section [Installing option modules \(page 153\)](#).

■ Electrical installation



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.

Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.

Necessary tools

- Screwdriver and a set of suitable bits

Wiring

Connect the external control cables to the applicable module terminals. Ground the outer shield of the cables 360 degrees under a grounding clamp on the grounding shelf of the control cables.



WARNING!

Do not connect the +24 V AC cable to the control unit ground when the control unit is powered using an external 24 V AC supply.

■ **Start-up**

Setting the parameters

1. Power up the drive.
2. If no warning is shown,
 - make sure that the value of both parameters *15.01 Extension module type* and *15.02 Detected extension module* is CMOD-01.

If the warning *A7AB Extension I/O configuration failure* is shown,

- make sure that the value of parameter *15.02* is CMOD-01.
- set the parameter *15.01* value to CMOD-01.

You can now see the parameters of the extension module in parameter group *15 I/O extension module*.

3. Set the parameters of the extension module to applicable values.

Examples are given below.

Parameter setting example for relay output

This example shows how make relay output RO4 of the extension module indicate the reverse direction of rotation of the motor with a one-second delay.

Parameter	Setting
15.07 RO4 source	Reverse
15.08 RO4 ON delay	1 s
15.09 RO4 OFF delay	1 s

Parameter setting example for digital output

This example shows how to make digital output DO1 of the extension module indicate the reverse direction of rotation of the motor with a one-second delay.

Parameter	Setting
15.22 DO1 configuration	Digital output
15.23 DO1 source	Reverse
15.24 DO1 ON delay	1 s
15.25 DO1 OFF delay	1 s

Parameter setting example for frequency output

This example shows how to make digital output DO1 of the extension module indicate the motor speed 0...1500 rpm with a frequency range of 0...10000 Hz.

Parameter	Setting
15.22 DO1 configuration	Frequency output
15.33 Freq out 1 source	01.01 Motor speed used
15.34 Freq out 1 src min	0
15.35 Freq out 1 src max	1500.00
15.36 Freq out 1 at src min	1000 Hz
15.37 Freq out 1 at src max	10000 Hz

DiagnosticsFaults and warning messages

Warning A7AB Extension I/O configuration failure.

LEDs

The extension module has one diagnostic LED.

Color	Description
Green	The extension module is powered up.

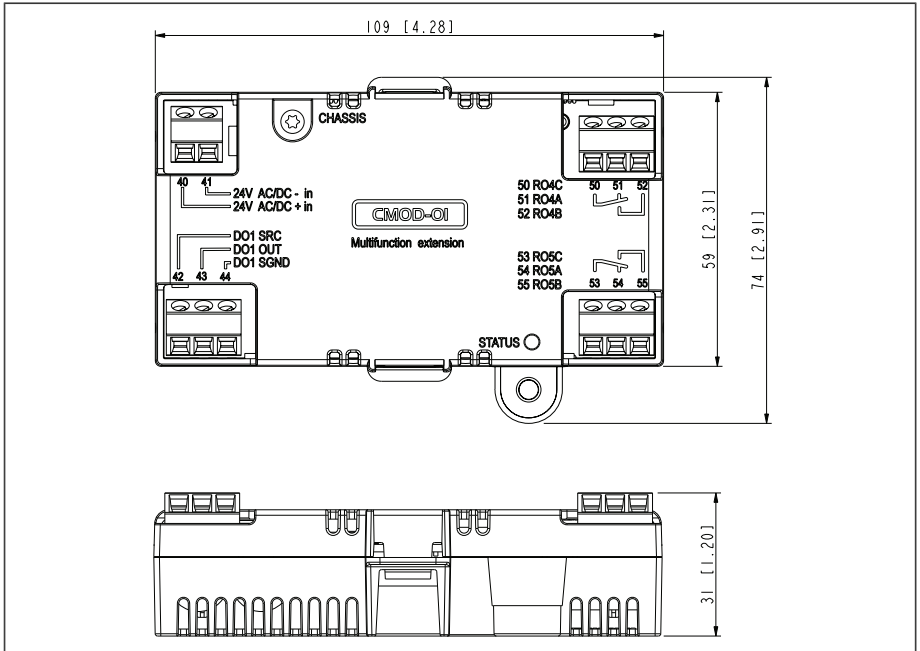
■ **Technical data**

Installation	Into an option slot on the drive control unit
Degree of protection	IP20 / UL Type 1
Ambient conditions	See the drive technical data.

Package	Cardboard
Relay outputs (50...52, 53...55)	
Maximum wire size	1.5 mm ²
Minimum contact rating	12 V / 10 mA
Maximum contact rating	250 V AC / 30 V DC / 2 A
Maximum breaking capacity	1500 VA
Transistor output (42...44)	
Maximum wire size	1.5 mm ²
Type	Transistor output PNP
Maximum load	4 kohm
Maximum switching voltage	30 V DC
Maximum switching current	100 mA / 30 V DC, short-circuit protected
Frequency	10 Hz ... 16 kHz
Resolution	1 Hz
Inaccuracy	0.2%
External power supply (40...41)	
Maximum wire size	1.5 mm ²
Input voltage	24 V AC / V DC ±10% (GND, user potential)
Maximum power consumption	25 W, 1.04 A at 24 V DC
Isolation areas	
1	Plugged to drive SLOT2
	Reinforced insulation (IEC 61800-5-1:2007)
	Functional insulation (IEC 61800-5-1:2007)

■ **Dimension drawing**

The dimensions are in millimeters and [inches].



CMOD-02 multifunction extension module (external 24 V AC/DC and isolated PTC interface)

■ Product overview

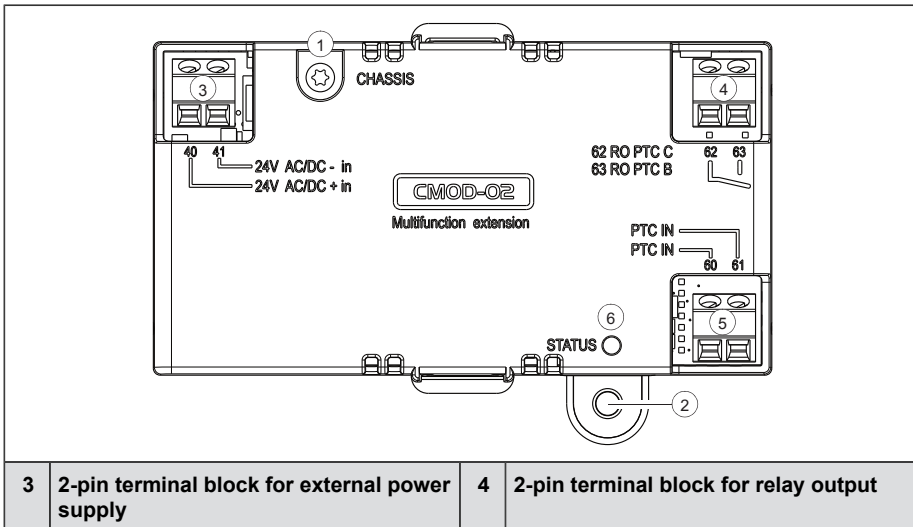
The CMOD-02 multifunction extension module (external 24 V AC/DC and isolated PTC interface) has a motor thermistor connection for supervising the motor temperature and one relay output, which indicates the thermistor status. In case the thermistor overheats, the drive trips on motor overtemperature. If Safe torque off tripping is required, the user must wire the overtemperature indication relay to the certified Safe torque off input of the drive.

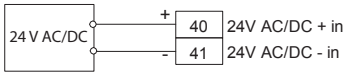
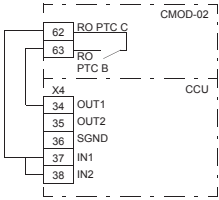
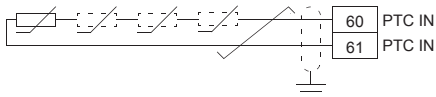
In addition, the extension module has an external power supply interface, which can be used to power up the drive control unit in case the drive power supply is not on. If you do not need the back-up power supply, you do not have to connect it because the module is powered from the drive control unit by default.

There is reinforced insulation between the motor thermistor connection, the relay output and the drive control unit interface. Thus, you can connect a motor thermistor to the drive through the extension module.

Note: With CCU-24 control unit, a CMOD-02 module is not necessary for external 24 V AC/DC supply connection. The external supply is connected directly to terminals 40 and 41 on the control unit.

■ Layout and example connections



					
40	24 V AC/DC + in	External 24 V (AC/DC) input	62	RO PTC C	Common, C
41	24 V AC/DC - in	External 24 V (AC/DC) input	63	RO PTC B	Normally open, NO
5 Motor thermistor connection			1 Grounding screw		
 <p>One to six PTC thermistors connected in series.</p>					
60	PTC IN	PTC connection			
61	PTC IN	Ground (earth) potential	6 Diagnostic LED		

■ **Mechanical installation**

Necessary tools

- Screwdriver and a set of suitable bits.

Unpacking and examining the delivery

1. Open the option package. Make sure that the package contains:
 - the option module
 - a mounting screw.
2. Make sure that there are no signs of damage.

Installing the module

See section *Installing option modules (page 153)*.

■ **Electrical installation**



WARNING!

Obey the safety instructions of the drive. If you ignore them, injury or death, or damage to the equipment can occur.


Stop the drive and do the steps in section *Electrical safety precautions (page 22)* before you start the work.

Necessary tools

- Screwdriver and a set of suitable bits

Wiring

Connect the external control cables to the applicable module terminals. Ground the outer shield of the cables 360 degrees under a grounding clamp on the grounding shelf of the control cables.

 **WARNING!** Do not connect the +24 V AC cable to the control unit ground when the control unit is powered using an external 24 V AC supply.

■ **Start-up**

Setting the parameters

1. Power up the drive.
2. If no warning is shown,
 - make sure that the values of both parameters *15.01 Extension module type* and *15.02 Detected extension module* are CMOD-02.

If the warning *A7AB Extension I/O configuration failure* is shown,

- make sure that the value of parameter *15.02* is CMOD-02.
- set the parameter *15.01* value to CMOD-02.

You can now see the parameters of the extension module in parameter group *15 I/O extension module*.

■ **Diagnostics**

Faults and warning messages

Warning *A7AB Extension I/O configuration failure*.

LEDs

The extension module has one diagnostic LED.

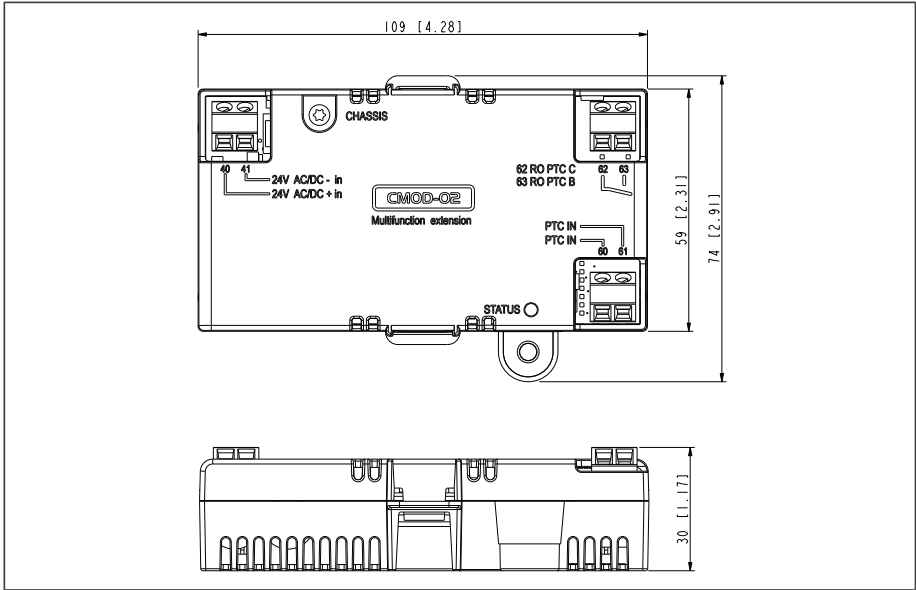
Color	Description
Green	The extension module is powered up.

■ Technical data

Installation	Into option slot 2 on the drive control unit
Degree of protection	IP20 / UL Type 1
Ambient conditions	See the drive technical data.
Package	Cardboard
Motor thermistor connection (60...61)	
Maximum wire size	1.5 mm ²
Supported standards	DIN 44081 and DIN 44082
Triggering threshold	3.6 kohm ±10%
Recovery threshold	1.6 kohm ±10%
PTC terminal voltage	≤ 5.0 V
PTC terminal current	< 1 mA
Short-circuit detection	< 50 ohm ±10%
<p>The PTC input is reinforced/double insulated. If the motor part of the PTC sensor and wiring are reinforced/double insulated, voltages on the PTC wiring are within SELV limits.</p> <p>If the motor PTC circuit is not reinforced/double insulated (ie, it is basic insulated), it is mandatory to use reinforced/double insulated wiring between the motor PTC and CMOD-02 PTC terminal.</p>	
Relay output (62...63)	
Maximum wire size	1.5 mm ²
Maximum contact rating	250 V AC / 30 V DC / 5 A
Maximum breaking capacity	1000 VA
External power supply (40...41)	
Maximum wire size	1.5 mm ²
Input voltage	24 V AC / V DC ±10% (GND, user potential)
Maximum power consumption	25 W, 1.04 A at 24 V DC
Isolation areas	
<p>The diagram shows the CMOD-02 terminal block with four terminals. Terminal 1 is marked with a circled '1' and a lightning bolt symbol, indicating reinforced insulation. Terminal 2 is labeled '24 V_{in}'. Terminal 3 is labeled 'RO PTC'. Terminal 4 is labeled 'PTC_{in}'. A thick vertical blue line separates terminal 1 from the other three terminals. A thick horizontal blue line connects terminal 3 and terminal 4. A thick vertical blue line also separates terminal 3 from terminal 4.</p>	
1	Plugged to drive SLOT2
	Reinforced insulation (IEC 61800-5-1:2007)

■ Dimension drawing

The dimensions are in millimeters and [inches].



15

Common mode, du/dt and sine filters

Content of this chapter

This chapter describes how to select external filters for the drive.

Common mode filters

■ When is a common mode filter needed?

See section [Examining the compatibility of the motor and drive \(page 86\)](#).

Common mode filter kits are available from ABB, see the table on page [Common mode filter types \(page 395\)](#). A kit includes three wound cores. For installation instructions of the cores, see the instruction included in the core package.

■ Common mode filter types

IEC ratings at $U_n = 400\text{ V}$ and 480 V , UL (NEC) ratings at $U_n = 480\text{ V}$

For common mode filters for smaller types, contact your local representative.

IEC type ACS580-01-	Common mode filters ABB drives	Frame size	North American type ACS580-01-
062A-4	64315811	R4	052A-4
073A-4	64315811	R4	065A-4
088A-4	64315811	R5	078A-4
106A-4	64315811	R5	096A-4

IEC type ACS580-01-	Common mode filters ABB drives	Frame size	North American type ACS580-01-
145A-4	3AXD50000017269	R6	124A-4
169A-4	3AXD50000017270	R7	156A-4
206A-4	3AXD50000017270	R7	180A-4
246A-4	3AXD50000018001	R8	240A-4
293A-4	3AXD50000018001	R8	-
363A-4	3AXD50000017940	R9	361A-4
430A-4	3AXD50000017940	R9	414A-4

du/dt filters

■ When is a du/dt filter needed?

See section *Examining the compatibility of the motor and drive (page 86)*.

See the table of du/dt filters on page *Common mode filter types (page 395)*.

■ du/dt filter types

IEC ratings at $U_n = 230\text{ V}$, UL (NEC) ratings at $U_n = 208/230\text{ V}$

IEC type ACS580-01-	Frame size	du/dt filters ABB drives	North American type ACS580-01-
04A7-2	R1	NOCH0016-6x	04A6-2
06A7-2	R1	NOCH0016-6x	06A6-2
07A6-2	R1	NOCH0016-6x	07A5-2
012A-2	R1	NOCH0016-6x	10A6-2
018A-2	R1	NOCH0016-6x	017A-2
025A-2	R2	NOCH0030-6x	024A-2
032A-2	R2	NOCH0030-6x	031A-2
047A-2	R3	NOCH0070-6x	046A-2
060A-2	R3	NOCH0070-6x	059A-2
-	R4	NOCH0070-6x	075A-2
089A-2	R5	NOCH0070-6x	088A-2
115A-2	R5	NOCH0120-6x	114A-2
144A-2	R6	FOCH0260-70	143A-2
171A-2	R7	FOCH0260-70	169A-2
213A-2	R7	FOCH0260-70	211A-2
276A-2	R8	FOCH0260-70	273A-2
-	R9	FOCH0320-50	343A-2
-	R9	FOCH0320-50	396A-2

IEC ratings at $U_n = 400$ and 480 V, UL (NEC) ratings at $U_n = 480$ V

IEC type ACS580-01-	Frame size	du/dt filters ABB drives	North American type ACS580-01-
02A7-4	R1	NOCH0016-6x	02A1-4
03A4-4	R1	NOCH0016-6x	03A0-4
04A1-4	R1	NOCH0016-6x	03A5-4
05A7-4	R1	NOCH0016-6x	04A8-4
07A3-4	R1	NOCH0016-6x	06A0-4
09A5-4	R1	NOCH0016-6x	07A6-4
12A7-4	R1	NOCH0016-6x	012A-4
018A-4	R2	NOCH0016-6x or NOCH0030-6x	014A-4
026A-4	R2	NOCH0030-6x	023A-4
033A-4	R3	NOCH0070-6x	027A-4
039A-4	R3	NOCH0070-6x	034A-4
046A-4	R3	NOCH0070-6x	044A-4
062A-4	R4	NOCH0070-6x	052A-4
073A-4	R4	NOCH0070-6x or NOCH0120-6x	065A-4
088A-4	R5	NOCH0120-6x	078A-4
106A-4	R5	NOCH0120-6x	096A-4
145A-4	R6	FOCH0260-70	124A-4
169A-4	R7	FOCH0260-70	156A-4
206A-4	R7	FOCH0260-70	180A-4
246A-4	R8	FOCH0260-70	240A-4
293A-4	R8	FOCH0260-70	260A-4
363A-4	R9	FOCH0320-50	361A-4
430A-4	R9	FOCH0320-50	414A-4

UL (NEC) ratings at $U_n = 600$ V

North American type ACS580-01-	Frame size	du/dt filters ABB drives
02A7-6	R2	NOCH0016-6x
03A9-6	R2	NOCH0016-6x
06A1-6	R2	NOCH0016-6x
09A0-6	R2	NOCH0016-6x
011A-6	R2	NOCH0016-6x
017A-6	R2	NOCH0016-6x
022A-6	R3	NOCH0030-6x
027A-6	R3	NOCH0030-6x
032A-6	R3	NOCH0070-6x

North American type ACS580-01-	Frame size	du/dt filters ABB drives
041A-6	R5	FOCH0070-6x
052A-6	R5	FOCH0070-6x
062A-6	R5	FOCH0070-6x
077A-6	R5	FOCH0120-6x
099A-6	R7	FOCH0260-70
125A-6	R7	FOCH0260-70
144A-6	R8	FOCH0260-70
192A-6	R8	FOCH0260-70
242A-6	R9	FOCH0260-70
271A-6	R9	FOCH0260-70

■ **Description, installation and technical data of the FOCH filters**

See *FOCH du/dt filters hardware manual* (3AFE68577519 [English]).

■ **Description, installation and technical data of the NOCH filters**

See *AOCH and NOCH du/dt filters hardware manual* (3AFE58933368 [English]).

Sine filters

■ **IEC ratings at $U_n = 400$ V, UL (NEC) ratings at $U_n = 480$ V**

IEC type ACS580-01-	Sine filter type		Frame size	North American type ACS580-01-
	IP00	IP20		
02A7-4	B84143V0006R231	B84143V0004R229 + B84143Q0002R229	R1	02A1-4
03A4-4	B84143V0006R231	B84143V0004R229 + B84143Q0002R229	R1	03A0-4
04A1-4	B84143V0006R231	B84143V0004R229 + B84143Q0002R229	R1	03A5-4
05A7-4	B84143V0006R231	B84143V0006R229 + B84143Q0002R229	R1	04A8-4
07A3-4	B84143V0007R231	B84143V0011R229 + B84143Q0004R229	R1	06A0-4
09A5-4	B84143V0012R231	B84143V0011R229 + B84143Q0004R229	R1	07A6-4
12A7-4	B84143V0012R231	B84143V0016R229 + B84143Q0006R229	R1	012A-4
018A-4	B84143V0016R229	B84143V0016R229 + B84143Q0006R229	R2	014A-4

026A-4	B84143V0038R231	B84143V0025R229 + B84143Q0008R229	R2	023A-4
033A-4	B84143V0038R231	B84143V0033R229 + B84143Q0008R229	R3	027A-4
039A-4	B84143V0038R231	B84143V0050R229 + B84143Q0010R229	R3	034A-4
046A-4	B84143V0043R231	B84143V0050R229 + B84143Q0010R229	R3	044A-4
062A-4	B84143V0064R231	B84143V0066R229 + B84143Q0010R229	R4	052A-4
073A-4	B84143V0064R231	B84143V0066R229 + B84143Q0010R229	R4	065A-4
088A-4	B84143V0077R231	B84143V0095R229 + B84143Q0012R229	R5	078A-4
106A-4	B84143V0091R231	B84143V0095R229 + B84143Q0012R229	R5	096A-4
145A-4	B84143V0145R231	B84143V0162S229 + B84143Q0014R229	R6	124A-4
169A-4	B84143V0209R231	B84143V0162S229 + B84143Q0014R229	R7	156A-4
206A-4	B84143V0209R231	B84143V0230S229 + B84143Q0016R229	R7	180A-4
246A-4	B84143V0209R231	B84143V0230S229 + B84143Q0016R229	R8	240A-4
293A-4	B84143V0249R231	B84143V0390S229 + B84143Q0018R229	R8	260A-4
363A-4	B84143V0390S229	B84143V0390S229 + B84143Q0018R229	R9	361A-4
430A-4	B84143V0390S229	B84143V0390S229 + B84143Q0018R229	R9	414A-4

■ Description, installation and technical data

See *Sine filters hardware manual* (3AXD50000016814 [English]).



Further information

Product and service inquiries

Address any inquiries about the product to your local ABB representative, quoting the type designation and serial number of the unit in question. A listing of ABB sales, support and service contacts can be found by navigating to www.abb.com/searchchannels.

Product training

For information on ABB product training, navigate to new.abb.com/service/training.

Providing feedback on ABB manuals

Your comments on our manuals are welcome. Navigate to new.abb.com/drives/manuals-feedback-form.

Document library on the Internet

You can find manuals and other product documents in PDF format on the Internet at www.abb.com/drives/documents.



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